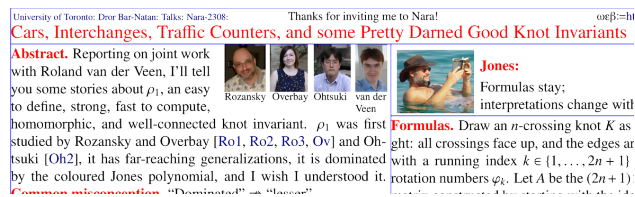


CARS, INTERCHANGES, TRAFFIC COUNTERS, AND SOME PRETTY DARNED GOOD KNOT INVARIANTS

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ABSTRACT. A condensed summary of a talk I gave in Nara on August 13, 2023: Reporting on joint work with Roland van der Veen, I'll tell you some stories about ρ_1 , an easy to define, strong, fast to compute, homomorphic, and well-connected knot invariant. ρ_1 was first studied by Rozansky and Overbay [Ro1, Ro2, Ro3, Ov] and Ohtsuki [Oh2], it has far-reaching generalizations, it is dominated by the coloured Jones polynomial, and I wish I understood it.

My talk's title and abstract were the same as the title and abstract of this summary. The talk used slides, and in this summary, they are shown on the right.




Those slides were all excerpts from a handout, which is attached at the end of this document. It is where the true content lies! It is also available on the web site of this talk, which is displayed on the next slide.



As an aside, I really believe in this way of giving talks, with slides and a handout. Slides are to save time and to allow for more elaborate figures. But slide talks without a handout are awful! Content disappears before it's been digested. A handout with identical content to the slides solves the problem – you can always look back to recall (and ahead, to decide how hard you want to fight sleep). But then the best way to make sure that the handout and the slides are fully synced is to have the slides simply be zoomed-in parts of the handout, and that's precisely what I do.

But it's a waste of so much paper, I hear you say. Yes, I say, but it's completely trivial relative to our travel to hear each other talk. Save where it matters. Where it's useful, spend.

Okay, it's all online, at <http://drorbn.net/na23>. There's also a paper, at drorbn.net/APAI.

<http://drorbn.net/na23>  **ants** More at drorbn.net/APAI

Thanks, NSERC and Arthur Chu!

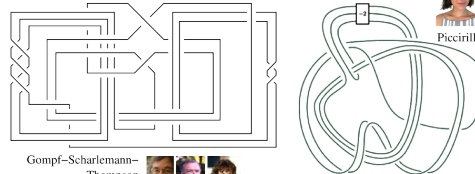
Acknowledgement. This work was supported by NSERC grant RGPIN-2018-04350 and by the Chu Family Foundation (NYC).

We seek strong, fast, and homomorphic invariants. Strong and fast are clear enough. Especially, we care for fast because of the likes of the GST48 knot [GST] and the Piccirillo knot [Pi]. Polynomial time is best!

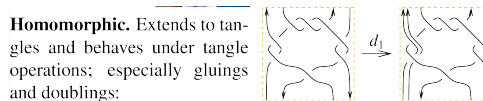
We seek strong, fast, homomorphic knot and tangle invariants.

Strong. Having a small “kernel”.

Fast. Computable even for large knots (best: poly time).

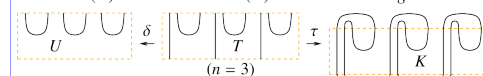


We then explained “homomorphic”. It means, “extends to tangles and is well behaved under tangle gluing and strand doubling”.



We care for “homomorphic” because using tangles and tangle operations we can define interesting classes of knots, and thus invariants that are homomorphic with respect to these operations may be able to tell us something about these classes. See ωεβ/AKT.

Why care for “Homomorphic”? **Theorem.** A knot K is ribbon iff there exists a $2n$ -component tangle T with skeleton as below such that $\tau(T) = K$ and where $\delta(T) = U$ is the *untangle*:



But enough with philosophy! I learned from Vaughan Jones that theories change with time, yet formulas stay. So let’s start with formulas!



Jones:

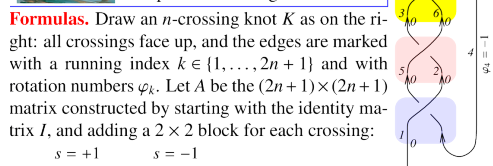
Formulas stay;
interpretations change with time.

To compute our knot invariant ρ_1 , we cut it to a long knot and place it in the plane so that at all vertices, all edges are “flowing up”. We then label each edge with serial number and with its rotation number φ_k .



Jones:

Formulas stay;
interpretations change with time.

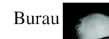


We make a $(2n+1) \times (2n+1)$ matrix A by starting with the identity matrix and adding a 2×2 block for each crossing, as shown on the right. We let $G = (g_{\alpha\beta})$ be the inverse of A .

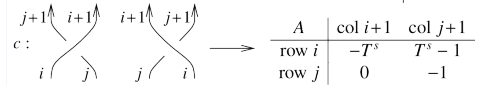
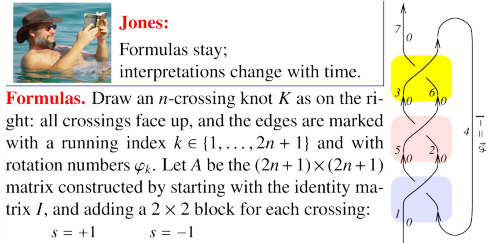
rotation numbers φ_k . Let A be the $(2n+1) \times (2n+1)$ matrix constructed by starting with the identity matrix I , and adding a 2×2 block for each crossing:

$$c : \begin{array}{cc} \begin{array}{c} s = +1 \\ j+1 \uparrow \quad i+1 \uparrow \\ \diagdown \quad \diagup \\ i \quad j \end{array} & \begin{array}{c} s = -1 \\ i+1 \uparrow \quad j+1 \uparrow \\ \diagdown \quad \diagup \\ j \quad i \end{array} \end{array} \longrightarrow \begin{array}{c|cc} A & \text{col } i+1 & \text{col } j+1 \\ \text{row } i & -T^s & T^s - 1 \\ \text{row } j & 0 & -1 \end{array}$$

Let $G = (g_{\alpha\beta}) = A^{-1}$. For the trefoil example, it is:



If we start from the trefoil knot diagram displayed before, the resulting A is shown on the right.



Let $G = (g_{\alpha\beta}) = A^{-1}$. For the trefoil example, it is:

$$A = \begin{pmatrix} 1 & -T & 0 & 0 & T-1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -T & 0 & 0 & T-1 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & T-1 & 0 & 1 & -T & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$



And now the corresponding G , the “Green Function”, is shown.

$$G = \begin{pmatrix} 1 & T & 1 & T & 1 & T & 1 \\ 0 & 1 & \frac{1}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T^2}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T^2}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1-T}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{T-T+1}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1-T}{T^2-T+1} & \frac{(T-1)T}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{T}{T^2-T+1} & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

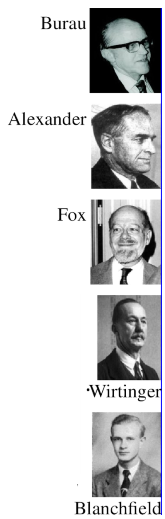
“The Green Function”

Note. The Alexander polynomial Δ is given by $\Delta = T^{(-\varphi-w)/2} \det(A)$, with $\varphi = \sum_k \varphi_k$, $w = \sum_c s_c$.

Classical Topologists: This is boring. Yawn.

We noted that $\det(A)$ is (up to a normalization) the good old Alexander polynomial. If you are a classical topologist, you should yawn and perhaps fall asleep right now, for so far everything is very old material.

The 2×2 matrices are the Burau matrices. The matrix A is a presentation matrix of the Alexander module, derived by applying Fox calculus to the Wirtinger presentation. Even G is not a great surprise; it is related to the “Blanchfield Pairing”. All of these people are old timers, so much so that their pictures are in black and white.



