

Shifted Partial Quadratics, their Pushforwards, and Signature Invariants for Tangles

Abstract. Following a general discussion of the computation of zombians of unfinished columbaria (with examples), I will tell you about my recent joint work w/ Jessica Liu on what we feel is the “textbook” extension of knot signatures to tangles, which for unknown reasons, is not in any of the textbooks that we know.



Jessica Liu



Columbaria in an East Sydney Cemetery



Jacobian, Hamiltonian, Zombian

Kashaev's Conjecture [Ka] For knots, $\sigma_{Kas} = 2\sigma_{TL}$.

Liu's Theorem [Li].

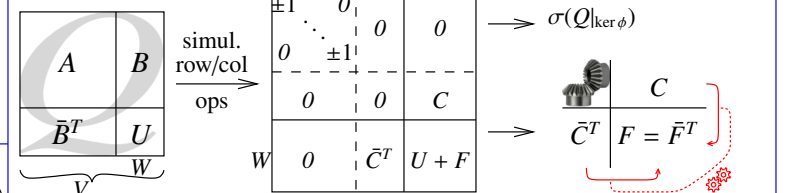
A **Partial Quadratic (PQ)** on V is a quadratic Q defined only on a subspace $\mathcal{D}_Q \subset V$. We add PQs with $\mathcal{D}_{Q_1+Q_2} := \mathcal{D}_{Q_1} \cap \mathcal{D}_{Q_2}$. Given a linear $\psi: V \rightarrow W$ and a PQ Q on W , there is an obvious **pullback** ψ^*Q , a PQ on V .

Theorem 1. Given a linear $\phi: V \rightarrow W$ and a PQ Q on V , there is a unique **pushforward** PQ ϕ_*Q on W such that for every PQ U on W , $\sigma_V(Q + \phi^*U) = \sigma_{\ker \phi}(Q|_{\ker \phi}) + \sigma_W(U + \phi_*Q)$.

(If you must, $\mathcal{D}(\phi_*Q) = \phi(\text{ann}_Q(\mathcal{D}(Q) \cap \ker \phi))$ and $(\phi_*Q)(w) = Q(v)$, where v is s.t. $\phi(v) = w$ and $Q(v, \text{rad } Q|_{\ker \phi}) = 0$).

Prior Art on signatures for tangles / braids. Gambaudo and Ghys [GG], Cimasoni and Conway [CC], Conway [Co], Merz [Me]. All define signatures of tangles / braids by first closing them to links and then work hard to derive composition properties.

Gist of the Proof.



... and the quadratic $F := \phi_*Q$ is well-defined only on $D := \ker C$.

Exactly what we want, if the Zombian is the signature!

V : The full space of faces.

W : The boundary, made of gaps.

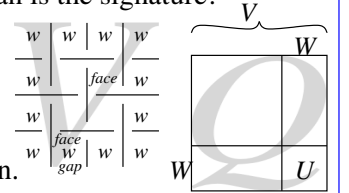
Q : The known parts.

U : The part yet unknown.

$\sigma_V(Q + \phi^*(U))$: The overall Zombian.

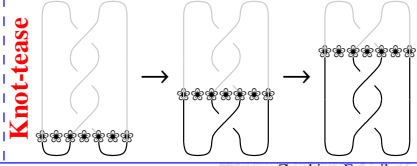
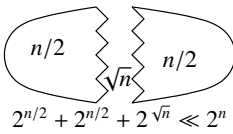
$\sigma(Q|_{\ker \phi})$: An internal bit. $U + \phi_*Q$: A boundary bit.

And so our ZPUC is the pair $S = (\sigma(Q|_{\ker \phi}), \phi_*Q)$.



Why Tangles? • Faster!

- Conceptually clearer proofs of invariance (and of skein relations).
- Often fun and consequential:
 - The Jones Polynomial \rightsquigarrow The Temperley-Lieb Algebra.
 - Khovanov Homology \rightsquigarrow “Unfinished complexes”, complexes in a category.
 - The Kontsevich Integral \rightsquigarrow Associators.
 - HFK \rightsquigarrow OMG, type D , type A , $\mathcal{A}_\infty, \dots$



Computing Zombians of Unfinished Columbaria.

- Must be no slower than for finished ones.
- Future zombians must be able to complete the computation.
- Future zombians must not even know the size of the task that today's zombies were facing.
- We must be able to extend to ZPUCs, Zombie Processed Unfinished Columbaria!

