

```
In[1]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\Theta"];
```

tex

We start by loading the package `\verb$KnotTheory`` --- it is only needed because it has many specific knots pre-defined:

pdf

```
In[2]:= << KnotTheory`
```

pdf

```
Loading KnotTheory` version of October 29, 2024, 10:29:52.1301.
Read more at http://katlas.org/wiki/KnotTheory.
```

tex

Next we quietly define the commands `\verb$Rot$`, used to compute rotation numbers, and `\verb$PolyPlot$`, used to plot polynomials as bar codes and as hexagonal QR codes. Neither is a part of the core of the computation of `\$Theta$`, so neither is shown; yet we do show some usage examples.

pdf

```
In[3]:= (* Rot suppressed *)
```

```
In[4]:= Rot[pd_PD] := Module[{n, xs, x, rots, Xp, Xm, front = {1}, k},
  n = Length@pd; rots = Table[0, {2 n}];
  xs = Cases[pd, x_X :> {Xp[x[[4]], x[[1]]] PositiveQ@x,
    Xm[x[[2]], x[[1]]] True}];
  For[k = 1, k ≤ 2 n, ++k,
    If[FreeQ[front, -k],
      front = Flatten@Replace[front, k → (xs /. {
          Xp[k, l_] | Xm[l_, k] :> {l + 1, k + 1, -l},
          Xp[l_, k] | Xm[k, l_] :> (++rots[[l]]; {-l, k + 1, l + 1}),
          _Xp | _Xm :> {}}),
        {1}], {1}],
      Cases[front, k | -k] /. {k, -k} :> --rots[[k]];
    ]
  ];
  {xs /. {Xp[i_, j_] :> {+1, i, j}, Xm[i_, j_] :> {-1, i, j}}, rots} ];
Rot[K_] := Rot[PD[K]];
```

pdf

```
In[5]:= Rot[Mirror@Knot[3, 1]]
```

```
Out[5]=
pdf
```

```
{ {{1, 1, 4}, {1, 3, 6}, {1, 5, 2}}, {0, 0, 0, -1, 0, 0} }
```

tex

We urge the reader to compare the above output with the knot diagram in Section~\ref{ssec:OldFormulas}.

