

Pensieve header: Notebook for DBN Lecture 3 in Matemale, April 2018. See <http://www.math.toronto.edu/~drorbn/Talks/Matemale-1804/>.

**Today.** First Dror, then Roland.

**Unrelated Question.** Anybody wants a French (azerty) keyboard for a surface pro?

## Before we Start...

### Please think about our Partial To do List!

**A Partial To Do List.**

- Complete all “docility” arguments by identifying a “contained” docile substructure.
- Understand denominators and get rid of them.
- See if much can be gained by including  $P$  in the exponential:  $\mathbb{Q}^{L+Q} P \sim \mathbb{Q}^{L+Q+P}$ ?
- Clean the program and make it efficient.
- Run it for all small knots and links, at  $k = 2, 3$ .
- Understand the centre and figure out how to read the output.
- Execute the Drinfel’d double procedure at  $\mathbb{B}$ -level (and thus get rid of `DeclareAlgebra` and all that is around it!).
- Extend to  $sl_3$  and beyond.
- Do everything with `Zip` and `Bind` as the fundamentals, without ever referring back to (quantized) Lie algebras.
- Prove a genus bound and a Seifert formula.
- Obtain “Gauss-Gassner formulas” ( $\omega\epsilon\beta$ /NCSU).
- Relate with Melvin-Morton-Rozansky and with Rozansky-Overbay.
- Understand the braid group representations that arise.
- Find a topological interpretation. The Garoufalidis-Rozansky “loop expansion” [GR]?
- Figure out the action of the Cartan automorphism.
- Disprove the ribbon-slice conjecture!
- Figure out the action of the Weyl group.
- Do everything at the “arrow diagram” level of finite-type invariants of (rotational) virtual tangles.
- What else can you do with the “solvable approximations”?
- And with the “Gaussian zip and bind” technology?

### Recall the Zipping Formula...

**The Zipping / Contraction Theorem.** If  $P$  has a finite  $\zeta$ -degree and the  $y$ ’s and the  $q$ ’s are “small” then

$$\left\langle P(z_i, \zeta^j) e^{\eta^i z_i + y_j \zeta^j} \right\rangle_{(\zeta^j)} = \left\langle P(z_i + y_i, \zeta^j) e^{\eta^i (z_i + y_i)} \right\rangle_{(\zeta^j)},$$

(proof: replace  $y_j \rightarrow \hbar y_j$  and test at  $\hbar = 0$  and at  $\partial_{\hbar}$ ), and

$$\begin{aligned} \left\langle P(z_i, \zeta^j) e^{c + \eta^i z_i + y_j \zeta^j + q_j^i z_i \zeta^j} \right\rangle_{(\zeta^j)} \\ = \det(\tilde{q}) \left\langle P(\tilde{q}_i^k (z_k + y_k), \zeta^j) e^{c + \eta^i \tilde{q}_i^k (z_k + y_k)} \right\rangle_{(\zeta^j)} \end{aligned}$$

where  $\tilde{q}$  is the inverse matrix of  $1 - q$ :  $(\delta_j^i - q_j^i) \tilde{q}_k^j = \delta_k^i$  (proof: replace  $q_j^i \rightarrow \hbar q_j^i$  and test at  $\hbar = 0$  and at  $\partial_{\hbar}$ ).

... and that we only need to compute operations on exponentials...

**Proposition.** If  $F: \mathcal{S}(B) \rightarrow \mathcal{S}(B')$  is linear and “continuous”, then  ${}^t F = \exp\left(\sum_{z_i \in B} \zeta_i z_i\right) // F$ .

### Our Algebra QU

QU =  $\langle y, a, x, t \rangle$ , with  $t$  central and subject to the relations  $[a, x] = \gamma x$ ,  $[a, y] = -\gamma y$ , and  $xy - qyx = \frac{1-TA^2}{\hbar}$ , where  $q = e^{\hbar\gamma\epsilon}$ ,  $T = e^{\hbar t}$  ( $t = \epsilon a - \gamma b$ , as Roland derived the algebra), and  $A = e^{-\hbar\epsilon a}$ . For convenience we set  $\mathcal{A} = e^{\gamma\alpha}$ .

QU has a co-product  $\Delta$  and an antipode  $S$  given by

$$\Delta(y,a,x,t) = (y_1 + T_1 y_2 A_1, a_1 + a_2, x_1 + A_1 x_2)$$

$$S(y,a,x,t) = (-T^{-1} A^{-1} y, -a, -A^{-1} x, -t)$$

## The Program

Initialization / Utilities

DeclareAlgebra

DeclareMorphism

Meta-Operations

Implementing CU =  $\mathcal{U}(\mathfrak{sl}_2^{\gamma\epsilon})$

Implementing QU =  $\mathcal{U}_q(\mathfrak{sl}_2^{\gamma\epsilon})$

The representation  $\rho$

tSW

Exponentials as needed.