All the news is in just one slide, the one on the right! We defined $R_1(c)$ and ρ_1 , explained why ρ_1 is easy to compute (as easy as the Alexander polynomial), and asserted that it is invariant (to be proven below). If you are a classical topologist, these formulas should come as a complete surprise to you.

These days I take what I learned from Vaughan Jones a step further. I care for programs even more than I care for formulas.

We load some libraries that play a mild role: just tables of knots, and some older invariants for comparison, and a program to compute rotation numbers (something we could have done by hand).

Next is the main part of the program. It is almost one-to-one the same as the formulas for ρ_1 , and if there's ever a disagreement, the program is to be trusted better because it's been tested extensively. Note that the program outputs the ordered pair $Z = (\Delta, \rho_1)$, because Δ is computed anyway within the computation of ρ_1 , and we consider it as a part of ρ_1 .

We run the program on all knots with up to 6 crossings.

Formulas, continued. Finally, set

$$R_1(c) := s(g_{ji}(g_{j+1,j} + g_{j,j+1} - g_{ij}) - g_{ii}(g_{j,j+1} - 1) - 1/2)$$

$$\rho_1 := \Delta^2 \left(\sum_c R_1(c) - \sum_k \varphi_k (g_{kk} - 1/2) \right).$$

In our example $\rho_1 = -T^2 + 2T - 2 + 2T^{-1} - T^{-2}$.

Theorem. ρ_1 is a knot invariant.

Proof: later.

Classical Topologists: Whiskey Tango Foxtrot?



Jones:

Formulas stay; interpretations change with time.

Preliminaries

This is Rho.nb of <http://drorbn.net/oa22/ap>.

Once [`<< KnotTheory``; `<< Rot.m`];

Loading KnotTheory` version

of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/1a22/ap>

to compute rotation numbers.

The Program

```
R1[s_, i_, j_] :=
  s (g_{ji} (g_{j+,j} + g_{j,j+} - g_{ij}) - g_{ii} (g_{j,j+} - 1) - 1/2);
Z[K_] := Module[{Cs, phi, n, A, s, i, j, k, Delta, G, rho1},
  {Cs, phi} = Rot[K]; n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  Cases[Cs, {s_, i_, j_} ->
    (A[[{i, j}, {i + 1, j + 1}] += ( -T^s T^s - 1 ) )];
  Delta = T^(-Total[phi] - Total[Cs[[All, 1]])/2) Det[A];
  G = Inverse[A];
  rho1 = Sum_{k=1}^n R1 @@ Cs[[k]] - Sum_{k=1}^{2n} phi[[k]] (g_{kk} - 1/2);
  Factor@
  {Delta, Delta^2 rho1 /. alpha_+ -> alpha + 1 /. g_{alpha, beta} -> G[[alpha, beta]]};
```

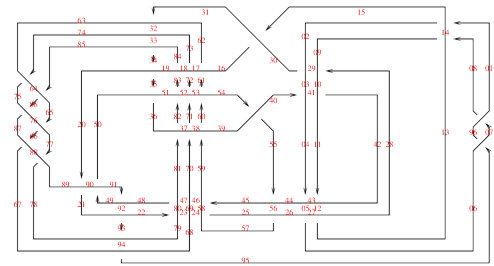
The First Few Knots

```
TableForm[Table[Join[{K[[1]]K[[2]]}, Z[K]],
  {K, AllKnots[{3, 6]}], TableAlignments -> Center]
```

3 ₁	$\frac{1-T+T^2}{T}$	$\frac{(-1+T)^2(1+T^2)}{T^2}$
4 ₁	$-\frac{1-3T+T^2}{T}$	0
5 ₁	$\frac{1-T+T^2-T^3+T^4}{T^2}$	$\frac{(-1+T)^2(1+T^2)(2+T^2+2T^4)}{T^4}$
5 ₂	$\frac{2-3T+2T^2}{T}$	$\frac{(-1+T)^2(5-4T+5T^2)}{T^2}$
6 ₁	$-\frac{(-2+T)(-1+2T)}{T}$	$\frac{(-1+T)^2(1-4T+T^2)}{T^2}$
6 ₂	$-\frac{1-3T+3T^2-3T^3+T^4}{T^2}$	$\frac{(-1+T)^2(1-4T+4T^2-4T^3+4T^4-4T^5+T^6)}{T^4}$
6 ₃	$\frac{1-3T+5T^2-3T^3+T^4}{T^2}$	0

The program is fast! Here is the GST48 knot once again,...

Fast!



and it takes only about 170 seconds to compute its ρ_1 .

Timing@

```
Z[GST48 = EPD[X14,1, X2,29, X3,40, X43,4, X26,5, X6,95,
X96,7, X13,8, X9,28, X10,41, X42,11, X27,12, X30,15,
X16,61, X17,72, X18,83, X19,34, X89,20, X21,92,
X79,22, X68,23, X57,24, X25,56, X62,31, X73,32,
X84,33, X50,35, X36,81, X37,70, X38,59, X39,54, X44,55,
X58,45, X69,46, X80,47, X48,91, X90,49, X51,82, X52,71,
X53,60, X63,74, X64,85, X76,65, X87,66, X67,94,
X75,86, X88,77, X78,93]]
{170.313, {-1/16 (-1 + 2 T - T^2 - T^3 + 2 T^4 - T^5 + T^8)
(-1 + T^3 - 2 T^4 + T^5 + T^6 - 2 T^7 + T^8), 1/16
(-1 + T)^2 (5 - 18 T + 33 T^2 - 32 T^3 + 2 T^4 + 42 T^5 - 62 T^6 -
8 T^7 + 166 T^8 - 242 T^9 + 108 T^10 + 132 T^11 - 226 T^12 +
148 T^13 - 11 T^14 - 36 T^15 - 11 T^16 + 148 T^17 - 226 T^18 +
132 T^19 + 108 T^20 - 242 T^21 + 166 T^22 - 8 T^23 - 62 T^24 +
42 T^25 + 2 T^26 - 32 T^27 + 33 T^28 - 18 T^29 + 5 T^30)}}}
```

$Z = (\Delta, \rho_1)$ is strong! It seems that it is stronger than HOMFLY-PT and Khovanov homology taken together.

Strong!

```
{NumberOfKnots[{3, 12}],
Length@
Union@Table[Z[K], {K, AllKnots[{3, 12]}]},
Length@
Union@Table[{HOMFLYPT[K], Kh[K]},
{K, AllKnots[{3, 12]}]}]}
{2977, 2882, 2785}
```

So the pair (Δ, ρ_1) attains 2,882 distinct values on the 2,977 prime knots with up to 12 crossings (a deficit of 95), whereas the pair (HOMFLYPT, Khovanov Homology) attains only 2,785 distinct values on the same knots (a deficit of 192).



On to interpretations, we discussed the traffic rules for cars on a knot diagram. All car crashes we discuss are gentle and no harm is ever caused to the occupants of our cars.

Cars, Interchanges, and Traffic Counters. Cars always drive forward. When a car crosses over a bridge it goes through with (algebraic) probability $T^s \sim 1$, but falls off with probability $1 - T^s \sim 0^*$. At the very end, cars fall off and disappear. See also [Jo, LTW].

$p = 1 - T^s$

* In algebra $x \sim 0$ if for every y in the ideal generated by x , $1 - y$ is invertible.

image credits: diamondtraffic.com, image credits: Dai-E

A relevant scene with Lightning McQueen, enacted by Roland's kids.



$$\rho = 1 - T^3$$

We claim that the matrix G of before is the traffic matrix for a knot diagram. Yet first we illustrate the traffic matrix using a very simple knot diagram (a single kink), and some simple-minded geometric summation.

Theorem. The Green function $g_{\alpha\beta}$ is the reading of a traffic counter at β , if car traffic is injected at α (if $\alpha = \beta$, the counter is *after* the injection point).

Example.

$$\sum_{p \geq 0} (1-T)^p = T^{-1} \quad T^{-1} \quad 0 \quad 1 \quad G = \begin{pmatrix} 1 & T^{-1} & 1 \\ 0 & T^{-1} & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

We then used “ g -rules” to prove the claim. These are rules that tell us how to move the traffic injection sites and the traffic counting sites, and they will also be useful below, within the actual proof of invariance.

