

Pensieve header: Hour 30: Perturbing the Heisenberg-algebra knot invariant (2).

Recall,

$$m_k^{ij} = e^{(\xi_i + \xi_j) x_k + (\pi_i + \pi_j) p_k - \xi_i \pi_j},$$

$$R_\epsilon = e^{(T-1)(p_i - p_j) x_j + R^i}; \quad R^i = \sum_{k=1}^k \epsilon^k R^{(k)},$$

$${}_A \mathcal{L}_B // {}_B \mathcal{M}_C = e^{\sum_{i \in B} \partial_{z_i} \partial_{\xi_i} (\mathcal{L} \cdot \mathcal{M})},$$

$$\langle F : \mathcal{E} \rangle_B = e^{\frac{1}{2} \sum_{u,v \in B} F_{uv} \partial^u \partial^v} \mathcal{E} \Big|_{z_B=0} \quad \text{and} \quad [F : \mathcal{E}]_B = e^{\frac{1}{2} \sum_{u,v \in B} F_{uv} \partial^u \partial^v} \mathcal{E}$$

(Note, the two are equi-computable: clearly if we know how to compute $[F : \mathcal{E}]$ we also know how to compute $\langle F : \mathcal{E} \rangle$, and also $[F : \mathcal{E}] \Big|_{z_B \rightarrow \bar{z}_B} = \langle F : \mathcal{E} \Big|_{z_B \rightarrow z_B + \bar{z}_B} \rangle$).

$Z_\lambda := \log[\lambda F : e^F]$ satisfies $Z_0 = E$ and the “synthesis equation”,

$$\partial_\lambda Z_\lambda = \frac{1}{2} F_{uv} (\partial_u \partial_v Z_\lambda + (\partial_u Z_\lambda) (\partial_v Z_\lambda)).$$

Lemma 1. $\left\langle F : \mathcal{E} e^{\frac{1}{2} \sum_{i,j \in B} G_{ij} z_i z_j} \right\rangle_B = \det(I - GF)^{-1/2} \langle F(I - GF)^{-1} : \mathcal{E} \rangle_B$.

Lemma 2. $\langle F : \mathcal{E} e^{\sum_{i \in B} y_i z_i} \rangle_B = e^{\frac{1}{2} \sum_{i,j \in B} F_{ij} z_i z_j} \langle F : \mathcal{E} \Big|_{z_B \rightarrow z_B + Fy_B} \rangle_B$.

To solve the synthesis equation in general, we write $Z_\lambda = \sum Z[m] \lambda^m$ and then solve iteratively $Z[0] = Z_0 = E$ and

$$(m + 1) Z[m + 1] = \frac{1}{2} F_{uv} (\partial_u \partial_v Z[m] + \sum_j (\partial_u Z[j]) \cdot (\partial_v Z[m - j])).$$

Definition. A power series f in an auxiliary variable ϵ and in the z_i 's, including $i \notin B$, is called *docile* if every monomial μ in it satisfies $\deg_z \mu \leq 2 \deg_\epsilon \mu + 2$; we will short that to $\deg_z f \leq 2 \deg_\epsilon f + 2$.

Claim 1. The synthesis equation preserves docility: if E is docile then so is Z_λ , and in particular, so is $\log \langle F : e^F \rangle$.

(And so it makes sense to restrict our attention to docile perturbations!)

Claim 2. Restricting attention to $\{z_i : i \in B\}$, if $\deg_{z_B} E \leq 4 \deg_\epsilon E$ then $\deg_{z_B} Z_\lambda \leq 4 \deg_\epsilon Z_\lambda - 2 \deg_\lambda Z_\lambda$ and thus $\deg_\lambda Z_\lambda \leq 2 \deg_\epsilon Z_\lambda$.

Claim 2 implies that if $E \Big|_{\epsilon=0}$ is independent of z_B and if we only care about Z_λ up to ϵ^k , then the iterative process for finding Z_λ terminates at $Z[2k]$.

Conclusion. We can compute efficiently (in polynomial time!) if all of our generating functions are of the form ωe^{Q+P} , where ω is a scalar, Q is an ϵ -free quadratic, and $P = \sum_{k=1}^k P^{(k)} \epsilon^k$, where $\deg P^{(k)} \leq 2k + 2$.

On to the implementation...

$E[\omega, Q, P_eSeries]$ represents ωe^{Q+P} , where ω is a scalar, Q is an ϵ -free quadratic, and $P = \sum_{k=0}^k P[[k]] \epsilon^k$ is a docile perturbation (it is ill-advised to include ω in P because then it will have log terms, so always, $P[[0]] = 0$).

Initialization and minor utilities

```
(Alt) In[ ]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Classes\\21-1350-KnotTheory"];
Once[<< "Common.m"];
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.
Read more at <http://katlas.org/wiki/KnotTheory>.

```
(Alt) In[ ]:= $k=1;
```

```
(Alt) In[ ]:= CCF[ $\mathcal{E}$ _] := ExpandDenominator@ExpandNumerator@Together[ $\mathcal{E}$ ];
```

```
(Alt) In[ ]:= CCF[ $\frac{1}{T-1} + \frac{1}{T-2}$ ]
```

```
(Alt) Out[ ]:=  $\frac{-3+2T}{2-3T+T^2}$ 
```

```
(Alt) In[ ]:= ComposeList[{{Together, ExpandNumerator, ExpandDenominator},  $\frac{1}{T-1} + \frac{1}{T-2}$ }]
```

```
(Alt) Out[ ]:=  $\left\{ \frac{1}{-2+T} + \frac{1}{-1+T}, \frac{-3+2T}{(-2+T) \times (-1+T)}, \frac{-3+2T}{(-2+T) \times (-1+T)}, \frac{-3+2T}{2-3T+T^2} \right\}$ 
```

```
(Alt) In[ ]:= CF[ $\mathcal{E}$ _List] := CF /@  $\mathcal{E}$ ;
CF[ $\mathcal{E}$ _eSeries] := CF /@  $\mathcal{E}$ ;
CF[ $\mathcal{E}$ _] := Module[
  {vs = Cases[ $\mathcal{E}$ , (p | x |  $\pi$  |  $\xi$ )_,  $\infty$ ]  $\cup$  {p | x |  $\pi$  |  $\xi$ }},
  Total[CoefficientRules[Expand[ $\mathcal{E}$ ], vs] /. (ps_ -> c_) -> CCF[c] (Times @@ vsps)];
CF[ $\mathcal{E}$ _E] := CF /@  $\mathcal{E}$ ;
CF[ $\mathbb{E}_{sp\_}$ [ $\mathcal{ES}$ \_\_\_\_]] := CF /@  $\mathbb{E}_{sp}$ [ $\mathcal{ES}$ ];
```

```
(Alt) In[ ]:= CF[(T x1 + (T - 1) x2) ( $\frac{p_1}{T-2} + p_2$ )]
```

```
(Alt) Out[ ]:=  $\frac{T p_1 x_1}{-2+T} + T p_2 x_1 + \frac{(-1+T) p_1 x_2}{-2+T} + (-1+T) p_2 x_2$ 
```

```
(Alt) In[ ]:=
eSeries /: S1_eSeries ≡ S2_eSeries :=
  Length[S1] == Length[S2] ∧ Inner[CF[#1] == CF[#2] &, S1, S2, And];
eSeries[0] := eSeries@@Table[0, $k + 1];
eSeries /: S1_eSeries + S2_eSeries :=
  eSeries@@Table[S1[[k]] + S2[[k]], {k, Min[Length@S1, Length@S2]};
eSeries /: S1_eSeries * S2_eSeries := eSeries@@
  Table[Sum[S1[[j + 1]] * S2[[k - j + 1]], {j, 0, k}], {k, 0, Min[Length@S1, Length@S2] - 1};
eSeries /: c_ * S_eSeries := (c #) & /@ S;
eSeries /: ∂vs S_eSeries := (s ↦ ∂vs s) /@ S;
```

```
(Alt) In[ ]:= eSeries[0, 2, 7, -1] eSeries[0, 3, 5, 19, 1350]
```

```
(Alt) Out[ ]:= eSeries[0, 0, 6, 31]
```

The Main Program

Variables and their duals:

```
(Alt) In[ ]:=
{p*, x*, π*, ξ*} = {π, ξ, p, x};
(vs_List)* := (v ↦ v*) /@ vs;
(u_i_)* := (u*)i;
```

E operations:

```
(Alt) In[ ]:=
E /: E[ω1_, Q1_, P1_] ≡ E[ω2_, Q2_, P2_] := CF[ω1 == ω2] ∧ CF[Q1 == Q2] ∧ (P1 == P2);
E /: E[ω1_, Q1_, P1_] E[ω2_, Q2_, P2_] := E[ω1 ω2, Q1 + Q2, P1 + P2];
Ed1 → r1[E1S___] ≡ Ed2 → r2[E2S___] ^:= (d1 == d2) ∧ (r1 == r2) ∧ (E[E1S] ≡ E[E2S]);
Ed1 → r1[E1S___] Ed2 → r2[E2S___] ^:= E[(d1|d2) → (r1|r2)] @@ (E[E1S] E[E2S]);
```

Getting rid of the quadratic using lemma 1.

Lemma 1. $\langle F : \mathcal{E} e^{\frac{1}{2} \sum_{i,j \in B} G_{ij} Z_i Z_j} \rangle_B = \langle F(I - GF)^{-1} : \det(I - GF)^{-1/2} \mathcal{E} \rangle_B$.

Lemma 1. $\langle F : \mathcal{E} \rangle_B = \langle F(I - GF)^{-1} : \det(I - GF)^{-1/2} \mathcal{E} e^{-\frac{1}{2} \sum_{i,j \in B} G_{ij} Z_i Z_j} \rangle_B$.