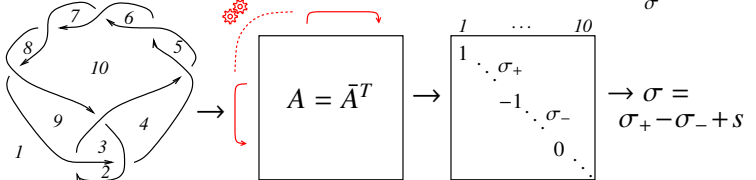


Columbarium near Assen

Example / Exercise. Compute the determinant of a $1,000 \times 1,000$ matrix in which 50 entries are not yet given.

Homework / Research Projects. • What with ZPUCs? • Use this to get an Alexander tangle invariant.

Reminders. {knots} \rightleftharpoons {matrices / quadratic forms} $\xrightarrow{\text{signature } \sigma} \mathbb{Z}$:



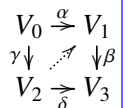
A **Shifted Partial Quadratic (SPQ)** on V is a pair $S = (s \in \mathbb{Z}, Q \text{ a PQ on } V)$. addition also adds the shifts, pullbacks keep the shifts, yet $\phi_*S := (s + \sigma_{\ker \phi}(Q|_{\ker \phi}), \phi_*Q)$ and $\sigma(S) := s + \sigma(Q)$.

Theorem 1' (Reciprocity). Given $\phi: V \rightarrow W$, for SPQs S on V and U on W we have $\sigma_V(S + \phi^*U) = \sigma_W(U + \phi_*S)$ (and this characterizes ϕ_*S).

Note. ψ^* is additive but ϕ_* is not.

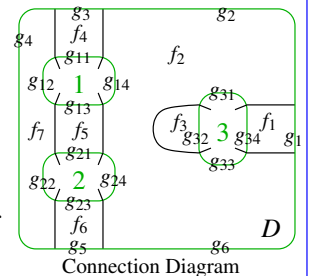
Theorem 2. ψ^* and ϕ_* are functorial.

Theorem 3. If, as on the right, $\beta\alpha = \delta\gamma$ and α and γ are surjective, then $\alpha_*\gamma^* = \beta^*\delta_*$. (Correction: <http://drorbn.net/ge23/PQ-UC.pdf>)

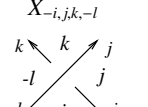


Definition. $S \left(\begin{matrix} g_2 \\ g_3 \dots g_1 \end{matrix} \right) := \left\{ \begin{matrix} \text{SPQ } S \\ \text{on } \langle g_i \rangle \end{matrix} \right\}$.

Theorem 4 (!). $\{S(\text{cyclic sets})\}$ is a planar algebra, with compositions $S(D)((S_i)) := \phi_*^D(\psi_D^*(\bigoplus_i S_i))$, where $\psi_D: \langle f_i \rangle \rightarrow \langle g_{oi} \rangle$ maps every face of D to the sum of the input gaps adjacent to it and $\phi^D: \langle f_i \rangle \rightarrow \langle g_i \rangle$ maps every face to the sum of the output gaps adjacent to it. So for our D , ψ_D is $f_1 \mapsto g_{34}$, $f_2 \mapsto g_{31} + g_{14} + g_{24} + g_{33}$, $f_3 \mapsto g_{32}$, $f_4 \mapsto g_{11}$, $f_5 \mapsto g_{13} + g_{21}$, $f_6 \mapsto g_{23}$, $f_7 \mapsto g_{12} + g_{22}$ and ϕ^D is $f_1 \mapsto g_1$, $f_2 \mapsto g_2 + g_6$, $f_3 \mapsto 0$, $f_4 \mapsto g_3$, $f_5 \mapsto 0$, $f_6 \mapsto g_5$, $f_7 \mapsto g_4$.



With $|\omega| = 1$, $t = 1 - \omega$, $r = t + \bar{t}$, $v = \text{Re}(\omega)$, and $u = \text{Re}(\omega^{1/2})$:

$X_{-i,j,k,-l}$	Tristram-Levine (TL)	Kashaev (Kas)
	$A += \begin{pmatrix} -r & -t & 2t & \bar{t} \\ -\bar{t} & 0 & \bar{t} & 0 \\ 2\bar{t} & t & -r & -\bar{t} \\ t & 0 & -t & 0 \end{pmatrix}$	$A += \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}$
$\bar{X}_{-i,j,k,-l}$	$A += \begin{pmatrix} r & -t & -2\bar{t} & \bar{t} \\ -\bar{t} & 0 & \bar{t} & 0 \\ -2t & t & r & -\bar{t} \\ t & 0 & -t & 0 \end{pmatrix}$	$A += \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}$

Theorem 5. TL and Kas, defined on X and \bar{X} as before, extend to planar algebra morphisms $\{\text{tangles}\} \rightarrow \{S\}$.



