

Pensieve header: Mathematica notebook for Talks: Bonn-2505.

Ancestors in Talks/Geneva-2408, Talks/Beijing-2407 and in Projects/HigherRank.

exec

```
nb2tex$TeXFileName = "IType.tex";
```

In[*]:=

```
SetDirectory["C:\\drorbn\\AcademicPensieve\\Talks\\Bonn-2505"];
```

Preliminaries

tex

{\bf\red Implementation} (see IType.nb of \web{ap}).

pdf

In[*]:=

```
Once[<< KnotTheory` ; << Rot.m];
```

pdf

Loading KnotTheory` version of October 29, 2024, 10:29:52.1301.

Read more at <http://katlas.org/wiki/KnotTheory>.

pdf

Loading Rot.m from <http://drorbn.net/AP/Talks/Bonn-2505> to compute rotation numbers.

pdf

In[*]:=

```
CF[ω_. ℰ_ℰ'] := CF[ω] CF /@ ℰ;
CF[ℰ_List] := CF /@ ℰ;
CF[ℰ_] := Module[{vs, ps, c},
  vs = Cases[ℰ, (x | p | ξ | π | g) __, ∞] ∪ {e};
  Total[CoefficientRules[Expand[ℰ], vs] /. (ps_ → c_) ⇒ Factor[c] (Times @@ vsps) ] ];
```

tex

\vskip 1mm\rule{\linewidth}{1pt}\vspace{-2mm}

Integration

tex

{\bf\red Integration} using Picard iteration. The \myyellow{core is in yellow} and \mpink{hacks are in pink}.

pdf

In[*]:=

```
E /: E[A_] E[B_] := E[A + B];
```

pdf

In[*]:=

```
$π = Identity; (* The Wisdom Projection *)
```

pdf

```

In[ ]:= Unprotect[Integrate];


$$\int \omega_- \cdot \mathbb{E}[L_-] \, d(vs\_List) := \text{Module}[\{n, L0, Q, \Delta, G, Z0, Z, \lambda, DZ, DDZ, FZ, a, b\},$$

  n = Length@vs; L0 = L /.  $\epsilon \rightarrow 0$ ;
  Q = Table[(- $\partial_{vs[a], vs[b]}$  L0) /. Thread[vs  $\rightarrow 0$ ] /. (p | x)  $\rightarrow 0$ , {a, n}, {b, n}];
  If[( $\Delta = \text{Det}[Q]$ ) == 0, Return@"Degenerate Q!"];
  Z = Z0 = CF@ $\pi[L + vs \cdot Q \cdot vs / 2]$ ; G = Inverse[Q];
  FixedPoint[
    {DZ = Table[ $\partial_v Z$ , {v, vs}];
     DDZ = Table[ $\partial_u DZ$ , {u, vs}];
     FZ = Sum[G[a, b] (DDZ[a, b] + DZ[a] DZ[b]), {a, n}, {b, n}] / 2;
     Z = CF[Z0 +  $\int_0^\lambda \pi[FZ] \, d\lambda$ ] &, Z];
  PowerExpand@Factor[ $\omega \Delta^{-1/2} \mathbb{E}[CF[Z /. \lambda \rightarrow 1 /. \text{Thread}[vs \rightarrow 0]]]$ ];
Protect[Integrate];

```

tex

```

\parpic[r]{\parbox{0.75in}{
\includegraphics[width=0.75in]{../Projects/Gallery/Fourier.jpg}
\footnotesize Joseph Fourier
}}
\picskip{2}

```

pdf

In[]:= $\int \mathbb{E}[-\mu x^2 / 2 + i \xi x] \, d\{x\}$

Out[]=

pdf

$$\frac{\mathbb{E}\left[-\frac{\xi^2}{2\mu}\right]}{\sqrt{\mu}}$$

tex

```
\needspace{12mm}
```

pdf

In[]:= FofG = $\int \mathbb{E}[-\mu (x - a)^2 / 2 + i \xi x] \, d\{x\}$

Out[]=

pdf

$$\frac{\mathbb{E}\left[\frac{i(2a\mu + i\xi)\xi}{2\mu}\right]}{\sqrt{\mu}}$$

tex

```
\needspace{12mm}
```

pdf

$$In[*]:= \int \mathbf{FofG} \left[-\mathbf{i} \, \xi \, \mathbf{x} \right] \, \mathbf{d} \{ \xi \}$$

