

Pensieve header: The rank 2 mod ϵ^2 invariant using integration techniques; continues UC4A2.nb and Theta.nb at pensieve://Projects/HigherRank/.

Initialization

```
In[*]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Talks\\Beijing-2407"];
Once[<< KnotTheory` ; << Rot.m];
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.
Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/AP/Talks/Beijing-2407> to compute rotation numbers.

pdf

```
In[*]:= T3 = T1 T2;
i_+ := i + 1;
```

The Lagrangian

exec

```
In[*]:= nb2tex$PDFWidth *= 1.25;
```

pdf

```
In[*]:= 
$$\mathcal{L}[X_{i,j}[1]] := T_3 \mathbb{E} \left[ \text{Plus} \left[ \begin{aligned} & \sum_{v=1}^3 (x_{vi} (p_{vi^+} - p_{vi}) + x_{vj} (p_{vj^+} - p_{vj}) + (T_v - 1) x_{vi} (p_{vi^+} - p_{vj^+})), \\ & p_{3j} x_{2i} (T_1 x_{1i} - x_{1j}), \\ & \epsilon (T_3 - 1) p_{1j} x_{3i} (p_{2j} - p_{2i}), \\ & \epsilon (1/2 - p_{3i} x_{3i} - T_3 p_{1j} p_{2j} x_{1i} x_{2i} + p_{2j} p_{3i} x_{2j} x_{3i} - T_2 p_{2j} p_{3j} x_{2i} x_{3j} + \\ & \quad (T_3 - 1) p_{3j} x_{3i} (T_1 p_{1j} x_{1i} + T_2 p_{2j} x_{2i}) + (p_{1j} x_{1j} (p_{2i} x_{2i} - p_{3i} x_{3i}) + \\ & \quad T_1 p_{1i} x_{1i} (p_{3j} x_{3j} - p_{2j} x_{2j}) + (T_3 - 1) p_{1j} x_{1j} (p_{2j} x_{2i} - T_1 p_{3j} x_{3i})) / (T_1 - 1)), \\ & 0[\epsilon]^2 \\ & \end{aligned} \right] \right]$$

```

$$\begin{aligned}
 \text{In[*]:= Simplify}\left[\text{First}\left[\mathcal{T}_3^{-1} \mathcal{L}[X_{i,j}[1]]\right]\right] = & \\
 & \left(\left((-p_{1,i} + p_{1,i^*}) x_{1,i} + (-1 + T_1) (p_{1,i^*} - p_{1,j^*}) x_{1,i} + (-p_{1,j} + p_{1,j^*}) x_{1,j} + (-p_{2,i} + p_{2,i^*}) x_{2,i} + \right. \right. \\
 & \quad (-1 + T_2) (p_{2,i^*} - p_{2,j^*}) x_{2,i} + T_1 p_{3,j} x_{1,i} x_{2,i} - p_{3,j} x_{1,j} x_{2,i} + (-p_{2,j} + p_{2,j^*}) x_{2,j} + \\
 & \quad \left. (-p_{3,i} + p_{3,i^*}) x_{3,i} + (-1 + T_1 T_2) (p_{3,i^*} - p_{3,j^*}) x_{3,i} + (-p_{3,j} + p_{3,j^*}) x_{3,j} \right) + \\
 & \left(\frac{1}{2} - T_1 T_2 p_{1,j} p_{2,j} x_{1,i} x_{2,i} + \frac{p_{1,j} p_{2,i} x_{1,j} x_{2,i}}{-1 + T_1} + \frac{(-1 + T_1 T_2) p_{1,j} p_{2,j} x_{1,j} x_{2,i}}{-1 + T_1} - \right. \\
 & \quad \frac{T_1 p_{1,i} p_{2,j} x_{1,i} x_{2,j}}{-1 + T_1} + (1 - T_1 T_2) p_{1,j} p_{2,i} x_{3,i} + (-1 + T_1 T_2) p_{1,j} p_{2,j} x_{3,i} - \\
 & \quad p_{3,i} x_{3,i} + T_1 (-1 + T_1 T_2) p_{1,j} p_{3,j} x_{1,i} x_{3,i} - \frac{p_{1,j} p_{3,i} x_{1,j} x_{3,i}}{-1 + T_1} - \\
 & \quad \left. \frac{T_1 (-1 + T_1 T_2) p_{1,j} p_{3,j} x_{1,j} x_{3,i}}{-1 + T_1} + T_2 (-1 + T_1 T_2) p_{2,j} p_{3,j} x_{2,i} x_{3,i} + \right. \\
 & \quad \left. p_{2,j} p_{3,i} x_{2,j} x_{3,i} + \frac{T_1 p_{1,i} p_{3,j} x_{1,i} x_{3,j}}{-1 + T_1} - T_2 p_{2,j} p_{3,j} x_{2,i} x_{3,j} \right) \epsilon + \mathcal{O}[\epsilon]^2 \Big)
 \end{aligned}$$

Out[*]= $\mathcal{O}[\epsilon]^2 = 0$

pdf

$$\begin{aligned}
 \text{In[*]:= } \mathcal{L}[X_{i,j}[-1]] := \mathcal{T}_3^{-1} \mathbb{E} \Big[\text{Plus} \Big[& \\
 & \sum_{v=1}^3 (x_{vi} (p_{vi^*} - p_{vi}) + x_{vj} (p_{vj^*} - p_{vj}) + (T_v^{-1} - 1) x_{vi} (p_{vi^*} - p_{vj^*})), \\
 & T_2^{-1} (p_{3j} x_{1j} x_{2i} - T_1^{-1} p_{3j} x_{1i} x_{2i}), \\
 & \epsilon T_1^{-1} ((T_3 - 1) p_{1j} p_{2i} x_{3i} - (T_3 - 1) p_{1j} p_{2j} x_{3i}), \\
 & \epsilon \left(-1/2 + p_{3i} x_{3i} - T_1^{-1} p_{1j} p_{2i} x_{1i} x_{2i} - (1 - T_1^{-1} - T_2^{-1}) p_{1j} p_{2j} x_{1i} x_{2i} - p_{1j} p_{2j} x_{1j} x_{2i} - \right. \\