Proof. Near a crossing c with sign s , incoming upper edge i and incoming lower edge j , both sides satisfy the g -rules:

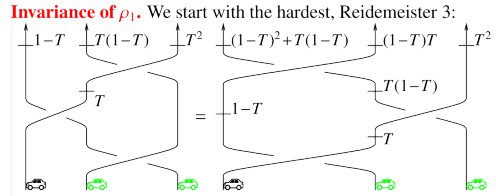
$$g_{j\beta} = \delta_{j\beta} + T^s g_{i+1,\beta} + (1-T^s) g_{j+1,\beta}, \quad g_{i\beta} = \delta_{i\beta} + g_{j+1,\beta}$$

and always, $g_{\alpha, 2n+1} = 1$: use common sense and $AG = I (= GA)$.

Bonus. Near c , both sides satisfy the further g -rules:

$$g_{\alpha i} = T^{-s}(g_{\alpha, i+1} - \delta_{\alpha, i+1}), \quad g_{\alpha j} = g_{\alpha, j+1} - (1-T^s)g_{\alpha i} - \delta_{\alpha, j+1}.$$

On to the invariance under the hardest of the Reidemeister moves, Reid3. We first establish that traffic away from the Reid3 site is not affected by the move. This is essentially the invariance of the Burau representation.



It follows that we only need to understand the contribution of the $R_1(c)$ terms from the crossings within the Reid3 area.

\Rightarrow Overall traffic patterns are unaffected by Reid3!
 \Rightarrow Green's $g_{\alpha\beta}$ is unchanged by Reid3, provided the cars injection site α and the traffic counters β are away.
 \Rightarrow Only the contribution from the R_1 terms within the Reid3 move matters, and using g -rules the relevant $g_{\alpha\beta}$'s can be pushed outside of the Reid3 area:

We could have done it by hand, but we are lazy and we have good computer skills. So we type in the g -rules, the three R_1 contributions for the left hand side of Reid3 and the three R_1 contributions for the right hand side. We then apply the g -rules to move the traffic injection sites and the traffic counting sites to outside of the Reid3-move area, to where they are unchanged by the move. Comparing lhs with rhs, the computer says True, which means that ρ_1 is invariant under Reid3.

\Rightarrow Only the contribution from the R_1 terms within the Reid3 move matters, and using g -rules the relevant $g_{\alpha\beta}$'s can be pushed outside of the Reid3 area:

$$\delta_{i, j_-} := \text{If}[i == j, 1, 0];$$

$$\mathbf{gRules}_{s, i, j_-} :=$$

$$\{ \mathbf{g}_{i, \beta_-} \mapsto \delta_{i, \beta} + T^s \mathbf{g}_{i^+, \beta} + (1-T^s) \mathbf{g}_{j^+, \beta}, \mathbf{g}_{j, \beta_-} \mapsto \delta_{j, \beta} + \mathbf{g}_{j^+, \beta},$$

$$\mathbf{g}_{\alpha, i} \mapsto T^{-s} (\mathbf{g}_{\alpha, i^+} - \delta_{\alpha, i^+}),$$

$$\mathbf{g}_{\alpha, j} \mapsto \mathbf{g}_{\alpha, j^+} - (1-T^s) \mathbf{g}_{\alpha i} - \delta_{\alpha, j^+} \}$$

$$\text{lhs} = R_1[1, j, k] + R_1[1, i, k^*] + R_1[1, i^*, j^*] //.$$

$$\mathbf{gRules}_{1, j, k} \cup \mathbf{gRules}_{1, i, k^*} \cup \mathbf{gRules}_{1, i^*, j^*};$$

$$\text{rhs} = R_1[1, i, j] + R_1[1, i^*, k] + R_1[1, j^*, k^*] //.$$

$$\mathbf{gRules}_{1, i, j} \cup \mathbf{gRules}_{1, i^*, k} \cup \mathbf{gRules}_{1, j^*, k^*};$$

$$\text{Simplify}[\text{lhs} == \text{rhs}]$$

True

As a second example we verify invariance under Reid1. Most of the work had already been done, because we computed already the “traffic matrix” of a kink. What remains is a little calculation (without forgetting the rotation-number correction!). We do that calculation on the right, using a hybrid of computer and human power (very little of each). A few further

Next comes Reid1, where we use results from an earlier example:

$$R_1[1, 2, 1] - 1 (\mathbf{g}_{22} - 1/2) /. \mathbf{g}_{\alpha, \beta_-} \mapsto \begin{pmatrix} 1 & T^{-1} & 1 \\ 0 & T^{-1} & 1 \\ 0 & 0 & 1 \end{pmatrix} [\alpha, \beta]$$

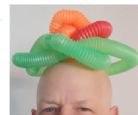
$$\frac{1}{T^2} - \frac{1}{T} - \frac{-1 + \frac{1}{T}}{T} = 0$$

Invariance under the other moves is proven similarly.

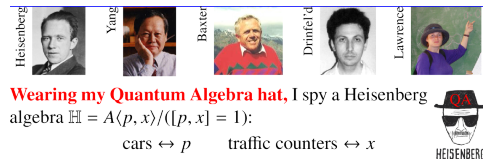
moves need to be shown — they are discussed at [ωεβ/APAI](#). This concludes the invariance proof for ρ_1 .

This slide ought to be shown bigger. Wearing my topology hat, I genuinely, honestly, don't know what's going on.

Wearing my Topology hat the formula for R_1 , and even the idea to look for R_1 , remain a complete mystery to me.



Unfortunately, at this point we had to rush towards the end, and be brief. Wearing my quantum algebra hat, the first thing to note is that there is a whiff of a Heisenberg relation in car traffic — a difference of 1 between the traffic counting before and after the place where traffic is injected, and that may remind us of the Heisenberg commutation relation, $[p, x] = 1$.



I have gone through the remaining few slides way too quickly. Here I will let them speak for themselves. The main things to learn from these reproduced slides are the references cited in them, and the comments in red.

Where did it come from? Consider $\mathfrak{g}_\epsilon := sl_{2+}^\epsilon := L\langle y, b, a, x \rangle$ with relations

$$[b, x] = \epsilon x, \quad [b, y] = -\epsilon y, \quad [b, a] = 0,$$

$$[a, x] = x, \quad [a, y] = -y, \quad [x, y] = b + \epsilon a.$$

At invertible ϵ , it is isomorphic to sl_2 plus a central factor, and it can be quantized à la Drinfel'd [Dr] much like sl_2 to get an algebra $QU = A\langle y, b, a, x \rangle$ subject to (with $q = e^{\hbar\epsilon}$):

$$[b, a] = 0, \quad [b, x] = \epsilon x, \quad [b, y] = -\epsilon y,$$

$$[a, x] = x, \quad [a, y] = -y,$$

$$xy - qyx = \frac{1 - e^{-\hbar(b+\epsilon a)}}{\hbar}.$$

Now QU has an R -matrix solving Yang-Baxter (meaning Reid3),

$$R = \sum_{m,n \geq 0} \frac{y^n b^m \otimes (\hbar a)^m (\hbar x)^n}{m! [n]_q!},$$

($[n]_q!$ is a “quantum factorial”)

and so it has an associated “universal quantum invariant” à la Lawrence and Ohtsuki [La, Oh1], $Z_\epsilon(K) \in QU$.

Now $QU \cong \mathcal{U}(\mathfrak{g}_\epsilon)$ (only as algebras!) and $\mathcal{U}(\mathfrak{g}_\epsilon)$ represents into \mathbb{H} via

$$y \rightarrow -tp - \epsilon \cdot xp^2, \quad b \rightarrow t + \epsilon \cdot xp,$$

$$a \rightarrow xp, \quad x \rightarrow x,$$

(abstractly, \mathfrak{g}_ϵ acts on its Verma module

$$\mathcal{U}(\mathfrak{g}_\epsilon) / (\mathcal{U}(\mathfrak{g}_\epsilon) \langle y, a, b - \epsilon a - t \rangle) \cong \mathbb{Q}[x]$$

by differential operators, namely via \mathbb{H}), so R can be pushed to $\mathcal{R} \in \mathbb{H} \otimes \mathbb{H}$.