Out[*]=

pdf

$$\mathbb{E} \left[-\frac{1}{2} (a - x)^2 \mu \right]$$

tex

So we've tested and nearly proven the Fourier inversion formula!

pdf

$$In[*]:= \mathbf{L} = -\frac{1}{2} \{ \mathbf{x}_1, \mathbf{x}_2 \} \cdot \begin{pmatrix} \mathbf{a} & \mathbf{b} \\ \mathbf{b} & \mathbf{c} \end{pmatrix} \cdot \{ \mathbf{x}_1, \mathbf{x}_2 \} + \{ \xi_1, \xi_2 \} \cdot \{ \mathbf{x}_1, \mathbf{x}_2 \};$$

tex

```
\parpic[r]{\parbox{0.65in}{
\includegraphics[width=0.65in]{../Projects/Gallery/Fubini.jpg}
\scriptsize Guido Fubini
}}
\pickskip{2}
```

pdf

$$In[*]:= \mathbf{Z12} = \int \mathbf{E} \left[\mathbf{L} \right] \, \mathbf{d} \{ \mathbf{x}_1, \mathbf{x}_2 \}$$

Out[*]=

pdf

$$\frac{\mathbb{E} \left[\frac{c \xi_1^2}{2 (-b^2 + a c)} + \frac{b \xi_1 \xi_2}{b^2 - a c} + \frac{a \xi_2^2}{2 (-b^2 + a c)} \right]}{\sqrt{-b^2 + a c}}$$

pdf

$$In[*]:= \left\{ \mathbf{Z1} = \int \mathbf{E} \left[\mathbf{L} \right] \, \mathbf{d} \{ \mathbf{x}_1 \}, \mathbf{Z12} = \int \mathbf{Z1} \, \mathbf{d} \{ \mathbf{x}_2 \} \right\}$$

Out[*]=

pdf

$$\left\{ \frac{\mathbb{E} \left[-\frac{(-b^2 + a c) x_2^2}{2 a} - \frac{b x_2 \xi_1}{a} + \frac{\xi_1^2}{2 a} + x_2 \xi_2 \right]}{\sqrt{a}}, \text{True} \right\}$$

pdf

$$In[*]:= \pi = \text{Normal} \left[\# + 0 \left[\epsilon \right]^{13} \right] \&; \int \mathbf{E} \left[-\phi^2 / 2 + \epsilon \phi^3 / 6 \right] \, \mathbf{d} \{ \phi \}$$

Out[*]=

pdf

$$\mathbb{E} \left[\frac{5 \epsilon^2}{24} + \frac{5 \epsilon^4}{16} + \frac{1105 \epsilon^6}{1152} + \frac{565 \epsilon^8}{128} + \frac{82825 \epsilon^{10}}{3072} + \frac{19675 \epsilon^{12}}{96} \right]$$

tex

```
\vfill
From \url{oeis.org/A226260}:
\vskip 1mm
\includegraphics[width=\linewidth]{../Groningen-240530/OEIS.png}
```

0 1 3 6 2 7
 : 13
 : 20
 23 12
 10 22 11 21

THE ON-LINE ENCYCLOPEDIA OF INTEGER SEQUENCES®

founded in 1964 by N. J. A. Sloane

[Hints](#)
 (Greetings from [The On-Line Encyclopedia of Integer Sequences!](#))

A226260 Numerators of mass formula for connected vacuum graphs on $2n$ nodes for a ϕ^3 field theory.
 1, 5, 5, 1105, 565, 82825, 19675, 1282031525, 80727925, 1683480621875, 13209845125,
 2239646759308375, 19739117098375, 6320791709083309375, 32468078556378125, 38362676768845045751875,
 281365778405032973125, 2824650747089425586152484375, 776632157034116712734375 ([list](#): [graph](#): [refs](#): [listen](#):
[history](#): [text](#): [internal format](#))

The Right-Handed Trefoil

tex

```
\vfill
\rule{\linewidth}{1pt}
{\bf\red The Right-Handed Trefoil.}
```

pdf

```
In[ ]:= K = Mirror@Knot[3, 1]; Features[K]
```

pdf

 KnotTheory: Loading precomputed data in PD4Knots`.

