

```
In[*]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Talks\\Beijing-2407"];
Once[<< IType.m];
T3 = T1 T2;
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/AP/Talks/Beijing-2407> to compute rotation numbers.

exec

```
In[*]:= nb2tex$PDFWidth *= 1.25;
```

The Programs

tex

{\red{\bf A faster program,}} in which the Feynman diagrams are ``pre-computed'' (see theta.nb at [\web{ap}](#)):

pdf

```
R1[1, i_, j_] = CF[
  1 / 2 - T3 g1ji g2ji - g3ii + g2jj g3ii + T1 (T3 - 1) g1ji g3ji +
  T2 (T3 - 1) g2ji g3ji - T2 g2ji g3jj + (g1jj g2ii + (T3 - 1) g1jj g2ji -
  T1 g1ii g2jj - g1jj g3ii - T1 (T3 - 1) g1jj g3ji + T1 g1ii g3jj) / (T1 - 1)];
```

```
In[*]:= Simplify[R1[1, i, j] == 1/2 + (g1,j,j g2,i,i) / (-1 + T1) - T1 T2 g1,j,i g2,j,i + ((-1 + T1 T2) g1,j,j g2,j,i) / (-1 + T1) -
  (T1 g1,i,i g2,j,j) / (-1 + T1) - g3,i,i - (g1,j,j g3,i,i) / (-1 + T1) + g2,j,j g3,i,i + T1 (-1 + T1 T2) g1,j,i g3,j,i -
  (T1 (-1 + T1 T2) g1,j,j g3,j,i) / (-1 + T1) + T2 (-1 + T1 T2) g2,j,i g3,j,i + (T1 g1,i,i g3,j,j) / (-1 + T1) - T2 g2,j,i g3,j,j]
```

Out[*]=

True

pdf