```
(Alt) In[ ]:=
Zip1_{ } = Identity;
Zip1vs @ {F_, E[ω_, Q_, P_]} := Module[{I, F, G, u, v},
  I = IdentityMatrix@Length@vs;
  F = Table[∂u,v F, {u, vs*}, {v, vs*}];
  G = Table[∂u,v Q, {u, vs}, {v, vs}];
  CF /@ {
    vs*.F.Inverse[I - G.F].vs* / 2,
    E[PowerExpand@Factor[ω Det[I - G.F]^{-1/2}], Q - vs.G.vs / 2, P]
  }
]
```

$$(Alt) In[] := \text{Ex1} = \text{CF} / @ \left\langle \frac{2}{2} \xi_1^2, \mathbb{E} \left[19, \frac{1}{2} \{x_1, x_2\} \cdot \begin{pmatrix} -3 & 2 \\ 2 & 13 \end{pmatrix} \cdot \{x_1, x_2\}, \text{eSeries}[\theta, x_1] \right] \right\rangle$$

$$(Alt) Out[] := \left\langle \xi_1^2, \mathbb{E} \left[19, -\frac{3 x_1^2}{2} + 2 x_1 x_2 + \frac{13 x_2^2}{2}, \text{eSeries}[\theta, x_1] \right] \right\rangle$$

$$(Alt) In[] := \text{Ex1} // \text{Zip1}_{\{x_1\}}$$

$$(Alt) Out[] := \left\langle \frac{\xi_1^2}{7}, \mathbb{E} \left[\frac{19}{\sqrt{7}}, 2 x_1 x_2 + \frac{13 x_2^2}{2}, \text{eSeries}[\theta, x_1] \right] \right\rangle$$

Getting rid of linear terms using Lemma 2.

Lemma 2. $\langle F : \mathcal{E} e^{\sum_{i \in B} Y_i Z_i} \rangle_B = \theta^{\frac{1}{2} \sum_{i, j \in B} F_{ij} Z_i Z_j} \langle F : \mathcal{E} |_{Z_B \rightarrow Z_B + F Y_B} \rangle_B$.

```
(Alt) In[ ] :=
Zip2_{ } = Identity;
Zip2_{vs_} @ < \mathcal{F}_-, \mathbb{E}[\omega_-, Q_-, P_-] > := Module[{F, Y, u, v},
  F = Table[\partial_{u,v} \mathcal{F}, {u, vs*}, {v, vs*}];
  Y = Table[\partial_v Q, {v, vs*}];
  CF / @ < \mathcal{F}, \mathbb{E}[\omega, Q - Y.v + Y.F.Y / 2, P /. Thread[vs \to vs + F.Y]] >
]
```

Dealing with Feynman diagrams without ever seeing them, using the synthesis equation and iteration.

Write $Z_\lambda = \sum Z[m] \lambda^m$ and then $Z[0] = Z_0 = E$ and

$$Z[m + 1] = \frac{1}{2(m+1)} F_{uv} (\partial_u \partial_v Z[m] + \sum_j (\partial_u Z[j]) \cdot (\partial_v Z[m - j])),$$

and we only care to compute up to $Z[[2 \$k]]$:

```
(Alt) In[ ] :=
Zip3_{vs_} @ < \mathcal{F}_-, \mathbb{E}[\omega_-, Q_-, P_-] > := Module[{Z, u, v, m, j},
  Z[0] = P;
  For[m = 0, m < 2 $k, ++m,
    Z[m + 1] = CF [
      \frac{1}{2(m+1)}
      Sum[\partial_{u*,v*} \mathcal{F} (\partial_{u,v} Z[m] + Sum[(\partial_u Z[j]) (\partial_v Z[m - j]), {j, 0, m}]), {u, vs}, {v, vs*}]
    ];
  \mathbb{E}[\omega, Q, CF[Sum[Z[m], {m, 0, 2 $k}]] /. Table[v \to \theta, {v, vs}]]]
]
```

$$(Alt) In[] := \text{Block}[\{\$k = 2\}, \left\langle \frac{1}{2} \xi^2, \mathbb{E} \left[1, \theta, \text{eSeries} \left[\theta, \frac{1}{6} x^3, \theta \right] \right] \right\rangle // \text{Zip3}_{\{x\}}$$

$$(Alt) Out[] := \mathbb{E} \left[1, \theta, \text{eSeries} \left[\theta, \theta, \frac{5}{24} \right] \right]$$

$$(Alt) In[*] = \frac{1}{2^3} + \frac{1}{3!2}$$

$$(Alt) Out[*] = \frac{5}{24}$$

$$(Alt) In[*] = \text{Block} \left[\{k = 4\}, \left\langle \frac{1}{2} \zeta^2, \mathbb{E} \left[1, \theta, \epsilon \text{Series} \left[\theta, \frac{1}{6} x^3, \theta, \theta, \theta \right] \right] \right\rangle // \text{Zip3}_{\{x\}} \right]$$

$$(Alt) Out[*] = \mathbb{E} \left[1, \theta, \epsilon \text{Series} \left[\theta, \theta, \frac{5}{24}, \theta, \frac{5}{16} \right] \right]$$

From “Cubic Multigraphs A005967” by Richard J. Mathar, <https://oeis.org/A005967/a005967.pdf>:

CUBIC MULTIGRAPHS A005967

RICHARD J. MATHAR

ABSTRACT. These are illustrations of the undirected connected cubic (3-regular) multigraphs up to 10 vertices as counted in [1, A005967].

1. 2 VERTICES

1.1. 0 multi-edges 2 loops. (1 graphs)



1.2. 1 multi-edges 0 loops. (1 graphs)



Total: 2 graphs, 1 without loops.

2. 4 VERTICES

2.1. 0 multi-edges 0 loops. (1 graphs)



2.2. 0 multi-edges 3 loops. (1 graphs)



2.3. 1 multi-edges 1 loops. (1 graphs)



2.4. 1 multi-edges 2 loops. (1 graphs)



2.5. 2 multi-edges 0 loops. (1 graphs)



Total: 5 graphs, 2 without loops.

Date: November 12, 2018.
 2010 Mathematics Subject Classification. Primary 05C30; Secondary 05C75, 81Q30.
 Key words and phrases. Graph Enumeration, Combinatorics.

$$(Alt) In[*]:= \frac{1}{4!} + \frac{1}{3!2^3} + \frac{1}{2^3} + \frac{1}{2^4} + \frac{1}{2^4}$$

$$(Alt) Out[*]:= \frac{5}{16}$$

$$(Alt) In[*]:= \text{Block} \left[\{ \$k = 8 \}, \left\langle \frac{1}{2} \zeta^2, \mathbb{E} \left[1, 0, \text{eSeries} \left[0, \frac{1}{6} x^3, \text{Sequence} @@ \text{Table} [0, \$k - 1] \right] \right] \right\rangle // \text{Zip3}_{\{x\}} \right]$$

$$(Alt) Out[*]:= \mathbb{E} \left[1, 0, \text{eSeries} \left[0, 0, \frac{5}{24}, 0, \frac{5}{16}, 0, \frac{1105}{1152}, 0, \frac{565}{128} \right] \right]$$

Check out <https://oeis.org/>!

$$(Alt) In[*]:= \text{Module} \left[\{1, m\}, \text{Log} \left[\text{Sum} \left[1 = 3 m / 2; \frac{(3 m)! \epsilon^m}{2^1 1! 6^m m!}, \{m, 0, 30, 2\} \right] + 0[\epsilon]^{31} \right] \right]$$

$$(Alt) Out[*]:= \frac{5 \epsilon^2}{24} + \frac{5 \epsilon^4}{16} + \frac{1105 \epsilon^6}{1152} + \frac{565 \epsilon^8}{128} + \frac{82825 \epsilon^{10}}{3072} + \frac{19675 \epsilon^{12}}{96} + \frac{1282031525 \epsilon^{14}}{688128} + \frac{80727925 \epsilon^{16}}{4096} +$$

$$\frac{1683480621875 \epsilon^{18}}{7077888} + \frac{13209845125 \epsilon^{20}}{4096} + \frac{2239646759308375 \epsilon^{22}}{46137344} + \frac{19739117098375 \epsilon^{24}}{24576} +$$

$$\frac{6320791709083309375 \epsilon^{26}}{436207616} + \frac{32468078556378125 \epsilon^{28}}{114688} + \frac{38362676768845045751875 \epsilon^{30}}{6442450944} + 0[\epsilon]^{31}$$

```
(Alt) In[*]:= Zipvs[ $\mathcal{F}$ ,  $\mathcal{E}$ ] := <math>\mathcal{F},  $\mathcal{E}$ > // Zip1vs // Zip2vs // Zip3vs
```

```
(Alt) In[*]:= Ed1r1[ $\mathcal{E}1S$ ] // Ed2r2[ $\mathcal{E}2S$ ] := Module[{is = r1 ∩ d2, lvs},
  lvs = Flatten@Table[{Xei, Pei}, {i, is}];
  E(d1 ∪ Complement[d2, is]) → (r2 ∪ Complement[r1, is]) @@ (Ziplvs ∪ lvs[lvs*.lvs, Times[
    E[ $\mathcal{E}1S$ ] /. Table[(v : x | p)i → Vei, {i, is}],
    E[ $\mathcal{E}2S$ ] /. Table[(v :  $\xi$  |  $\pi$ )i → Vei, {i, is}]
  ]])
]
```

The Basic Tensors

```
(Alt) In[*]:=  $\eta_{i\_} := \mathbb{E}_{\{i\} \rightarrow \{i\}} [1, 0, \text{eSeries}[0]];$ 
 $m_{i\_ , j\_ \rightarrow k\_} := \mathbb{E}_{\{i, j\} \rightarrow \{k\}} [1, -\xi_i \pi_j + (\pi_i + \pi_j) p_k + (\xi_i + \xi_j) x_k, \text{eSeries}[0]]$ 
```

```
(Alt) In[*]:= AllMonomials[{}, 0] = {1};
AllMonomials[{}, d_Integer] /; d > 0 := {};
AllMonomials[{v_, vs___}, d_Integer] :=
  Join@@Table[vd-k AllMonomials[{vs}, k], {k, 0, d}];
AllMonomials[vs_List, {d_}] := Join@@Table[AllMonomials[vs, k], {k, 0, d}];
```

(Alt) In[*]:= AllMonomials[{x, y, z}, 2]

(Alt) Out[*]:= {x², x y, x z, y², y z, z²}

```
(Alt) In[*]:= Basis[js_List, m_] := Flatten@Outer[Times,
  AllMonomials[Table[p_j, {j, js}], m], AllMonomials[Table[x_j, {j, js}], m]];
Basis[js_List, {m_}] := Flatten@Table[Basis[js, k], {k, 0, m}]
```

(Alt) In[*]:= Basis[{i, j}, {2}]

(Alt) Out[*]:= {1, p_i x_i, p_i x_j, p_j x_i, p_j x_j, p_i² x_i², p_i² x_i x_j, p_i² x_j², p_i p_j x_i², p_i p_j x_i x_j, p_i p_j x_j², p_j² x_i², p_j² x_i x_j, p_j² x_j²}