pdf

```
In[0]:= (* PolyPlot suppressed *)
```

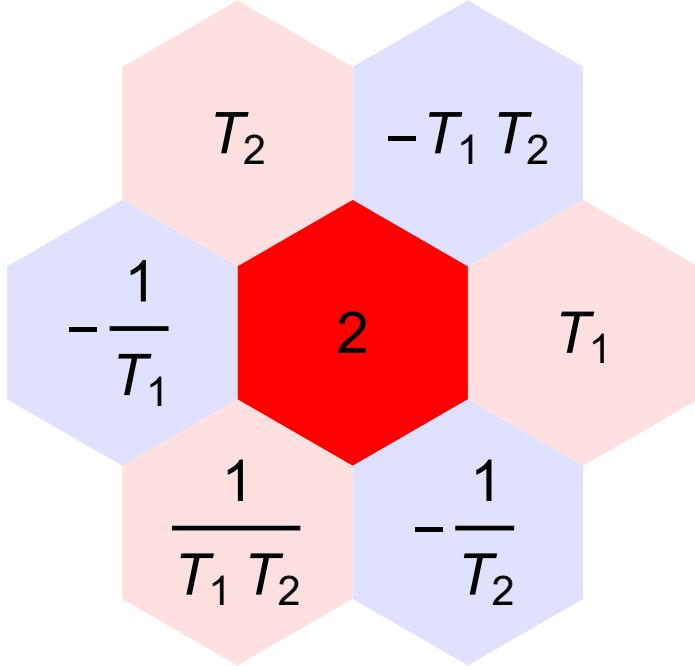
```

In[1]:= PolyPlot1[ $\Delta$ ] := Module[{crs, m, maxc, minc, s, rect},
  rect = {{0, 0}, {1, 0}, {1, 1}, {0, 1}};
  If[Expand[ $\Delta$ ] === 0, Graphics[],
    m = Max[-Exponent[ $\Delta$ , T, Min], Exponent[ $\Delta$ , T, Max]];
    crs = CoefficientRules[T $\Delta$ , {T}];
    maxc = N@Log@Max@Abs[Last /@ crs];
    minc = N@Log@Min@Select[Abs[Last /@ crs], # > 0 &];
    If[minc == maxc, s[_] = 0, s[c_] := s[c] = (maxc - Log@c) / (maxc - minc)];
    Graphics[crs /. ({x_} → c_) :> {
      Lighter[Which[c == 0, White, c > 0, Red, c < 0, Blue], 0.88 s[Abs@c]],
      Tooltip[Polygon[({x + m - 1/2, 0} + #) & /@ rect], c Tx-m]
    }, AspectRatio → Min[1/5, 1/√(m+1)],
    ImagePadding → None, PlotRangePadding → None]
  }];
Options[PolyPlot2] = {Labeled → False};
PolyPlot2[θ_, OptionsPattern[]] := Module[{crs, m1, m2, maxc, minc, s, hex, p},
  If[Expand[θ] === 0, Graphics[{White, Disk[]}]],
  hex = Table[{Cos[α], Sin[α]} / Cos[2π/12]/2, {α, 2π/12, 2π, 2π/6}];
  m1 = Max[-Exponent[θ, T1, Min], Exponent[θ, T1, Max]];
  m2 = Max[-Exponent[θ, T2, Min], Exponent[θ, T2, Max]];
  crs = CoefficientRules[T1m1 T2m2 θ, {T1, T2}];
  maxc = N@Log@Max@Abs[Last /@ crs];
  minc = N@Log@Min@Select[Abs[Last /@ crs], # > 0 &];
  If[minc == maxc, s[_] = 0, s[c_] := s[c] = (maxc - Log@c) / (maxc - minc)];
  Graphics[{{(*{Yellow,Disk[{0,0},1+Cos[2π/12]Norm[{m1,m2}]/√2]),*}
    crs /. ({x1_, x2_} → c_) :> {
      Lighter[Which[c == 0, White, c > 0, Red, c < 0, Blue], 0.88 s[Abs@c]],
      p = {{1, -1/2}, {0, √3/2}}. {x1 - m1, x2 - m2};
      Tooltip[Polygon[(p + #) & /@ hex], c T1x1-m1 T2x2-m2],
      If[Not@OptionValue[Labeled], {}, {Black, Text[Style[c T1x1-m1 T2x2-m2, 30], p}]}
    }
  }, ImagePadding → None, PlotRangePadding → None]
];
PolyPlot[{\mathDelta_, \theta_}, opts___Rule] := GraphicsColumn[
  {PolyPlot1[\mathDelta], PolyPlot2[\theta, FilterRules[{opts}, Options[PolyPlot2]]]}, 
  Spacings → Scaled@0.08, ImagePadding → None, PlotRangePadding → None,
  FilterRules[{opts}, Options[GraphicsColumn]]]
];

```

```
In[1]:= PPDemo = PolyPlot2[2 + T1 - T1 T2 + T2 - T1-1 + T1-1 T2-1 - T2-1, Labeled → True]
```

Out[1]=



```
In[2]:= Export["PPDemo.pdf", PPDemo]
```

Out[2]=

PPDemo.pdf

```
In[3]:= 1 / 2 + T1 - T1 T2 + T2 - T1-1 + T1-1 T2-1 - T2-1 // TexForm
```

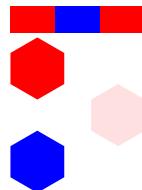
Out[3]//TeXForm=

$$-\frac{1}{T_2} \frac{T_1+T_2-T_1 T_2}{T_2 T_1} - \frac{1}{T_1} \frac{1}{T_1+T_2-T_1 T_2}$$

pdf

```
In[4]:= PolyPlot[{T - 1 + T-1, T1 + 2 T2 - 2 T1-1 T2-1}, ImageSize → Tiny]
```

Out[4]=



pdf

```
In[5]:= T3 = T1 T2;
```

pdf

```
In[6]:= R11[{s_, i_, j_}] =
  s (1/2 - g3ii + T2s g1ii g2ji - g1ii g2jj - (T2s - 1) g2ji g3ii + 2 g2jj g3ii - (1 - T3s) g2ji g3ji -
  g2ii g3jj - T2s g2ji g3jj + g1ii g3jj + ((T1s - 1) g1ji (T22s g2ji - T2s g2jj + T2s g3jj) +
  (T3s - 1) g3ji (1 - T2s g1ii - (T1s - 1) (T2s + 1) g1ji + (T2s - 2) g2jj + g2ij)) / (T2s - 1));
```