```
R1[-1, i_, j_] = CF[
  -1 / 2 - T1^-1 g1ji g2ii - (1 - T1^-1 - T2^-1) g1ji g2ji - g1jj g2ji - g1ji g2jj + g3ii +
  T1^-1 g1ji g3ii - (1 - T2^-1) g2ji g3ii - g2jj g3ii + (1 - T3^-1) g1ji g3ji - (1 - T3^-1) g2ii g3ji +
  (2 - T2^-1) (1 - T3^-1) g2ji g3ji + (1 - T3^-1) g2jj g3ji + g1ji g3jj + g2ji g3jj + (T1 (1 - T2^-1) g1ii g2ji -
  g1jj g2ii + T1 g1ii g2jj + g1jj g3ii - T2^-1 (T3 - 1) g1ii g3ji - T1 g1ii g3jj) / (T1 - 1)];
```

In[*]:= $R_1[-1, i, j]$

Out[*]=

$$\begin{aligned} & -\frac{1}{2} \frac{g_{1,j,i} g_{2,i,i}}{T_1} - \frac{g_{1,j,j} g_{2,i,i}}{-1+T_1} + \frac{T_1 (-1+T_2) g_{1,i,i} g_{2,j,i}}{(-1+T_1) T_2} - \\ & \frac{(-T_1 - T_2 + T_1 T_2) g_{1,j,i} g_{2,j,i}}{T_1 T_2} - g_{1,j,j} g_{2,j,i} + \frac{T_1 g_{1,i,i} g_{2,j,j}}{-1+T_1} - g_{1,j,i} g_{2,j,j} + g_{3,i,i} + \\ & \frac{g_{1,j,i} g_{3,i,i}}{T_1} + \frac{g_{1,j,j} g_{3,i,i}}{-1+T_1} - \frac{(-1+T_2) g_{2,j,i} g_{3,i,i}}{T_2} - g_{2,j,j} g_{3,i,i} - \frac{(-1+T_1 T_2) g_{1,i,i} g_{3,j,i}}{(-1+T_1) T_2} + \\ & \frac{(-1+T_1 T_2) g_{1,j,i} g_{3,j,i}}{T_1 T_2} - \frac{(-1+T_1 T_2) g_{2,i,i} g_{3,j,i}}{T_1 T_2} + \frac{(-1+2 T_2) (-1+T_1 T_2) g_{2,j,i} g_{3,j,i}}{T_1 T_2^2} + \\ & \frac{(-1+T_1 T_2) g_{2,j,j} g_{3,j,i}}{T_1 T_2} - \frac{T_1 g_{1,i,i} g_{3,j,j}}{-1+T_1} + g_{1,j,i} g_{3,j,j} + g_{2,j,i} g_{3,j,j} \end{aligned}$$

In[*]:= Simplify[$R_1[-1, i, j]$ == $-\frac{1}{2} \frac{g_{1,j,i} g_{2,i,i}}{T_1} - \frac{g_{1,j,j} g_{2,i,i}}{-1+T_1} + \frac{T_1 (-1+T_2) g_{1,i,i} g_{2,j,i}}{(-1+T_1) T_2} - \frac{(-T_1 - T_2 + T_1 T_2) g_{1,j,i} g_{2,j,i}}{T_1 T_2} - g_{1,j,j} g_{2,j,i} + \frac{T_1 g_{1,i,i} g_{2,j,j}}{-1+T_1} - g_{1,j,i} g_{2,j,j} + g_{3,i,i} + \frac{g_{1,j,i} g_{3,i,i}}{T_1} + \frac{g_{1,j,j} g_{3,i,i}}{-1+T_1} - \frac{(-1+T_2) g_{2,j,i} g_{3,i,i}}{T_2} - g_{2,j,j} g_{3,i,i} - \frac{(-1+T_1 T_2) g_{1,i,i} g_{3,j,i}}{(-1+T_1) T_2} + \frac{(-1+T_1 T_2) g_{1,j,i} g_{3,j,i}}{T_1 T_2} - \frac{(-1+T_1 T_2) g_{2,i,i} g_{3,j,i}}{T_1 T_2} + \frac{(-1+2 T_2) (-1+T_1 T_2) g_{2,j,i} g_{3,j,i}}{T_1 T_2^2} + \frac{(-1+T_1 T_2) g_{2,j,j} g_{3,j,i}}{T_1 T_2} - \frac{T_1 g_{1,i,i} g_{3,j,j}}{-1+T_1} + g_{1,j,i} g_{3,j,j} + g_{2,j,i} g_{3,j,j}$]

Out[*]=

True

pdf

In[*]:= $\Theta[\{1, i0_, j0_ \}, \{1, i1_, j1_ \}] =$
 $-T_1 (T_3 - 1) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} + (T_3 - 1) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1} +$
 $T_1 (T_3 - 1) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} - (T_3 - 1) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1};$

In[*]:= Simplify[$\Theta[\{1, i0, j0 \}, \{1, i1, j1 \}] =$
 $-T_1 (-1+T_1 T_2) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} + (-1+T_1 T_2) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1} +$
 $T_1 (-1+T_1 T_2) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} + (1-T_1 T_2) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}]$

Out[*]=

True

pdf

In[*]:= $\Theta[\{1, i0_, j0_ \}, \{-1, i1_, j1_ \}] =$
 $(T_3 - 1) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} - T_1^{-1} (T_3 - 1) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1} -$
 $(T_3 - 1) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} + T_1^{-1} (T_3 - 1) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1};$

$$\text{In[*]:= Simplify}\left[\theta[\{1, i0, j0\}, \{-1, i1, j1\}] = \right. \\ \left. (-1 + T_1 T_2) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} - \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1}}{T_1} + \right. \\ \left. (1 - T_1 T_2) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} + \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}}{T_1} \right]$$

Out[*]= True

pdf

$$\theta[\{-1, i0_, j0_ \}, \{1, i1_, j1_ \}] = \text{CF} \left[\right. \\ \left. T_1^{-1} T_2^{-1} (T_3 - 1) (g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} - \right. \\ \left. T_1 g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1} - g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} + T_1 g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}) \right];$$

$$\text{In[*]:= Simplify}\left[\theta[\{-1, i0, j0\}, \{1, i1, j1\}] = \right. \\ \left. \frac{(-1 + T_1 T_2) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1}}{T_1 T_2} - \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1}}{T_2} - \right. \\ \left. \frac{(-1 + T_1 T_2) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1}}{T_1 T_2} + \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}}{T_2} \right]$$

Out[*]= True

pdf

$$\theta[\{-1, i0_, j0_ \}, \{-1, i1_, j1_ \}] = \text{CF} \left[\right. \\ \left. (1 - T_3^{-1}) (-T_1^{-1} g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1} + \right. \\ \left. g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1} + T_1^{-1} g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1} - g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}) \right];$$

$$\text{In[*]:= Simplify}\left[\theta[\{-1, i0, j0\}, \{-1, i1, j1\}] = \right. \\ \left. - \frac{(-1 + T_1 T_2) g_{1,j1,i0} g_{2,i1,i0} g_{3,j0,i1}}{T_1^2 T_2} + \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,i1,i0} g_{3,j0,i1}}{T_1 T_2} + \right. \\ \left. \frac{(-1 + T_1 T_2) g_{1,j1,i0} g_{2,j1,i0} g_{3,j0,i1}}{T_1^2 T_2} - \frac{(-1 + T_1 T_2) g_{1,j1,j0} g_{2,j1,i0} g_{3,j0,i1}}{T_1 T_2} \right]$$

Out[*]= True

pdf

$$\text{In[*]:= } T_1[\varphi_, k_] = -\varphi / 2 + \varphi g_{3,k,k};$$

tex

We call the invariant computed θ :

pdf

