



# Shifted Partial Quadratics, their Pushforwards, and Signature Invariants for Tangles

**Abstract.** Following a general discussion of the computation of zombians of unfinished columbaria (with examples), I will tell you about my recent joint work w/ Jessica Liu on what we feel is the “textbook” extension of knot signatures to tangles, which for unknown reasons, is not in any of the textbooks that we know.



Jessica Liu



Columbaria in an East Sydney Cemetery



Jacobian, Hamiltonian, Zombian

**Kashaev's Conjecture** [Ka] For knots,  $\sigma_{Kas} = 2\sigma_{TL}$ .

**Liu's Theorem** [Li].

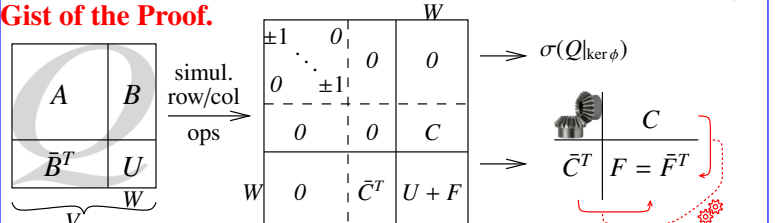
A **Partial Quadratic (PQ)** on  $V$  is a quadratic  $Q$  defined only on a subspace  $\mathcal{D}_Q \subset V$ . We add PQs with  $\mathcal{D}_{Q_1+Q_2} := \mathcal{D}_{Q_1} \cap \mathcal{D}_{Q_2}$ . Given a linear  $\psi: V \rightarrow W$  and a PQ  $Q$  on  $W$ , there is an obvious **pullback**  $\psi^*Q$ , a PQ on  $V$ .

**Theorem 1.** Given a linear  $\phi: V \rightarrow W$  and a PQ  $Q$  on  $V$ , there is a unique **pushforward** PQ  $\phi_*Q$  on  $W$  such that for every PQ  $U$  on  $W$ ,  $\sigma_V(Q + \phi^*U) = \sigma_{\ker \phi}(Q|_{\ker \phi}) + \sigma_W(U + \phi_*Q)$ .

(If you must,  $\mathcal{D}(\phi_*Q) = \phi(\text{ann}_Q(\mathcal{D}(Q) \cap \ker \phi))$  and  $(\phi_*Q)(w) = Q(v)$ , where  $v$  is s.t.  $\phi(v) = w$  and  $Q(v, \text{rad } Q|_{\ker \phi}) = 0$ .) *Needs a proof!*

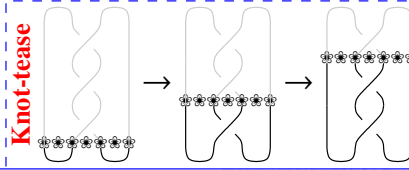
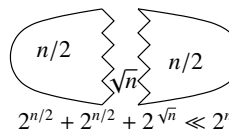
**Prior Art** on signatures for tangles / braids. Gambaudo and Ghys [GG], Cimasoni and Conway [CC], Conway [Co], Merz [Me]. All define signatures of tangles / braids by first closing them to links and then work hard to derive composition properties.

**Gist of the Proof.**



**Why Tangles?** • Faster!

- Conceptually clearer proofs of invariance (and of skein relations).
- Often fun and consequential:
  - The Jones Polynomial  $\rightsquigarrow$  The Temperley-Lieb Algebra.
  - Khovanov Homology  $\rightsquigarrow$  “Unfinished complexes”, complexes in a category.
  - The Kontsevich Integral  $\rightsquigarrow$  Associators.
  - HFK  $\rightsquigarrow$  OMG, type  $D$ , type  $A$ ,  $\mathcal{A}_\infty, \dots$



**Computing Zombians of Unfinished Columbaria.**

- Must be no slower than for finished ones.
- Future zombies must be able to complete the computation.
- Future zombies must not even know the size of the task that today's zombies were facing.
- We must be able to extend to ZPUCs, Zombie Processed Unfinished Columbaria!

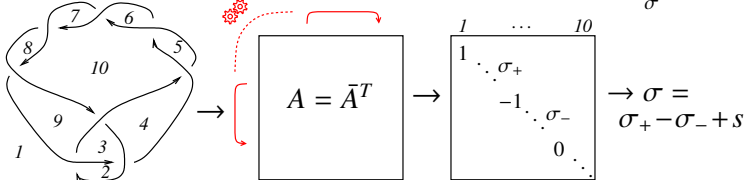


Columbarium near Assen

**Example / Exercise.** Compute the determinant of a  $1,000 \times 1,000$  matrix in which 50 entries are not yet given.