Everything still makes sense at $\epsilon = 0$ and can be expanded near $\epsilon = 0$ resulting with $\mathcal{R} = \mathcal{R}_0(1 + \epsilon \mathcal{R}_1 + \dots)$, with $\mathcal{R}_0 = e^{t(xp \otimes 1 - x \otimes p)}$ and \mathcal{R}_1 a quartic polynomial in p and x . So p 's and x 's get created along K and need to be pushed around to a standard location (“normal ordering”). This is done using

$$(p \otimes 1) \mathcal{R}_0 = \mathcal{R}_0(T(p \otimes 1) + (1 - T)(1 \otimes p)),$$

$$(1 \otimes p) \mathcal{R}_0 = \mathcal{R}_0(1 \otimes p),$$

and when the dust settles, we get our formulas for ρ_1 . But QU is a quasi-triangular Hopf algebra, and hence ρ_1 is **homomorphic**. Read more at [BV1, BV2] and hear more at [ωεβ/SolvApp](#), [ωεβ/Dogma](#), [ωεβ/DoPeGDO](#), [ωεβ/FDA](#), [ωεβ/AQDW](#).

Also, we can (and know how to) look at higher powers of ϵ and we can (and more or less know how to) replace sl_2 by arbitrary semi-simple Lie algebra (e.g., [Sch]). So **ρ_1 is not alone!**



Schaveling

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- [Ro1] L. Rozansky, *A Contribution of the Trivial Flat Connection to the Jones Polynomial and Witten’s Invariant of 3D Manifolds, I*, *Comm. Math. Phys.* **175-2** (1996) 275–296, [arXiv:hep-th/9401061](#).
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- [Ro3] L. Rozansky, *A Universal U(1)-RCC Invariant of Links and Rationality Conjecture*, [arXiv:math/0201139](#).
- [Sch] S. Schaveling, *Expansions of Quantum Group Invariants*, Ph.D. thesis, Universiteit Leiden, September 2020, [ωεβ/Scha](#).

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Cars, Interchanges, Traffic Counters, and some Pretty Darned Good Knot Invariants

More at ωεβ/APAI

Abstract. Reporting on joint work with Roland van der Veen, I'll tell you some stories about ρ_1 , an easy to define, strong, fast to compute,



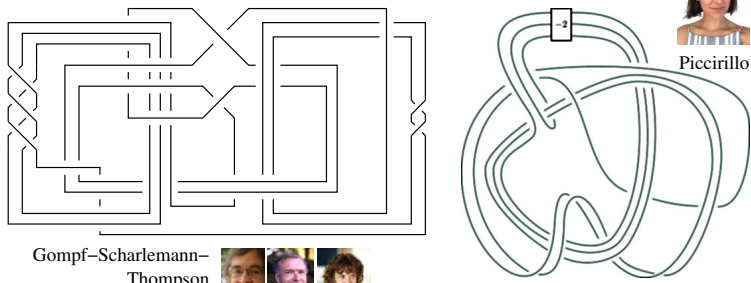
homomorphic, and well-connected knot invariant. ρ_1 was first studied by Rozansky and Overbay [Ro1, Ro2, Ro3, Ov] and Ohtsuki [Oh2], it has far-reaching generalizations, it is dominated by the coloured Jones polynomial, and I wish I understood it.

Common misconception. "Dominated" \Rightarrow "lesser".

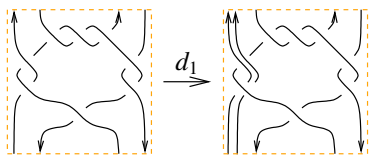
We seek strong, fast, homomorphic knot and tangle invariants.

Strong. Having a small "kernel".

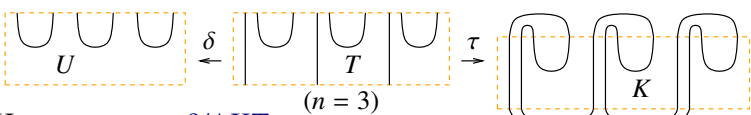
Fast. Computable even for large knots (best: poly time).



Homomorphic. Extends to tangles and behaves under tangle operations; especially gluings and doublings:



Why care for "Homomorphic"? **Theorem.** A knot K is ribbon iff there exists a $2n$ -component tangle T with skeleton as below such that $\tau(T) = K$ and where $\delta(T) = U$ is the untangle:



Hear more at ωεβ/AKT.

Acknowledgement. This work was supported by NSERC grant RGPIN-2018-04350 and by the Chu Family Foundation (NYC).

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[Sch] S. Schaveling, *Expansions of Quantum Group Invariants*, Ph.D. thesis, Universiteit Leiden, September 2020, ωεβ/Scha.

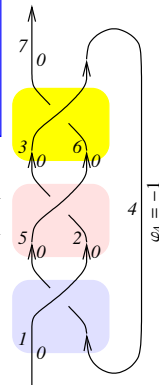
References.



Jones:

Formulas stay; interpretations change with time.

Formulas. Draw an n -crossing knot K as on the right: all crossings face up, and the edges are marked with a running index $k \in \{1, \dots, 2n + 1\}$ and with rotation numbers φ_k . Let A be the $(2n + 1) \times (2n + 1)$ matrix constructed by starting with the identity matrix I , and adding a 2×2 block for each crossing:



$$c : \begin{matrix} s = +1 & s = -1 \\ \begin{matrix} j+1 \uparrow & i+1 \uparrow \\ i & j \end{matrix} & \begin{matrix} i+1 \uparrow & j+1 \uparrow \\ j & i \end{matrix} \end{matrix} \longrightarrow \begin{matrix} A & \text{col } i+1 & \text{col } j+1 \\ \text{row } i & -T^s & T^s - 1 \\ \text{row } j & 0 & -1 \end{matrix}$$

Let $G = (g_{\alpha\beta}) = A^{-1}$. For the trefoil example, it is:

$$A = \begin{pmatrix} 1 & -T & 0 & 0 & T-1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -T & 0 & 0 & T-1 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & T-1 & 0 & 1 & -T & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix},$$

$$G = \begin{pmatrix} 1 & T & 1 & T & 1 & T & 1 \\ 0 & 1 & \frac{1}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T}{T^2-T+1} & \frac{T^2}{T^2-T+1} & 1 \\ 0 & 0 & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & 1 \\ 0 & 0 & \frac{T^2-T+1}{1-T} & \frac{T^2-T+1}{1-T} & \frac{T^2-T+1}{1-T} & \frac{T^2-T+1}{1-T} & 1 \\ 0 & 0 & \frac{1-T}{T^2-T+1} & -\frac{(T-1)T}{T^2-T+1} & \frac{1}{T^2-T+1} & \frac{1}{T^2-T+1} & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

"The Green Function"

Note. The Alexander polynomial Δ is given by

$$\Delta = T^{-(\varphi-w)/2} \det(A), \quad \text{with } \varphi = \sum_k \varphi_k, \quad w = \sum_c s.$$

Classical Topologists: This is boring. Yawn.

Formulas, continued. Finally, set

$$R_1(c) := s(g_{ji}(g_{j+1,j} + g_{j,j+1} - g_{ij}) - g_{ii}(g_{j,j+1} - 1) - 1/2)$$

$$\rho_1 := \Delta^2 \left(\sum_c R_1(c) - \sum_k \varphi_k (g_{kk} - 1/2) \right).$$

In our example $\rho_1 = -T^2 + 2T - 2 + 2T^{-1} - T^{-2}$.

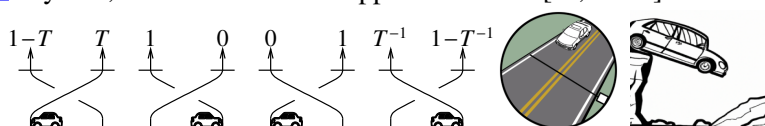
Theorem. ρ_1 is a knot invariant.

