

```
In[*]:= SetDirectory["C:\\drorbn\\AcademicPensive\\Projects\\HigherRank\\Rolands_A2"];
Once[<< KnotTheory`];
<< ../Rot.m
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/AP/Projects/HigherRank> to compute rotation numbers.

```
In[*]:= r0[1, i_, j_] := 2 (-T1 + T2 + T1 T2) p3,j x1,i x2,i - 2 (-1 + T2) p3,j x1,j x2,i - 2 p3,j x1,i x2,j
(*from r0p*)
r0[-1, i_, j_] := - 2 p3,j x1,i x2,i / T1 + 2 (-1 + T2) p3,j x1,j x2,i / T2 + 2 p3,j x1,i x2,j / T1
r1[1, i_, j_] :=
- 3 / 2 - 2 p1,i x1,i - 2 p1,j x1,i - p1,i p1,j x1,i^2 - 1 / 2 (-1 + T1) (2 + T1) p1,j^2 x1,i^2 + 4 p1,j x1,j / T1 -
p1,i p1,j x1,i x1,j + 1 / 2 (3 + T1) p1,j^2 x1,i x1,j - 2 p2,i x2,i + 2 p2,j x2,i - 2 p1,j p2,i x1,i x2,i +
((1 - 3 T1 + 2 T2 - 4 T1 T2 + 9 T1^2 T2 - 4 T2^2 + 11 T1 T2^2 - 18 T1^2 T2^2 - 4 T1 T2^3 + 9 T1^2 T2^3) p1,i p2,j x1,i x2,i) /
((-1 + T1) (-1 + 2 T2)) + (1 + 4 T1 - 6 T2 + 9 T1 T2 - 9 T1^2 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,j x1,i x2,i +
(-4 + 3 T1 + 16 T1 T2 - 9 T1^2 T2 + 8 T2^2 - 22 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,i x1,j x2,i /
(-1 + T1) (-1 + 2 T2)
(-1 + T2) (2 + T1 - 11 T1 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,j x1,j x2,i /
(-1 + T1) (-1 + 2 T2)
2 p2,i p2,j x2,i^2 - 1 / 2 (-1 + T2) (4 + T2) p2,j^2 x2,i^2 + 2 p1,i p2,j x1,i x2,j -
(3 T1 - 4 T2 + 7 T1 T2 - 9 T1^2 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,j x1,i x2,j /
-1 + 2 T2
1 / 2 (5 + T2) p2,j^2 x2,i x2,j + (T1 + 4 T2 - 11 T1 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,i x3,i /
2 (-1 + 2 T2)
1 / 2 p1,i p2,j x3,i - (-1 + T1 + 6 T2 - 11 T1 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p2,j x3,i /
2 (-1 + 2 T2)
2 p3,i x3,i + p3,j x3,i + 2 p1,j p3,i x1,i x3,i - 2 p1,i p3,j x1,i x3,i - 1 / (-1 + 2 T2)
(-3 T1 + 4 T2 - 5 T1 T2 + 10 T1^2 T2 - 4 T1 T2^2 + 2 T1^2 T2^2 - 9 T1^3 T2^2 - 4 T1^2 T2^3 + 9 T1^3 T2^3) p1,j p3,j x1,i x3,i +
(6 - 4 T1 + T1^2 + 4 T2 - 13 T1 T2 - 4 T1 T2^2 + 9 T1^2 T2^2) p1,j p3,i x1,j x3,i /
(-1 + T1) (-1 + T1 T2)
((-3 + T1 - T1^2 + 6 T2 - 4 T1 T2 + 12 T1^2 T2 - 7 T1^2 T2^2 - 9 T1^3 T2^2 - 4 T1^2 T2^3 + 9 T1^3 T2^3) p1,j p3,j x1,j x3,i) /
((-1 + T1) (-1 + 2 T2)) + p2,j p3,i x2,i x3,i - (p2,i p3,j x2,i x3,i -
1 / (-1 + T1) (-1 + 2 T2) (-1 + T1 + 5 T2 - 4 T1 T2 + 2 T2^2 - 20 T1 T2^2 + 10 T1^2 T2^2 - 8 T2^3 +
18 T1 T2^3 + 11 T1^2 T2^3 - 9 T1^3 T2^3 + 8 T1 T2^4 - 22 T1^2 T2^4 + 9 T1^3 T2^4) p2,j p3,j x2,i x3,i -
```

$$\begin{aligned}
& \left( (-3 + 2 T_1 - T_2 + 21 T_1 T_2 - 11 T_1^2 T_2 + 14 T_2^2 - 44 T_1 T_2^2 + T_1^2 T_2^2 + 9 T_1^3 T_2^2 - 8 T_2^3 + 10 T_1 T_2^3 + \right. \\
& \quad \left. 33 T_1^2 T_2^3 - 18 T_1^3 T_2^3 + 8 T_1 T_2^4 - 22 T_1^2 T_2^4 + 9 T_1^3 T_2^4) p_{2,j} p_{3,i} x_{2,j} x_{3,i} \right) / ((-1 + T_1) (-1 + T_2) \\