Out[]:=

pdf

```
Features[7, C4[-1] X1,5[1] X3,7[1] X6,2[1]]
```

pdf

```
In[ ]:= 
$$\mathcal{L}[X_{i,j}[S]] := T^{S/2} \mathbb{E} \left[ \begin{aligned} & x_i (p_{i+1} - p_i) + x_j (p_{j+1} - p_j) + (T^S - 1) x_i (p_{i+1} - p_{j+1}) + \\ & (\epsilon S / 2) \times (x_i (p_i - p_j) ((T^S - 1) x_i p_j + 2(1 - x_j p_j)) - 1) \end{aligned} \right]$$


$$\mathcal{L}[C_i[\varphi]] := T^{\varphi/2} \mathbb{E} \left[ x_i (p_{i+1} - p_i) + \epsilon \varphi \left( \frac{1}{2} - x_i p_i \right) \right]$$


$$\mathcal{L}[K] := CF[\mathcal{L} / @ Features[K][[2]]]$$


$$vs[K] := Join @@ Table[{p_i, x_i}, {i, Features[K][[1]]}]$$

```

exec

```
In[ ]:= nb2tex$PDFwidth *= 1.25;
```

tex

```
\needspace{5cm}
```

pdf

In[*]:= **vs**[**K**], **L**[**K**]

Out[*]=

pdf

$$\left\{ \{p_1, x_1, p_2, x_2, p_3, x_3, p_4, x_4, p_5, x_5, p_6, x_6, p_7, x_7\}, \right. \\ \mathbb{T} \mathbb{E} \left[-2 \in -p_1 x_1 + \in p_1 x_1 + \mathbb{T} p_2 x_1 - \in p_5 x_1 + (1 - \mathbb{T}) p_6 x_1 + \frac{1}{2} (-1 + \mathbb{T}) \in p_1 p_5 x_1^2 + \right. \\ \frac{1}{2} (1 - \mathbb{T}) \in p_5^2 x_1^2 - p_2 x_2 + p_3 x_2 - p_3 x_3 + \in p_3 x_3 + \mathbb{T} p_4 x_3 - \in p_7 x_3 + (1 - \mathbb{T}) p_8 x_3 + \\ \frac{1}{2} (-1 + \mathbb{T}) \in p_3 p_7 x_3^2 + \frac{1}{2} (1 - \mathbb{T}) \in p_7^2 x_3^2 - p_4 x_4 + \in p_4 x_4 + p_5 x_4 - p_5 x_5 + p_6 x_5 - \in p_1 p_5 x_1 x_5 + \\ \in p_5^2 x_1 x_5 - \in p_2 x_6 + (1 - \mathbb{T}) p_3 x_6 - p_6 x_6 + \in p_6 x_6 + \mathbb{T} p_7 x_6 + \in p_2^2 x_2 x_6 - \in p_2 p_6 x_2 x_6 + \\ \left. \left. \frac{1}{2} (1 - \mathbb{T}) \in p_2^2 x_6^2 + \frac{1}{2} (-1 + \mathbb{T}) \in p_2 p_6 x_6^2 - p_7 x_7 + p_8 x_7 - \in p_3 p_7 x_3 x_7 + \in p_7^2 x_3 x_7 \right] \right\}$$

exec

In[*]:= **nb2tex**\$**PDFWidth** /= **1.25**;

tex

\needspace{10mm}

pdf

In[*]:= **\$\pi** = **Normal**[**#** + **0**[**\epsilon**]²] &; $\int \mathcal{L}[\mathbf{K}] \, d\mathbf{vs}[\mathbf{K}]$