```
In[*]:=  $\Theta[K_] := \text{Module}[\{Cs, \varphi, n, A, s, i, j, k, \Delta, G, v, \alpha, \beta, \text{gEval}, c, z\},$ 
   $\{Cs, \varphi\} = \text{Rot}[K]; n = \text{Length}[Cs];$ 
   $A = \text{IdentityMatrix}[2n + 1];$ 
   $\text{Cases}[Cs, \{s_, i_, j_ \} \Rightarrow \left( A[\{i, j\}, \{i + 1, j + 1\}] += \begin{pmatrix} -T^s & T^s - 1 \\ 0 & -1 \end{pmatrix} \right)];$ 
   $\Delta = T^{(-\text{Total}[\varphi] - \text{Total}[Cs[[All, 1]])]/2} \text{Det}[A];$ 
   $G = \text{Inverse}[A]; \text{gEval}[\mathcal{E}_] := \text{Factor}[\mathcal{E} /. \mathbf{g}_{v, \alpha, \beta} \Rightarrow (G[\alpha, \beta] /. T \rightarrow T_v)];$ 
   $z = \text{gEval}\left[\sum_{k1=1}^n \sum_{k2=1}^n \Theta[Cs[[k1], Cs[[k2]]]\right];$ 
   $z += \text{gEval}\left[\sum_{k=1}^n R_1 @ Cs[[k]]\right];$ 
   $z += \text{gEval}\left[\sum_{k=1}^{2^n} T_1[\varphi[[k], k]]\right];$ 
   $\{\Delta, (\Delta /. T \rightarrow T_1) (\Delta /. T \rightarrow T_2) (\Delta /. T \rightarrow T_3) z\} // \text{Factor}];$ 
```

exec

```
nb2tex$PDFWidth /= 1.25;
```

Some Knots

tex

```
\needspace{15mm}
{\bf\red Some Knots.}
```

pdf

```
In[*]:= Expand[\Theta[Knot[3, 1]]]
```

pdf

 KnotTheory: Loading precomputed data in PD4Knots`.

Out[*]=

pdf

$$\left\{ -1 + \frac{1}{T} + T, -\frac{1}{T_1^2} - T_1^2 - \frac{1}{T_2^2} - \frac{1}{T_1^2 T_2^2} + \frac{1}{T_1 T_2^2} + \frac{1}{T_1^2 T_2} + \frac{T_1}{T_2} + \frac{T_2}{T_1} + T_1^2 T_2 - T_2^2 + T_1 T_2^2 - T_1^2 T_2^2 \right\}$$

exec