& \quad (-1 + 2 T_2) (-1 + T_1 T_2)) + \frac{(T_1 + 4 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{2,i} p_{3,j} x_{2,j} x_{3,i}}{(-1 + T_1) (-1 + 2 T_2)} - \\
& \left( (-1 - 3 T_2 + 12 T_1 T_2 - T_1^2 T_2 + 6 T_2^2 - 11 T_1 T_2^2 - 7 T_1^2 T_2^2 - 4 T_1 T_2^3 + 9 T_1^2 T_2^3) p_{2,j} p_{3,j} x_{2,j} x_{3,i} \right) / \\
& \left( (-1 + T_1) (-1 + T_2) (-1 + 2 T_2) \right) - p_{3,i} p_{3,j} x_{3,i}^2 + \frac{1}{2 (-1 + T_1) (-1 + 2 T_2)} (-1 + T_1 T_2) \\
& \left( -2 + 2 T_1 + 4 T_2 - 7 T_1 T_2 + 2 T_1^2 T_2 - 2 T_1 T_2^2 + 18 T_1^2 T_2^2 - 9 T_1^3 T_2^2 + 8 T_1 T_2^3 - 22 T_1^2 T_2^3 + 9 T_1^3 T_2^3 \right) \\
& p_{3,j}^2 x_{3,i}^2 + \frac{(-4 + 9 T_1) p_{3,j} x_{3,j}}{T_1} - \\
& \left( (-4 + 3 T_1 - T_1^2 + 12 T_2 - 17 T_1 T_2 + 12 T_1^2 T_2 - 4 T_1 T_2^2 + 2 T_1^2 T_2^2 - 9 T_1^3 T_2^2 - 4 T_1^2 T_2^3 + 9 T_1^3 T_2^3) \right. \\
& \quad \left. p_{1,i} p_{3,j} x_{1,i} x_{3,j} \right) / ((-1 + T_1) (-1 + 2 T_2) (-1 + T_1 T_2)) - \\
& \frac{(2 - 4 T_1 + T_1^2) p_{1,j} p_{3,j} x_{1,i} x_{3,j}}{-1 + T_1 T_2} + \frac{(-1 - T_2 + T_1 T_2) p_{2,i} p_{3,j} x_{2,i} x_{3,j}}{(-1 + T_2) (-1 + T_1 T_2)} + \\
& \left( (-1 + T_2) (1 - T_1 - 2 T_2 + T_1^2 T_2 - 8 T_2^2 + 26 T_1 T_2^2 - 11 T_1^2 T_2^2 + 8 T_1 T_2^3 - 22 T_1^2 T_2^3 + 9 T_1^3 T_2^3) \right. \\
& \quad \left. p_{2,j} p_{3,j} x_{2,i} x_{3,j} \right) / ((-1 + T_1) (-1 + 2 T_2) (-1 + T_1 T_2)) + \\
& \frac{(-3 + 2 T_1 - 2 T_2 + 18 T_1 T_2 - 9 T_1^2 T_2 + 8 T_2^2 - 22 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{3,i} p_{3,j} x_{3,i} x_{3,j}}{(-1 + T_1) (-1 + 2 T_2)} - \\
& \frac{1}{2 (-1 + T_1) (-1 + 2 T_2)} (-5 + 4 T_1 + 2 T_2 + 11 T_1 T_2 - 7 T_1^2 T_2 + 8 T_2^2 - \\
& \quad 24 T_1 T_2^2 + 27 T_1^2 T_2^2 - 9 T_1^3 T_2^2 + 8 T_1 T_2^3 - 22 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{3,j}^2 x_{3,i} x_{3,j} \\
r_1[-1, i_-, j_-] := & \\
& \frac{3}{2} + 2 p_{1,i} x_{1,i} - \frac{2 (-2 + T_1^2) p_{1,j} x_{1,i}}{T_1^2} + p_{1,i} p_{1,j} x_{1,i}^2 - \frac{(-1 + T_1) (1 + 2 T_1) p_{1,j}^2 x_{1,i}^2}{2 T_1^2} - \\
& \frac{4 p_{1,j} x_{1,j}}{T_1} + p_{1,i} p_{1,j} x_{1,i} x_{1,j} - \frac{(1 + 3 T_1) p_{1,j}^2 x_{1,i} x_{1,j}}{2 T_1} + 2 p_{2,i} x_{2,i} - 2 p_{2,j} x_{2,i} - \\
& \frac{(-2 + 3 T_1 - 4 T_2 + 16 T_1 T_2 - 9 T_1^2 T_2 + 8 T_2^2 - 22 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{2,i} x_{1,i} x_{2,i}}{T_1 (-1 + 2 T_2)} - \\
& \left( (-1 - T_1 + 8 T_2 - 10 T_1 T_2 + 9 T_1^2 T_2 - 8 T_2^2 + 15 T_1 T_2^2 - 18 T_1^2 T_2^2 - 4 T_1 T_2^3 + 9 T_1^2 T_2^3) p_{1,i} p_{2,j} x_{1,i} x_{2,i} \right) / \\
& \left( (-1 + T_1) T_2 (-1 + 2 T_2) \right) + \frac{1}{T_1 T_2 (-1 + 2 T_2)} \\
& \left( -4 T_1 + 8 T_2 - 14 T_1 T_2 + 18 T_1^2 T_2 - 12 T_2^2 + 35 T_1 T_2^2 - 36 T_1^2 T_2^2 + 8 T_2^3 - 26 T_1 T_2^3 + 18 T_1^2 T_2^3 \right) p_{1,j} \\