Proof: later.

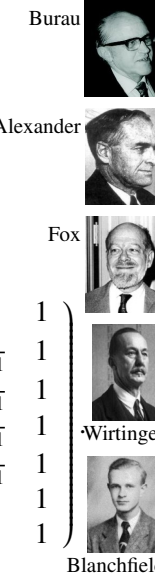
Classical Topologists: Whiskey Tango Foxtrot?

Cars, Interchanges, and Traffic Counters.

Cars always drive forward. When a car crosses over a bridge it goes through with (algebraic) probability $T^s \sim 1$, but falls off with probability $1 - T^s \sim 0^*$. At the very end, cars fall off and disappear. See also [Jo, LTW].



$p = 1 - T^s$
* In algebra $x \sim 0$ if for every y in the ideal generated by x , $1 - y$ is invertible.



Preliminaries

This is Rho.nb of <http://drorbn.net/oa22/ap>.

Once [`<< KnotTheory``; `<< Rot.m`];

Loading KnotTheory` version

of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/la22/ap>

to compute rotation numbers.

The Program

```
R1[s_, i_, j_] :=
  S (g_{ji} (g_{j^+, j} + g_{j, j^+} - g_{ij}) - g_{ii} (g_{j, j^+} - 1) - 1/2);
Z[K_] := Module[{Cs, phi, n, A, s, i, j, k, Delta, G, rho1},
  {Cs, phi} = Rot[K]; n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  Cases[Cs, {s_, i_, j_} ->
    (A[[{i, j}, {i + 1, j + 1}] + = ( -T^s T^s - 1 ) )];
  Delta = T^(-Total[phi] - Total[Cs[[All, 1]])/2) Det[A];
  G = Inverse[A];
  rho1 = Sum_{k=1}^n R1 @@ Cs[[k]] - Sum_{k=1}^{2n} phi[[k]] (g_{kk} - 1/2);
  Factor@
    {Delta, Delta^2 rho1 /. alpha_+ -> alpha + 1 /. g_{alpha, beta} -> G[[alpha, beta]]};
```

The First Few Knots

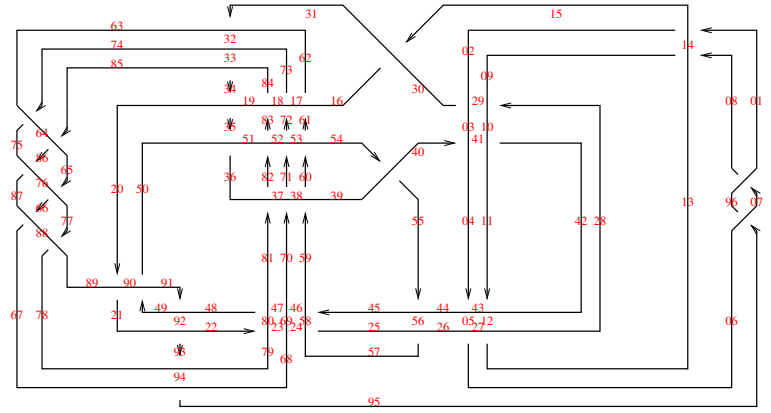
```
TableForm[Table[Join[{K[[1]]_k[[2]]}, Z[K]],
  {K, AllKnots[{3, 6]}}, TableAlignments -> Center]
```

3 ₁	$\frac{1-T+T^2}{T}$	$\frac{(-1+T)^2(1+T^2)}{T^2}$
4 ₁	$-\frac{1-3T+T^2}{T}$	0
5 ₁	$\frac{1-T+T^2-T^3+T^4}{T^2}$	$\frac{(-1+T)^2(1+T^2)(2+T^2+2T^4)}{T^4}$
5 ₂	$\frac{2-3T+2T^2}{T}$	$\frac{(-1+T)^2(5-4T+5T^2)}{T^2}$
6 ₁	$-\frac{(-2+T)(-1+2T)}{T}$	$\frac{(-1+T)^2(1-4T+T^2)}{T^2}$
6 ₂	$-\frac{1-3T+3T^2-3T^3+T^4}{T^2}$	$\frac{(-1+T)^2(1-4T+4T^2-4T^3+4T^4-4T^5+T^6)}{T^4}$
6 ₃	$\frac{1-3T+5T^2-3T^3+T^4}{T^2}$	0



$$p = 1 - T^s$$

Fast!



Timing@

```
Z[GST48 = EPD[X_{14,1}, X_{2,29}, X_{3,40}, X_{43,4}, X_{26,5}, X_{6,95},
  X_{96,7}, X_{13,8}, X_{9,28}, X_{10,41}, X_{42,11}, X_{27,12}, X_{30,15},
  X_{16,61}, X_{17,72}, X_{18,83}, X_{19,34}, X_{89,20}, X_{21,92},
  X_{79,22}, X_{68,23}, X_{57,24}, X_{25,56}, X_{62,31}, X_{73,32},
  X_{84,33}, X_{50,35}, X_{36,81}, X_{37,70}, X_{38,59}, X_{39,54}, X_{44,55},
  X_{58,45}, X_{69,46}, X_{80,47}, X_{48,91}, X_{90,49}, X_{51,82}, X_{52,71},
  X_{53,60}, X_{63,74}, X_{64,85}, X_{76,65}, X_{87,66}, X_{67,94},
  X_{75,86}, X_{88,77}, X_{78,93}]]
```

$$\{170.313, \left\{ -\frac{1}{T^8} (-1 + 2T - T^2 - T^3 + 2T^4 - T^5 + T^8) \right.$$

$$\left. (-1 + T^3 - 2T^4 + T^5 + T^6 - 2T^7 + T^8) \right\}, \frac{1}{T^{16}}$$

$$(-1 + T)^2 (5 - 18T + 33T^2 - 32T^3 + 2T^4 + 42T^5 - 62T^6 - 8T^7 + 166T^8 - 242T^9 + 108T^{10} + 132T^{11} - 226T^{12} + 148T^{13} - 11T^{14} - 36T^{15} - 11T^{16} + 148T^{17} - 226T^{18} + 132T^{19} + 108T^{20} - 242T^{21} + 166T^{22} - 8T^{23} - 62T^{24} + 42T^{25} + 2T^{26} - 32T^{27} + 33T^{28} - 18T^{29} + 5T^{30}) \}$$

Strong!

```
{NumberOfKnots[{3, 12}],
```

```
Length@
```

```
Union@Table[Z[K], {K, AllKnots[{3, 12]}],
```

```
Length@
```

```
Union@Table[{HOMFLYPT[K], Kh[K]},
  {K, AllKnots[{3, 12]}]}}
```

```
{2977, 2882, 2785}
```

So the pair (Δ, ρ_1) attains 2,882 distinct values on the 2,977 prime knots with up to 12 crossings (a deficit of 95), whereas the pair (HOMFLYPT, Khovanov Homology) attains only 2,785 distinct values on the same knots (a deficit of 192).



Hoste

Ocneanu

Millett

Freyd

Lickorish

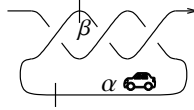
Yetter

Przytycki

Traczyk

Khovanov

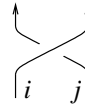
Theorem. The Green function $g_{\alpha\beta}$ is the reading of a traffic counter at β , if car traffic is injected at α (if $\alpha = \beta$, the counter is *after* the injection point).