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$$\text{In}[{\color{blue} \circ}] := \mathbf{R}_{12}[\{s\theta_-, i\theta_-, j\theta_-\}, \{s1_-, i1_-, j1_-\}] = s1 \left(T_1^{s\theta} - 1\right) \left(T_2^{s1} - 1\right)^{-1} \left(T_3^{s1} - 1\right) g_{1,j1,i\theta} g_{3,j\theta,i1} \left( \left(T_2^{s\theta} g_{2,i1,i\theta} - g_{2,i1,j\theta}\right) - \left(T_2^{s\theta} g_{2,j1,i\theta} - g_{2,j1,j\theta}\right) \right);$$

pdf

$$\text{In}[{\color{blue} \circ}] := \Gamma_1[\varphi_-, k_-] = -\varphi / 2 + \varphi g_{3kk};$$

pdf

$$\begin{aligned} \text{In}[{\color{blue} \circ}] := & \Theta[K_-] := \text{Module}\left[\{\mathbf{Cs}, \varphi, n, A, \Delta, G, \text{ev}, \theta\}, \right. \\ & \{\mathbf{Cs}, \varphi\} = \text{Rot}[K]; n = \text{Length}[\mathbf{Cs}]; \\ & A = \text{IdentityMatrix}[2n+1]; \\ & \mathbf{Cases}[\mathbf{Cs}, \{s_-, i_-, j_-\} \rightarrow \left(A[\{i, j\}, \{i+1, j+1\}] += \begin{pmatrix} -T^s & T^s - 1 \\ 0 & -1 \end{pmatrix}\right)]; \\ & \Delta = T^{(-\text{Total}[\varphi] - \text{Total}[\mathbf{Cs}[\text{All}, 1]])/2} \text{Det}[A]; \\ & G = \text{Inverse}[A]; \\ & \mathbf{ev}[\mathcal{E}_-] := \text{Factor}[\mathcal{E} / . g_{v_-, \alpha_-, \beta_-} \rightarrow (G[\alpha, \beta] / . T \rightarrow T_v)]; \\ & \theta = \mathbf{ev}\left[\sum_{k1=1}^n \sum_{k2=1}^n R_{12}[\mathbf{Cs}[k1], \mathbf{Cs}[k2]]\right]; \\ & \theta += \mathbf{ev}\left[\sum_{k=1}^n R_{11}[\mathbf{Cs}[k]]\right]; \\ & \theta += \mathbf{ev}\left[\sum_{k=1}^n \Gamma_1[\varphi[k], k]\right]; \\ & \text{Factor}@\{\Delta, (\Delta / . T \rightarrow T_1) (\Delta / . T \rightarrow T_2) (\Delta / . T \rightarrow T_3) \theta\} \\ \left. \right]; \end{aligned}$$

$$\text{In}[{\color{blue} \circ}] := \text{Expand}[\Theta[\text{Knot}[3, 1]]]$$

**KnotTheory:** Loading precomputed data in PD4Knots`.

Out[{\color{blue} \circ}] =

$$\left\{ -1 + \frac{1}{T}, -\frac{1}{T_1^2} - T_1^2 - \frac{1}{T_2^2} - \frac{1}{T_1^2 T_2^2} - \frac{1}{T_1 T_2^2} + \frac{1}{T_1^2 T_2} + \frac{1}{T_1^2} + \frac{T_1}{T_2} + \frac{T_2}{T_1} + T_1^2 T_2 - T_2^2 + T_1 T_2^2 - T_1^2 T_2^2 \right\}$$

In[ $\#$ ]:= **Expand**[ $\Theta[\text{Knot}[10, 165]]$ ]

Out[ $\#$ ]=

$$\left\{ -15 - \frac{2}{T^2} + \frac{10}{T} + 10T - 2T^2, \right.$$

$$-1404 - \frac{9}{T_1^4} - \frac{178}{T_1^3} + \frac{607}{T_1^2} + \frac{624}{T_1} + 624T_1 + 607T_1^2 - 178T_1^3 - 9T_1^4 - \frac{9}{T_2^4} - \frac{9}{T_1^4 T_2^4} + \frac{44}{T_1^3 T_2^4} -$$