Implementation (sources: <http://drorbn.net/icerm23/ap>). I like it most when the implementation matches the math perfectly. We failed here.

Once[<< KnotTheory`];

Loading KnotTheory` version

of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Utilities. The step function, algebraic numbers, canonical forms.

$\theta[x_]$ /; NumericQ[x] := UnitStep[x]

```
 $\omega 2[v\_][p\_]$  := Module[{q = Expand[p], n, c},
  If[q == 0, 0,
    c = Coefficient[q,  $\omega$ , n = Exponent[q,  $\omega$ ]];
     $c v^n + \omega 2[v][q - c(\omega + \omega^{-1})^n]$ ];
```

```
sign[ $\mathcal{E}$ _] := Module[{n, d, v, p, rs, e, k},
  {n, d} = NumeratorDenominator[ $\mathcal{E}$ ];
  {n, d} /=  $\omega^{\text{Exponent}[n, \omega]/2 + \text{Exponent}[n, \omega, \text{Min}]/2}$ ;
  p = Factor[ $\omega 2[v]@n * \omega 2[v]@d / . v \rightarrow 4 u^2 - 2$ ];
  rs = Solve[p == 0, u, Reals];
  If[rs == {}, Sign[p /. u -> 0],
    rs = Union@{u /. rs};
    Sign[(-1)e=Exponent[p, u] Coefficient[p, u, e]] + Sum[
      k = 0;
      While[{d = RootReduce[ $\partial_{\{u, ++k\}} p / . u \rightarrow r$ ]} == 0];
      If[EvenQ[k], 0, 2 Sign[d]] *  $\theta[u - r]$ ,
      {r, rs}]]
  ]
]
```

SetAttributes[B, Orderless];

$CF[b_B]$:= RotateLeft[#, First@Ordering[#] - 1] & /@ DeleteCases[b, {}]

$CF[\mathcal{E}_]$:= Module[{ $\gamma s = \text{Union@Cases}[\mathcal{E}, \gamma_ | \bar{\gamma}_, \infty]$ },
Total[CoefficientRules[$\mathcal{E}, \gamma s$] /.
($ps_ \rightarrow c_$) => Factor[c] \times Times@@ γs^{ps}]]

$CF[\{\}] = \{\}$;

$CF[C_List]$:=

```
Module[{ $\gamma s = \text{Union@Cases}[C, \gamma_, \infty], \gamma$ },
  CF /@ DeleteCases[0] [
    RowReduce[Table[ $\partial_{\gamma} r$ , {r, C}, { $\gamma, \gamma s$ }]]. $\gamma s$ ] ]
```

(\mathcal{E} _)* := $\mathcal{E} / . \{\bar{\gamma} \rightarrow \gamma, \gamma \rightarrow \bar{\gamma}, \omega \rightarrow \omega^{-1}, c_Complex \rightarrow c^*\}$;

r_Rule^+ := {r, r*}

RulesOf[$\gamma_i + rest_$] := ($\gamma_i \rightarrow -rest$)+;

$CF[PQ[C_, q_]]$:= Module[{nC = CF[C]},
PQ[nC, CF[q /. Union@@RulesOf /@nC]]]

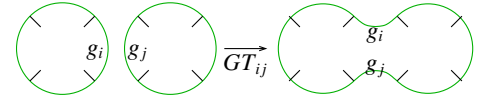
$CF[\Sigma_b[\sigma_, pq_]]$:= $\Sigma_{CF[b]}$ [σ , CF[pq]]

Pretty-Printing.

```
Format[ $\Sigma_{b,B}[\sigma_, PQ[C_, q\_]]$ ] := Module[{ $\gamma s$ },
   $\gamma s = \gamma\#$  & /@ Join@@b;
  Column[{TraditionalForm@ $\sigma$ ,
    TableForm[Join[
      Prepend[""] /@ Table[TraditionalForm[ $\partial_c r$ ],
        {r, C}, {c,  $\gamma s$ }],
      {Prepend[""] [
        Join@@
          (b /. {L_, m___, r_} =>
            {DisplayForm@RowBox[{"(", L}],
              m, DisplayForm@RowBox[{r, ")"}]}) / .
            i_Integer =>  $\gamma_i$  ]}],
      MapThread[Prepend,
        {Table[TraditionalForm[ $\partial_{r,c} q$ ], {r,  $\gamma s^*$ },
          {c,  $\gamma s$ }],  $\gamma s^*$ }]
      ], TableAlignments -> Center]
    ], Center] ];
```

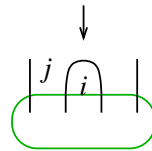
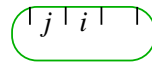
The Face-Centric Core.