Out[*]=

pdf

$$- \frac{\mathbb{T} \mathbb{E} \left[- \frac{(-1+\mathbb{T})^2 (1+\mathbb{T}^2) \in}{(1-\mathbb{T}+\mathbb{T}^2)^2} \right]}{1 - \mathbb{T} + \mathbb{T}^2}$$

In[*]:= $\int (\mathcal{L}[\mathbf{K}] \, / \cdot \mathbf{x}_{i_} \Rightarrow \mathbb{T} \mathbf{x}_i) \, d(\mathbf{vs} @ \mathbf{K})$

Out[*]=

$$\frac{\mathbb{T} \mathbb{E} \left[- \frac{(-1+\mathbb{T})^2 (1+\mathbb{T}^2) \in}{(1-\mathbb{T}+\mathbb{T}^2)^2} \right]}{1 - \mathbb{T} + \mathbb{T}^2}$$

tex

\vskip 1mm

A faster program to compute ρ_1 , and more stories about it, are at~\cite{APAI}.

\rule{\linewidth}{1pt}\vspace{2mm}\vskip -2mm

\newcolumn

Invariance Under Reidemeister 3

tex

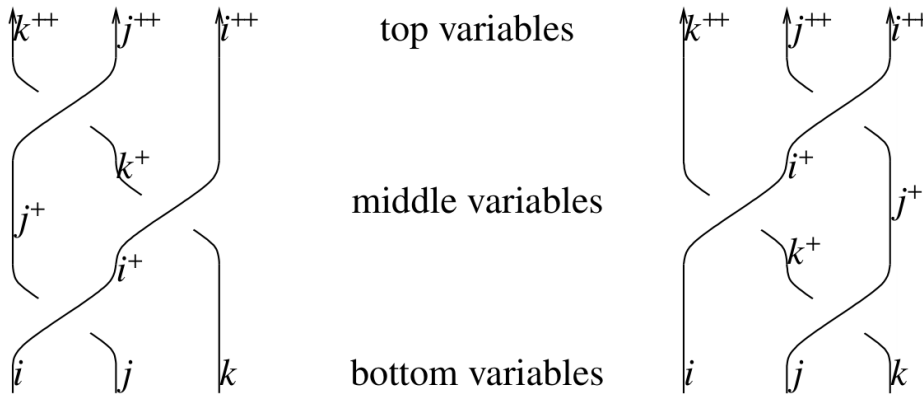
\{\bf red Invariance Under Reidemeister 3.\}

\vskip 2mm

\def\ip{{i^+}} \def\jp{{j^+}} \def\kp{{k^+}}

\def\ipp{{i^+!+}} \def\jpp{{j^+!+}} \def\kpp{{k^+!+}}

\import{../Beijing-2407/figs}{R3.pdf_t}



pdf

```

In[*]:= lhs = Integrate[ $\mathcal{L} / @ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])$ ], {pi+1, pj+1, pk+1, xi+1, xj+1, xk+1};
rhs = Integrate[ $\mathcal{L} / @ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])$ ], {xi+1, pi+1, pj+1, pk+1, xj+1, xk+1};
lhs === rhs

```

Out[*]=

pdf

False

Invariance Under Reidemeister 3, Take 2

tex

```

\vskip 1mm\rule{\linewidth}{1pt}
\par{\bf\red Invariance Under Reidemeister 3, Take 2.}

```

pdf

```

In[*]:= lhs = Integrate[ $\mathcal{L} / @ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])$ ], {xi, xj, xk, pi+1, pj+1, pk+1, xi+1, xj+1, xk+1};
rhs = Integrate[ $\mathcal{L} / @ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])$ ], {xi, xj, xk, xi+1, pi+1, pj+1, pk+1, xj+1, xk+1};
lhs === rhs

```

Out[*]=

pdf

True

pdf

In[*]:= lhs

Out[*]=

pdf

Degenerate Q!