$$\frac{65}{T_1^2 T_2^4} + \frac{44}{T_1 T_2^4} - \frac{178}{T_2^3} + \frac{44}{T_1^4 T_2^3} - \frac{178}{T_1^3 T_2^3} + \frac{104}{T_1^2 T_2^3} + \frac{104}{T_1 T_2^3} + \frac{44 T_1}{T_2^3} + \frac{607}{T_2^2} - \frac{65}{T_1^4 T_2^2} + \frac{104}{T_1^3 T_2^2} + \frac{607}{T_1^2 T_2^2} -$$

$$\frac{1041}{T_1 T_2^2} + \frac{104 T_1}{T_2^2} - \frac{65 T_1^2}{T_2^2} + \frac{624}{T_2} + \frac{44}{T_1^4 T_2} + \frac{104}{T_1^3 T_2} - \frac{1041}{T_1^2 T_2} + \frac{624}{T_1 T_2} - \frac{1041 T_1}{T_2} + \frac{104 T_1^2}{T_2} + \frac{44 T_1^3}{T_2} +$$

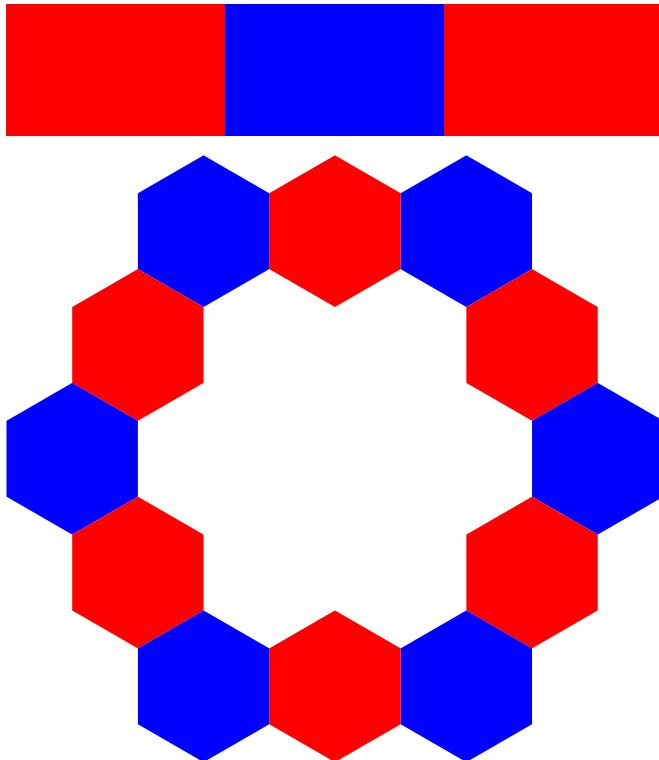
$$624 T_2 + \frac{44 T_2}{T_1^3} + \frac{104 T_2}{T_1^2} - \frac{1041 T_2}{T_1} + 624 T_1 T_2 - 1041 T_1^2 T_2 + 104 T_1^3 T_2 + 44 T_1^4 T_2 +$$

$$\left. 607 T_2^2 - \frac{65 T_2^2}{T_1^2} + \frac{104 T_2^2}{T_1} - 1041 T_1 T_2^2 + 607 T_1^2 T_2^2 + 104 T_1^3 T_2^2 - 65 T_1^4 T_2^2 - 178 T_2^3 + \frac{44 T_2^3}{T_1} + \right.$$

$$\left. 104 T_1 T_2^3 + 104 T_1^2 T_2^3 - 178 T_1^3 T_2^3 + 44 T_1^4 T_2^3 - 9 T_2^4 + 44 T_1 T_2^4 - 65 T_1^2 T_2^4 + 44 T_1^3 T_2^4 - 9 T_1^4 T_2^4 \right\}$$

In[ $\#$ ]:= **PolyPlot**[ $\Theta[\text{Knot}[3, 1]]$ ]

