```
Γ[X_{i_,j_,k_,l_}[S_, T_]] := Γ[{{l, i}, {j, k}, <|ξ_i → S, x_j → T, x_k → S, ξ_l → T|>,
    T^(-1/2), CF[{ξ_l, ξ_i}.{{1, 1 - T}, {0, T}}.{x_j, x_k}]]];
Γ[X̄_{i_,j_,k_,l_}[S_, T_]] := Γ[{{i, j}, {k, l}, <|ξ_i → S, ξ_j → T, x_k → S, x_l → T|>,
    T^(1/2), CF[{ξ_i, ξ_j}.{{T^-1, 0}, {1 - T^-1, 1}}.{x_k, x_l}]]];
Γ[X_{i_,j_,k_,l_}] := Γ[X_{i,j,k,l}[τ_i, τ_l]];
Γ[X̄_{i_,j_,k_,l_}] := Γ[X̄_{i,j,k,l}[τ_i, τ_j]];
```