& p_{2,j} x_{1,i} x_{2,i} - \frac{(-4 + 3 T_1 + 16 T_1 T_2 - 9 T_1^2 T_2 + 8 T_2^2 - 22 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{2,i} x_{1,j} x_{2,i}}{(-1 + T_1) (-1 + 2 T_2)} + \\
& \frac{(-1 + T_2) (2 - 4 T_1 + 4 T_2 - 13 T_1 T_2 + 9 T_1^2 T_2) p_{1,j} p_{2,j} x_{1,j} x_{2,i}}{(-1 + T_1) T_2} + \frac{(1 + T_2) p_{2,i} p_{2,j} x_{2,i}^2}{T_2} - \\
& \frac{(-1 + T_2) (3 + 2 T_2) p_{2,j}^2 x_{2,i}^2}{2 T_2^2} - 2 p_{1,i} p_{2,j} x_{1,i} x_{2,j} +
\end{aligned}$$

$$\begin{aligned}
& \frac{(2 + T_1 - 8 T_2 + 11 T_1 T_2 - 9 T_1^2 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{2,j} x_{1,i} x_{2,j}}{T_1 (-1 + 2 T_2)} + p_{2,i} p_{2,j} x_{2,i} x_{2,j} - \\
& \frac{3 (1 + T_2) p_{2,j}^2 x_{2,i} x_{2,j}}{2 T_2} - \frac{(T_1 + 4 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{2,i} x_{3,i}}{2 T_1 (-1 + 2 T_2)} - \frac{p_{1,i} p_{2,j} x_{3,i}}{2 T_2} + \\
& \frac{(-T_1 + 3 T_1 T_2 + 4 T_2^2 - 11 T_1 T_2^2 - 4 T_1 T_2^3 + 9 T_1^2 T_2^3) p_{1,j} p_{2,j} x_{3,i}}{2 T_1 T_2 (-1 + 2 T_2)} + 2 p_{3,i} x_{3,i} - \frac{1}{T_1^2 T_2 (-1 + 2 T_2)} \\
& (-4 + 9 T_1 - T_1^2 + 8 T_2 - 18 T_1 T_2 + T_1^2 T_2 - 4 T_1 T_2^2 + 15 T_1^2 T_2^2 - 9 T_1^3 T_2^2 - 4 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{3,j} x_{3,i} - \\
& \frac{(4 - 4 T_1 + T_1^2 + 4 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{3,i} x_{1,i} x_{3,i}}{T_1 (-1 + T_1 T_2)} + \\
& \left( (-2 T_1 + 4 T_2 - 7 T_1 T_2 + 10 T_1^2 T_2 - 4 T_1 T_2^2 + 2 T_1^2 T_2^2 - 9 T_1^3 T_2^2 - 4 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{1,i} p_{3,j} x_{1,i} x_{3,i} \right) / \\
& \frac{((-1 + T_1) T_1 T_2 (-1 + 2 T_2)) - 1}{T_1^2 T_2 (-1 + 2 T_2)} \\
& (2 - 6 T_1 + T_1^2 + T_1 T_2 + 8 T_1^2 T_2 - 4 T_1 T_2^2 + 2 T_1^2 T_2^2 - 9 T_1^3 T_2^2 - 4 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{1,j} p_{3,j} x_{1,i} x_{3,i} - \\
& \frac{(6 - 4 T_1 + T_1^2 + 4 T_2 - 13 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{3,i} x_{1,j} x_{3,i}}{(-1 + T_1) (-1 + T_1 T_2)} - \frac{p_{1,i} p_{3,j} x_{1,j} x_{3,i}}{T_2} + \\
& \left( (-4 + 6 T_1 - 2 T_1^2 + 8 T_2 - 11 T_1 T_2 + 4 T_1^2 T_2 + 4 T_2^2 - 11 T_1 T_2^2 - 4 T_1 T_2^3 + 9 T_1^2 T_2^3) p_{1,j} p_{3,j} x_{1,j} x_{3,i} \right) / \\
& \left( (-1 + T_1) T_1 T_2 (-1 + 2 T_2) \right) + \left( (-2 + T_1 - 3 T_2 + 22 T_1 T_2 - 10 T_1^2 T_2 + 14 T_2^2 - 42 T_1 T_2^2 - \right. \\
& \quad \left. T_1^2 T_2^2 + 9 T_1^3 T_2^2 - 8 T_2^3 + 10 T_1 T_2^3 + 33 T_1^2 T_2^3 - 18 T_1^3 T_2^3 + 8 T_1 T_2^4 - 22 T_1^2 T_2^4 + 9 T_1^3 T_2^4) \right. \\
& \quad \left. p_{2,j} p_{3,i} x_{2,i} x_{3,i} \right) / \left( (-1 + T_1) T_2 (-1 + 2 T_2) (-1 + T_1 T_2) \right) + \\
& \left( (-2 + T_1) (T_1 + 3 T_2 - 12 T_1 T_2 - 6 T_2^2 + 17 T_1 T_2^2 + 9 T_1^2 T_2^2 + 4 T_2^3 - 3 T_1 T_2^3 - 18 T_1^2 T_2^3 - 4 T_1 T_2^4 + 9 T_1^2 T_2^4) \right. \\