```
(Alt) In[*]:= GenericCombination[bas_, c_] := bas.Table[c_j, {j, Length@bas}];
GenericCombination[bas_, c_k_] := bas.Table[c_{k,j}, {j, Length@bas}];
```

(Alt) In[*]:= GenericCombination[Basis[{i, j}, {2}], c₁]

(Alt) Out[*]:= c_{1,1} + p_i x_i c_{1,2} + p_i x_j c_{1,3} + p_j x_i c_{1,4} + p_j x_j c_{1,5} + p_i² x_i² c_{1,6} + p_i² x_i x_j c_{1,7} + p_i² x_j² c_{1,8} +
p_i p_j x_i² c_{1,9} + p_i p_j x_i x_j c_{1,10} + p_i p_j x_j² c_{1,11} + p_j² x_i² c_{1,12} + p_j² x_i x_j c_{1,13} + p_j² x_j² c_{1,14}

```
(Alt) In[*]:= R_{i,j}_ := E_{() -> {i,j}} [T^{1/2}, (T - 1) (p_i - p_j) x_j, eSeries @@
  Prepend[0] @ Table[GenericCombination[Basis[{i, j}, {k + 1}], c_k], {k, $k}]];
R_{i,j}_ := E_{() -> {i,j}} [T^{-1/2}, (T^{-1} - 1) (p_i - p_j) x_j, eSeries @@
  Prepend[0] @ Table[GenericCombination[Basis[{i, j}, {k + 1}], d_k], {k, $k}]];
C_{i}_ := E_{() -> {i}} [T^{1/2}, 0, eSeries @@ Prepend[0] @
  Table[GenericCombination[Basis[{i}, {k + 1}], e_k], {k, $k}]];
C_{i}_ := E_{() -> {i}} [T^{-1/2}, 0, eSeries @@ Prepend[0] @
  Table[GenericCombination[Basis[{i}, {k + 1}], f_k], {k, $k}]];
```

(Alt) In[*]:= {R_{1,2}, R̄_{1,2}, C₁, C̄₁}

(Alt) Out[*]:= {E_{{() -> {1,2}}} [√T, (-1 + T) (p₁ - p₂) x₂,
eSeries[0, c_{1,1} + p₁ x₁ c_{1,2} + p₁ x₂ c_{1,3} + p₂ x₁ c_{1,4} + p₂ x₂ c_{1,5} + p₁² x₁² c_{1,6} + p₁² x₁ x₂ c_{1,7} + p₁² x₂² c_{1,8} +
p₁ p₂ x₁² c_{1,9} + p₁ p₂ x₁ x₂ c_{1,10} + p₁ p₂ x₂² c_{1,11} + p₂² x₁² c_{1,12} + p₂² x₁ x₂ c_{1,13} + p₂² x₂² c_{1,14}],
E_{{() -> {1,2}}} [1/√T, (-1 + 1/T) (p₁ - p₂) x₂, eSeries[0,
d_{1,1} + p₁ x₁ d_{1,2} + p₁ x₂ d_{1,3} + p₂ x₁ d_{1,4} + p₂ x₂ d_{1,5} + p₁² x₁² d_{1,6} + p₁² x₁ x₂ d_{1,7} + p₁² x₂² d_{1,8} +
p₁ p₂ x₁² d_{1,9} + p₁ p₂ x₁ x₂ d_{1,10} + p₁ p₂ x₂² d_{1,11} + p₂² x₁² d_{1,12} + p₂² x₁ x₂ d_{1,13} + p₂² x₂² d_{1,14}],
E_{{() -> {1}}} [√T, 0, eSeries[0, e_{1,1} + p₁ x₁ e_{1,2} + p₁² x₁² e_{1,3}]],
E_{{() -> {1}}} [1/√T, 0, eSeries[0, f_{1,1} + p₁ x₁ f_{1,2} + p₁² x₁² f_{1,3}]]}

(Alt) In[*]:=

$$\begin{aligned}
 \text{RMoves} := \{ & \\
 & (R_{1,2} R_{4,3} R_{5,6} // m_{1,4 \rightarrow 1} // m_{2,5 \rightarrow 2} // m_{3,6 \rightarrow 3}) \equiv (R_{2,3} R_{4,5} R_{1,6} // m_{1,4 \rightarrow 1} // m_{2,5 \rightarrow 2} // m_{3,6 \rightarrow 3}), \\
 & (R_{1,2} \bar{R}_{3,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2}) \equiv (\eta_1 \eta_2), \\
 & (C_1 \bar{C}_2 // m_{1,2 \rightarrow 1}) \equiv \eta_1, \\
 & (R_{1,4} \bar{R}_{5,2} \bar{C}_3 // m_{2,4 \rightarrow 2} // m_{1,3 \rightarrow 1} // m_{1,5 \rightarrow 1}) \equiv \bar{C}_1 \eta_2, \\
 & (C_3 R_{1,2} // m_{2,3 \rightarrow 2} // m_{2,1 \rightarrow 1}) \equiv (\bar{C}_3 R_{1,2} // m_{1,3 \rightarrow 1} // m_{1,2 \rightarrow 1}), \\
 & (\bar{C}_2 R_{1,3} // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}) \equiv \eta_1, \quad (\bar{C}_2 \bar{R}_{3,1} // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}) \equiv \eta_1, \\
 & (C_2 \bar{R}_{1,3} // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}) \equiv \eta_1, \quad (C_2 R_{3,1} // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}) \equiv \eta_1 \\
 & \}
 \end{aligned}$$

(Alt) In[*]:= **RMoves**

$$\begin{aligned}
 \text{(Alt) Out[*]} = \{ & 3 c_{1,1} + 2 p_1 x_1 c_{1,2} + p_2 x_1 c_{1,4} + p_3 x_1 c_{1,4} + T p_3 x_2 c_{1,4} + p_1 x_2 (c_{1,2} - T c_{1,2} + c_{1,3} + c_{1,4} - T c_{1,4}) + \\
 & 2 T p_3 x_3 c_{1,5} + p_2 x_2 (T c_{1,2} + c_{1,5}) + p_1 x_3 (T c_{1,2} - T^2 c_{1,2} + 2 c_{1,3} - T c_{1,3} + c_{1,5} - T c_{1,5}) + \\
 & p_2 x_3 (T c_{1,3} + T c_{1,4} - T^2 c_{1,4} + c_{1,5} - T c_{1,5}) + 2 p_1^2 x_1^2 c_{1,6} + p_1^2 x_1 x_2 c_{1,7} + \\
 & p_1^2 x_1 x_3 (2 T c_{1,6} - 2 T^2 c_{1,6} + c_{1,7}) + p_1 p_2 x_1^2 c_{1,9} + p_1 p_3 x_1^2 c_{1,9} + T^2 p_2 p_3 x_2^2 c_{1,9} + p_1 p_2 x_1 x_2 c_{1,10} + \\
 & T p_1 p_3 x_1 x_3 c_{1,10} + T^2 p_2 p_3 x_2 x_3 c_{1,10} + p_1 p_2 x_1 x_3 (2 T c_{1,9} - 2 T^2 c_{1,9} + c_{1,10} - T c_{1,10}) + \\
 & T^2 p_2 p_3 x_3^2 c_{1,11} + p_1 p_2 x_2^2 (2 T c_{1,6} - 2 T^2 c_{1,6} + T c_{1,9} - T^2 c_{1,9} + c_{1,11}) + \\
 & p_1 p_2 x_2 x_3 (2 T c_{1,7} - 2 T^2 c_{1,7} + 2 T c_{1,10} - 2 T^2 c_{1,10} + 2 c_{1,11} - 2 T c_{1,11}) + p_1 p_2 x_3^2 \\
 & (2 T c_{1,8} - 2 T^2 c_{1,8} + T^2 c_{1,9} - 2 T^3 c_{1,9} + T^4 c_{1,9} + T c_{1,10} - 2 T^2 c_{1,10} + T^3 c_{1,10} + c_{1,11} - T c_{1,11}) + \\
 & p_2^2 x_1^2 c_{1,12} + p_3^2 x_1^2 c_{1,12} + T^2 p_3^2 x_2^2 c_{1,12} + p_1 p_3 x_2^2 (T c_{1,9} - T^2 c_{1,9} + 2 T c_{1,12} - 2 T^2 c_{1,12}) + \\
 & p_1^2 x_2^2 (c_{1,6} - 2 T c_{1,6} + T^2 c_{1,6} + c_{1,8} + c_{1,9} - 2 T c_{1,9} + T^2 c_{1,9} + c_{1,12} - 2 T c_{1,12} + T^2 c_{1,12}) + \\
 & p_2^2 x_1 x_2 c_{1,13} + T p_3^2 x_1 x_3 c_{1,13} + T^2 p_3^2 x_2 x_3 c_{1,13} + p_2^2 x_1 x_3 (2 T c_{1,12} - 2 T^2 c_{1,12} + c_{1,13} - T c_{1,13}) + \\
 & p_1 p_3 x_2 x_3 (T c_{1,10} - T^2 c_{1,10} + 2 T c_{1,13} - 2 T^2 c_{1,13}) + \\
 & p_1^2 x_2 x_3 (c_{1,7} - T c_{1,7} + 2 c_{1,8} - 2 T c_{1,8} + c_{1,10} - 2 T c_{1,10} + T^2 c_{1,10} + c_{1,13} - 2 T c_{1,13} + T^2 c_{1,13}) + \\
 & 2 T^2 p_3^2 x_3^2 c_{1,14} + p_2^2 x_2^2 (T^2 c_{1,6} + c_{1,14}) + p_2^2 x_2 x_3 (T^2 c_{1,7} + T c_{1,13} - T^2 c_{1,13} + 2 c_{1,14} - 2 T c_{1,14}) + \\
 & p_1 p_3 x_3^2 (T c_{1,11} + 2 T c_{1,14} - 2 T^2 c_{1,14}) + p_1^2 x_3^2 (T^2 c_{1,6} - 2 T^3 c_{1,6} + T^4 c_{1,6} + T c_{1,7} - 2 T^2 c_{1,7} + T^3 c_{1,7} + \\
 & 2 c_{1,8} - 4 T c_{1,8} + 3 T^2 c_{1,8} + c_{1,11} - 2 T c_{1,11} + T^2 c_{1,11} + c_{1,14} - 2 T c_{1,14} + T^2 c_{1,14}) + p_2^2 x_3^2 \\
 & (T^2 c_{1,8} + T^2 c_{1,12} - 2 T^3 c_{1,12} + T^4 c_{1,12} + T c_{1,13} - 2 T^2 c_{1,13} + T^3 c_{1,13} + c_{1,14} - 2 T c_{1,14} + T^2 c_{1,14}) = \\
 & 3 c_{1,1} + 2 p_1 x_1 c_{1,2} + p_1 x_3 c_{1,3} + p_1 x_2 (c_{1,2} - T c_{1,2} + c_{1,3}) + T p_3 x_1 c_{1,4} + p_2 x_1 (2 c_{1,4} - T c_{1,4}) + \\
 & p_3 x_2 (2 T c_{1,4} - T^2 c_{1,4}) + 2 T p_3 x_3 c_{1,5} + p_2 x_2 (T c_{1,2} + c_{1,4} - 2 T c_{1,4} + T^2 c_{1,4} + c_{1,5}) + \\
 & p_2 x_3 (T c_{1,3} + c_{1,5} - T c_{1,5}) + 2 p_1^2 x_1^2 c_{1,6} + p_1^2 x_1 x_3 c_{1,7} + p_1^2 x_1 x_2 (2 c_{1,6} - 2 T c_{1,6} + c_{1,7}) + \\