$\Sigma_{b1}[\sigma_1, PQ[C1_, q1_]] \oplus \Sigma_{b2}[\sigma_2, PQ[C2_, q2_]] \wedge :=$
 $CF@_{\Sigma_{\text{Join}[b1, b2]}}[\sigma_1 + \sigma_2, PQ[C1 \cup C2, q1 + q2]]$;



GT for Gap Touch:

$GT_{i,j}@_{\Sigma_B[\{li_ , i, ri_ \}, \{lj_ , j, rj_ \}, bs_]}[\sigma_,$
 $PQ[C_, q_]] :=$
 $CF@_{\Sigma_B[\{ri, li, j, rj, lj, i\}, bs]}[\sigma, PQ[C \cup \{\gamma_i - \gamma_j\}, q]]$



cordon (kôr'dn)

n.

1. A line of people, military posts, or ships stationed around an area to enclose or guard it: *a police cordon*.
2. A rope, line, tape, or similar border stretched around an area, usually by the police, indicating that access is restricted.



$s \begin{pmatrix} 0 & \phi C_{rest} \\ \bar{\phi}^T & \lambda \theta \\ \bar{C}_{rest}^T & \bar{\theta}^T A_{rest} \end{pmatrix} \rightarrow \begin{cases} \exists p \phi_p \neq 0 & \text{use } \phi_p \text{ to kill its row and} \\ \phi = 0, \lambda \neq 0 & \text{column, drop a } \begin{pmatrix} 01 \\ 10 \end{pmatrix} \text{ summand} \\ \phi = 0, \lambda = 0 & \text{use } \lambda \text{ to kill } \theta, \text{ let } s += \text{sign}(\lambda) \\ & \text{append } \theta \text{ to } C_{rest}. \end{cases}$

$Cordon_i@_{\Sigma_B[\{li_ , i, ri_ \}, bs_]}[\sigma_, PQ[C_, q_]] :=$

```
Module[{ $\phi = \partial_{\gamma_i} C$ ,  $\lambda = \partial_{\bar{\gamma}_i, \gamma_i} q$ ,  $n\sigma = \sigma$ ,  $nC$ ,  $nq$ ,  $p$ },
  {p} = FirstPosition[ (# != 0) & /@  $\phi$ , True, {0}];
  {nC, nq} = Which[
    p > 0, {C, q} /. ( $\gamma_i \rightarrow -C[[p]] / \phi[[p]]$ ) + / . ( $\gamma_i \rightarrow \theta$ ) +,
     $\lambda \neq 0$ , ( $n\sigma += \text{sign}[\lambda]$ );
    {C, q} /. ( $\gamma_i \rightarrow -(\partial_{\bar{\gamma}_i} q) / \lambda$ ) + / . ( $\gamma_i \rightarrow \theta$ ) +},
     $\lambda == 0$ , {C  $\cup$  { $\partial_{\bar{\gamma}_i} q$ }, q} /. ( $\gamma_i \rightarrow \theta$ ) +};
  CF@ $\Sigma_B[\text{Most}@\{ri, li\}, bs]$  [n $\sigma$ ,
    PQ[nC, nq] /. ( $\gamma_{\text{Last}@\{ri, li\}} \rightarrow \gamma_{\text{First}@\{ri, li\}}$ ) + ] ]
```