Zip and Bind

Tensorial Representations

Alternative Algorithms

New Utilities (not on handout)

```
In[*]:=  $\alpha 2\mathcal{A} = \{e^{c_- \cdot \alpha_i + b_- \cdot} \mapsto \mathcal{A}_i^{c/\gamma} e^b, e^{c_- \cdot \alpha + b_- \cdot} \mapsto \mathcal{A}^{c/\gamma} e^b, e^{\delta_-} \mapsto e^{\text{Expand@}\delta}\};$ 
```

## Some Runs

The Structure Tensors

```
In[*]:= $k = 1;  $\gamma = 1;$ 
```

$$\text{In}[*]:= \text{tm}_{1,2 \rightarrow 3} // . \alpha 2 \mathcal{A}$$

But that's not the form we like! Let's open **Zip and Bind!**

How was it computed? Let's open the **tSW** box!

$$\text{In}[*]:= \text{tS}_1$$

How was it computed? Let's open **Exponentials as Needed!**

$$\text{In}[*]:= \text{t}\Delta_{1 \rightarrow 1, 2}$$

$$\text{In}[*]:= \{ \text{tR}_{1,2}, \overline{\text{tR}}_{1,2} \}$$

$$\text{In}[*]:= \{ \text{tC}_1, \overline{\text{tC}}_2 \}$$

## Some Testing

Associativity of tm.

$$\text{In}[*]:= \text{tm}_{1,2 \rightarrow 2} \sim \mathbf{B}_2 \sim \text{tm}_{2,3 \rightarrow 1} // . \alpha 2 \mathcal{A}$$

$$\text{In}[*]:= \text{tm}_{1,2 \rightarrow 2} \sim \mathbf{B}_2 \sim \text{tm}_{2,3 \rightarrow 1} \equiv \text{tm}_{2,3 \rightarrow 2} \sim \mathbf{B}_2 \sim \text{tm}_{1,2 \rightarrow 1}$$

tS is an anti-homomorphism for tm.

$$\text{In}[*]:= (\text{tS}_1 \text{tS}_2) \sim \mathbf{B}_{1,2} \sim \text{tm}_{1,2 \rightarrow 1} \equiv \text{tm}_{2,1 \rightarrow 1} \sim \mathbf{B}_1 \sim \text{tS}_1$$

Testing convolution inverse:

$$\text{In}[*]:= \text{t}\Delta_{1 \rightarrow 1, 2} \sim \mathbf{B}_1 \sim \text{tS}_1 \sim \mathbf{B}_{1,2} \sim \text{tm}_{1,2 \rightarrow 1}$$

Testing quasi-triangular axioms

$$\text{In}[*]:= (\text{t}\Delta_{1 \rightarrow 1, 2} \text{tR}_{3,4}) \sim \mathbf{B}_{1,2,3,4} \sim (\text{tm}_{1,3 \rightarrow 1} \text{tm}_{2,4 \rightarrow 2}) \equiv (\text{t}\Delta_{1 \rightarrow 2, 1} \text{tR}_{3,4}) \sim \mathbf{B}_{1,2,3,4} \sim (\text{tm}_{3,1 \rightarrow 1} \text{tm}_{4,2 \rightarrow 2})$$

Testing R3

$$\text{In}[*]:= (\text{tR}_{2,3} \text{tR}_{1,4} \text{tR}_{5,6}) \sim \mathbf{B}_{1,2,3,4,5,6} \sim (\text{tm}_{1,5 \rightarrow 1} \text{tm}_{2,6 \rightarrow 2} \text{tm}_{3,4 \rightarrow 3}) \equiv (\text{tR}_{1,2} \text{tR}_{5,3} \text{tR}_{6,4}) \sim \mathbf{B}_{1,2,3,4,5,6} \sim (\text{tm}_{1,5 \rightarrow 1} \text{tm}_{2,6 \rightarrow 2} \text{tm}_{3,4 \rightarrow 3})$$

## Docility and why it matters:

**Definition.** A “docile perturbed Gaussian” in the variables  $(z_i)_{i \in S}$  over the ring  $R$  is an expression of the form

$$e^{q^{ij} z_i z_j} P = e^{q^{ij} z_i z_j} \left( \sum_{k \geq 0} \epsilon^k P_k \right),$$

where all coefficients are in  $R$  and where  $P$  is a “docile series”:  $\deg P_k \leq 4k$ .

**Docility Matters!** The rank of the space of docile series to  $\epsilon^k$  is polynomial in the number of variables  $|S|$ .

In our case our invariants and operations are of the form  $e^{L+Q} P$ , where

**doc·ile**  
 /ˈdɑːsəl/ ⓘ  
 adjective  
 ready to accept control or instruction; submissive  
 “a cheap and docile workforce”



- $L$  is a quadratic of the form  $\sum l_{z\zeta} z\zeta$ , where  $z$  runs over  $\{t_i, \alpha_i\}_{i \in S}$  and  $\zeta$  runs over  $\{\tau_i, a_i\}_{i \in S}$ , with integer coefficients  $l_{z\zeta}$ .
- $Q$  is a quadratic of the form  $\sum q_{z\zeta} z\zeta$ , where  $z$  runs over  $\{x_i, \eta_i\}_{i \in S}$  and  $\zeta$  runs over  $\{\xi_i, y_i\}_{i \in S}$ , with coefficients  $q_{z\zeta}$  in the ring  $R_S$  of rational functions in  $(T_i)_{i \in S}$  and  $(\mathcal{A}_i)_{i \in S}$ .
- $P = \sum \epsilon^k P_k$  is a docile power series in  $\{y_i, a_i, x_i, \eta_i, \xi_i\}_{i \in S}$ , where  $\deg(y_i, a_i, x_i, \eta_i, \xi_i) = (1, 2, 1, 1, 1)$ .

## The Trefoil

Seeing that our invariant is poly-time and the trefoil knot is tiny, the following will compute in no time at all:

```
In[ ]:= Timing@Block[{k = 1},
  Z = tR1,5 tR6,2 tR3,7 tC4 tKink8 tKink9 tKink10;
  Do[Z = Z ~ B1,k ~ tm1,k→1, {k, 2, 10}]; Z]
```

```
In[ ]:= Timing@Block[{k = 1},
  Z = tR1,5 tR6,2 tR3,7 tC4 tKink8 tKink9 tKink10 /. T- → T1;
  Do[Z = Z ~ B1,k ~ tm1,k→1 /. T- → T1, {k, 2, 10}]; Z]
```