 & p_1^2 x_2 x_3 (c_{1,7} - T c_{1,7}) + p_1^2 x_3^2 c_{1,8} + p_1^2 x_2^2 (c_{1,6} - 2 T c_{1,6} + T^2 c_{1,6} + c_{1,8}) + T p_1 p_3 x_1^2 c_{1,9} + \\
 & p_1 p_2 x_1^2 (2 c_{1,9} - T c_{1,9}) + p_1 p_3 x_1 x_2 (2 T c_{1,9} - 2 T^2 c_{1,9}) + p_1 p_3 x_2^2 (T c_{1,9} - 2 T^2 c_{1,9} + T^3 c_{1,9}) + \\
 & T p_1 p_3 x_1 x_3 c_{1,10} + p_1 p_2 x_1 x_2 (2 c_{1,9} - 4 T c_{1,9} + 2 T^2 c_{1,9} + c_{1,10}) + p_1 p_2 x_1 x_3 (c_{1,10} - T c_{1,10}) + \\
 & p_1 p_3 x_2 x_3 (T c_{1,10} - T^2 c_{1,10}) + p_1 p_2 x_2 x_3 (c_{1,10} - 2 T c_{1,10} + T^2 c_{1,10}) + T p_1 p_3 x_3^2 c_{1,11} + \\
 & p_1 p_2 x_2^2 (c_{1,9} - 3 T c_{1,9} + 3 T^2 c_{1,9} - T^3 c_{1,9} + c_{1,11}) + p_1 p_2 x_3^2 (c_{1,11} - T c_{1,11}) + \\
 & T^2 p_3^2 x_1^2 c_{1,12} + p_2 p_3 x_1^2 (2 T c_{1,12} - 2 T^2 c_{1,12}) + p_2^2 x_1^2 (2 c_{1,12} - 2 T c_{1,12} + T^2 c_{1,12}) + \\
 & p_3^2 x_1 x_2 (2 T^2 c_{1,12} - 2 T^3 c_{1,12}) + p_2 p_3 x_1 x_2 (4 T c_{1,12} - 8 T^2 c_{1,12} + 4 T^3 c_{1,12}) + \\
 & p_2 p_3 x_2^2 (T^2 c_{1,9} + 2 T c_{1,12} - 6 T^2 c_{1,12} + 6 T^3 c_{1,12} - 2 T^4 c_{1,12}) + \\
 & \}
 \end{aligned}$$

$$\begin{aligned}
 & p_3^2 x_2^2 (2 T^2 c_{1,12} - 2 T^3 c_{1,12} + T^4 c_{1,12}) + T^2 p_3^2 x_1 x_3 c_{1,13} + \\
 & p_2^2 x_1 x_2 (2 c_{1,12} - 6 T c_{1,12} + 6 T^2 c_{1,12} - 2 T^3 c_{1,12} + c_{1,13}) + \\
 & p_2 p_3 x_1 x_3 (2 T c_{1,13} - 2 T^2 c_{1,13}) + p_2^2 x_1 x_3 (c_{1,13} - 2 T c_{1,13} + T^2 c_{1,13}) + \\
 & p_3^2 x_2 x_3 (2 T^2 c_{1,13} - T^3 c_{1,13}) + p_2^2 x_2 x_3 (T^2 c_{1,7} + c_{1,13} - 3 T c_{1,13} + 3 T^2 c_{1,13} - T^3 c_{1,13}) + \\
 & p_2 p_3 x_2 x_3 (T^2 c_{1,10} + 2 T c_{1,13} - 4 T^2 c_{1,13} + 2 T^3 c_{1,13}) + 2 T^2 p_3^2 x_3^2 c_{1,14} + \\
 & p_2^2 x_2^2 (T^2 c_{1,6} + c_{1,12} - 4 T c_{1,12} + 6 T^2 c_{1,12} - 4 T^3 c_{1,12} + T^4 c_{1,12} + c_{1,14}) + \\
 & p_2 p_3 x_3^2 (T^2 c_{1,11} + 2 T c_{1,14} - 2 T^2 c_{1,14}) + p_2^2 x_3^2 (T^2 c_{1,8} + c_{1,14} - 2 T c_{1,14} + T^2 c_{1,14}), \\
 & c_{1,1} + d_{1,1} + p_1 x_1 (c_{1,2} + d_{1,2} + d_{1,4} - T d_{1,4}) + p_2 x_1 (c_{1,4} + T d_{1,4}) + \\
 & \frac{p_1 x_2 (-c_{1,2} + T c_{1,2} + c_{1,3} + T d_{1,3} + T d_{1,5} - T^2 d_{1,5})}{T} + \frac{p_2 x_2 (-c_{1,4} + T c_{1,4} + c_{1,5} + T^2 d_{1,5})}{T} + \\
 & \frac{p_1 p_2 x_1^2 (c_{1,9} + T d_{1,9} + 2 T d_{1,12} - 2 T^2 d_{1,12}) + p_2^2 x_1^2 (c_{1,12} + T^2 d_{1,12}) +}{T} \\
 & \frac{p_1^2 x_1^2 (c_{1,6} + d_{1,6} + d_{1,9} - T d_{1,9} + d_{1,12} - 2 T d_{1,12} + T^2 d_{1,12}) +}{T} \\
 & \frac{p_1 p_2 x_1 x_2 (-2 c_{1,9} + 2 T c_{1,9} + c_{1,10} + T^2 d_{1,10} + 2 T^2 d_{1,13} - 2 T^3 d_{1,13})}{T} + \\
 & \frac{p_2^2 x_1 x_2 (-2 c_{1,12} + 2 T c_{1,12} + c_{1,13} + T^3 d_{1,13})}{T} + \\
 & \frac{p_1^2 x_1 x_2 (-2 c_{1,6} + 2 T c_{1,6} + c_{1,7} + T d_{1,7} + T d_{1,10} - T^2 d_{1,10} + T d_{1,13} - 2 T^2 d_{1,13} + T^3 d_{1,13})}{T} + \\
 & \frac{p_1 p_2 x_2^2 (c_{1,9} - 2 T c_{1,9} + T^2 c_{1,9} - c_{1,10} + T c_{1,10} + c_{1,11} + T^3 d_{1,11} + 2 T^3 d_{1,14} - 2 T^4 d_{1,14})}{T^2} + \\
 & \frac{p_2^2 x_2^2 (c_{1,12} - 2 T c_{1,12} + T^2 c_{1,12} - c_{1,13} + T c_{1,13} + c_{1,14} + T^4 d_{1,14})}{T^2} + \frac{1}{T^2} p_1^2 x_2^2 (c_{1,6} - 2 T c_{1,6} + \\
 & T^2 c_{1,6} - c_{1,7} + T c_{1,7} + c_{1,8} + T^2 d_{1,8} + T^2 d_{1,11} - T^3 d_{1,11} + T^2 d_{1,14} - 2 T^3 d_{1,14} + T^4 d_{1,14}) = \theta, \\
 & e_{1,1} + f_{1,1} + p_1 x_1 (e_{1,2} + f_{1,2}) + p_1^2 x_1^2 (e_{1,3} + f_{1,3}) = \theta, \frac{p_2 x_1 (T c_{1,4} + 4 c_{1,12} - 4 T c_{1,12} + T^2 d_{1,4})}{T^2} + \\
 & \frac{p_2 x_2 (-T c_{1,4} + T^2 c_{1,4} + T c_{1,5} - 4 c_{1,12} + 8 T c_{1,12} - 4 T^2 c_{1,12} + 2 c_{1,13} - 2 T c_{1,13} + T^3 d_{1,5})}{T^2} + \\
 & \frac{p_1 p_2 x_1^2 (T c_{1,9} - 2 c_{1,12} + 2 T c_{1,12} + T^2 d_{1,9})}{T^2} + \frac{1}{T^2} p_1 p_2 x_1 x_2 \\
 & (-2 T c_{1,9} + 2 T^2 c_{1,9} + T c_{1,10} + 4 c_{1,12} - 8 T c_{1,12} + 4 T^2 c_{1,12} - 2 c_{1,13} + 2 T c_{1,13} + T^3 d_{1,10}) + \\
 & \frac{1}{T^2} p_1 p_2 x_2^2 (T c_{1,9} - 2 T^2 c_{1,9} + T^3 c_{1,9} - T c_{1,10} + T^2 c_{1,10} + T c_{1,11} - 2 c_{1,12} + 6 T c_{1,12} - \\
 & 6 T^2 c_{1,12} + 2 T^3 c_{1,12} + 2 c_{1,13} - 4 T c_{1,13} + 2 T^2 c_{1,13} - 2 c_{1,14} + 2 T c_{1,14} + T^4 d_{1,11}) + \\
 & \frac{p_2^2 x_1^2 (c_{1,12} + T^2 d_{1,12})}{T^2} + \frac{p_2^2 x_1 x_2 (-2 c_{1,12} + 2 T c_{1,12} + c_{1,13} + T^3 d_{1,13})}{T^2} + \\
 & \frac{p_2^2 x_2^2 (c_{1,12} - 2 T c_{1,12} + T^2 c_{1,12} - c_{1,13} + T c_{1,13} + c_{1,14} + T^4 d_{1,14})}{T^2} +
 \end{aligned}$$

$$\begin{aligned}
 & \frac{T^2 c_{1,1} + T c_{1,4} - T^2 c_{1,4} + 2 c_{1,12} - 4 T c_{1,12} + 2 T^2 c_{1,12} + T^2 d_{1,1} + T^2 f_{1,1}}{T^2} + \\
 & \frac{\rho_1 x_1 (T^2 c_{1,2} - T c_{1,4} + T^2 c_{1,4} + 2 T c_{1,9} - 2 T^2 c_{1,9} - 4 c_{1,12} + 8 T c_{1,12} - 4 T^2 c_{1,12} + T^2 d_{1,2} + T^2 f_{1,2})}{T^2} + \\
 & \frac{1}{T^2} \rho_1 x_2 (-T^2 c_{1,2} + T^3 c_{1,2} + T^2 c_{1,3} + T c_{1,4} - 2 T^2 c_{1,4} + T^3 c_{1,4} - T c_{1,5} + \\
 & \quad T^2 c_{1,5} - 2 T c_{1,9} + 4 T^2 c_{1,9} - 2 T^3 c_{1,9} + T c_{1,10} - T^2 c_{1,10} + 4 c_{1,12} - 12 T c_{1,12} + \\
 & \quad 12 T^2 c_{1,12} - 4 T^3 c_{1,12} - 2 c_{1,13} + 4 T c_{1,13} - 2 T^2 c_{1,13} + T^3 d_{1,3} - T^2 f_{1,2} + T^3 f_{1,2}) + \\
 & \frac{\rho_1^2 x_1^2 (T^2 c_{1,6} - T c_{1,9} + T^2 c_{1,9} + c_{1,12} - 2 T c_{1,12} + T^2 c_{1,12} + T^2 d_{1,6} + T^2 f_{1,3})}{T^2} + \\
 & \frac{1}{T^2} \rho_1^2 x_1 x_2 (-2 T^2 c_{1,6} + 2 T^3 c_{1,6} + T^2 c_{1,7} + 2 T c_{1,9} - 4 T^2 c_{1,9} + 2 T^3 c_{1,9} - T c_{1,10} + T^2 c_{1,10} - 2 c_{1,12} + \\
 & \quad 6 T c_{1,12} - 6 T^2 c_{1,12} + 2 T^3 c_{1,12} + c_{1,13} - 2 T c_{1,13} + T^2 c_{1,13} + T^3 d_{1,7} - 2 T^2 f_{1,3} + 2 T^3 f_{1,3}) + \\
 & \frac{1}{T^2} \rho_1^2 x_2^2 (T^2 c_{1,6} - 2 T^3 c_{1,6} + T^4 c_{1,6} - T^2 c_{1,7} + T^3 c_{1,7} + T^2 c_{1,8} - T c_{1,9} + 3 T^2 c_{1,9} - \\
 & \quad 3 T^3 c_{1,9} + T^4 c_{1,9} + T c_{1,10} - 2 T^2 c_{1,10} + T^3 c_{1,10} - T c_{1,11} + T^2 c_{1,11} + c_{1,12} - 4 T c_{1,12} + \\
 & \quad 6 T^2 c_{1,12} - 4 T^3 c_{1,12} + T^4 c_{1,12} - c_{1,13} + 3 T c_{1,13} - 3 T^2 c_{1,13} + T^3 c_{1,13} + c_{1,14} - \\
 & \quad 2 T c_{1,14} + T^2 c_{1,14} + T^4 d_{1,8} + T^2 f_{1,3} - 2 T^3 f_{1,3} + T^4 f_{1,3}) = f_{1,1} + \rho_1 x_1 f_{1,2} + \rho_1^2 x_1^2 f_{1,3}, \\