& \quad \left. p_{2,i} p_{3,j} x_{2,i} x_{3,i} \right) / \left( (-1 + T_1) T_1 (-1 + T_2) T_2 (-1 + 2 T_2) \right) - \\
& \frac{1}{(-1 + T_1) T_1 T_2^2} (1 + T_1 - T_1^2 + 5 T_2 - 24 T_1 T_2 + 11 T_1^2 T_2 - 8 T_2^2 + 18 T_1 T_2^2 + 11 T_1^2 T_2^2 - \\
& \quad 9 T_1^3 T_2^2 + 8 T_1 T_2^3 - 22 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{2,j} p_{3,j} x_{2,i} x_{3,i} + \\
& \left( (-3 + 2 T_1 - T_2 + 21 T_1 T_2 - 11 T_1^2 T_2 + 14 T_2^2 - 44 T_1 T_2^2 + T_1^2 T_2^2 + 9 T_1^3 T_2^2 - 8 T_2^3 + 10 T_1 T_2^3 + \right. \\
& \quad \left. 33 T_1^2 T_2^3 - 18 T_1^3 T_2^3 + 8 T_1 T_2^4 - 22 T_1^2 T_2^4 + 9 T_1^3 T_2^4) p_{2,j} p_{3,i} x_{2,j} x_{3,i} \right) / \left( (-1 + T_1) (-1 + T_2) \right. \\
& \quad \left. (-1 + 2 T_2) (-1 + T_1 T_2) \right) - \frac{(T_1 + 4 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{2,i} p_{3,j} x_{2,j} x_{3,i}}{(-1 + T_1) T_1 (-1 + 2 T_2)} - \\
& \frac{1}{(-1 + T_1) T_1 T_2 (-1 + 2 T_2)} (1 + 6 T_2 - 25 T_1 T_2 + 10 T_1^2 T_2 - 12 T_2^2 + 29 T_1 T_2^2 + \\
& \quad 11 T_1^2 T_2^2 - 9 T_1^3 T_2^2 + 12 T_1 T_2^3 - 31 T_1^2 T_2^3 + 9 T_1^3 T_2^3) p_{2,j} p_{3,j} x_{2,j} x_{3,i} - \\
& \left( (2 - T_1 + 4 T_2 - 23 T_1 T_2 + 11 T_1^2 T_2 - 8 T_2^2 + 20 T_1 T_2^2 + 9 T_1^2 T_2^2 - 9 T_1^3 T_2^2 + 8 T_1 T_2^3 - 22 T_1^2 T_2^3 + 9 T_1^3 T_2^3) \right. \\
& \quad \left. p_{3,i} p_{3,j} x_{3,i}^2 \right) / \left( (-1 + T_1) T_1 T_2 (-1 + 2 T_2) \right) + \\
& \left( (-1 + T_1 T_2) (1 + 6 T_2 - 28 T_1 T_2 + 13 T_1^2 T_2 - 8 T_2^2 + 18 T_1 T_2^2 + 27 T_1^2 T_2^2 - 18 T_1^3 T_2^2 + 16 T_1 T_2^3 - \right. \\
& \quad \left. 44 T_1^2 T_2^3 + 18 T_1^3 T_2^3) p_{3,j}^2 x_{3,i}^2 \right) / \left( 2 (-1 + T_1) T_1^2 T_2^2 (-1 + 2 T_2) \right) - \frac{(-4 + 9 T_1) p_{3,j} x_{3,j}}{T_1} + \\
& \left( (-4 + 3 T_1 - T_1^2 + 12 T_2 - 17 T_1 T_2 + 12 T_1^2 T_2 - 4 T_1 T_2^2 + 2 T_1^2 T_2^2 - 9 T_1^3 T_2^2 - 4 T_1^2 T_2^3 + 9 T_1^3 T_2^3) \right. \\
& \quad \left. p_{1,i} p_{3,j} x_{1,i} x_{3,j} \right) / \left( (-1 + T_1) (-1 + 2 T_2) (-1 + T_1 T_2) \right) -
\end{aligned}$$

$$\frac{(2 + T_1 - 8 T_2 + 11 T_1 T_2 - 9 T_1^2 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{1,j} p_{3,j} x_{1,i} x_{3,j}}{T_1 (-1 + 2 T_2)} -$$

$$\frac{(-1 - T_2 + T_1 T_2) p_{2,i} p_{3,j} x_{2,i} x_{3,j}}{(-1 + T_2) (-1 + T_1 T_2)} -$$

$$\frac{(-2 + T_1) (1 + 2 T_2 - 9 T_1 T_2 - 4 T_2^2 + 9 T_1 T_2^2) p_{2,j} p_{3,j} x_{2,i} x_{3,j}}{(-1 + T_1) (-1 + 2 T_2)} -$$

$$\frac{(-3 + 2 T_1 - 2 T_2 + 18 T_1 T_2 - 9 T_1^2 T_2 + 8 T_2^2 - 22 T_1 T_2^2 + 9 T_1^2 T_2^2) p_{3,i} p_{3,j} x_{3,i} x_{3,j}}{(-1 + T_1) (-1 + 2 T_2)} +$$

$$\frac{((1 + 6 T_2 - 31 T_1 T_2 + 15 T_1^2 T_2 - 8 T_2^2 + 16 T_1 T_2^2 + 45 T_1^2 T_2^2 - 27 T_1^3 T_2^2 + 24 T_1 T_2^3 - 66 T_1^2 T_2^3 + 27 T_1^3 T_2^3) p_{3,j}^2 x_{3,i} x_{3,j})}{(2 (-1 + T_1) T_1 T_2 (-1 + 2 T_2))}$$