Strand Operations. c for contract, mc for magnetic contract:

$$C_{i,j}@t : \Sigma_B[\{l_{i,j}, i, r_{i,j}\}, \{c, j, \dots\}, \dots] [] := \\ t // GT_{j, \text{First}\{r_i, l_i\}} // \text{Cordon}_j$$

$$C_{i,j}@t : \Sigma_B[\{c, i, j, \dots\}, \dots] [] := \text{Cordon}_j @ t$$

$$C_{i,j}@t : \Sigma_B[\{j, \dots, i, \dots\}, \dots] [] := \text{Cordon}_j @ t$$

$$C_{i,j}@t : \Sigma_B[\{c, j, i, \dots\}, \dots] [] := \text{Cordon}_i @ t$$

$$C_{i,j}@t : \Sigma_B[\{i, \dots, j, \dots\}, \dots] [] := \text{Cordon}_i @ t$$

$$mc[\mathcal{E}_] := \mathcal{E} //$$

$$t : \Sigma_B[\{c, i, \dots\}, \{c, j, \dots\}, \dots] [] | \\ \Sigma_B[\{c, i, j, \dots\}, \dots] [] | \Sigma_B[\{j, \dots, i, \dots\}, \dots] [] / ; \\ i + j == \theta \Rightarrow C_{i,j}@t$$

The Crossings (and empty strands).

$$\text{Kas}@P_{i,j} := CF @ \Sigma_B[\{i, j\}] [\theta, PQ[\{\}, \theta]] ;$$

$$TL @ P_{i,j} := CF @ \Sigma_B[\{i, j\}] [\theta, PQ[\{\}, \theta]]$$

$$\text{Kas}[x : X[i, j, k, l]] :=$$

$$\text{Kas}@If[\text{PositiveQ}[x], X_{-i, j, k, -l}, \bar{X}_{-j, k, l, -i}] ;$$

$$\text{Kas}[(x : X | \bar{X})_{fs}] := \text{Module}[\{v = 2u^2 - 1, p, \gamma s, m\},$$

$$\gamma s = \gamma_{\#} \& / @ \{fs\}; p = (x == X);$$

$$m = If[p, \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}, - \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}] ;$$

$$CF @ \Sigma_B[\{fs\}] [If[p, -1, 1], PQ[\{\}, \gamma s^* . m . \gamma s]]$$

$$TL[x : X[i, j, k, l]] :=$$

$$TL @ If[\text{PositiveQ}[x], X_{-i, j, k, -l}, \bar{X}_{-j, k, l, -i}] ;$$

$$TL[(x : X | \bar{X})_{fs}] := \text{Module}[\{t = 1 - \omega, r, \gamma s, m\},$$

$$r = t + t^*; \gamma s = \gamma_{\#} \& / @ \{fs\};$$

$$m = If[x == X,$$

$$\begin{pmatrix} -r & -t & 2t & t^* \\ -t^* & \theta & t^* & \theta \\ 2t^* & t & -r & -t^* \\ t & \theta & -t & \theta \end{pmatrix}, \begin{pmatrix} r & -t & -2t^* & t^* \\ -t^* & \theta & t^* & \theta \\ -2t & t & r & -t^* \\ t & \theta & -t & \theta \end{pmatrix}] ;$$

$$CF @ \Sigma_B[\{fs\}] [\theta, PQ[\{\}, \gamma s^* . m . \gamma s]]$$

Evaluation on Tangles and Knots.

$$\text{Kas}[K_] := \text{Fold}[mc[\#1 @ \#2] \&, \Sigma_B[\{\theta, PQ[\{\}, \theta]\}], \\ \text{List} @@ (\text{Kas} / @ PD @ K)] ;$$

$$\text{KasSig}[K_] := \text{Expand}[\text{Kas}[K][[1]] / 2]$$

$$TL[K_] :=$$

$$\text{Fold}[mc[\#1 @ \#2] \&, \Sigma_B[\{\theta, PQ[\{\}, \theta]\}], \\ \text{List} @@ (TL / @ PD @ K)] / .$$

$$\theta[c_{-} + u] / ; \text{Abs}[c] \geq 1 \Rightarrow \theta[c] ;$$

$$TL\text{Sig}[K_] := TL[K][[1]]$$

Reidemeister 3.

$$R3L = PD[X_{-2,5,4,-1}, X_{-3,7,6,-5}, \\ X_{-6,9,8,-4}] ;$$

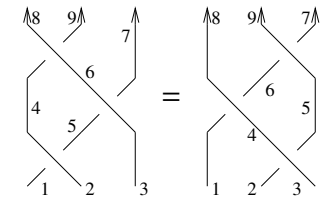
$$R3R = PD[X_{-3,5,4,-2}, X_{-4,6,8,-1}, \\ X_{-5,7,9,-6}] ;$$

$$\{TL @ R3L == TL @ R3R, \text{Kas} @ R3L == \text{Kas} @ R3R\}$$

{True, True}

Kas@R3L

		$2\theta(u - \frac{1}{2}) - 2\theta(u + \frac{1}{2}) - 2$			
	γ_3	γ_7	γ_9	γ_8	γ_{-1}
$\bar{\gamma}_{-3}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$
$\bar{\gamma}_7$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2(2u^2-1)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$
$\bar{\gamma}_9$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$
$\bar{\gamma}_8$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$
$\bar{\gamma}_{-1}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2(2u^2-1)}{(2u-1)(2u+1)}$
$\bar{\gamma}_{-2}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$