 & \frac{\rho_1^2 x_1^2 (T^2 c_{1,6} + T c_{1,7} + c_{1,8} + T^2 c_{1,9} + T c_{1,10} + c_{1,11} + T^2 c_{1,12} + T c_{1,13} + c_{1,14} + e_{1,3})}{T^2} + \\
 & \frac{\rho_1 x_1 (T^2 c_{1,2} + T c_{1,3} + T^2 c_{1,4} + T c_{1,5} - 2 T c_{1,7} - 4 c_{1,8} - T c_{1,10} - 2 c_{1,11} + T e_{1,2} - 4 e_{1,3} + 4 T e_{1,3})}{T^2} + \\
 & \frac{T^2 c_{1,1} - T c_{1,3} + 2 c_{1,8} + T^2 e_{1,1} - T e_{1,2} + T^2 e_{1,2} + 2 e_{1,3} - 4 T e_{1,3} + 2 T^2 e_{1,3}}{T^2} = c_{1,1} - c_{1,4} + \\
 & 2 c_{1,12} + f_{1,1} + \rho_1 x_1 (T c_{1,2} + c_{1,3} + T c_{1,4} + c_{1,5} - 2 T c_{1,9} - c_{1,10} - 4 T c_{1,12} - 2 c_{1,13} + T f_{1,2}) + \\
 & \rho_1^2 x_1^2 (T^2 c_{1,6} + T c_{1,7} + c_{1,8} + T^2 c_{1,9} + T c_{1,10} + c_{1,11} + T^2 c_{1,12} + T c_{1,13} + c_{1,14} + T^2 f_{1,3}), \\
 & c_{1,1} - c_{1,4} + 2 c_{1,12} + f_{1,1} + \rho_1 x_1 (T c_{1,2} + c_{1,3} + T c_{1,4} + c_{1,5} - 2 T c_{1,9} - c_{1,10} - 4 T c_{1,12} - 2 c_{1,13} + T f_{1,2}) + \\
 & \rho_1^2 x_1^2 (T^2 c_{1,6} + T c_{1,7} + c_{1,8} + T^2 c_{1,9} + T c_{1,10} + c_{1,11} + T^2 c_{1,12} + T c_{1,13} + c_{1,14} + T^2 f_{1,3}) = \theta, \\
 & d_{1,1} - T d_{1,3} + 2 T^2 d_{1,8} + f_{1,1} + f_{1,2} - T f_{1,2} + 2 f_{1,3} - 4 T f_{1,3} + 2 T^2 f_{1,3} + \\
 & \rho_1 x_1 (d_{1,2} + T d_{1,3} + d_{1,4} + T d_{1,5} - 2 T d_{1,7} - 4 T^2 d_{1,8} - T d_{1,10} - 2 T^2 d_{1,11} + T f_{1,2} + 4 T f_{1,3} - 4 T^2 f_{1,3}) + \\
 & \rho_1^2 x_1^2 (d_{1,6} + T d_{1,7} + T^2 d_{1,8} + d_{1,9} + T d_{1,10} + T^2 d_{1,11} + d_{1,12} + T d_{1,13} + T^2 d_{1,14} + T^2 f_{1,3}) = \theta, \\
 & d_{1,1} - d_{1,4} + 2 d_{1,12} + e_{1,1} + \frac{\rho_1 x_1 (d_{1,2} + T d_{1,3} + d_{1,4} + T d_{1,5} - 2 d_{1,9} - T d_{1,10} - 4 d_{1,12} - 2 T d_{1,13} + e_{1,2})}{T} + \\
 & \frac{\rho_1^2 x_1^2 (d_{1,6} + T d_{1,7} + T^2 d_{1,8} + d_{1,9} + T d_{1,10} + T^2 d_{1,11} + d_{1,12} + T d_{1,13} + T^2 d_{1,14} + e_{1,3})}{T^2} = \theta, \\
 & \frac{\rho_1^2 x_1^2 (T^2 c_{1,6} + T c_{1,7} + c_{1,8} + T^2 c_{1,9} + T c_{1,10} + c_{1,11} + T^2 c_{1,12} + T c_{1,13} + c_{1,14} + e_{1,3})}{T^2} + \\
 & \frac{\rho_1 x_1 (T^2 c_{1,2} + T c_{1,3} + T^2 c_{1,4} + T c_{1,5} - 2 T c_{1,7} - 4 c_{1,8} - T c_{1,10} - 2 c_{1,11} + T e_{1,2} - 4 e_{1,3} + 4 T e_{1,3})}{T^2} +
 \end{aligned}$$

$$\frac{T^2 c_{1,1} - T c_{1,3} + 2 c_{1,8} + T^2 e_{1,1} - T e_{1,2} + T^2 e_{1,2} + 2 e_{1,3} - 4 T e_{1,3} + 2 T^2 e_{1,3}}{T^2} = \theta$$

Solving for R, C, \$k = 1

(Alt) In[*]= \$k = 1;

{R_{1,2}, C₁}

unknowns = Cases[{R_{1,2}, R̄_{1,2}, C₁, C̄₁}, (c | d | e | f)_{\$k,_, ∞}] // Union

(Alt) Out[*]= {E_{}→{1,2} [√T, (-1 + T) (p₁ - p₂) x₂,
 ∈Series[0, c_{1,1} + p₁ x₁ c_{1,2} + p₁ x₂ c_{1,3} + p₂ x₁ c_{1,4} + p₂ x₂ c_{1,5} + p₁² x₁² c_{1,6} + p₁² x₁ x₂ c_{1,7} + p₁² x₂² c_{1,8} +
 p₁ p₂ x₁² c_{1,9} + p₁ p₂ x₁ x₂ c_{1,10} + p₁ p₂ x₂² c_{1,11} + p₂² x₁² c_{1,12} + p₂² x₁ x₂ c_{1,13} + p₂² x₂² c_{1,14}],
 E_{}→{1} [√T, 0, ∈Series[0, e_{1,1} + p₁ x₁ e_{1,2} + p₁² x₁² e_{1,3}]]]}

(Alt) Out[*]= {c_{1,1}, c_{1,2}, c_{1,3}, c_{1,4}, c_{1,5}, c_{1,6}, c_{1,7}, c_{1,8}, c_{1,9}, c_{1,10}, c_{1,11}, c_{1,12}, c_{1,13}, c_{1,14}, d_{1,1}, d_{1,2}, d_{1,3},
 d_{1,4}, d_{1,5}, d_{1,6}, d_{1,7}, d_{1,8}, d_{1,9}, d_{1,10}, d_{1,11}, d_{1,12}, d_{1,13}, d_{1,14}, e_{1,1}, e_{1,2}, e_{1,3}, f_{1,1}, f_{1,2}, f_{1,3}}

(Alt) In[*]= Short[errors = CCF /@ Cases[RMoves, a_ = b_ => a - b], 25]

(Alt) Out[*]//Short=

$$\left\{ T p_1 x_3 c_{1,2} - T^2 p_1 x_3 c_{1,2} + p_1 x_3 c_{1,3} - T p_1 x_3 c_{1,3} - p_2 x_1 c_{1,4} + T p_2 x_1 c_{1,4} + p_3 x_1 c_{1,4} - T p_3 x_1 c_{1,4} + \right. \\
 p_1 x_2 c_{1,4} - T p_1 x_2 c_{1,4} - p_2 x_2 c_{1,4} + 2 T p_2 x_2 c_{1,4} - T^2 p_2 x_2 c_{1,4} - T p_3 x_2 c_{1,4} + T^2 p_3 x_2 c_{1,4} + T p_2 x_3 c_{1,4} - \\
 T^2 p_2 x_3 c_{1,4} + \ll 169 \gg + 4 T^2 p_2 p_3 x_2 x_3 c_{1,13} - 2 T^3 p_2 p_3 x_2 x_3 c_{1,13} - T^2 p_3^2 x_2 x_3 c_{1,13} + T^3 p_3^2 x_2 x_3 c_{1,13} + \\
 T p_2^2 x_3^2 c_{1,13} - 2 T^2 p_2^2 x_3^2 c_{1,13} + T^3 p_2^2 x_3^2 c_{1,13} + 2 p_2^2 x_2 x_3 c_{1,14} - 2 T p_2^2 x_2 x_3 c_{1,14} + p_1^2 x_3^2 c_{1,14} - \\
 2 T p_1^2 x_3^2 c_{1,14} + T^2 p_1^2 x_3^2 c_{1,14} + 2 T p_1 p_3 x_3^2 c_{1,14} - 2 T^2 p_1 p_3 x_3^2 c_{1,14} - 2 T p_2 p_3 x_3^2 c_{1,14} + 2 T^2 p_2 p_3 x_3^2 c_{1,14}, \\
 \left. \frac{\ll 1 \gg}{T^2}, \ll 1 \gg, \ll 3 \gg, \ll 1 \gg, \frac{\ll 1 \gg}{T^2}, \frac{\ll 1 \gg}{T^2} \right\}$$

(Alt) In[*]= eqns = Thread[0 == Union@@(CoefficientRules[#, {x₁, x₂, x₃, p₁, p₂, p₃}]][[;;, 2]] & /@ errors]

(Alt) Out[*]= {0 == c_{1,4} - T c_{1,4}, 0 == -c_{1,4} + T c_{1,4}, 0 == T c_{1,4} - T² c_{1,4}, 0 == -c_{1,4} + 2 T c_{1,4} - T² c_{1,4},
 0 == -T c_{1,4} + T² c_{1,4}, 0 == T c_{1,2} - T² c_{1,2} + c_{1,3} - T c_{1,3} + c_{1,5} - T c_{1,5},
 0 == -2 c_{1,6} + 2 T c_{1,6}, 0 == 2 T c_{1,6} - 2 T² c_{1,6}, 0 == c_{1,9} - T c_{1,9},
 0 == -c_{1,9} + T c_{1,9}, 0 == 2 T c_{1,9} - 2 T² c_{1,9}, 0 == -2 c_{1,9} + 4 T c_{1,9} - 2 T² c_{1,9},
 0 == -2 T c_{1,9} + 2 T² c_{1,9}, 0 == 2 T c_{1,6} - 2 T² c_{1,6} - c_{1,9} + 4 T c_{1,9} - 4 T² c_{1,9} + T³ c_{1,9},
 0 == 2 T c_{1,8} - 2 T² c_{1,8} + T² c_{1,9} - 2 T³ c_{1,9} + T⁴ c_{1,9} + T c_{1,10} - 2 T² c_{1,10} + T³ c_{1,10},
 0 == 2 T c_{1,7} - 2 T² c_{1,7} - c_{1,10} + 4 T c_{1,10} - 3 T² c_{1,10} + 2 c_{1,11} - 2 T c_{1,11},
 0 == T² c_{1,9} - T³ c_{1,9} + 2 T c_{1,12} - 2 T² c_{1,12}, 0 == c_{1,12} - T² c_{1,12}, 0 == -c_{1,12} + 2 T c_{1,12} - T² c_{1,12},
 0 == c_{1,9} - 2 T c_{1,9} + T² c_{1,9} + c_{1,12} - 2 T c_{1,12} + T² c_{1,12}, 0 == -2 T c_{1,12} + 2 T² c_{1,12},
 0 == -4 T c_{1,12} + 8 T² c_{1,12} - 4 T³ c_{1,12}, 0 == -2 c_{1,12} + 6 T c_{1,12} - 6 T² c_{1,12} + 2 T³ c_{1,12},
 0 == -2 T² c_{1,12} + 2 T³ c_{1,12}, 0 == -T² c_{1,12} + 2 T³ c_{1,12} - T⁴ c_{1,12},
 0 == -c_{1,12} + 4 T c_{1,12} - 6 T² c_{1,12} + 4 T³ c_{1,12} - T⁴ c_{1,12}, 0 == -2 T c_{1,12} + 6 T² c_{1,12} - 6 T³ c_{1,12} + 2 T⁴ c_{1,12},
 0 == 2 T c_{1,13} - 2 T² c_{1,13}, 0 == T c_{1,13} - T² c_{1,13}, 0 == 2 T c_{1,12} - 2 T² c_{1,12} + T c_{1,13} - T² c_{1,13},
 0 == 2 c_{1,8} - 2 T c_{1,8} + c_{1,10} - 2 T c_{1,10} + T² c_{1,10} + c_{1,13} - 2 T c_{1,13} + T² c_{1,13}, 0 == -2 T c_{1,13} + 2 T² c_{1,13},