Out[ $\#$ ]=

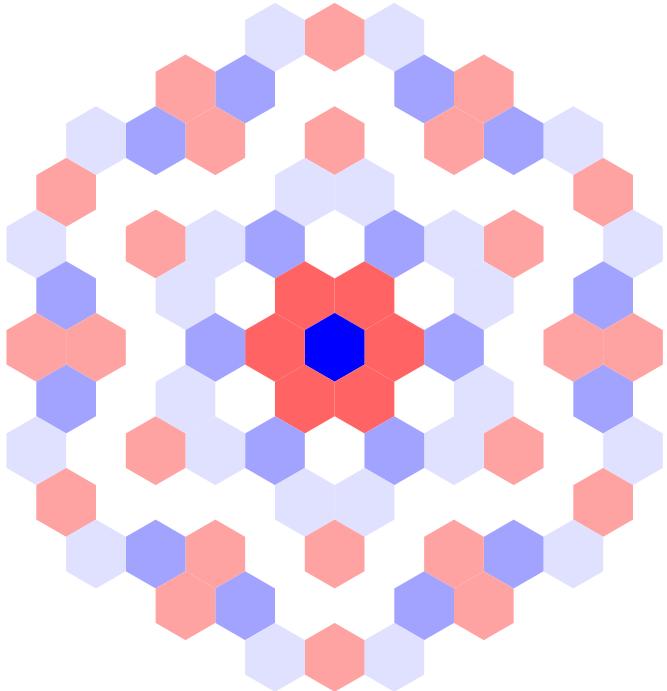


In[=]:= **PolyPlot**[ $\Theta$ [Knot["K11n34"]]]

↳ **KnotTheory**: Loading precomputed data in DTCode4KnotsTo11`.

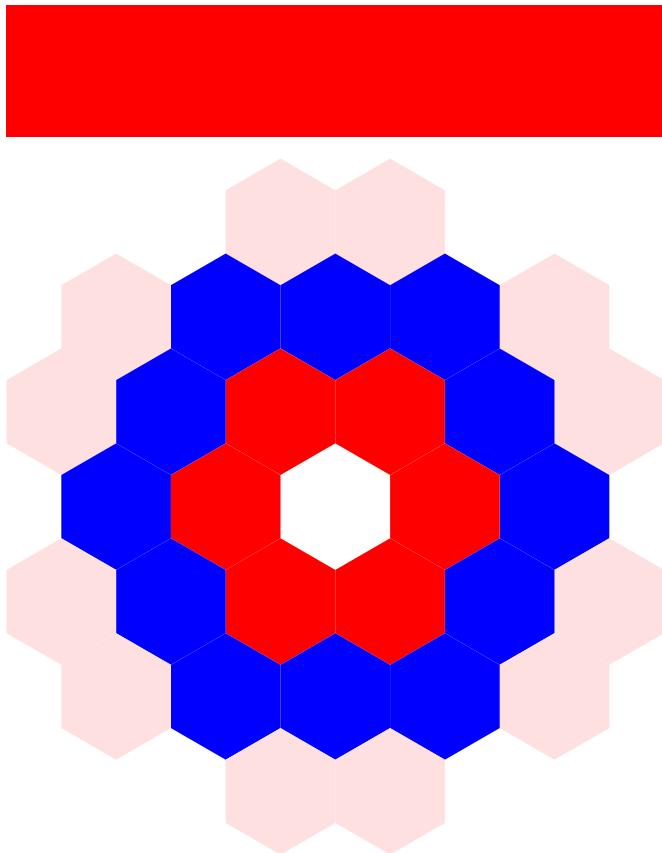
↳ **KnotTheory**: The GaussCode to PD conversion was written by Siddarth Sankaran at the University of Toronto in the summer of 2005.

Out[=]=



```
In[]:= PolyPlot[\Theta[Knot["K11n42"]]]
```

```
Out[]=
```



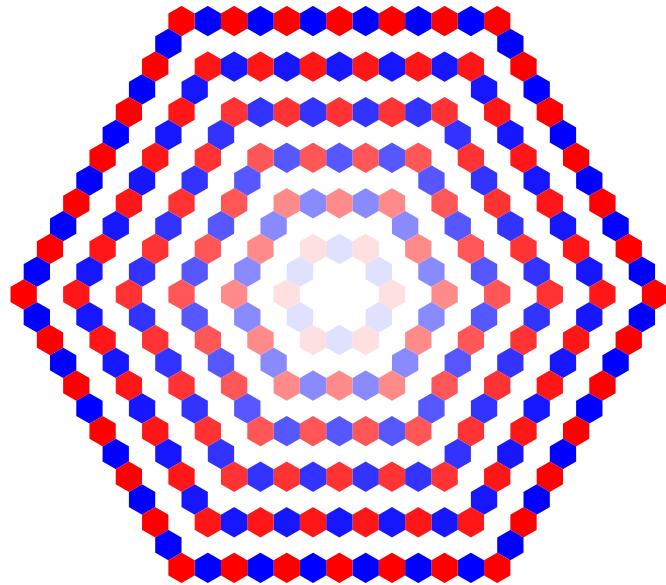
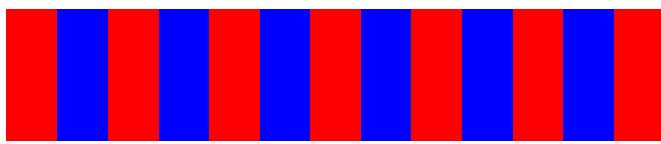
```
In[]:= PositiveQ /@ PD[TorusKnot[13, 2]]
```

```
Out[]=
```

```
PD[True, True, True, True, True, True, True, True, True, True, True]
```