Example.

$$\sum_{p \geq 0} (1-T)^p = T^{-1} \quad T^{-1} \quad 0 \quad 1 \quad 0 \quad 1 \quad 0 \quad 1 \quad G = \begin{pmatrix} 1 & T^{-1} & 1 \\ 0 & T^{-1} & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Proof. Near a crossing c with sign s , incoming upper edge i and incoming lower edge j , both sides satisfy the g -rules:



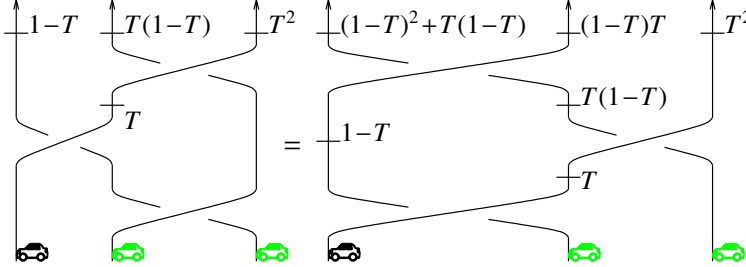
$$g_{i\beta} = \delta_{i\beta} + T^s g_{i+1,\beta} + (1-T^s) g_{j+1,\beta}, \quad g_{j\beta} = \delta_{j\beta} + g_{j+1,\beta},$$

and always, $g_{\alpha,2n+1} = 1$: use common sense and $AG = I (= GA)$.

Bonus. Near c , both sides satisfy the further g -rules:

$$g_{\alpha i} = T^{-s}(g_{\alpha,i+1} - \delta_{\alpha,i+1}), \quad g_{\alpha j} = g_{\alpha,j+1} - (1-T^s)g_{\alpha i} - \delta_{\alpha,j+1}.$$

Invariance of ρ_1 . We start with the hardest, Reidemeister 3:



⇒ Overall traffic patterns are unaffected by Reid3!
 ⇒ Green's $g_{\alpha\beta}$ is unchanged by Reid3, provided the cars injection site α and the traffic counters β are away.
 ⇒ Only the contribution from the R_1 terms within the Reid3 move matters, and using g -rules the relevant $g_{\alpha\beta}$'s can be pushed outside of the Reid3 area:

$\delta_{i,j} := \text{If}[i == j, 1, 0];$
 $gRules_{s,i,j} :=$

$$\{g_{i\beta} \mapsto \delta_{i\beta} + T^s g_{i+1,\beta} + (1-T^s) g_{j+1,\beta}, \quad g_{j\beta} \mapsto \delta_{j\beta} + g_{j+1,\beta},$$

$$g_{\alpha,i} \mapsto T^{-s}(g_{\alpha,i+1} - \delta_{\alpha,i+1}),$$

$$g_{\alpha,j} \mapsto g_{\alpha,j+1} - (1-T^s)g_{\alpha i} - \delta_{\alpha,j+1}\}$$

$lhs = R_1[1, j, k] + R_1[1, i, k^+] + R_1[1, i^+, j^+] // .$

$gRules_{1,j,k} \cup gRules_{1,i,k^+} \cup gRules_{1,i^+,j^+};$

$rhs = R_1[1, i, j] + R_1[1, i^+, k] + R_1[1, j^+, k^+] // .$

$gRules_{1,i,j} \cup gRules_{1,i^+,k} \cup gRules_{1,j^+,k^+};$

Simplify[lhs == rhs]

True

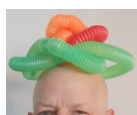
Next comes Reid1, where we use results from an earlier example:

$$R_1[1, 2, 1] - 1 (g_{22} - 1/2) /. g_{\alpha,\beta} \mapsto \begin{pmatrix} 1 & T^{-1} & 1 \\ 0 & T^{-1} & 1 \\ 0 & 0 & 1 \end{pmatrix} [[\alpha, \beta]]$$

$$\frac{1}{T^2} - \frac{1}{T} - \frac{-1 + \frac{1}{T}}{T} = 0$$

Invariance under the other moves is proven similarly.

Wearing my Topology hat the formula for R_1 , and even the idea to look for R_1 , remain a complete mystery to me.



Wearing my Quantum Algebra hat, I spy a Heisenberg algebra $\mathbb{H} = A\langle p, x \rangle / ([p, x] = 1)$:

$$\text{cars} \leftrightarrow p \quad \text{traffic counters} \leftrightarrow x$$

Where did it come from? Consider $g_\epsilon := sl_{2+}^\epsilon := L\langle y, b, a, x \rangle$ with relations

$$[b, x] = \epsilon x, \quad [b, y] = -\epsilon y, \quad [b, a] = 0,$$

$$[a, x] = x, \quad [a, y] = -y, \quad [x, y] = b + \epsilon a.$$

At invertible ϵ , it is isomorphic to sl_2 plus a central factor, and it can be quantized à la Drinfel'd [Dr] much like sl_2 to get an algebra $QU = A\langle y, b, a, x \rangle$ subject to (with $q = e^{\hbar\epsilon}$):

$$[b, a] = 0, \quad [b, x] = \epsilon x, \quad [b, y] = -\epsilon y,$$

$$[a, x] = x, \quad [a, y] = -y, \quad xy - qyx = \frac{1 - e^{-\hbar(b+\epsilon a)}}{\hbar}.$$

Now QU has an R -matrix solving Yang-Baxter (meaning Reid3),

$$R = \sum_{m,n \geq 0} \frac{y^m b^m \otimes (\hbar a)^m (\hbar x)^n}{m! [n]_q!}, \quad ([n]_q! \text{ is a "quantum factorial"})$$

and so it has an associated "universal quantum invariant" à la Lawrence and Ohtsuki [La, Oh1], $Z_\epsilon(K) \in QU$.

Now $QU \cong \mathcal{U}(g_\epsilon)$ (only as algebras!) and $\mathcal{U}(g_\epsilon)$ represents into \mathbb{H} via

$$y \rightarrow -tp - \epsilon \cdot xp^2, \quad b \rightarrow t + \epsilon \cdot xp, \quad a \rightarrow xp, \quad x \rightarrow x,$$

(abstractly, g_ϵ acts on its Verma module

$$\mathcal{U}(g_\epsilon) / (\mathcal{U}(g_\epsilon)\langle y, a, b - \epsilon a - t \rangle) \cong \mathbb{Q}[x]$$

by differential operators, namely via \mathbb{H}), so R can be pushed to $\mathcal{R} \in \mathbb{H} \otimes \mathbb{H}$.

Everything still makes sense at $\epsilon = 0$ and can be expanded near $\epsilon = 0$ resulting with $\mathcal{R} = \mathcal{R}_0(1 + \epsilon \mathcal{R}_1 + \dots)$, with $\mathcal{R}_0 = e^{t(xp \otimes 1 - x \otimes p)}$ and \mathcal{R}_1 a quartic polynomial in p and x . So p 's and x 's get created along K and need to be pushed around to a standard location ("normal ordering"). This is done using

$$(p \otimes 1)\mathcal{R}_0 = \mathcal{R}_0(T(p \otimes 1) + (1-T)(1 \otimes p)),$$

$$(1 \otimes p)\mathcal{R}_0 = \mathcal{R}_0(1 \otimes p),$$

and when the dust settles, we get our formulas for ρ_1 . But QU is a quasi-triangular Hopf algebra, and hence ρ_1 is **homomorphic**. Read more at [BV1, BV2] and hear more at $\omega\epsilon\beta/\text{SolvApp}$, $\omega\epsilon\beta/\text{Dogma}$, $\omega\epsilon\beta/\text{DoPeGDO}$, $\omega\epsilon\beta/\text{FDA}$, $\omega\epsilon\beta/\text{AQDW}$.

Also, we can (and know how to) look at higher powers of ϵ and we can (and more or less know how to) replace sl_2 by arbitrary semi-simple Lie algebra (e.g., [Sch]). So ρ_1 is **not alone!**



Schaveling

These constructions are very similar to Rozansky-Overbay [Ro1, Ro2, Ro3, Ov] and hence to the "loop expansion" of the Kontsevich integral and the coloured Jones polynomial [Oh2].

If this all reads like **insanity** to you, it should (and you haven't seen half of it). Simple things should have simple explanations.

Hence, **Homework**. Explain ρ_1 with no reference to quantum voodoo and find it a topology home (large enough to house generalizations!). Make explicit the homomorphic properties of ρ_1 . Use them to do topology!

P.S. As a friend of Δ , ρ_1 gives a genus bound, sometimes better than Δ 's. How much further does this friendship extend?