 0 == -2 T c_{1,13} + 4 T² c_{1,13} - 2 T³ c_{1,13}, 0 == T² c_{1,12} - 2 T³ c_{1,12} + T⁴ c_{1,12} + T c_{1,13} - 2 T² c_{1,13} + T³ c_{1,13},
 0 == -T² c_{1,13} + T³ c_{1,13}, 0 == -c_{1,13} + 4 T c_{1,13} - 4 T² c_{1,13} + T³ c_{1,13} + 2 c_{1,14} - 2 T c_{1,14},
 0 == 2 T c_{1,14} - 2 T² c_{1,14}, 0 == T² c_{1,6} - 2 T³ c_{1,6} + T⁴ c_{1,6} + T c_{1,7} - 2 T² c_{1,7} + T³ c_{1,7} +

$$\begin{aligned}
 & c_{1,8} - 4 T c_{1,8} + 3 T^2 c_{1,8} + c_{1,11} - 2 T c_{1,11} + T^2 c_{1,11} + c_{1,14} - 2 T c_{1,14} + T^2 c_{1,14}, \\
 \theta = & -2 T c_{1,14} + 2 T^2 c_{1,14}, \theta = c_{1,1} + d_{1,1}, \theta = c_{1,1} - c_{1,4} + \frac{c_{1,4}}{T} + 2 c_{1,12} + \frac{2 c_{1,12}}{T^2} - \frac{4 c_{1,12}}{T} + d_{1,1}, \\
 \theta = & c_{1,2} + c_{1,4} - \frac{c_{1,4}}{T} - 2 c_{1,9} + \frac{2 c_{1,9}}{T} - 4 c_{1,12} - \frac{4 c_{1,12}}{T^2} + \frac{8 c_{1,12}}{T} + d_{1,2}, \\
 \theta = & \frac{c_{1,4}}{T} + \frac{4 c_{1,12}}{T^2} - \frac{4 c_{1,12}}{T} + d_{1,4}, \theta = c_{1,2} + d_{1,2} + d_{1,4} - T d_{1,4}, \theta = c_{1,4} + T d_{1,4}, \\
 \theta = & c_{1,2} - \frac{c_{1,2}}{T} + \frac{c_{1,3}}{T} + d_{1,3} + d_{1,5} - T d_{1,5}, \theta = c_{1,4} - \frac{c_{1,4}}{T} + \frac{c_{1,5}}{T} + T d_{1,5}, \\
 \theta = & c_{1,4} - \frac{c_{1,4}}{T} + \frac{c_{1,5}}{T} - 4 c_{1,12} - \frac{4 c_{1,12}}{T^2} + \frac{8 c_{1,12}}{T} + \frac{2 c_{1,13}}{T^2} - \frac{2 c_{1,13}}{T} + T d_{1,5}, \\
 \theta = & c_{1,6} + c_{1,9} - \frac{c_{1,9}}{T} + c_{1,12} + \frac{c_{1,12}}{T^2} - \frac{2 c_{1,12}}{T} + d_{1,6}, \theta = \frac{c_{1,9}}{T} - \frac{2 c_{1,12}}{T^2} + \frac{2 c_{1,12}}{T} + d_{1,9}, \\
 \theta = & 2 c_{1,9} - \frac{2 c_{1,9}}{T} + \frac{c_{1,10}}{T} + 4 c_{1,12} + \frac{4 c_{1,12}}{T^2} - \frac{8 c_{1,12}}{T} - \frac{2 c_{1,13}}{T^2} + \frac{2 c_{1,13}}{T} + T d_{1,10}, \\
 \theta = & -2 c_{1,9} + \frac{c_{1,9}}{T} + T c_{1,9} + c_{1,10} - \frac{c_{1,10}}{T} + \frac{c_{1,11}}{T} - 6 c_{1,12} - \frac{2 c_{1,12}}{T^2} + \\
 & \frac{6 c_{1,12}}{T} + 2 T c_{1,12} + 2 c_{1,13} + \frac{2 c_{1,13}}{T^2} - \frac{4 c_{1,13}}{T} - \frac{2 c_{1,14}}{T^2} + \frac{2 c_{1,14}}{T} + T^2 d_{1,11}, \\
 \theta = & \frac{c_{1,12}}{T^2} + d_{1,12}, \theta = c_{1,9} + T d_{1,9} + 2 T d_{1,12} - 2 T^2 d_{1,12}, \theta = c_{1,12} + T^2 d_{1,12}, \\
 \theta = & c_{1,6} + d_{1,6} + d_{1,9} - T d_{1,9} + d_{1,12} - 2 T d_{1,12} + T^2 d_{1,12}, \theta = -\frac{2 c_{1,12}}{T^2} + \frac{2 c_{1,12}}{T} + \frac{c_{1,13}}{T^2} + T d_{1,13}, \\
 \theta = & 2 c_{1,9} - \frac{2 c_{1,9}}{T} + \frac{c_{1,10}}{T} + T d_{1,10} + 2 T d_{1,13} - 2 T^2 d_{1,13}, \theta = 2 c_{1,12} - \frac{2 c_{1,12}}{T} + \frac{c_{1,13}}{T} + T^2 d_{1,13}, \\
 \theta = & 2 c_{1,6} - \frac{2 c_{1,6}}{T} + \frac{c_{1,7}}{T} + d_{1,7} + d_{1,10} - T d_{1,10} + d_{1,13} - 2 T d_{1,13} + T^2 d_{1,13}, \\
 \theta = & c_{1,9} + \frac{c_{1,9}}{T^2} - \frac{2 c_{1,9}}{T} - \frac{c_{1,10}}{T^2} + \frac{c_{1,10}}{T} + \frac{c_{1,11}}{T^2} + T d_{1,11} + 2 T d_{1,14} - 2 T^2 d_{1,14}, \\
 \theta = & c_{1,12} + \frac{c_{1,12}}{T^2} - \frac{2 c_{1,12}}{T} - \frac{c_{1,13}}{T^2} + \frac{c_{1,13}}{T} + \frac{c_{1,14}}{T^2} + T^2 d_{1,14}, \\
 \theta = & c_{1,6} + \frac{c_{1,6}}{T^2} - \frac{2 c_{1,6}}{T} - \frac{c_{1,7}}{T^2} + \frac{c_{1,7}}{T} + \frac{c_{1,8}}{T^2} + d_{1,8} + d_{1,11} - T d_{1,11} + d_{1,14} - 2 T d_{1,14} + T^2 d_{1,14}, \\
 \theta = & d_{1,1} - d_{1,4} + 2 d_{1,12} + e_{1,1}, \theta = \frac{d_{1,2}}{T} + d_{1,3} + \frac{d_{1,4}}{T} + d_{1,5} - \frac{2 d_{1,9}}{T} - d_{1,10} - \frac{4 d_{1,12}}{T} - 2 d_{1,13} + \frac{e_{1,2}}{T}, \\
 \theta = & c_{1,6} + \frac{c_{1,7}}{T} + \frac{c_{1,8}}{T^2} + c_{1,9} + \frac{c_{1,10}}{T} + \frac{c_{1,11}}{T^2} + c_{1,12} + \frac{c_{1,13}}{T} + \frac{c_{1,14}}{T^2} + \frac{e_{1,3}}{T^2}, \\
 \theta = & \frac{d_{1,6}}{T^2} + \frac{d_{1,7}}{T} + d_{1,8} + \frac{d_{1,9}}{T^2} + \frac{d_{1,10}}{T} + d_{1,11} + \frac{d_{1,12}}{T^2} + \frac{d_{1,13}}{T} + d_{1,14} + \frac{e_{1,3}}{T^2}, \\
 \theta = & c_{1,1} - \frac{c_{1,3}}{T} + \frac{2 c_{1,8}}{T^2} + e_{1,1} + e_{1,2} - \frac{e_{1,2}}{T} + 2 e_{1,3} + \frac{2 e_{1,3}}{T^2} - \frac{4 e_{1,3}}{T}, \\
 \theta = & c_{1,2} + \frac{c_{1,3}}{T} + c_{1,4} + \frac{c_{1,5}}{T} - \frac{2 c_{1,7}}{T} - \frac{4 c_{1,8}}{T^2} - \frac{c_{1,10}}{T} - \frac{2 c_{1,11}}{T^2} + \frac{e_{1,2}}{T} - \frac{4 e_{1,3}}{T^2} + \frac{4 e_{1,3}}{T},
 \end{aligned}$$

$$\begin{aligned}
 \theta &= -\frac{c_{1,3}}{T} + c_{1,4} + \frac{2c_{1,8}}{T^2} - 2c_{1,12} + e_{1,1} + e_{1,2} - \frac{e_{1,2}}{T} + 2e_{1,3} + \frac{2e_{1,3}}{T^2} - \frac{4e_{1,3}}{T} - f_{1,1}, \\
 \theta &= c_{1,1} - c_{1,4} + 2c_{1,12} + f_{1,1}, \quad \theta = e_{1,1} + f_{1,1}, \quad \theta = e_{1,2} + f_{1,2}, \\
 \theta &= c_{1,2} - Tc_{1,2} - c_{1,3} + \frac{c_{1,3}}{T} + c_{1,4} - Tc_{1,4} - c_{1,5} + \frac{c_{1,5}}{T} - \frac{2c_{1,7}}{T} - \frac{4c_{1,8}}{T^2} + \\
 &\quad 2Tc_{1,9} + c_{1,10} - \frac{c_{1,10}}{T} - \frac{2c_{1,11}}{T^2} + 4Tc_{1,12} + 2c_{1,13} + \frac{e_{1,2}}{T} - \frac{4e_{1,3}}{T^2} + \frac{4e_{1,3}}{T} - Tf_{1,2}, \\
 \theta &= Tc_{1,2} + c_{1,3} + Tc_{1,4} + c_{1,5} - 2Tc_{1,9} - c_{1,10} - 4Tc_{1,12} - 2c_{1,13} + Tf_{1,2}, \\
 \theta &= -c_{1,2} + Tc_{1,2} + c_{1,3} - 2c_{1,4} + \frac{c_{1,4}}{T} + Tc_{1,4} + c_{1,5} - \frac{c_{1,5}}{T} + 4c_{1,9} - \frac{2c_{1,9}}{T} - 2Tc_{1,9} - c_{1,10} + \frac{c_{1,10}}{T} + \\
 &\quad 12c_{1,12} + \frac{4c_{1,12}}{T^2} - \frac{12c_{1,12}}{T} - 4Tc_{1,12} - 2c_{1,13} - \frac{2c_{1,13}}{T^2} + \frac{4c_{1,13}}{T} + Td_{1,3} - f_{1,2} + Tf_{1,2}, \\
 \theta &= e_{1,3} + f_{1,3}, \quad \theta = -2c_{1,6} + 2Tc_{1,6} + c_{1,7} - 4c_{1,9} + \frac{2c_{1,9}}{T} + 2Tc_{1,9} + c_{1,10} - \frac{c_{1,10}}{T} - \\
 &\quad 6c_{1,12} - \frac{2c_{1,12}}{T^2} + \frac{6c_{1,12}}{T} + 2Tc_{1,12} + c_{1,13} + \frac{c_{1,13}}{T^2} - \frac{2c_{1,13}}{T} + Td_{1,7} - 2f_{1,3} + 2Tf_{1,3}, \\
 \theta &= d_{1,2} + Td_{1,3} + d_{1,4} + Td_{1,5} - 2Td_{1,7} - 4T^2d_{1,8} - Td_{1,10} - 2T^2d_{1,11} + Tf_{1,2} + 4Tf_{1,3} - 4T^2f_{1,3}, \\
 \theta &= c_{1,6} - T^2c_{1,6} + \frac{c_{1,7}}{T} - Tc_{1,7} - c_{1,8} + \frac{c_{1,8}}{T^2} + c_{1,9} - T^2c_{1,9} + \frac{c_{1,10}}{T} - Tc_{1,10} - \\