tex

```

%\newcolumn

```

Invariance Under Reidemeister 3, Take 3

tex

```

\vskip 1mm\rule{\linewidth}{1pt}
\par{\bf\red Invariance Under Reidemeister 3, Take 3.}

```

exec

In[]:= **nb2tex\$PDFWidth** *= 1.25;

pdf

```

In[ ]:= lhs =  $\int (\mathbb{E}[\dot{\pi}_i p_i + \dot{\pi}_j p_j + \dot{\pi}_k p_k] \mathcal{L} / @ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1]))$ 
 $\mathbb{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\};$ 
rhs =  $\int (\mathbb{E}[\dot{\pi}_i p_i + \dot{\pi}_j p_j + \dot{\pi}_k p_k] \mathcal{L} / @ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1]))$ 
 $\mathbb{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\};$ 
lhs == rhs

```

Out[]=

pdf

True

tex

\needspace{20mm}

pdf

In[]:= **lhs**

Out[]=

pdf

$$\begin{aligned}
& T^{3/2} \mathbb{E} \left[-\frac{3}{2} \in + \dot{\pi} T^2 p_{2+i} \pi_i - \dot{\pi} (-1 + T) T p_{2+j} \pi_i + \dot{\pi} T^2 \in p_{2+j} \pi_i - \dot{\pi} (-1 + T) p_{2+k} \pi_i + \dot{\pi} T \in p_{2+k} \pi_i - \right. \\
& \frac{1}{2} (-1 + T) T^3 \in p_{2+i} p_{2+j} \pi_i^2 + \frac{1}{2} (-1 + T) T^3 \in p_{2+j}^2 \pi_i^2 - \frac{1}{2} (-1 + T) T^2 \in p_{2+i} p_{2+k} \pi_i^2 + \\
& \frac{1}{2} (-1 + T)^2 T \in p_{2+j} p_{2+k} \pi_i^2 + \frac{1}{2} (-1 + T) T \in p_{2+k}^2 \pi_i^2 + \dot{\pi} T p_{2+j} \pi_j - \dot{\pi} T \in p_{2+j} \pi_j - \\
& \dot{\pi} (-1 + T) p_{2+k} \pi_j + \dot{\pi} (-1 + 2 T) \in p_{2+k} \pi_j + T^3 \in p_{2+i} p_{2+j} \pi_i \pi_j - T^3 \in p_{2+j}^2 \pi_i \pi_j - \\
& (-1 + T) T^2 \in p_{2+i} p_{2+k} \pi_i \pi_j + (-1 + T)^2 T \in p_{2+j} p_{2+k} \pi_i \pi_j + (-1 + T) T \in p_{2+k}^2 \pi_i \pi_j - \\
& \frac{1}{2} (-1 + T) T \in p_{2+j} p_{2+k} \pi_j^2 + \frac{1}{2} (-1 + T) T \in p_{2+k}^2 \pi_j^2 + \dot{\pi} p_{2+k} \pi_k - 2 \dot{\pi} \in p_{2+k} \pi_k + T^2 \in p_{2+i} p_{2+k} \pi_i \pi_k - \\
& \left. (-1 + T) T \in p_{2+j} p_{2+k} \pi_i \pi_k - T \in p_{2+k}^2 \pi_i \pi_k + T \in p_{2+j} p_{2+k} \pi_j \pi_k - T \in p_{2+k}^2 \pi_j \pi_k \right]
\end{aligned}$$

exec

In[]:= **nb2tex\$PDFWidth** /= 1.25;

tex

Invariance under the other Reidemeister moves is proven in a similar way. See IType.nb at \web{ap}.

