

Pensieve header: Examples for “Geography vs. Identity”. Most material is from TurboGassner.nb at pensieve://2019-11/.

P

```
In[*]:=  $\delta /: \delta_{i,j} := \text{If}[i == j, 1, 0];$ 
```

```
In[*]:=  $\tau_{i,j}[\xi] := (\xi /. \{z_{-k} \Rightarrow z_k /. \{i \rightarrow j, j \rightarrow i\}, z_{-L,k} \Rightarrow z_L /. \{i \rightarrow j, j \rightarrow i\}, k /. \{i \rightarrow j, j \rightarrow i\}\})$   

  (* Non-linear over  $\mathbb{Q}(t^{\pm 1})$  ! *)
```

The Burau Representation

B

```
In[*]:=  $B_{i,j}[\xi] := \xi /. v_k \Rightarrow v_k + \delta_{k,j} (t - 1) (v_j - v_i) // \text{Expand}$ 
```

B

```
In[*]:=  $(\text{bas3} = \{v_1, v_2, v_3\}) // B_{1,2}$ 
```

B

```
Out[*]:=  $\{v_1, v_1 - t v_1 + t v_2, v_3\}$ 
```

B

```
In[*]:=  $\text{bas3} // B_{1,2} // B_{1,3} // B_{2,3}$ 
```

B

```
Out[*]:=  $\{v_1, v_1 - t v_1 + t v_2, v_1 - t v_1 + t v_2 - t^2 v_2 + t^2 v_3\}$ 
```

B

```
In[*]:=  $\text{bas3} // B_{2,3} // B_{1,3} // B_{1,2}$ 
```

B

```
Out[*]:=  $\{v_1, v_1 - t v_1 + t v_2, v_1 - t v_1 + t v_2 - t^2 v_2 + t^2 v_3\}$ 
```

The Gassner Representation

G

```
In[*]:=  $G_{i,j}[\xi] := \xi /. v_k \Rightarrow v_k + \delta_{k,j} (t_i - 1) (v_j - v_i) // \text{Expand}$ 
```

G

```
In[*]:=  $(\text{bas3} // G_{1,2} // G_{1,3} // G_{2,3}) == (\text{bas3} // G_{2,3} // G_{1,3} // G_{1,2})$ 
```

G

```
Out[*]:= True
```

```
In[*]:=  $\{v_1, v_2, v_3\} // G_{1,2} // G_{1,3}$   

 $\{v_1, v_2, v_3\} // G_{1,3} // G_{1,2}$ 
```

```
Out[*]:=  $\{v_1, v_1 - t_1 v_1 + t_1 v_2, v_1 - t_1 v_1 + t_1 v_3\}$ 
```

```
Out[*]:=  $\{v_1, v_1 - t_1 v_1 + t_1 v_2, v_1 - t_1 v_1 + t_1 v_3\}$ 
```

```
In[*]:=  $\{v_1, v_2, v_3\} // G_{1,3} // G_{2,3}$   

 $\{v_1, v_2, v_3\} // G_{2,3} // G_{1,3}$ 
```

```
Out[*]:=  $\{v_1, v_2, v_1 - t_1 v_1 + t_1 v_2 - t_1 t_2 v_2 + t_1 t_2 v_3\}$ 
```

```
Out[*]:=  $\{v_1, v_2, t_2 v_1 - t_1 t_2 v_1 + v_2 - t_2 v_2 + t_1 t_2 v_3\}$ 
```

$$\text{In}[*]:= (\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} // \mathbf{G}_{1,2} // \tau_{1,2} // \tau_{2,3} // \tau_{1,2}) - (\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} // \tau_{2,3} // \tau_{1,2} // \mathbf{G}_{2,3} // \tau_{2,3})$$

$$\text{Out}[*]:= \{0, 0, 0\}$$

$$\text{In}[*]:= (\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} // \mathbf{G}_{1,2} // \tau_{2,3} // \tau_{1,2}) - (\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} // \tau_{2,3} // \tau_{1,2} // \mathbf{G}_{2,3})$$