 &\quad c_{1,11} + \frac{c_{1,11}}{T^2} + c_{1,12} - T^2c_{1,12} + \frac{c_{1,13}}{T} - Tc_{1,13} - c_{1,14} + \frac{c_{1,14}}{T^2} + \frac{e_{1,3}}{T^2} - T^2f_{1,3}, \\
 \theta &= T^2c_{1,6} + Tc_{1,7} + c_{1,8} + T^2c_{1,9} + Tc_{1,10} + c_{1,11} + T^2c_{1,12} + Tc_{1,13} + c_{1,14} + T^2f_{1,3}, \\
 \theta &= d_{1,6} + Td_{1,7} + T^2d_{1,8} + d_{1,9} + Td_{1,10} + T^2d_{1,11} + d_{1,12} + Td_{1,13} + T^2d_{1,14} + T^2f_{1,3}, \\
 \theta &= c_{1,6} - 2Tc_{1,6} + T^2c_{1,6} - c_{1,7} + Tc_{1,7} + c_{1,8} + 3c_{1,9} - \frac{c_{1,9}}{T} - 3Tc_{1,9} + T^2c_{1,9} - 2c_{1,10} + \\
 &\quad \frac{c_{1,10}}{T} + Tc_{1,10} + c_{1,11} - \frac{c_{1,11}}{T} + 6c_{1,12} + \frac{c_{1,12}}{T^2} - \frac{4c_{1,12}}{T} - 4Tc_{1,12} + T^2c_{1,12} - 3c_{1,13} - \\
 &\quad \frac{c_{1,13}}{T^2} + \frac{3c_{1,13}}{T} + Tc_{1,13} + c_{1,14} + \frac{c_{1,14}}{T^2} - \frac{2c_{1,14}}{T} + T^2d_{1,8} + f_{1,3} - 2Tf_{1,3} + T^2f_{1,3}, \\
 \theta &= d_{1,1} - Td_{1,3} + 2T^2d_{1,8} + f_{1,1} + f_{1,2} - Tf_{1,2} + 2f_{1,3} - 4Tf_{1,3} + 2T^2f_{1,3} \}
 \end{aligned}$$

(Alt) In[*]:= {sol} = Solve[eqns, unknowns]

••• Solve: Equations may not give solutions for all "solve" variables.

$$\begin{aligned}
 \text{(Alt) Out[*]} = & \left\{ \left\{ c_{1,1} \rightarrow -\frac{c_{1,2}}{2} - \frac{c_{1,5}}{2T}, c_{1,3} \rightarrow -Tc_{1,2} - c_{1,5}, c_{1,4} \rightarrow \theta, c_{1,6} \rightarrow \theta, c_{1,8} \rightarrow -\frac{1}{2} \times (1-T)c_{1,10}, c_{1,9} \rightarrow \theta, \right. \right. \\
 & c_{1,11} \rightarrow -Tc_{1,7} - \frac{1}{2} \times (-1+3T)c_{1,10}, c_{1,12} \rightarrow \theta, c_{1,13} \rightarrow \theta, c_{1,14} \rightarrow \theta, d_{1,1} \rightarrow \frac{c_{1,2}}{2} + \frac{c_{1,5}}{2T}, \\
 & d_{1,2} \rightarrow -c_{1,2}, d_{1,3} \rightarrow \frac{c_{1,2}}{T} + \frac{c_{1,5}}{T^2}, d_{1,4} \rightarrow \theta, d_{1,5} \rightarrow -\frac{c_{1,5}}{T^2}, d_{1,6} \rightarrow \theta, d_{1,7} \rightarrow -\frac{c_{1,7}}{T} - \frac{(-1+T)c_{1,10}}{T^2}, \\
 & d_{1,8} \rightarrow -\frac{(1-T)c_{1,10}}{2T^3}, d_{1,9} \rightarrow \theta, d_{1,10} \rightarrow -\frac{c_{1,10}}{T^2}, d_{1,11} \rightarrow \frac{c_{1,7}}{T^2} - \frac{(-1-T)c_{1,10}}{2T^3}, d_{1,12} \rightarrow \theta, d_{1,13} \rightarrow \theta, \\
 & \left. \left. d_{1,14} \rightarrow \theta, e_{1,1} \rightarrow -\frac{c_{1,2}}{2} - \frac{c_{1,5}}{2T}, e_{1,2} \rightarrow -\frac{c_{1,10}}{T}, e_{1,3} \rightarrow \theta, f_{1,1} \rightarrow \frac{c_{1,2}}{2} + \frac{c_{1,5}}{2T}, f_{1,2} \rightarrow \frac{c_{1,10}}{T}, f_{1,3} \rightarrow \theta \right\} \right\}
 \end{aligned}$$

(Alt) In[*]:= sol /. (a_ -> b_) :-> (a = b)

$$(Alt) Out[*]:= \left\{ -\frac{c_{1,2}}{2} - \frac{c_{1,5}}{2T}, -T c_{1,2} - c_{1,5}, \theta, \theta, -\frac{1}{2} \times (1-T) c_{1,10}, \theta, -T c_{1,7} - \frac{1}{2} \times (-1+3T) c_{1,10}, \theta, \theta, \right. \\ \left. \theta, \frac{c_{1,2}}{2} + \frac{c_{1,5}}{2T}, -c_{1,2}, \frac{c_{1,2}}{T} + \frac{c_{1,5}}{T^2}, \theta, -\frac{c_{1,5}}{T^2}, \theta, -\frac{c_{1,7}}{T} - \frac{(-1+T) c_{1,10}}{T^2}, -\frac{(1-T) c_{1,10}}{2T^3}, \right. \\ \left. \theta, -\frac{c_{1,10}}{T^2}, \frac{c_{1,7}}{T^2} - \frac{(-1-T) c_{1,10}}{2T^3}, \theta, \theta, \theta, -\frac{c_{1,2}}{2} - \frac{c_{1,5}}{2T}, -\frac{c_{1,10}}{T}, \theta, \frac{c_{1,2}}{2} + \frac{c_{1,5}}{2T}, \frac{c_{1,10}}{T}, \theta \right\}$$

(Alt) In[*]:= {R1,2, R1,2, C1, C1}

$$(Alt) Out[*]:= \left\{ \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\sqrt{T}, (-1+T) (p_1 - p_2) x_2, \right. \right. \\ \left. \in \text{Series} \left[\theta, -\frac{c_{1,2}}{2} + p_1 x_1 c_{1,2} + p_1 x_2 (-T c_{1,2} - c_{1,5}) - \frac{c_{1,5}}{2T} + p_2 x_2 c_{1,5} + p_1^2 x_1 x_2 c_{1,7} + \right. \right. \\ \left. \left. p_1 p_2 x_1 x_2 c_{1,10} - \frac{1}{2} \times (1-T) p_1^2 x_2^2 c_{1,10} + p_1 p_2 x_2^2 \left(-T c_{1,7} - \frac{1}{2} \times (-1+3T) c_{1,10} \right) \right] \right], \\ \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\frac{1}{\sqrt{T}}, \left(-1 + \frac{1}{T} \right) (p_1 - p_2) x_2, \in \text{Series} \left[\theta, \right. \right. \\ \left. \frac{c_{1,2}}{2} - p_1 x_1 c_{1,2} + \frac{c_{1,5}}{2T} - \frac{p_2 x_2 c_{1,5}}{T^2} + p_1 x_2 \left(\frac{c_{1,2}}{T} + \frac{c_{1,5}}{T^2} \right) - \frac{p_1 p_2 x_1 x_2 c_{1,10}}{T^2} - \right. \\ \left. \frac{(1-T) p_1^2 x_2^2 c_{1,10}}{2T^3} + p_1 p_2 x_2^2 \left(\frac{c_{1,7}}{T^2} - \frac{(-1-T) c_{1,10}}{2T^3} \right) + p_1^2 x_1 x_2 \left(-\frac{c_{1,7}}{T} - \frac{(-1+T) c_{1,10}}{T^2} \right) \right] \right], \\ \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\sqrt{T}, \theta, \in \text{Series} \left[\theta, -\frac{c_{1,2}}{2} - \frac{c_{1,5}}{2T} - \frac{p_1 x_1 c_{1,10}}{T} \right] \right], \\ \left. \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\frac{1}{\sqrt{T}}, \theta, \in \text{Series} \left[\theta, \frac{c_{1,2}}{2} + \frac{c_{1,5}}{2T} + \frac{p_1 x_1 c_{1,10}}{T} \right] \right] \right\}$$

(Alt) In[*]:= Cases[{R1,2, R1,2, C1, C1}, (c | d | e | f) \$k,_, \infty] // Union

(Alt) Out[*]:= {C1,2, C1,5, C1,7, C1,10}

(Alt) In[*]:= {c1,2 = 0, c1,5 = 0, c1,7 = 0, c1,10 = 1};
{R1,2, R1,2, C1, C1}

$$(Alt) Out[*]:= \left\{ \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\sqrt{T}, (-1+T) (p_1 - p_2) x_2, \right. \right. \\ \left. \in \text{Series} \left[\theta, p_1 p_2 x_1 x_2 + \frac{1}{2} \times (-1+T) p_1^2 x_2^2 + \frac{1}{2} \times (1-3T) p_1 p_2 x_2^2 \right] \right], \\ \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\frac{1}{\sqrt{T}}, \left(-1 + \frac{1}{T} \right) (p_1 - p_2) x_2, \right. \\ \left. \in \text{Series} \left[\theta, -\frac{(-1+T) p_1^2 x_1 x_2}{T^2} - \frac{p_1 p_2 x_1 x_2}{T^2} - \frac{(1-T) p_1^2 x_2^2}{2T^3} - \frac{(-1-T) p_1 p_2 x_2^2}{2T^3} \right] \right], \\ \left. \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\sqrt{T}, \theta, \in \text{Series} \left[\theta, -\frac{p_1 x_1}{T} \right] \right], \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\frac{1}{\sqrt{T}}, \theta, \in \text{Series} \left[\theta, \frac{p_1 x_1}{T} \right] \right] \right\}$$