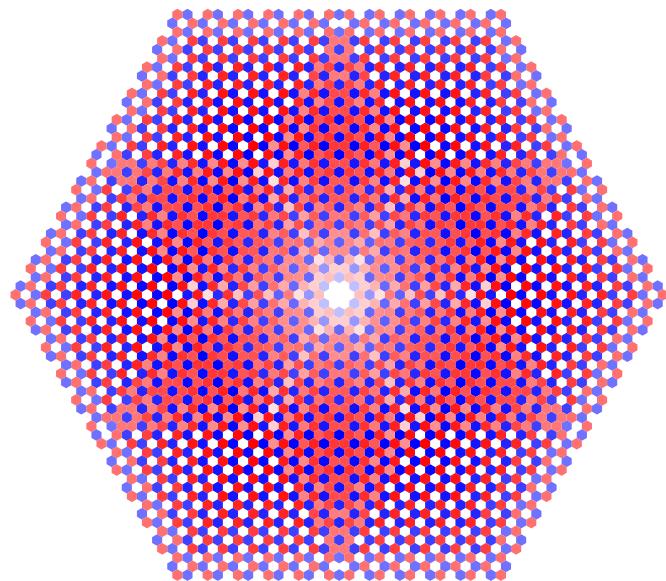
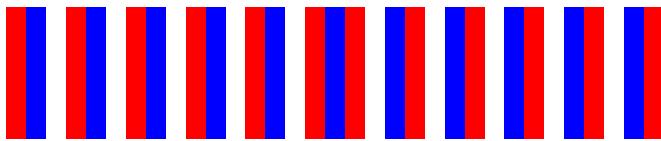
```
In[6]:= PolyPlot[\Theta[TorusKnot[13, 2]]]
```

```
Out[6]=
```



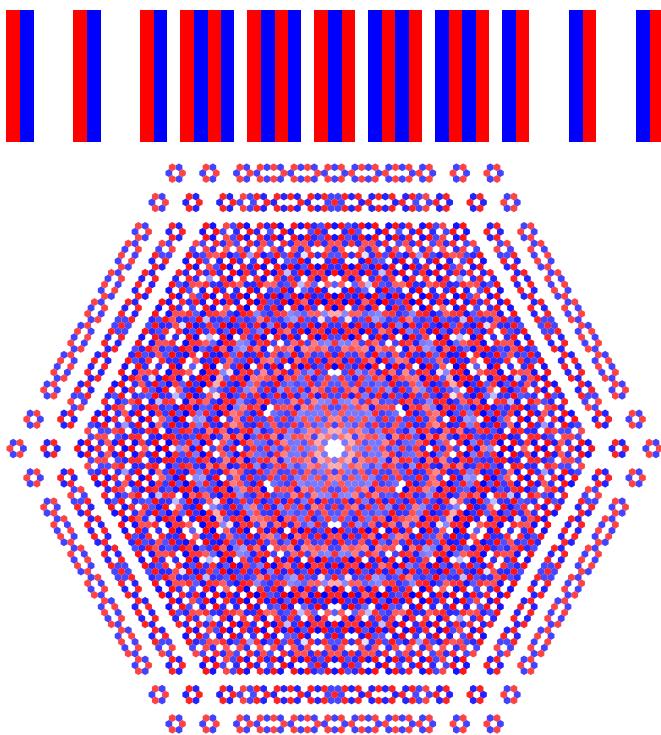
```
In[6]:= PolyPlot[\Theta[TorusKnot[17, 3]]]
```

```
Out[6]=
```