```
nb2tex$PDFWidth *= 1.25;
```

pdf

```
In[*]:= PolyPlot[0] = Graphics[{}];
PolyPlot[p_] := Module[{crs, m1, m2, maxc, minc, s, hex},
  crs = CoefficientRules[T1^m1 == -Exponent[p, T1, Min] T2^m2 == -Exponent[p, T2, Min] p, {T1, T2}];
  maxc = N@Log@Max@Abs[Last /@ crs];
  minc = N@Log@Min@Select[Abs[Last /@ crs], # > 0 &];
  If[minc == maxc, s[_] = 0, s[c_] := s[c] = (maxc - Log@c) / (maxc - minc)];
  hex = Table[{Cos[α], Sin[α]} / Cos[2 π / 12] / 2, {α, 2 π / 12, 2 π, 2 π / 6}];
  Graphics[crs /. ({x1_, x2_} → c_) ⇒ {
    If[c == 0, White, Lighter[If[c > 0, Red, Blue], 0.88 s[Abs@c]]],
    Polygon[{{(1 - 1/2), 0}, {1, 0}, {1/2, √3/2}} · {x1 + m1, x2 + m2} + #] & /@ hex}]]]
```

exec

```
nb2tex$PDFWidth /= 1.25;
```

tex

```
\parpic[r]{$
  \includegraphics[height=0.45in]{K11n34.png}
  \atop\text{\tiny K11n34}}
  \includegraphics[height=0.45in]{K11n42.png}
  \atop\text{\tiny K11n42}}
}$
```


pdf

```
In[*]:= GraphicsRow[PolyPlot[0[Knot[#]]][2]] &
  /@ {"3_1", "K11n34", "K11n42"}
```

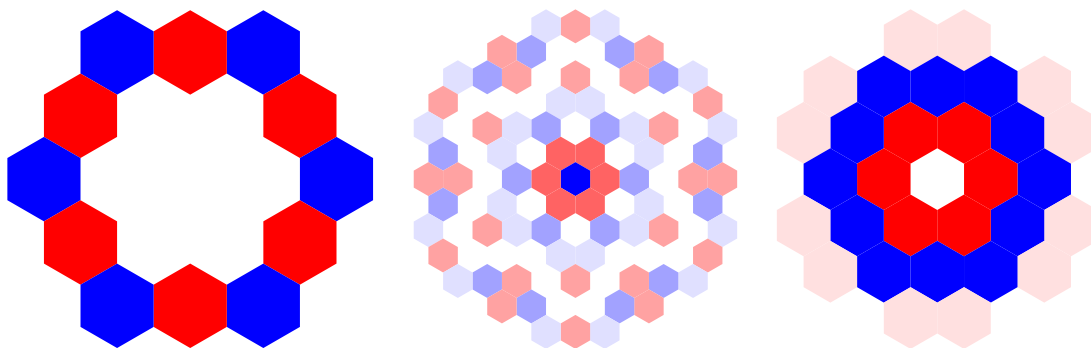
pdf

 KnotTheory: Loading precomputed data in DTCode4KnotsTo11`.

pdf

 KnotTheory: The GaussCode to PD conversion was written by Siddarth Sankaran at the University of Toronto in the summer of 2005.

Out[*]=
pdf



tex

```
\parpic[r]{$
```

```
{\includegraphics[height=0.6in]{../Projects/Gallery/Conway.png}
\atop\text{\scriptsize Conway}}
{\includegraphics[height=0.6in]{../Projects/Gallery/PhotoNotAvailable.png}
\atop\text{\scriptsize Kinoshita}}
{\includegraphics[height=0.6in]{../Projects/Gallery/Terasaka.jpg}
\atop\text{\scriptsize Terasaka}}
```

\$}

So θ detects knot mutation and separates the Conway knot $K11n34$ from the Kinoshita-Terasaka knot $K11n42$!

\vskip 8mm

%\needspace{50mm}

