

$$\left\{ \begin{array}{c} \omega \\ P_1 \\ P_2 \\ P_3 \end{array} \begin{array}{c} x_1 \\ \alpha \\ \gamma \\ \phi \end{array} \begin{array}{c} x_2 \\ \beta \\ \delta \\ \psi \end{array} \begin{array}{c} x_3 \\ \theta \\ \epsilon \\ [\epsilon] \end{array} \right\}_h, \left\{ \begin{array}{c} \omega + \gamma \omega \\ P_\theta \\ P_3 \end{array} \begin{array}{c} X_\theta \\ \frac{\alpha + \beta + \gamma + \beta \gamma + \delta - \alpha \delta}{1 + \gamma} \\ \frac{\phi - \delta \phi + \psi + \gamma \psi}{1 + \gamma} \end{array} \begin{array}{c} X_3 \\ \frac{\epsilon - \alpha \epsilon + \theta + \gamma \theta}{1 + \gamma} \\ \frac{\epsilon + \gamma \epsilon - \epsilon \phi}{1 + \gamma} \end{array} \right\}_h$$