$$\text{Out}[*]:= \{0, 0, 0\}$$

The Turbo-Gassner Representation

TG

$$\begin{aligned} \text{In}[*]:= \text{TG}_{i,j}[\xi] &:= \xi /. \{ \\ &\mathbf{v}_{k_} \rightarrow \mathbf{v}_k + \delta_{k,j} \left((\mathbf{t}_i - 1) (\mathbf{v}_j - \mathbf{v}_i) + \mathbf{v}_{i,j} - \mathbf{v}_{i,i} \right) + \delta_{k,i} (\mathbf{u}_j - \mathbf{u}_i) \mathbf{u}_i \mathbf{w}_j, \\ &\mathbf{v}_{l,k} \rightarrow \mathbf{v}_{l,k} + (\mathbf{t}_i - 1) \times \\ &\quad \left(\delta_{k,j} (\mathbf{v}_{l,j} - \mathbf{v}_{l,i}) + (\delta_{l,i} - \delta_{l,j} \mathbf{t}_i^{-1} \mathbf{t}_j) (\mathbf{u}_k + \delta_{k,j} (\mathbf{t}_i - 1) (\mathbf{u}_j - \mathbf{u}_i)) \mathbf{u}_i \mathbf{w}_j \right), \\ &\mathbf{u}_{k_} \rightarrow \mathbf{u}_k + \delta_{k,j} (\mathbf{t}_i - 1) (\mathbf{u}_j - \mathbf{u}_i), \\ &\mathbf{w}_{k_} \rightarrow \mathbf{w}_k + (\delta_{k,j} - \delta_{k,i}) (\mathbf{t}_i^{-1} - 1) \mathbf{w}_j \} // \text{Expand} \end{aligned}$$

TG

$$\begin{aligned} \text{In}[*]:= \text{bas3} &= \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_{1,1}, \mathbf{v}_{1,2}, \mathbf{v}_{1,3}, \mathbf{v}_{2,1}, \mathbf{v}_{2,2}, \mathbf{v}_{2,3}, \mathbf{v}_{3,1}, \\ &\mathbf{v}_{3,2}, \mathbf{v}_{3,3}, \mathbf{u}_1^2 \mathbf{w}_1, \mathbf{u}_1^2 \mathbf{w}_2, \mathbf{u}_1^2 \mathbf{w}_3, \mathbf{u}_1 \mathbf{u}_2 \mathbf{w}_1, \mathbf{u}_1 \mathbf{u}_2 \mathbf{w}_2, \mathbf{u}_1 \mathbf{u}_2 \mathbf{w}_3, \mathbf{u}_1 \mathbf{u}_3 \mathbf{w}_1, \mathbf{u}_1 \mathbf{u}_3 \mathbf{w}_2, \\ &\mathbf{u}_1 \mathbf{u}_3 \mathbf{w}_3, \mathbf{u}_2^2 \mathbf{w}_1, \mathbf{u}_2^2 \mathbf{w}_2, \mathbf{u}_2^2 \mathbf{w}_3, \mathbf{u}_2 \mathbf{u}_3 \mathbf{w}_1, \mathbf{u}_2 \mathbf{u}_3 \mathbf{w}_2, \mathbf{u}_2 \mathbf{u}_3 \mathbf{w}_3, \mathbf{u}_3^2 \mathbf{w}_1, \mathbf{u}_3^2 \mathbf{w}_2, \mathbf{u}_3^2 \mathbf{w}_3\}; \\ (\text{bas3} // \text{TG}_{1,2} // \text{TG}_{1,3} // \text{TG}_{2,3}) &= (\text{bas3} // \text{TG}_{2,3} // \text{TG}_{1,3} // \text{TG}_{1,2}) \end{aligned}$$

TG

$$\text{Out}[*]:= \text{True}$$

$$\text{In}[*]:= (\text{bas3} // \text{TG}_{1,2} // \tau_{2,3} // \tau_{1,2}) = (\text{bas3} // \tau_{2,3} // \tau_{1,2} // \text{TG}_{2,3})$$

$$\text{Out}[*]:= \text{True}$$