Reidemeister 2.

$$TL @ PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}]$$

	1	0	-1	0
	(γ_{-2})	γ_6	γ_5	γ_{-1}
$\bar{\gamma}_{-2}$	0	0	0	0
$\bar{\gamma}_6$	0	0	0	0
$\bar{\gamma}_5$	0	0	0	0
$\bar{\gamma}_{-1}$	0	0	0	0

$$\{TL @ PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}] == GT_{5,-2} @ TL @ PD[P_{-1,5}, P_{-2,6}], \\ \text{Kas} @ PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}] == GT_{5,-2} @ \text{Kas} @ PD[P_{-1,5}, P_{-2,6}]\}$$

{True, True}

Reidemeister 1.

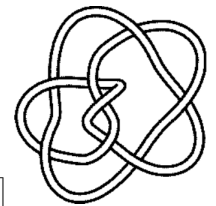
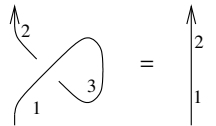
$$\{TL @ PD[X_{-3,3,2,-1}] == TL @ P_{-1,2}, \\ \text{Kas} @ PD[X_{-3,3,2,-1}] == \text{Kas} @ P_{-1,2}\}$$

{True, True}

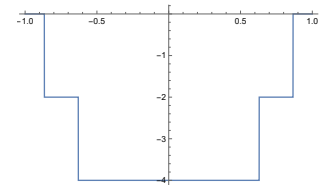
A Knot.

$$f = TL\text{Sig}[\text{Knot}[8, 5]]$$

$$2\theta\left[-\frac{\sqrt{3}}{2} + u\right] - 2\theta\left[\frac{\sqrt{3}}{2} + u\right] - \\ 2\theta\left[u - \left(\text{clockwise} - 0.630\dots\right)\right] + 2\theta\left[u - \left(\text{counterclockwise} 0.630\dots\right)\right]$$



$$\text{Plot}[f, \{u, -1, 1\}]$$

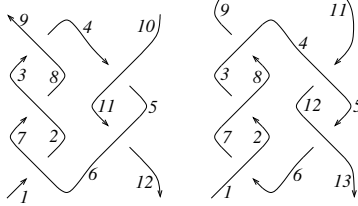


The Conway-Kinoshita-Terasaka Tangles.



$$T1 = PD [\bar{X}_{-6,2,7,-1}, \bar{X}_{-2,8,3,-7}, \bar{X}_{-8,4,9,-3}, X_{-11,6,12,-5}, X_{-4,11,5,-10}];$$

$$T2 = PD [X_{-6,2,7,-1}, X_{-2,8,3,-7}, X_{-8,4,9,-3}, \bar{X}_{-12,6,13,-5}, \bar{X}_{-4,12,5,-11}, \bar{X}_{-10,15,11,-14}, \bar{X}_{-15,10,16,-9}];$$



Column@{TL [T1], Kas [T1]}

$$-2\theta(u - \frac{\sqrt{3}}{2}) + 2\theta(u + \frac{\sqrt{3}}{2}) - 1$$

\bar{Y}_{-10}	Y_9	Y_{-1}	Y_{12}
$\frac{\omega-1}{\omega}$	$1-\omega$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$

\bar{Y}_{-10}	Y_9	Y_{-1}	Y_{12}
$2(u-1)(u+1)(4u^2-3)$	$\frac{1}{2(4u^2-3)}$	$-2(u-1)(u+1)(4u^2-3)$	$\frac{1}{2(4u^2-3)}$
$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$
$-2(u-1)(u+1)(4u^2-3)$	$\frac{1}{2(4u^2-3)}$	$2(u-1)(u+1)(4u^2-3)$	$\frac{1}{2(4u^2-3)}$
$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$	$\frac{1}{2(4u^2-3)}$

