

$\text{K}\delta_{i_,j_} := \text{KroneckerDelta}[i, j];$

$\text{TG}_{i_,j_}[\mathcal{F}_] := \text{Expand}[\mathcal{F} /. \{$   
     $\mathbf{f}_. \mathbf{v}_{k_} \rightarrow \text{Plus}[\mathbf{f} \mathbf{v}_k /. \mathbf{v}_j \rightarrow (1 - t_i) \mathbf{v}_i + t_i \mathbf{v}_j,$   
     $(1 - t_i^{-1}) (t_i \partial_{t_i} \mathbf{f} - t_j \partial_{t_j} \mathbf{f}) *$   
     $(\mathbf{u}_k /. \mathbf{u}_j \rightarrow (1 - t_i) \mathbf{u}_i + t_i \mathbf{u}_j) * \mathbf{u}_i \mathbf{w}_j,$   
     $\text{K}\delta_{k,i} \mathbf{f} (\mathbf{u}_j - \mathbf{u}_i) \mathbf{u}_i \mathbf{w}_j],$   
     $\mathbf{u}_j \rightarrow (1 - t_i) \mathbf{u}_i + t_i \mathbf{u}_j,$   
     $\mathbf{w}_i \rightarrow \mathbf{w}_i + (1 - t_i^{-1}) \mathbf{w}_j, \mathbf{w}_j \rightarrow t_i^{-1} \mathbf{w}_j\}];$

$\text{bas} = \{\mathbf{f}[t_1, t_2, t_3] \mathbf{v}_1, \mathbf{f}[t_1, t_2, t_3] \mathbf{v}_2, \mathbf{f}[t_1, t_2, t_3] \mathbf{v}_3,$   
     $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\};$