```
In[*]:= g2px[ε_] := Module[{λ}, Expand[ε /. g_{α,i,j} => λ p_{α,i} x_{α,j}] /. λ^{k-} => 1/k!]
```

```
In[*]:= {p*, x*, π*, ξ*} = {π, ξ, p, x}; (u_{i-})* := (u*)_i;
```

```
In[*]:= Zip[_][ε_] := ε;
Zip[{ε_, εs___}][ε_] := (Collect[ε // Zip[{εs}], ε] /. f_. ε^{d-} => (D[f, {ε*, d}])) /. ε* -> 0
```

```
In[*]:= px2g[ε_] := Module[{ps, xs, Q},
  ps = Union[Cases[ε, p_, ∞]];
  xs = Union[Cases[ε, x_, ∞]];
  Q = Sum[p0* x0* g_{p0[[2]], x0[[2]], p0[[3]], x0[[3]]}, {p0, ps}, {x0, xs}];
  Expand[Zip[ps][ε e^Q] /. g_{α,β,i,j} => If[α == β, g_{α,i,j}, 0]]
]
```

```
In[*]:= Coefficient[r_1[1, i, j] /. t: (x | p) -> λ t, λ^3] /. x_{3,α} p_{1,β} p_{2,γ} => y_{α,β,γ}
```

```
Out[*]=
```

$$\frac{1}{2} y_{i,i,j} + \frac{(T_1 + 4 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) y_{i,j,i}}{2 (-1 + 2 T_2)} -$$

$$\frac{(-1 + T_1 + 6 T_2 - 11 T_1 T_2 - 4 T_1 T_2^2 + 9 T_1^2 T_2^2) y_{i,j,j}}{2 (-1 + 2 T_2)}$$

```
In[*]:= R_1[1, i_, j_] := Evaluate[px2g[r_1[1, i, j]] +
  (Coefficient[r_1[1, i, j] /. t: (x | p) -> λ t, λ^3] /. x_{3,α} p_{1,β} p_{2,γ} => y_{α,β,γ})]
R_1[-1, i_, j_] := Evaluate[px2g[r_1[-1, i, j]] +
  (Coefficient[r_1[-1, i, j] /. t: (x | p) -> λ t, λ^3] /. x_{3,α} p_{1,β} p_{2,γ} => y_{α,β,γ})]
```

```
In[*]:=
 $\Theta[1, i_, j_, \alpha_, \beta_, \gamma_] :=$ 
  Evaluate[r $\Theta[1, i, j]$  /. {p $_{3,j} \mapsto g_{3,\alpha,j}$ , x $_{1,i} \mapsto g_{1,i,\beta}$ , x $_{2,i} \mapsto g_{2,i,\gamma}$ }] ;
  (* The  $\Theta$  graph with light (pxx) vertex at (1,i,j) and
  unspecified heavy (xpp) vertex *)
 $\Theta[-1, i_, j_, \alpha_, \beta_, \gamma_] :=$ 
  Evaluate[r $\Theta[-1, i, j]$  /. {p $_{3,j} \mapsto g_{3,\alpha,j}$ , x $_{1,i} \mapsto g_{1,i,\beta}$ , x $_{2,i} \mapsto g_{2,i,\gamma}$ }] ;
  (* The  $\Theta$  graph with light (pxx) vertex at (-1,i,j)
  and unspecified heavy (xpp) vertex *)
 $\Theta[1, 5, 8, 21, 22, 23]$ 
```

```
Out[*]=
2 (-T $_1$  + T $_2$  + T $_1$  T $_2$ ) g $_{1,5,22}$  g $_{2,5,23}$  g $_{3,21,8}$  - 2 (-1 + T $_2$ ) g $_{1,8,22}$  g $_{2,5,23}$  g $_{3,21,8}$  - 2 g $_{1,5,22}$  g $_{2,8,23}$  g $_{3,21,8}$ 
```