Invariance Under Reidemeister 3, Take 4 (just for fun)

$$\begin{aligned}
 \text{lhs} &= \int (\mathbb{E} [\dot{\pi}_i p_i + \dot{\pi}_j p_j + \dot{\pi}_k p_k + \dot{\pi}_{i+2} p_{i+2} + \dot{\pi}_{j+2} p_{j+2} + \dot{\pi}_{k+2} p_{k+2} + \\
 &\quad \dot{\xi}_{i+2} x_{i+2} + \dot{\xi}_{j+2} x_{j+2} + \dot{\xi}_{k+2} x_{k+2}] \mathcal{L} / @ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])) \\
 &\quad \mathfrak{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}, p_{i+2}, p_{j+2}, p_{k+2}, x_{i+2}, x_{j+2}, x_{k+2}\}; \\
 \text{rhs} &= \int (\mathbb{E} [\dot{\pi}_i p_i + \dot{\pi}_j p_j + \dot{\pi}_k p_k + \dot{\pi}_{i+2} p_{i+2} + \dot{\pi}_{j+2} p_{j+2} + \dot{\pi}_{k+2} p_{k+2} + \\
 &\quad \dot{\xi}_{i+2} x_{i+2} + \dot{\xi}_{j+2} x_{j+2} + \dot{\xi}_{k+2} x_{k+2}] \mathcal{L} / @ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])) \\
 &\quad \mathfrak{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}, p_{i+2}, p_{j+2}, p_{k+2}, x_{i+2}, x_{j+2}, x_{k+2}\}; \\
 \text{lhs} &= \text{rhs}
 \end{aligned}$$

Out[⌘]=

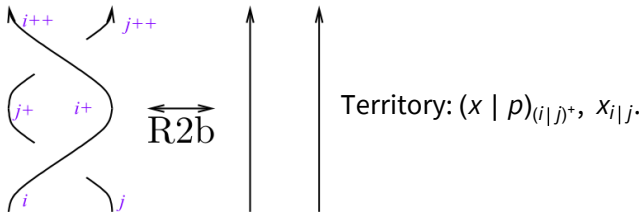
True

In[⌘]:= lhs

Out[⌘]=

Degenerate Q!

Invariance Under Reidemeister 2b



$$\begin{aligned}
 \text{lhs} &= \int \mathbb{E} [\dot{\pi}_i p_i + \dot{\pi}_j p_j] \mathcal{L} / @ (X_{i,j}[1] X_{i+1,j+1}[-1]) \mathfrak{d}\{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}\} \\
 \text{rhs} &= \\
 &\quad \int \mathbb{E} [\dot{\pi}_i p_i + \dot{\pi}_j p_j] \mathcal{L} / @ (C_i[0] C_{i+1}[0] C_j[0] C_{j+1}[0]) \mathfrak{d}\{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}\}; \\
 \text{lhs} &= \text{rhs}
 \end{aligned}$$

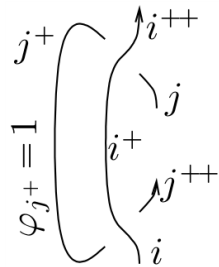
Out[⌘]=

 $\mathbb{E} [\dot{\pi}_{2+i} p_i + \dot{\pi}_{2+j} p_j]$

Out[⌘]=

True

Invariance Under R2c



```

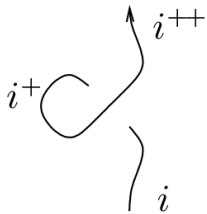
In[*]:= lhs =  $\int \mathbb{E}[\mathfrak{i} \pi_i p_i + \mathfrak{i} \pi_j p_j] \mathcal{L} / @ (X_{i+1,j}[1] X_{i,j+2}[-1] C_{j+1}[1])$ 
            $\mathfrak{d}\{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{j+2}, p_{j+2}\}$ 
rhs =  $\int \mathbb{E}[\mathfrak{i} \pi_i p_i + \mathfrak{i} \pi_j p_j] \mathcal{L} / @ (C_i[0] C_{i+1}[0] C_j[0] C_{j+1}[1] C_{j+2}[0])$ 
            $\mathfrak{d}\{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{j+2}, p_{j+2}\};$ 
lhs == rhs
Out[*]=

$$-\mathfrak{i} \sqrt{T} \mathbb{E} \left[ -\frac{\epsilon}{2} + \mathfrak{i} p_{2+i} \pi_i + \mathfrak{i} p_{3+j} \pi_j - \mathfrak{i} \epsilon p_{3+j} \pi_j \right]$$

Out[*]=
True