Column@{TL [T2], Kas [T2]}

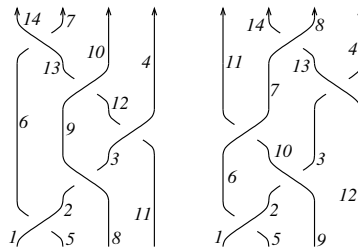
\bar{Y}_{-14}	Y_{16}	Y_{-1}	Y_{13}
$\frac{\omega-1}{\omega}$	$1-\omega$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$
$\frac{\omega-1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4-3\omega^3+5\omega^2-3\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4-3\omega^3+5\omega^2-3\omega+1}$
$\frac{\omega-1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4-3\omega^3+5\omega^2-3\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4-3\omega^3+5\omega^2-3\omega+1}$

\bar{Y}_{-14}	Y_{16}	Y_{-1}	Y_{13}
$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(16u^4-28u^2+13)$	$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(16u^4-28u^2+13)$
$\frac{1}{2}(16u^4-28u^2+13)$	$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(16u^4-28u^2+13)$
$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(16u^4-28u^2+13)$	$\frac{1}{2}(-16u^4+28u^2-13)$	$\frac{1}{2}(16u^4-28u^2+13)$

Examples with non-trivial co-dimension.

$$B1 = PD [X_{-5,2,6,-1}, \bar{X}_{-8,3,9,-2}, X_{-11,4,12,-3}, X_{-12,10,13,-9}, \bar{X}_{-13,7,14,-6}];$$

$$B2 = PD [X_{-5,2,6,-1}, \bar{X}_{-9,3,10,-2}, X_{-10,7,11,-6}, \bar{X}_{-12,4,13,-3}, X_{-13,8,14,-7}];$$



Column@{TL [B1], Kas [B1]}

\bar{Y}_{-11}	Y_4	Y_{10}	Y_7	Y_{14}	Y_{-1}	Y_{-5}	Y_{-8}
$\frac{\omega-1}{\omega}$	$1-\omega$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$

\bar{Y}_{-11}	Y_4	Y_{10}	Y_7	Y_{14}	Y_{-1}	Y_{-5}	Y_{-8}
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$

Column@{TL [B2], Kas [B2]}

\bar{Y}_{-12}	Y_4	Y_8	Y_{14}	Y_{11}	Y_{-1}	Y_{-5}	Y_{-9}
$\frac{\omega-1}{\omega}$	$1-\omega$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$	$\frac{\omega-1}{\omega}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$
$\frac{\omega-1}{\omega}$	$\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$	$\frac{\omega-1}{\omega}$	$-\frac{2\omega}{\omega^2-\omega+1}$

\bar{Y}_{-12}	Y_4	Y_8	Y_{14}	Y_{11}	Y_{-1}	Y_{-5}	Y_{-9}
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$
$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$	$\frac{1}{\omega}$

$\begin{pmatrix} A & B \\ C & U \end{pmatrix} \xrightarrow{\det(A)} \begin{pmatrix} I & A^{-1}B \\ C & U \end{pmatrix} \xrightarrow{1} \begin{pmatrix} I & A^{-1}B \\ 0 & U - CA^{-1}B \end{pmatrix}$. Roughly, $\det(A)$ is "det on ker", $-CA^{-1}B$ is "a pushforward of $\begin{pmatrix} A & B \\ C & U \end{pmatrix}$ ".
so $\det \begin{pmatrix} A & B \\ C & U \end{pmatrix} = \det(A) \det(U - CA^{-1}B)$. (what if $\mathbb{A}A^{-1}$?)

Questions. 1. Does this have a topological meaning? 2. Is there a version of the Kashaev Conjecture for tangles? 3. Find all solutions of R123 in our "algebra". 4. Braids and the Burau representation. 5. Recover the work in "Prior Art". 6. Are there any concordance properties? 7. What is the "SPQ group"? 8. The jumping points of signatures are the roots of the Alexander polynomial. Does this generalize to tangles? 9. Which of the three Cordon cases is the most common? 10. Are there interesting examples of tangles for which rels is non-trivial? 11. Is the pq part determined by Γ -calculus? 12. Is the pq part determined by finite type invariants? 13. Does it work with closed components / links? 14. Strand-doubling formulas? 15. A multivariable version? 16. Mutation invariance? 17. Ribbon knots? 18. Are there "face-virtual knots"? 19. Does the pushforward story extend to ranks? To formal Gaussian measures? To super Gaussian measures?

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Acknowledgement. This work was partially supported by NSERC grant RGPIN-2018-04350 and by the Chu Family Foundation (NYC).