```
In[*]:=
T $_3 = T_1 T_2$ ;
CF[ $\mathcal{E}_-$ ] := Factor@Together[ $\mathcal{E}$ ];
 $\lambda[K_-]$  := Module[{Cs,  $\varphi$ , n, A, s, i, j, k,  $\Delta$ , G, gEval, Y, yEval, c,  $\lambda 1$ },
  {Cs,  $\varphi$ } = Rot[K]; n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  Cases[Cs, {s_, i_, j_}  $\mapsto$  (A[[{i, j}, {i + 1, j + 1}]] +=  $\begin{pmatrix} -T^s & T^s - 1 \\ \theta & -1 \end{pmatrix}$ )]];
 $\Delta = T^{(-Total[\varphi] - Total[Cs[[All, 1]])/2}$  Det[A];
  G = Inverse[A];
  gEval[ $\mathcal{E}_-$ ] := CF[ $\mathcal{E}$  /.
    {g $_{1,\alpha,\beta} \mapsto$  (G[[ $\alpha, \beta$ ]] /. T  $\rightarrow$  T $_1$ ),
    g $_{2,\alpha,\beta} \mapsto$  (G[[ $\alpha, \beta$ ]] /. T  $\rightarrow$  T $_2$ ), g $_{3,\alpha,\beta} \mapsto$  (G[[ $\alpha, \beta$ ]] /. T  $\rightarrow$  T $_3$ )}];
  Y[ $\alpha_, \beta_, \gamma_$ ] :=
  Y[ $\alpha, \beta, \gamma$ ] = Sum[{s, i, j} = c; (* The expectation value of x $_{3,\alpha} p_{1,\beta} p_{2,\gamma}$  *)
     $\Theta[s, i, j, \alpha, \beta, \gamma]$ ,
    {c, Cs}];
  yEval[ $\mathcal{E}_-$ ] := CF[ $\mathcal{E}$  /. y $_{\alpha,\beta,\gamma} \mapsto$  Y[ $\alpha, \beta, \gamma$ ]];
   $\lambda 1 = \sum_{k=1}^n R_1 @@ Cs[[k]] - \sum_{k=1}^{2^n} \varphi[[k]] (g_{1,k,k} + g_{2,k,k} + g_{3,k,k} - 3/2)$ ;
  { $\Delta$ , ( $\Delta^2$  /. T  $\rightarrow$  T $_1$ ) ( $\Delta^2$  /. T  $\rightarrow$  T $_2$ ) ( $\Delta^2$  /. T  $\rightarrow$  T $_3$ )  $\lambda 1$ } // yEval // gEval
];
```

In[\*]:= **Timing**[ $\lambda$ [**Knot**[3, 1]]]

 **KnotTheory**: Loading precomputed data in PD4Knots`.

Out[\*]=

$$\left\{ 1.15625, \right. \\ \left. \left\{ \frac{1 - T + T^2}{T}, \frac{1}{T_1^6 T_2^6 (-1 + 2 T_2)} \left( -2 T_1^2 + 8 T_1^3 - 15 T_1^4 + 15 T_1^5 - 9 T_1^6 + 2 T_1^7 + 13 T_1^2 T_2 - 44 T_1^3 T_2 + 70 T_1^4 T_2 - \right. \right. \right. \\ 50 T_1^5 T_2 + 13 T_1^6 T_2 + 13 T_1^7 T_2 - 6 T_1^8 T_2 + 7 T_1 T_2^2 - 70 T_1^2 T_2^2 + 171 T_1^3 T_2^2 - 214 T_1^4 T_2^2 + 90 T_1^5 T_2^2 + \\ 18 T_1^6 T_2^2 - 58 T_1^7 T_2^2 - 2 T_1^8 T_2^2 + 9 T_1^9 T_2^2 - 30 T_1 T_2^3 + 175 T_1^2 T_2^3 - 285 T_1^3 T_2^3 + 177 T_1^4 T_2^3 + 222 T_1^5 T_2^3 - \\ 268 T_1^6 T_2^3 + 155 T_1^7 T_2^3 + 86 T_1^8 T_2^3 - 24 T_1^9 T_2^3 - 7 T_1^{10} T_2^3 + 4 T_2^4 + 48 T_1 T_2^4 - 214 T_1^2 T_2^4 + 97 T_1^3 T_2^4 + \\ 349 T_1^4 T_2^4 - 888 T_1^5 T_2^4 + 304 T_1^6 T_2^4 + 107 T_1^7 T_2^4 - 434 T_1^8 T_2^4 - 15 T_1^9 T_2^4 + 28 T_1^{10} T_2^4 + 3 T_1^{11} T_2^4 - 16 T_2^5 - \\ 24 T_1 T_2^5 + 77 T_1^2 T_2^5 + 366 T_1^3 T_2^5 - 768 T_1^4 T_2^5 + 707 T_1^5 T_2^5 + 870 T_1^6 T_2^5 - 871 T_1^7 T_2^5 + 690 T_1^8 T_2^5 + \\ 385 T_1^9 T_2^5 - 30 T_1^{10} T_2^5 - 17 T_1^{11} T_2^5 + 16 T_2^6 + 49 T_1 T_2^6 - 50 T_1^2 T_2^6 - 438 T_1^3 T_2^6 + 372 T_1^4 T_2^6 + 201 T_1^5 T_2^6 - \\ 1688 T_1^6 T_2^6 + 256 T_1^7 T_2^6 + 185 T_1^8 T_2^6 - 1089 T_1^9 T_2^6 - 188 T_1^{10} T_2^6 + 43 T_1^{11} T_2^6 - 12 T_2^7 - 31 T_1 T_2^7 - 99 T_1^2 T_2^7 + \\ 489 T_1^3 T_2^7 + 105 T_1^4 T_2^7 - 837 T_1^5 T_2^7 + 1520 T_1^6 T_2^7 + 877 T_1^7 T_2^7 - 661 T_1^8 T_2^7 + 888 T_1^9 T_2^7 + 836 T_1^{10} T_2^7 - \\ 24 T_1^{11} T_2^7 + 48 T_1 T_2^8 + 18 T_1^2 T_2^8 - 25 T_1^3 T_2^8 - 689 T_1^4 T_2^8 + 628 T_1^5 T_2^8 + 81 T_1^6 T_2^8 - 2316 T_1^7 T_2^8 + 798 T_1^8 T_2^8 - \\ 251 T_1^9 T_2^8 - 1191 T_1^{10} T_2^8 - 181 T_1^{11} T_2^8 - 100 T_1^2 T_2^9 + 81 T_1^3 T_2^9 + 204 T_1^4 T_2^9 + 293 T_1^5 T_2^9 - 821 T_1^6 T_2^9 + \\ 1273 T_1^7 T_2^9 + 874 T_1^8 T_2^9 - 975 T_1^9 T_2^9 + 1144 T_1^{10} T_2^9 + 388 T_1^{11} T_2^9 + 18 T_1^{12} T_2^9 + 128 T_1^3 T_2^{10} - 212 T_1^4 T_2^{10} - \\ 228 T_1^5 T_2^{10} + 422 T_1^6 T_2^{10} - 172 T_1^7 T_2^{10} - 1039 T_1^8 T_2^{10} + 511 T_1^9 T_2^{10} - 191 T_1^{10} T_2^{10} - 571 T_1^{11} T_2^{10} - \\ 18 T_1^{12} T_2^{10} - 104 T_1^4 T_2^{11} + 258 T_1^5 T_2^{11} - 479 T_1^6 T_2^{11} + 815 T_1^7 T_2^{11} - 134 T_1^8 T_2^{11} - 214 T_1^9 T_2^{11} + 394 T_1^{10} T_2^{11} + \\ 27 T_1^{11} T_2^{11} + 52 T_1^5 T_2^{12} - 175 T_1^6 T_2^{12} + 164 T_1^7 T_2^{12} + 52 T_1^8 T_2^{12} - 397 T_1^9 T_2^{12} + 377 T_1^{10} T_2^{12} - 213 T_1^{11} T_2^{12} - \\ \left. \left. \left. 9 T_1^{12} T_2^{12} - 12 T_1^6 T_2^{13} + 51 T_1^7 T_2^{13} - 90 T_1^8 T_2^{13} + 101 T_1^9 T_2^{13} - 53 T_1^{10} T_2^{13} + 14 T_1^{11} T_2^{13} + 9 T_1^{12} T_2^{13} \right) \right\} \right\}$$

In[\*]:= **Timing**[ $\lambda$ [**Knot**[4, 1]]]

Out[\*]=

$$\left\{ 2.29688, \right. \\ \left. \left\{ -\frac{1 - 3 T + T^2}{T}, \frac{1}{T_1^4 T_2^4 (-1 + 2 T_2)} \left( (1 - 3 T_1 + T_1^2) (1 - 3 T_2 + T_2^2) (1 - 3 T_1 T_2 + T_1^2 T_2^2) (12 - 18 T_1 - T_1^2 + \right. \right. \right. \\ 12 T_1^3 - 5 T_1^4 + T_1^5 - 79 T_2 + 133 T_1 T_2 - 6 T_1^2 T_2 - 72 T_1^3 T_2 + 13 T_1^4 T_2 - 3 T_1^5 T_2 + 151 T_2^2 - 203 T_1 T_2^2 - \\ 124 T_1^2 T_2^2 + 178 T_1^3 T_2^2 + 27 T_1^4 T_2^2 + 50 T_1^5 T_2^2 - 5 T_1^6 T_2^2 - 4 T_1^7 T_2^2 - 138 T_2^3 + 217 T_1 T_2^3 + 51 T_1^2 T_2^3 - \\ 62 T_1^3 T_2^3 - 130 T_1^4 T_2^3 - 54 T_1^5 T_2^3 - 206 T_1^6 T_2^3 + 78 T_1^7 T_2^3 + T_1^8 T_2^3 + 64 T_2^4 - 109 T_1 T_2^4 - 161 T_1^2 T_2^4 + \\ 309 T_1^3 T_2^4 + 128 T_1^4 T_2^4 - 282 T_1^5 T_2^4 + 805 T_1^6 T_2^4 - 125 T_1^7 T_2^4 - 52 T_1^8 T_2^4 - 20 T_2^5 + 22 T_1 T_2^5 + \\ 264 T_1^2 T_2^5 - 578 T_1^3 T_2^5 + 128 T_1^4 T_2^5 + 232 T_1^5 T_2^5 - 759 T_1^6 T_2^5 - 341 T_1^7 T_2^5 + 203 T_1^8 T_2^5 + 9 T_1^9 T_2^5 + \\ 4 T_2^6 + 13 T_1 T_2^6 - 194 T_1^2 T_2^6 + 322 T_1^3 T_2^6 + 163 T_1^4 T_2^6 - 483 T_1^5 T_2^6 + 366 T_1^6 T_2^6 + 755 T_1^7 T_2^6 - \\ 208 T_1^8 T_2^6 - 45 T_1^9 T_2^6 - 8 T_1 T_2^7 + 44 T_1^2 T_2^7 + 23 T_1^3 T_2^7 - 315 T_1^4 T_2^7 + 325 T_1^5 T_2^7 + 102 T_1^6 T_2^7 - \\ 552 T_1^7 T_2^7 + 6 T_1^8 T_2^7 + 72 T_1^9 T_2^7 + 4 T_1^2 T_2^8 - 37 T_1^3 T_2^8 + 82 T_1^4 T_2^8 - 10 T_1^5 T_2^8 - 142 T_1^6 T_2^8 + \\ \left. \left. \left. 131 T_1^7 T_2^8 + 81 T_1^8 T_2^8 - 45 T_1^9 T_2^8 + 4 T_1^4 T_2^9 - 21 T_1^5 T_2^9 + 35 T_1^6 T_2^9 - 10 T_1^7 T_2^9 - 22 T_1^8 T_2^9 + 9 T_1^9 T_2^9 \right) \right\} \right\}$$

## Invariance Proof

In[\*]:=  $\delta_{i,j} := \text{If}[i == j, 1, 0];$