 & \quad p_{1j} p_{2j} x_{1i} x_{2j} + T_1^{-1} p_{1j} p_{3i} x_{1i} x_{3i} - (1 - T_2^{-1}) p_{2j} p_{3i} x_{2i} x_{3i} - p_{2j} p_{3i} x_{2j} x_{3i} + p_{1j} p_{3j} x_{1i} x_{3j} + \\
 & \quad p_{2j} p_{3j} x_{2i} x_{3j} + (1 - T_3^{-1}) p_{3j} x_{3i} (p_{2j} x_{2j} + p_{1j} x_{1i} - p_{2i} x_{2i} + (2 - T_2^{-1}) p_{2j} x_{2i}) + \\
 & \quad \left. (T_1 (1 - T_2^{-1}) p_{1i} p_{2j} x_{1i} x_{2i} - p_{1j} p_{2i} x_{1j} x_{2i} + T_1 p_{1i} p_{2j} x_{1i} x_{2j} - \right. \\
 & \quad \left. T_2^{-1} (T_3 - 1) p_{1i} p_{3j} x_{1i} x_{3i} + p_{1j} p_{3i} x_{1j} x_{3i} - T_1 p_{1i} p_{3j} x_{1i} x_{3j}) / (T_1 - 1) \right), \\
 & \mathcal{O}[\epsilon]^2 \\
 & \Big]
 \end{aligned}$$

In[*]:= Simplify[First[T₃ L[X_{i,j}[-1]]] ==

$$\left(\left((-p_{1,i} + p_{1,i^*}) x_{1,i} + \left(-1 + \frac{1}{T_1}\right) (p_{1,i^*} - p_{1,j^*}) x_{1,i} + (-p_{1,j} + p_{1,j^*}) x_{1,j} + (-p_{2,i} + p_{2,i^*}) x_{2,i} + \right. \right. \\ \left. \left(-1 + \frac{1}{T_2} \right) (p_{2,i^*} - p_{2,j^*}) x_{2,i} - \frac{p_{3,j} x_{1,i} x_{2,i}}{T_1 T_2} + \frac{p_{3,j} x_{1,j} x_{2,i}}{T_2} + (-p_{2,j} + p_{2,j^*}) x_{2,j} + \right. \\ \left. (-p_{3,i} + p_{3,i^*}) x_{3,i} + \left(-1 + \frac{1}{T_1 T_2}\right) (p_{3,i^*} - p_{3,j^*}) x_{3,i} + (-p_{3,j} + p_{3,j^*}) x_{3,j} \right) + \\ \left(-\frac{1}{2} - \frac{p_{1,j} p_{2,i} x_{1,i} x_{2,i}}{T_1} + \frac{T_1 (-1 + T_2) p_{1,i} p_{2,j} x_{1,i} x_{2,i}}{(-1 + T_1) T_2} - \frac{(-T_1 - T_2 + T_1 T_2) p_{1,j} p_{2,j} x_{1,i} x_{2,i}}{T_1 T_2} - \right. \\ \frac{p_{1,j} p_{2,i} x_{1,j} x_{2,i}}{-1 + T_1} - p_{1,j} p_{2,j} x_{1,j} x_{2,i} + \frac{T_1 p_{1,i} p_{2,j} x_{1,i} x_{2,j}}{-1 + T_1} - p_{1,j} p_{2,j} x_{1,i} x_{2,j} + \\ \frac{(-1 + T_1 T_2) p_{1,j} p_{2,i} x_{3,i}}{T_1} - \frac{(-1 + T_1 T_2) p_{1,j} p_{2,j} x_{3,i}}{T_1} + p_{3,i} x_{3,i} + \\ \frac{p_{1,j} p_{3,i} x_{1,i} x_{3,i}}{T_1} - \frac{(-1 + T_1 T_2) p_{1,i} p_{3,j} x_{1,i} x_{3,i}}{(-1 + T_1) T_2} + \frac{(-1 + T_1 T_2) p_{1,j} p_{3,j} x_{1,i} x_{3,i}}{T_1 T_2} + \\ \frac{p_{1,j} p_{3,i} x_{1,j} x_{3,i}}{-1 + T_1} - \frac{(-1 + T_2) p_{2,j} p_{3,i} x_{2,i} x_{3,i}}{T_2} - \frac{(-1 + T_1 T_2) p_{2,i} p_{3,j} x_{2,i} x_{3,i}}{T_1 T_2} + \\ \left. \frac{(-1 + 2 T_2) (-1 + T_1 T_2) p_{2,j} p_{3,j} x_{2,i} x_{3,i}}{T_1 T_2^2} - p_{2,j} p_{3,i} x_{2,j} x_{3,i} + \frac{(-1 + T_1 T_2) p_{2,j} p_{3,j} x_{2,j} x_{3,i}}{T_1 T_2} - \right. \\ \left. \frac{T_1 p_{1,i} p_{3,j} x_{1,i} x_{3,j}}{-1 + T_1} + p_{1,j} p_{3,j} x_{1,i} x_{3,j} + p_{2,j} p_{3,j} x_{2,i} x_{3,j} \right) \epsilon + O[\epsilon]^2 \Big]$$

Out[*]= 0[ε]² == 0

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In[*]:= $\mathcal{L}[C_{i-}[\varphi_-]] := T_3^\varphi \mathbb{E} \left[\sum_{v=1}^3 x_{v,i} (p_{v,i^*} - p_{v,i}) + \epsilon \varphi (p_{3,i} x_{3,i} - 1/2) + O[\epsilon]^2 \right]$

In[*]:= L[C_i[φ]]

Out[*]=

$$(T_1 T_2)^\varphi \mathbb{E} \left[((-p_{1,i} + p_{1,1+i}) x_{1,i} + (-p_{2,i} + p_{2,1+i}) x_{2,i} + (-p_{3,i} + p_{3,1+i}) x_{3,i}) + \varphi \left(-\frac{1}{2} + p_{3,i} x_{3,i} \right) \epsilon + O[\epsilon]^2 \right]$$

exec

In[*]:= nb2tex\$PDFWidth / = 1.25;

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In[*]:= << FormalGaussianIntegration.m

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```
In[*]:= ps_i := Sequence[p1,i, p2,i, p3,i];
xs_i := Sequence[x1,i, x2,i, x3,i];
vs_i := Sequence[ps_i, xs_i];
F[is___] := E[Sum[πv,i p_v,i, {i, {is}}, {v, 3}]];
L[K_] := CF[L/@Features[K][[2]]];
vs[K_] := Union@@Table[{vs_i}, {i, Features[K][[1]]}]
```