Proof of Theorem 1'. Fix W and consider triples $(V, S, \phi: V \rightarrow W)$ where $S = (s, D, Q)$ is an SPQ on V . Declare $(V_1, S_1, \phi_1) \sim (V_2, S_2, \phi_2)$ if for every quadratic U on W ,

$$\sigma_{V_1}(S_1 + \phi_1^*U) = \sigma_{V_2}(S_2 + \phi_2^*U).$$

Given our (V, S, ϕ) , we need to show:

1. There is an SPQ S' on W such that $(V, S, \phi) \sim (W, S', I)$.
2. If $(W, S', I) \sim (W, S'', I)$ then $S' = S''$.

Property 2 is easy. Property 1 follows from the following four claims, each of which is easy.

Claim 1. $(V, S, \phi) \sim (D(S), S, \phi|_{D(S)})$, so wlog, S is “full”, meaning $D(S) = V$. \square

Claim 2. If S is full, $v \in \ker \phi$, and $\lambda := Q(v) \neq 0$, then $(V, S, \phi) \sim \left(V/\langle v \rangle, \left(s + \text{sign}(\lambda), V/\langle v \rangle, Q - \frac{Q(-, v) \otimes Q(v, -)}{|\lambda|^2} \right), \phi/\langle v \rangle \right)$.

So wlog $Q|_{\ker \phi} = 0$ (meaning, $Q|_{\ker \phi \otimes \ker \phi} = 0$). \square

Claim 3. If $Q|_{\ker \phi} = 0$ and $v \in \ker \phi$, let $V' = \ker Q(v, -)$ and then $(V, S, \phi) \sim (V', S|_{V'}, \phi|_{V'})$ so wlog $Q|_{V \otimes \ker \phi + \ker \phi \otimes V} = 0$. \square

Claim 4. If $Q|_{V \otimes \ker \phi + \ker \phi \otimes V} = 0$ then $S = \phi^*S'$ for some SPQ S' on $\text{im } \phi$ and then $(V, S, \phi) \sim (W, S', I)$. $\square \square$

Proof of Theorem 2. The functoriality of pullbacks needs no proof. Now assume $V_0 \xrightarrow{\alpha} V_1 \xrightarrow{\beta} V_2$ and that S is an SPQ on V_0 . Then for every SPQ U on V_2 we have, using reciprocity three times, that $\sigma(\beta_*\alpha_*S + U) = \sigma(\alpha_*S + \beta^*U) = \sigma(S + \alpha^*\beta^*U) = \sigma(S + (\beta\alpha)^*U) = \sigma((\beta\alpha)_*S + U)$. Hence $\beta_*\alpha_*S = (\beta\alpha)_*S$. \square

Lemma 1. $\phi_*\phi^*S = S|_{\text{im } \phi}$.

Proof. For every PQ U with $D(U) = \text{im } \phi$ we have $\sigma(S|_{\text{im } \phi} + U) = \sigma(S + U) = \sigma(\phi^*(S + U)) = \sigma(\phi^*S + \phi^*U) = \sigma(\phi_*\phi^*S + U)$ where for the second equality we use the fact that a pullback by a surjective map does not change the signature, and the last equality is the reciprocity property. \square

Lemma 2. Under the conditions of Theorem 3, if S_i is an SPQ on V_i for $i = 1, 2$, then $\sigma(\alpha^*S_1 + \gamma^*S_2) = \sigma(\beta_*S_1 + \delta_*S_2)$.

Proof. Let $\pi := \beta\alpha = \delta\gamma$. Then (in order) by reciprocity with $U = 0$, by the functoriality of pushforwards, by Lemma 1, and using the surjectivity of α and of γ , $\sigma(\alpha^*S_1 + \gamma^*S_2) = \sigma(\pi_*(\alpha^*S_1 + \gamma^*S_2)) = \sigma(\beta_*\alpha_*\alpha^*S_1 + \delta_*\gamma_*\gamma^*S_2) = \sigma(\beta_*(S_1|_{\text{im } \alpha}) + \delta_*(S_2|_{\text{im } \gamma})) = \sigma(\beta_*S_1 + \delta_*S_2)$. \square

Proof of Theorem 3. Given S on V_2 , for every U on V_1 we have using reciprocity, Lemma 2, and reciprocity again, that $\sigma(\alpha_*\gamma^*S + U) = \sigma(\gamma^*S + \alpha^*U) = \sigma(\delta_*S + \beta_*U) = \sigma(\beta^*\delta_*S + U)$. Hence $\alpha_*\gamma^*S = \beta^*\delta_*S$. \square