A Small-Print Page on $\rho_d, d > 1$.

Definition. $\langle f(z_i), h(\zeta_i) \rangle_{\{z_i\}} := f(\partial_{\zeta_i})h|_{\zeta_i=0}$, so $\langle p^2 x^2, \mathbb{e}^{g\pi\xi} \rangle = 2g^2$.

Baby Theorem. There exist (non unique) power series $r^\pm(p_1, p_2, x_1, x_2) = \sum_d \epsilon^d r_d^\pm(p_1, p_2, x_1, x_2) \in \mathbb{Q}[T^{\pm 1}, p_1, p_2, x_1, x_2][[\epsilon]]$ with $\deg r_d^\pm \leq 2d + 2$ ("docile") such that the power series $Z^b = \sum \rho_d \epsilon^d :=$

$$\left\langle \exp\left(\sum_c r^s(p_i, p_j, x_i, x_j)\right), \exp\left(\sum_{\alpha, \beta} g_{\alpha\beta} \pi_\alpha \xi_\beta\right) \right\rangle_{\{p_\alpha, x_\beta\}}$$

is a bnot invariant. Beyond the once-and-for-all computation of $g_{\alpha\beta}$ (a matrix inversion), Z^b is computable in $O(n^d)$ operations in the ring $\mathbb{Q}[T^{\pm 1}]$.

(Bnots are knot diagrams modulo the braid-like Reidemeister moves, but not the cyclic ones).

Theorem. There also exist docile power series $\gamma^\varphi(\bar{p}, \bar{x}) = \sum_d \epsilon^d \gamma_d^\varphi \in \mathbb{Q}[T^{\pm 1}, \bar{p}, \bar{x}][[\epsilon]]$ such that the power series $Z = \sum \rho_d \epsilon^d :=$

$$\left\langle \exp\left(\sum_c r^s(p_i, p_j, x_i, x_j) + \sum_k \gamma^{\varphi k}(\bar{p}_k, \bar{x}_k)\right), \exp\left(\sum_{\alpha, \beta} g_{\alpha\beta}(\pi_\alpha + \bar{\pi}_\alpha)(\xi_\beta + \bar{\xi}_\beta) + \sum_\alpha \pi_\alpha \bar{\xi}_\alpha\right) \right\rangle_{\{p_\alpha, \bar{p}_\alpha, x_\beta, \bar{x}_\beta\}}$$

is a knot invariant, as easily computable as Z^b .

Implementation. Data, then program (with output using the Conway variable $z = \sqrt{T} - 1 / \sqrt{T}$), and then a demo. See Rho.nb of $\omega\epsilon\beta/ap$.

```
V@r_{1,\varphi}[k_] := \varphi (1/2 - \bar{p}_k \bar{x}_k); V@r_{2,\varphi}[k_] := -\varphi^2 \bar{p}_k \bar{x}_k / 2;
V@r_{3,\varphi}[k_] := -\varphi^3 \bar{p}_k \bar{x}_k / 6
```

```
V@r_{1,s}[i_, j_] :=
s (-1 + 2 p_i x_i - 2 p_j x_j + (-1 + T^5) p_i p_j x_i^2 + (1 - T^5) p_j^2 x_i^2 - 2 p_i p_j x_i x_j + 2 p_j^2 x_i x_j) / 2
```

```
V@r_{2,1}[i_, j_] :=
(-6 p_i x_i + 6 p_j x_j - 3 (-1 + 3 T) p_i p_j x_i^2 + 3 (-1 + 3 T) p_j^2 x_i^2 + 4 (-1 + T) p_i^2 p_j x_i^3 -
2 (-1 + T) (5 + T) p_i p_j^2 x_i^3 + 2 (-1 + T) (3 + T) p_j^3 x_i^3 + 18 p_i p_j x_i x_j -
18 p_j^2 x_i x_j - 6 p_i^2 p_j x_i^2 x_j + 6 (2 + T) p_i p_j^2 x_i^2 x_j - 6 (1 + T) p_j^3 x_i^2 x_j -
6 p_i p_j^2 x_i x_j^2 + 6 p_j^3 x_i x_j^2) / 12
```

```
V@r_{2,-1}[i_, j_] :=
(-6 T^2 p_i x_i + 6 T^2 p_j x_j + 3 (-3 + T) T p_i p_j x_i^2 - 3 (-3 + T) T p_j^2 x_i^2 -
4 (-1 + T) T p_i^2 p_j x_i^3 + 2 (-1 + T) (1 + 5 T) p_i p_j^2 x_i^3 - 2 (-1 + T) (1 + 3 T) p_j^3 x_i^3 +
18 T^2 p_i p_j x_i x_j - 18 T^2 p_j^2 x_i x_j - 6 T^2 p_i^2 p_j x_i^2 x_j + 6 T (1 + 2 T) p_i p_j^2 x_i^2 x_j -
6 T (1 + T) p_j^3 x_i^2 x_j - 6 T^2 p_i p_j^2 x_i x_j^2 + 6 T^2 p_j^3 x_i x_j^2) / (12 T^2)
```

$Z_2[\text{GST48}]$ (* takes a few minutes *)

$$\{1 - 4 z^2 - 61 z^4 - 207 z^6 - 296 z^8 - 210 z^{10} - 77 z^{12} - 14 z^{14} - z^{16}, \\ 1 + (38 z^2 + 255 z^4 + 1696 z^6 + 16281 z^8 + 86952 z^{10} + 259994 z^{12} + 487372 z^{14} + 615066 z^{16} + 543148 z^{18} + 341714 z^{20} + \\ 153722 z^{22} + 48983 z^{24} + 10776 z^{26} + 1554 z^{28} + 132 z^{30} + 5 z^{32}) \epsilon + \\ (-8 - 484 z^2 + 9709 z^4 + 165952 z^6 + 1590491 z^8 + 16256508 z^{10} + 115341797 z^{12} + 432685748 z^{14} + 395838354 z^{16} - 4017557792 z^{18} - 23300064167 z^{20} - \\ 70082264972 z^{22} - 142572271191 z^{24} - 209475503700 z^{26} - 221616295209 z^{28} - 151502648428 z^{30} - 23700199243 z^{32} + \\ 99462146328 z^{34} + 164920463074 z^{36} + 162550825432 z^{38} + 119164552296 z^{40} + 69153062608 z^{42} + 32547596611 z^{44} + 12541195448 z^{46} + \\ 3961384155 z^{48} + 1021219696 z^{50} + 212773106 z^{52} + 35264208 z^{54} + 4537548 z^{56} + 436600 z^{58} + 29536 z^{60} + 1252 z^{62} + 25 z^{64}) \epsilon^2\}$$

$\text{TableForm}[\text{Table}[\text{Join}[\{\mathbb{K}[\{1\}, \mathbb{K}[\{2\}]\}], Z_3[\mathbb{K}], \{\mathbb{K}, \text{AllKnots}[\{3, 6\}]\}], \text{TableAlignments} \rightarrow \text{Center}]$ (* takes a few minutes *)