```
In[*]:= gRules_{s_,i_,j_} := {
  g_{v,i,\beta} \Rightarrow \delta_{i,\beta} + T_v^s g_{v,i^+,\beta} + (1 - T_v^s) g_{v,j^+,\beta}, g_{v,j,\beta} \Rightarrow \delta_{j,\beta} + g_{v,j^+,\beta},
  g_{v,\alpha,i} \Rightarrow T_v^{-s} (g_{v,\alpha,i^+} - \delta_{\alpha,i^+}), g_{v,\alpha,j} \Rightarrow g_{v,\alpha,j^+} - (1 - T_v^s) g_{v,\alpha,i} - \delta_{\alpha,j^+}
}
```

## Invariance of $y_{\alpha\beta\gamma}$ under remote R2s

```
In[*]:= Clear[i, j];
Cs = {{1, i, j}, {-1, i^+, j^+}}
Z = Module[{s, i, j}, Sum[{s, i, j} = c;
  \theta[s, i, j, \alpha, \beta, \gamma], {c, Cs}]]
```

```
Out[*]=
{{1, i, j}, {-1, i^+, j^+}}
```

```
Out[*]=

$$\frac{2(-T_1 + T_2 + T_1 T_2) g_{1,i,\beta} g_{2,i,\gamma} g_{3,\alpha,j} - 2(-1 + T_2) g_{1,j,\beta} g_{2,i,\gamma} g_{3,\alpha,j} - 2 g_{1,i,\beta} g_{2,j,\gamma} g_{3,\alpha,j} - 2 g_{1,i^+,\beta} g_{2,i^+,\gamma} g_{3,\alpha,j^+}}{T_1} + \frac{2(-1 + T_2) g_{1,j^+,\beta} g_{2,i^+,\gamma} g_{3,\alpha,j^+}}{T_2} + \frac{2 g_{1,i^+,\beta} g_{2,j^+,\gamma} g_{3,\alpha,j^+}}{T_1}$$

```

In[\*]:= Expand[Z /. gRules<sub>1,i,j</sub> ∪ gRules<sub>-1,i\*,j\*</sub> /. \_If → 0]

Out[\*]=

$$\begin{aligned}
& \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1} - \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1^2 T_2} + 2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}} - \\
& \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1} - 2 T_1 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}} - \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2^2} + \\
& \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1^2 T_2} - \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1 T_2} + \\
& \frac{2 T_1 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2} - \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1} + \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1^2 T_2} + \\
& \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1} + 4 T_1 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2^2} - \\
& \frac{4 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2} - \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1^2 T_2} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_1 T_2} - \\
& \frac{2 T_1 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}}}{T_2} - 2 T_1 T_2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(i^+)^{\alpha}} - \\
& 2 T_1 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} - \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1^2 T_2} + 2 T_2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} + \\
& 2 T_1 T_2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} + 2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} - \\
& \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_2^2} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_2} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1^2 T_2} - \\
& \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1 T_2} - 2 T_2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(i^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} - 2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} + \\
& \frac{2 \mathfrak{g}_{1,(i^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1^2 T_2} + 2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_2^2} - \\
& \frac{4 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_2} - \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1^2 T_2} + \frac{2 \mathfrak{g}_{1,(j^+)^{\beta}} \mathfrak{g}_{2,(j^+)^{\gamma}} \mathfrak{g}_{3,\alpha,(j^+)^{\alpha}}}{T_1 T_2}
\end{aligned}$$