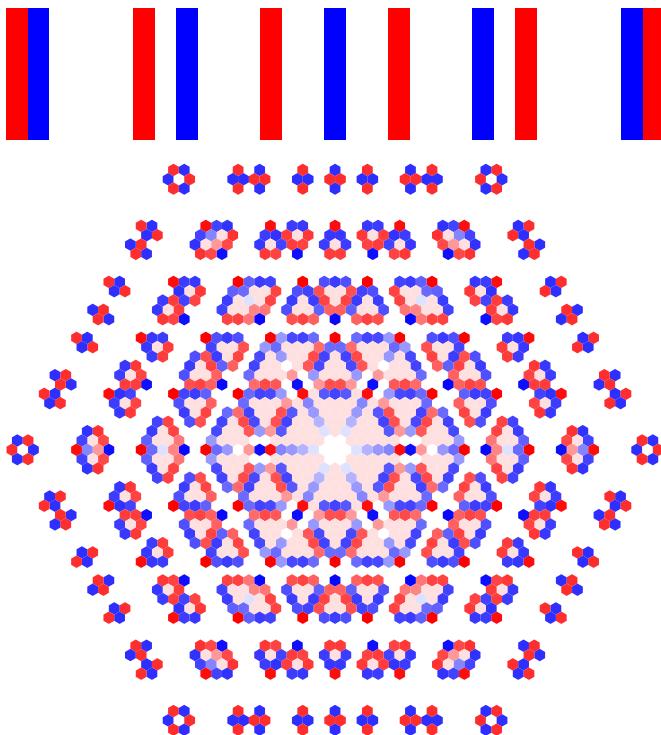
```
In[=]:= PolyPlot[\Theta[TorusKnot[13, 5]]]
```

```
Out[=]=
```



```
In[=]:= PolyPlot[\Theta[TorusKnot[7, 6]]]
```

```
Out[=]=
```



In[ $\#$ ]:= **AbsoluteTiming[th = Θ[TorusKnot[22, 7]]]**

**PolyPlot[th]**

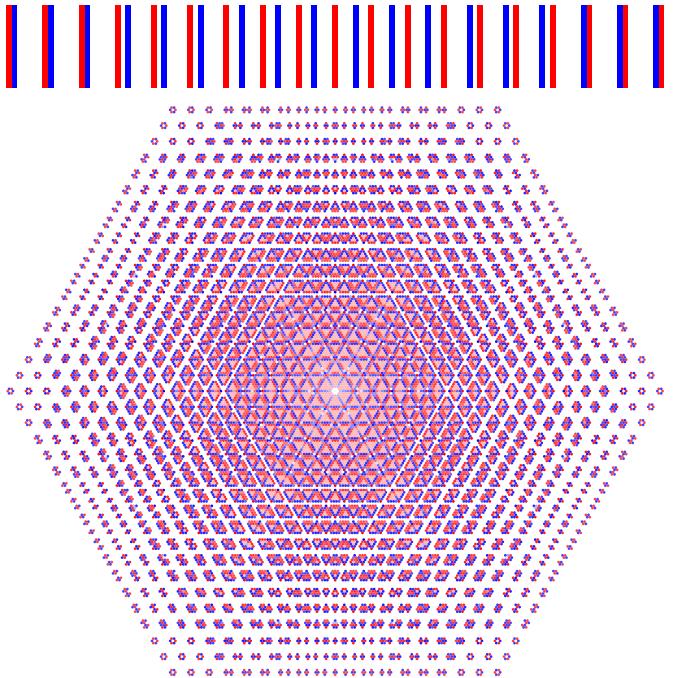
Out[ $\#$ ]=

$$\left\{ 4805.79, \left\{ \frac{1}{T^{63}} \left( 1 - T + T^2 - T^3 + T^4 - T^5 + T^6 \right) \left( 1 - T + T^7 - T^8 + T^{11} - T^{12} + T^{14} - T^{15} + T^{18} - T^{19} + \dots + T^{42} - T^{45} + T^{46} - T^{48} + T^{49} - T^{52} + T^{53} - T^{59} + T^{60} \right) \left( 1 + T - T^7 - T^8 - T^{11} - T^{12} + T^{14} + T^{15} + T^{18} + T^{19} - T^{21} + T^{23} - T^{25} - T^{26} + T^{28} - T^{30} + T^{32} - T^{34} - T^{35} + T^{37} - T^{39} + T^{41} + T^{42} + T^{45} + T^{46} - T^{48} - T^{49} - T^{52} - T^{53} + T^{59} + T^{60} \right), \frac{63 - 63 T_1 + 63 T_1^7 - 63 T_1^8 + \dots + 30638 \dots + 63 T_1^{245} T_2^{252} - 63 T_1^{251} T_2^{252} + 63 T_1^{252} T_2^{252}}{T_1^{126} T_2^{126}} \right\} \right\}$$