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Reidemeister 3

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```
In[*]:= BalancingHack = ReplaceAll[εSeries[most___, last_] =>
εSeries[most, CF[last /. {πss_ => B^-1 πss, pss_ => B pss}]] /. B^b_ /; b < 0 -> 0];
```

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```
In[*]:= Short[lhs = ∫ F[i, j, k] L /@ (Xi,j[1] Xi,k[1] Xj+,k+[1]) d{vs_i, vs_j, vs_k, vs_i+, vs_j+, vs_k+} //
BalancingHack]
```

Out[*]//Short=
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$$T_1^3 T_2^3 E \left[\epsilon \text{Series} \left[T_1^2 p_{1,2+i} \pi_{1,i} - (-1 + T_1) T_1 p_{1,2+j} \pi_{1,i} + (1 - T_1) p_{1,2+k} \pi_{1,i} + \right. \right. \\ \left. \left. \ll 24 \gg + T_1 T_2 p_{3,2+j} \pi_{3,j} + (1 - T_1 T_2) p_{3,2+k} \pi_{3,j} + p_{3,2+k} \pi_{3,k}, \frac{3}{2} + \ll 107 \gg \right] \right]$$

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```
In[*]:= rhs = ∫ F[i, j, k] L /@ (Xj,k[1] Xi,k+[1] Xi+,j+[1]) d{vs_i, vs_j, vs_k, vs_i+, vs_j+, vs_k+} //
BalancingHack;
lhs == rhs
```

Out[*]=
pdf

True

pdf

The Trefoil

pdf

```
In[*]:= K = Knot[3, 1]; ∫ L[K] d vs[K]
```

Out[*]=
pdf

$$\frac{i T_1^2 T_2^2 E \left[\epsilon \text{Series} \left[0, - \frac{1 - T_1 + T_1^2 - T_2 - T_1^3 T_2 + T_2^2 + T_1^4 T_2^2 - T_1 T_2^3 - T_1^4 T_2^3 + T_1^2 T_2^4 - T_1^3 T_2^4 + T_1^4 T_2^4}{(1 - T_1 + T_1^2) (1 - T_2 + T_2^2) (1 - T_1 T_2 + T_1^2 T_2^2)} \right] \right]}{(1 - T_1 + T_1^2) (1 - T_2 + T_2^2) (1 - T_1 T_2 + T_1^2 T_2^2)}$$