3_1	$1 + z^2$	$1 + (2z^2 + z^4) \epsilon + (2 - 4z^2 + 3z^4 + 4z^6 + z^8) \epsilon^2 + (-12 + 74z^2 - 27z^4 - 20z^6 + 8z^8 + 6z^{10} + z^{12}) \epsilon^3$
4_1	$1 - z^2$	$1 + (-2 - 2z^4) \epsilon^2$
5_1	$1 + 3z^2 + z^4$	$1 + (10z^2 + 21z^4 - 12z^6 + 2z^8) \epsilon + (6 - 28z^2 + 33z^4 + 364z^6 + 655z^8 + 536z^{10} + 227z^{12} + 48z^{14} + 4z^{16}) \epsilon^2 + (-60 - 970z^2 + 645z^4 - 3380z^6 - 3280z^8 - 7470z^{10} - 19475z^{12} + 20536z^{14} + 12564z^{16} + 4774z^{18} - 1109z^{20} - 144z^{22} + 8z^{24}) \epsilon^3$
5_2	$1 - 2z^2$	$1 + (6z^2 + 5z^4) \epsilon + (4 - 20z^2 + 43z^4 + 64z^6 + 26z^8) \epsilon^2 + (-36 + 498z^2 - 883z^4 + 100z^6 + 816z^8 + 556z^{10} + 146z^{12}) \epsilon^3$
6_1	$1 - 2z^2$	$1 + (-2z^2 + z^4) \epsilon + (-4 + 4z^2 + 25z^4 - 8z^6 + 2z^8) \epsilon^2 + (12 + 154z^2 - 223z^4 - 608z^6 + 100z^8 - 52z^{10} + 10z^{12}) \epsilon^3$
6_2	$1 - 2z^2 - z^4$	$1 + (-2z^2 - 3z^4 + 2z^6 + z^8) \epsilon + (-2 - 4z^2 + 29z^4 + 28z^6 + 42z^8 - 8z^{10} - 2z^{12} + 4z^{14} + z^{16}) \epsilon^2 + (12 + 166z^2 + 155z^4 - 194z^6 - 2453z^8 - 1622z^{10} - 1967z^{12} - 258z^{14} + 49z^{16} - 30z^{18} + z^{20} + 6z^{22} + 2z^{24}) \epsilon^3$
6_3	$1 + z^2 + z^4$	$1 + (2 + 8z^2 - 16z^4 - 24z^6 - 16z^8 - 2z^{10}) \epsilon^2$

```
V@r_{3,1}[i_, j_] :=
(4 p_i x_i - 4 p_j x_j + 2 (5 + 7 T) p_i p_j x_i^2 - 2 (5 + 7 T) p_j^2 x_i^2 - 4 (-5 + 6 T) p_i^2 p_j x_i^3 +
4 (-16 + 17 T + 2 T^2) p_i p_j^2 x_i^3 - 4 (-11 + 11 T + 2 T^2) p_j^3 x_i^3 + 3 (-1 + T) p_i^3 p_j x_i^4 -
3 (-1 + T) (4 + 3 T) p_i^2 p_j^2 x_i^4 + (-1 + T) (13 + 22 T + T^2) p_i p_j^3 x_i^4 -
(-1 + T) (4 + 13 T + T^2) p_j^4 x_i^4 - 28 p_i p_j x_i x_j + 28 p_j^2 x_i x_j + 36 p_i^2 p_j x_i^2 x_j -
12 (9 + 2 T) p_i p_j^2 x_i^2 x_j + 24 (3 + T) p_j^3 x_i^2 x_j - 4 p_i^3 p_j x_i^3 x_j + 28 T p_i^2 p_j^2 x_i^3 x_j -
4 (-6 + 17 T + T^2) p_i p_j^3 x_i^3 x_j + 4 (-5 + 10 T + T^2) p_j^4 x_i^3 x_j + 24 p_i p_j^3 x_i^2 x_j^2 -
24 p_j^4 x_i^2 x_j^2 - 24 p_i^2 p_j^2 x_i^2 x_j^2 + 6 (10 + T) p_i p_j^3 x_i^2 x_j^2 - 6 (6 + T) p_j^4 x_i^2 x_j^2 -
4 p_i p_j^3 x_i x_j^3 + 4 p_j^4 x_i x_j^3) / 24
```

```
V@r_{3,-1}[i_, j_] :=
(-4 T^3 p_i x_i + 4 T^3 p_j x_j - 2 T^2 (7 + 5 T) p_i p_j x_i^2 + 2 T^2 (7 + 5 T) p_j^2 x_i^2 -
4 T^2 (-6 + 5 T) p_i^2 p_j x_i^3 + 4 T (-2 - 17 T + 16 T^2) p_i p_j^2 x_i^3 -
4 T (-2 - 11 T + 11 T^2) p_j^3 x_i^3 + 3 (-1 + T) T^2 p_i^3 p_j x_i^4 - 3 (-1 + T) T (3 + 4 T) p_i^2 p_j^2 x_i^4 +
(-1 + T) (1 + 22 T + 13 T^2) p_i p_j^3 x_i^4 - (-1 + T) (1 + 13 T + 4 T^2) p_j^4 x_i^4 +
28 T^3 p_i p_j x_i x_j - 28 T^3 p_j^2 x_i x_j - 36 T^3 p_i^2 p_j x_i^2 x_j + 12 T^2 (2 + 9 T) p_i p_j^2 x_i^2 x_j -
24 T^2 (1 + 3 T) p_j^3 x_i^2 x_j + 4 T^3 p_i^3 p_j x_i^3 x_j - 28 T^2 p_i^2 p_j^2 x_i^3 x_j -
4 T (-1 - 17 T + 6 T^2) p_i p_j^3 x_i^3 x_j + 4 T (-1 - 10 T + 5 T^2) p_j^4 x_i^3 x_j -
24 T^3 p_i p_j^2 x_i x_j^2 + 24 T^3 p_j^3 x_i x_j^2 + 24 T^3 p_i^2 p_j^2 x_i^2 x_j^2 - 6 T^2 (1 + 10 T) p_i p_j^3 x_i^2 x_j^2 +
6 T^2 (1 + 6 T) p_j^4 x_i^2 x_j^2 + 4 T^3 p_i p_j^3 x_i x_j^3 - 4 T^3 p_j^4 x_i x_j^3) / (24 T^3)
```

```
{p*, x*, p-bar, x-bar} = {pi, xi, pi-bar, xi-bar}; (z-)_i := (z*)_i;
Zip_{i}[e_] := e;
Zip_{(z, z-bar)}[e_] :=
(Collect[e // Zip_{(z, z-bar)}[z] /. f_ . z^d_ -> {D[f, {z*, d}]}] /. z* -> 0
```

```
gPair[f_s_, w_] :=
gPair[f_s, w] =
Collect[ZipJoinTable[{p_alpha, p_bar_alpha, x_alpha, x_bar_alpha}, {alpha, w}][
(Times @@ (V / @ f_s))
Exp[Sum[g_alpha, beta (pi_alpha + pi_bar_alpha) (xi_beta + xi_bar_beta), {alpha, w}, {beta, w}] - Sum[xi_bar_alpha pi_alpha, {alpha, w}]]],
g_, Factor]
```

```
T2z[p_] := Module[{q = Expand[p], n, c},
If[q === 0, 0, c = Coefficient[q, T, n = Exponent[q, T]];
c z^n + T2z[q - c (T^{1/2} - T^{-1/2})^2 n]];]
```

```
Z_u[K_] := Module[{CS, phi, n, A, s, i, j, k, Delta, G, d1, Z1, Z2, Z3},
{CS, phi} = Rot[K]; n = Length[CS]; A = IdentityMatrix[2 n + 1];
Cases[CS, {s_, i_, j_} -> {A[[{i, j}], {i + 1, j + 1}]} + (-T^s T^j - 1)];
{Delta, G} = Factor@{T^{-Total[phi] - Total[CS[All, 1]]} / 2 Det@A, Inverse@A};
Z1 =
Exp[Total[Cases[CS, {s_, i_, j_} -> Sum[e^{d1} r_{d1, s}[i, j], {d1, d}]]] +
Sum[e^{d1} y_{d1, phi[[k]]}[k], {k, 2 n}, {d1, d}] /. y_u, 0] -> 0];
Z2 = Expand[F[{}], {}] x Normal@Series[Z1, {e, 0, d}] // .
F[f_s_, {e_s_}] x (f : (r | y)_{p_s_}[i_s_])^{p_s_} ->
F[Join[f_s, Table[f, p]], DeleteDuplicates@{e_s, i_s}];
Z3 = Expand[Z2 /. F[f_s_, e_s] -> Expand[gPair[
Replace[f_s, Thread[e_s -> Range@Length@e_s], {2}], Length@e_s
] /. g_alpha, beta -> G[[e_s][alpha], e_s[beta]]]];
Collect[{Delta, Z3 /. e^{p_s_} -> p! Delta^{p_s} e^{p_s}, e, T2z}];]
```