```
(Alt) In[ ]:= RMoves
(Alt) Out[ ]:= {True, True, True, True, True, True, True, True, True}
```

Some Knot Theory at \$k=1

```
(Alt) In[ ]:= ZF[Knot[3, 1]]
```

KnotTheory: Loading precomputed data in PD4Knots`.

```
(Alt) Out[ ]:=  $\mathbb{E}_{\{\} \rightarrow \{1\}} \left[ \frac{T}{1 - T + T^2}, \theta, \in \text{Series} \left[ \theta, \frac{-2 + 3T - 2T^2 + T^3}{T - 2T^2 + 3T^3 - 2T^4 + T^5} \right] \right]$ 
```

```
(Alt) In[ ]:= ZF /@ {Knot[6, 1], Knot[9, 46]}
```

```
(Alt) Out[ ]:= {  $\mathbb{E}_{\{\} \rightarrow \{1\}} \left[ \frac{T}{2 - 5T + 2T^2}, \theta, \in \text{Series} \left[ \theta, \frac{-5 + 16T - 10T^2 - 4T^3 + 3T^4}{4T - 20T^2 + 33T^3 - 20T^4 + 4T^5} \right] \right],$   

 $\mathbb{E}_{\{\} \rightarrow \{1\}} \left[ \frac{T}{2 - 5T + 2T^2}, \theta, \in \text{Series} \left[ \theta, \frac{-7 + 28T - 30T^2 + 8T^3 + T^4}{4T - 20T^2 + 33T^3 - 20T^4 + 4T^5} \right] \right] }$ 
```

```
(Alt) In[ ]:= equiv = {Knot[10, 106], Knot[12, NonAlternating, 369]};  

Length@Union@Echo[ZF /@ equiv]
```

```
(Alt) In[ ]:= equiv =  

{Knot[12, Alternating, 427], Knot[12, Alternating, 435], Knot[12, Alternating, 990]};  

Length@Union[ZF /@ equiv]
```

Solving for R, C, \$k = 2

```
In[ ]:= $k = 2;  

{R1,2, C1}  

Short[RMoves, 20]
```

```
In[ ]:= unknowns = Cases[{R1,2, R̄1,2, C1, C̄1}, (c | d | e | f)$k,_, ∞] // Union
```

```
In[ ]:= Short[errors = CCF /@ Cases[RMoves, a_ == b_ => a - b], 25]
```

```
In[ ]:= Short[#, 10] &[eqns =  

Thread[0 == Union@@(CoefficientRules[#, {x1, x2, x3, p1, p2, p3}] [[;;, 2] & /@ errors]]]
```

```
In[ ]:= {sol} = Solve[eqns, unknowns]
```

```
In[ ]:= sol /. (a_ -> b_) => (a = b)
```

```
In[ ]:= Cases[{R1,2, R̄1,2, C1, C̄1}, (c | d | e | f)$k,_, ∞] // Union
```

```
In[ ]:= {c2,2 = 0, c2,5 = 0, c2,7 = 0, c2,10 = 0, c2,16 = 0};  

{R1,2, R̄1,2, C1, C̄1}
```

```
In[ ]:= RMoves
```

Some Knot Theory at \$k=2

According to 12XingStats.nb at pensieve://Projects/SL2Invariant/k=2/ the following pair have equal ρ_1 but different ρ_2 :

```
In[ ]:= equiv = {Knot[10, 106], Knot[12, NonAlternating, 369]};
res21 = ZF /@ equiv
Simplify[res21[[1]] == res21[[2]]]
```

According to 12XingStats.nb at pensieve://Projects/SL2Invariant/k=2/ the following triple have equal ρ_1 but different ρ_2 :

```
In[ ]:= equiv =
  {Knot[12, Alternating, 427], Knot[12, Alternating, 435], Knot[12, Alternating, 990]};
Length@Union[res22 = ZF /@ equiv]
```

Solving for $R, C, \mathcal{C}_k = 3$

```
In[ ]:= $k = 3;
Short[RMoves, 20]

In[ ]:= unknowns = Cases[{R1,2, R1,2, C1, C1}, (c | d | e | f)$k,_, ∞] // Union

In[ ]:= Short[errors = CCF /@ Cases[RMoves, a_ == b_ => a - b], 25]

In[ ]:= Short[#, 10] & [eqns =
  Thread[0 == Union@@ (CoefficientRules[#, {x1, x2, x3, p1, p2, p3}] [[ ; ; , 2] & /@ errors]]]

In[ ]:= {sol} = Solve[eqns, unknowns]

In[ ]:= sol /. (a_ -> b_) => (a = b)

In[ ]:= Cases[{R1,2, R1,2, C1, C1}, (c | d | e | f)$k,_, ∞] // Union

In[ ]:= {c3,2 = 0, c3,5 = 0, c3,7 = 0, c3,10 = 0, c3,16 = 0, c3,32 = 1};
  {R1,2, R1,2, C1, C1}
```

```
In[ ]:= RMoves
```