```

Invariance Under R1l



```

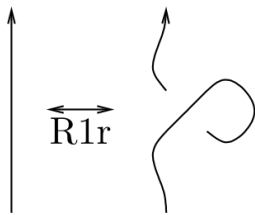
In[*]:= lhs =  $\int \mathbb{E}[\mathfrak{i} \pi_i p_i] \mathcal{L} / @ (X_{i+2,i}[1] C_{i+1}[1]) \mathfrak{d}\{x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}\}$ 
rhs =  $\int \mathbb{E}[\mathfrak{i} \pi_i p_i] \mathcal{L} / @ (C_i[0] C_{i+1}[0] C_{i+2}[0]) \mathfrak{d}\{x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}\};$ 
lhs == rhs
Out[*]=

$$-\mathfrak{i} \mathbb{E}[\mathfrak{i} p_{3+i} \pi_i]$$

Out[*]=
True

```

Invariance Under R1r



```

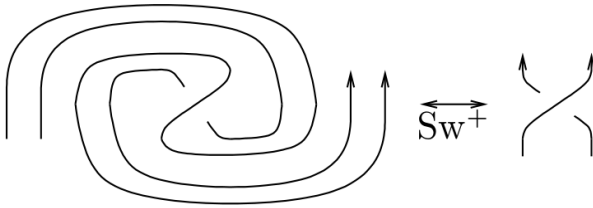
In[*]:= lhs =  $\int \mathbb{E}[\imath \pi_i p_i] \mathcal{L} / @ (X_{i,i+2}[1] C_{i+1}[-1]) \mathfrak{d} \{x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}\}$ 
rhs =  $\int \mathbb{E}[\imath \pi_i p_i] \mathcal{L} / @ (C_i[0] C_{i+1}[0] C_{i+2}[0]) \mathfrak{d} \{x_i, p_i, x_{i+1}, p_{i+1}, x_{i+2}, p_{i+2}\};$ 
lhs == rhs

Out[*]=
 $-\imath \mathbb{E}[\imath p_{3+i} \pi_i]$ 

Out[*]=
True

```

Invariance Under Sw



```

In[*]:= lhs =  $\int \mathbb{E}[\imath \pi_i p_i + \imath \pi_j p_j] \mathcal{L} / @ (X_{i+1,j+1}[1] C_i[-1] C_j[-1] C_{i+2}[1] C_{j+2}[1])$ 
 $\mathfrak{d} \{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{i+2}, p_{i+2}, x_{j+2}, p_{j+2}\}$ 
rhs =  $\int \mathbb{E}[\imath \pi_i p_i + \imath \pi_j p_j] \mathcal{L} / @ (X_{i+1,j+1}[1] C_i[0] C_j[0] C_{i+2}[0] C_{j+2}[0])$ 
 $\mathfrak{d} \{x_i, x_j, p_i, p_j, x_{i+1}, x_{j+1}, p_{i+1}, p_{j+1}, x_{i+2}, p_{i+2}, x_{j+2}, p_{j+2}\};$ 
lhs == rhs

Out[*]=
 $\sqrt{T} \mathbb{E} \left[ -\frac{\epsilon}{2} + \imath T p_{3+i} \pi_i - \imath (-1 + T) p_{3+j} \pi_i + \imath T \in p_{3+j} \pi_i - \frac{1}{2} (-1 + T) T \in p_{3+i} p_{3+j} \pi_i^2 + \right.$ 
 $\left. \frac{1}{2} (-1 + T) T \in p_{3+j}^2 \pi_i^2 + \imath p_{3+j} \pi_j - \imath \in p_{3+j} \pi_j + T \in p_{3+i} p_{3+j} \pi_i \pi_j - T \in p_{3+j}^2 \pi_i \pi_j \right]$ 

Out[*]=
True

```