```
\parpic[r]{$
{\includegraphics[height=0.6in]{../Projects/Gallery/Gompf.jpg}
\atop\text{\scriptsize Gompf}}
{\includegraphics[height=0.6in]{../Projects/Gallery/Scharlemann.jpg}
\atop\text{\scriptsize Scharlemann}}
{\includegraphics[height=0.6in]{../Projects/Gallery/Thompson.jpg}
\atop\text{\scriptsize Thompson}}
```

\$}

The 48-crossing Gompf-Scharlemann-Thompson knot [\cite{GompfScharlemannThompson:Counterexample}](#) is significant because it may be a counterexample to the slice-ribbon conjecture:

`\[\resizebox{\linewidth}{!}{\import{../Waco-2203/}{GST48-Marked.pdf_t}} \]`

exec

nb2tex\$PDFwidth *= 1.25;

pdf

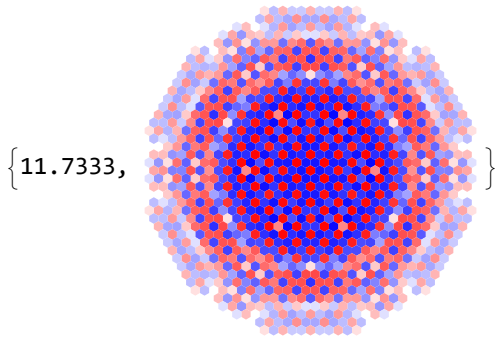
In[]:= AbsoluteTiming@

```

PolyPlot[ $\theta$ [EPD[X14,1, X̄2,29, X3,40, X43,4, X̄26,5, X6,95, X96,7, X13,8, X̄9,28, X10,41, X42,11, X̄27,12,
X30,15, X̄16,61, X̄17,72, X̄18,83, X19,34, X̄89,20, X̄21,92, X̄79,22, X̄68,23, X̄57,24, X̄25,56, X62,31,
X73,32, X84,33, X̄50,35, X36,81, X37,70, X38,59, X̄39,54, X44,55, X58,45, X69,46, X80,47, X48,91,
X90,49, X51,82, X52,71, X53,60, X̄63,74, X̄64,85, X̄76,65, X̄87,66, X̄67,94, X̄75,86, X̄88,77, X̄78,93]]][[2]]

```

Out[]:= pdf



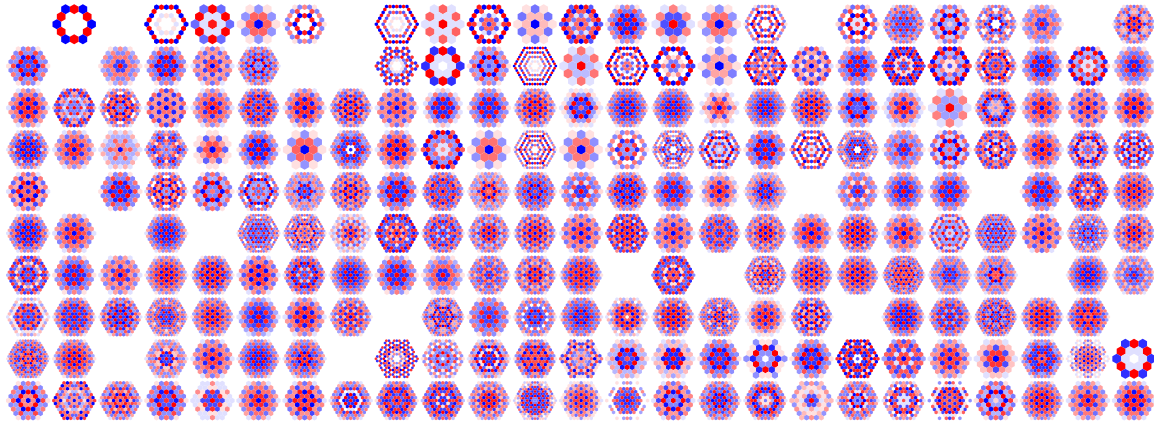
exec

In[]:= nb2tex\$PDFWidth / = 1.25;

In[]:= tab250 = { θ } ~ Join ~ Table[θ [K][[2]], {K, AllKnots[{3, 10}]}];

In[]:= g250 = GraphicsGrid[Partition[PolyPlot /@ tab250, 25], Spacings -> θ]

Out[]:=



In[]:= Export["g250.png", g250, ImageSize -> 2400]

Out[]:=

g250.png