Full expression not available (original memory size: 8.1 MB)



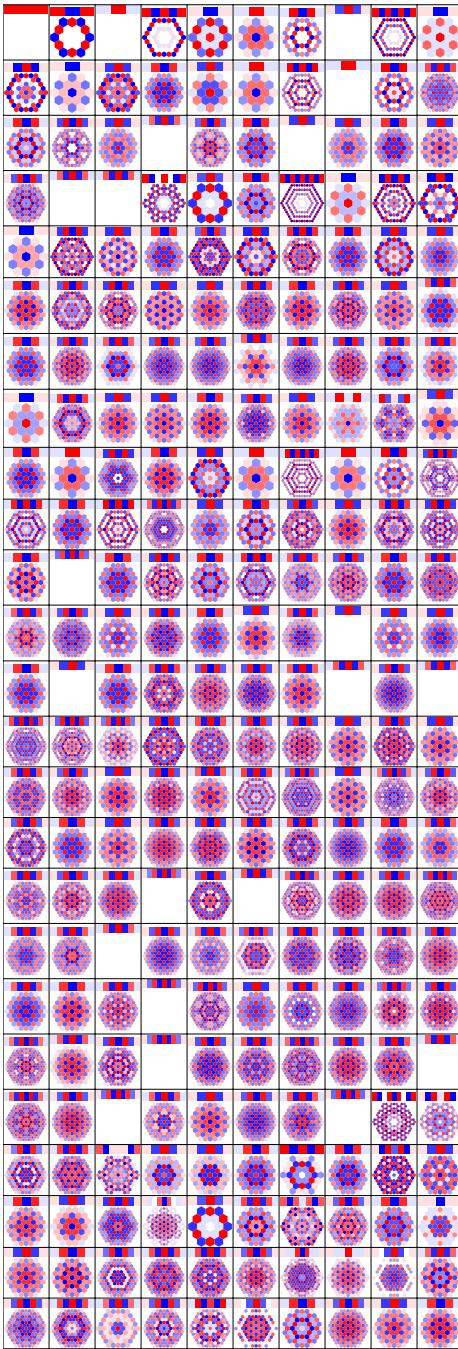
Out[ $\#$ ]=



In[ $\#$ ]:= **tab250 = {{1, 0}} ~Join~ Table[Θ[K], {K, AllKnots[{3, 10}]}];**

```
In[]:= g250 = GraphicsGrid[Partition[PolyPlot /@ tab250, 10],  
  Spacings -> 0, Dividers -> All, ImagePadding -> None, PlotRangePadding -> None]
```

```
Out[]=
```



```
In[]:= Export["Theta4Rolfsen.pdf", g250]
```

```
Out[]=
```

Theta4Rolfsen.pdf

See also <https://drorbn.net/AcademicPensieve/Projects/HigerRank/DunfieldKnots/>.

In[ $\#$ ]:=  $\Theta[\text{BR}[5, \{1, 2, 3, -1, 2, 1, 3\}]]$

Out[ $\#$ ]=

$$\left\{ \frac{2 - 3 T + 2 T^2}{T}, \frac{1}{T_1^2 T_2^2} (9 - 13 T_1 + 9 T_1^2 - 13 T_2 + 6 T_1 T_2 + 6 T_1^2 T_2 - 13 T_1^3 T_2 + 9 T_2^2 + 6 T_1 T_2^2 - 12 T_1^2 T_2^2 + 6 T_1^3 T_2^2 + 9 T_1^4 T_2^2 - 13 T_1 T_2^3 + 6 T_1^2 T_2^3 + 6 T_1^3 T_2^3 - 13 T_1^4 T_2^3 + 9 T_1^2 T_2^4 - 13 T_1^3 T_2^4 + 9 T_1^4 T_2^4) \right\}$$

$\Theta[\text{BR}[5, \{1, 2, 3, -1, 2, 1, 3\}]]$

In[ $\#$ ]:= **PolyPlot@Expand[**

**Get["C:\\drorbn\\AcademicPensieve\\Projects\\HigherRank\\DunfieldKnots\\D300.m"][[2]] /.**  
**{T1 \rightarrow T1, T2 \rightarrow T2}]**

Out[ $\#$ ]=