**Homework / Research Projects.** • What with ZPUCs? • Use this to get an Alexander tangle invariant.

**Reminders.** {knots}  $\rightleftharpoons$  {matrices / quadratic forms}  $\xrightarrow{\text{signature } \sigma} \mathbb{Z}$ :



With  $|\omega| = 1$ ,  $t = 1 - \omega$ ,  $r = t + \bar{t}$ ,  $v = \text{Re}(\omega)$ , and  $u = \text{Re}(\omega^{1/2})$ :

$X_{-i,j,k,-l}$	Tristram-Levine (TL)	Kashaev (Kas)
$A += \begin{pmatrix} -r & -t & 2t & \bar{t} \\ -\bar{t} & 0 & \bar{t} & 0 \\ 2\bar{t} & t & -r & -\bar{t} \\ t & 0 & -t & 0 \end{pmatrix}$	$s = 0$	$A += \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}$
$X_{-i,j,k,-l}$	Tristram-Levine (TL)	Kashaev (Kas)
$A += \begin{pmatrix} r & -t & -2\bar{t} & \bar{t} \\ -\bar{t} & 0 & \bar{t} & 0 \\ -2t & t & r & -\bar{t} \\ t & 0 & -t & 0 \end{pmatrix}$	$s = 0$	$A -= \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}$
$X_{-i,j,k,-l}$	Tristram-Levine (TL)	Kashaev (Kas)
$A += \begin{pmatrix} r & -t & -2\bar{t} & \bar{t} \\ -\bar{t} & 0 & \bar{t} & 0 \\ -2t & t & r & -\bar{t} \\ t & 0 & -t & 0 \end{pmatrix}$	$s = 0$	$s = +1$

... and the quadratic  $F := \phi_*Q$  is well-defined only on  $D := \ker C$ .

**Exactly** what we want, if the Zombian is the signature!

$V$ : The full space of faces.  
 $W$ : The boundary, made of gaps.  
 $Q$ : The known parts.  
 $U$ : The part yet unknown.  
 $\sigma_V(Q + \phi^*(U))$ : The overall Zombian.  
 $\sigma(Q|_{\ker \phi})$ : An internal bit.  $U + \phi_*Q$ : A boundary bit.  
 And so our ZPUC is the pair  $S = (\sigma(Q|_{\ker \phi}), \phi_*Q)$ .

A **Shifted Partial Quadratic (SPQ)** on  $V$  is a pair  $S = (s \in \mathbb{Z}, Q \text{ a PQ on } V)$ . addition also adds the shifts, pullbacks keep the shifts, yet  $\phi_*S := (s + \sigma_{\ker \phi}(Q|_{\ker \phi}), \phi_*Q)$  and  $\sigma(S) := s + \sigma(Q)$ .

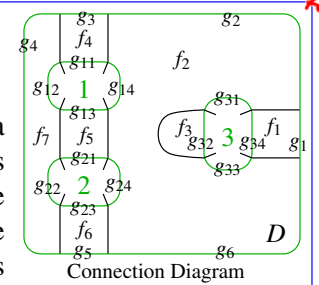
**Theorem 1' (Reciprocity).** Given  $\phi: V \rightarrow W$ , for SPQs  $S$  on  $V$  and  $U$  on  $W$  we have  $\sigma_V(S + \phi^*U) = \sigma_W(U + \phi_*S)$  (and this characterizes  $\phi_*S$ ). *Note.*  $\psi^*$  is additive but  $\phi_*$  is not.

**Theorem 2.**  $\psi^*$  and  $\phi_*$  are functorial.

**Theorem 3.** “The pullback of a pushforward scene is a  $\mu \downarrow \nearrow \downarrow \gamma$  pushforward scene”: If, on the right,  $\beta$  and  $\delta$  are arbitrary,  $\downarrow \equiv \text{EQ}(\beta, \gamma) = B \oplus_A C = \{(b, c) : \beta b = \gamma c\}$  and  $\mu$  and  $\gamma$  are the obvious projections, then  $\gamma^* \beta_* = \nu_* \mu^*$ .

**Definition.**  $S \left( \begin{matrix} g_2 \\ g_3 \\ \dots \end{matrix} \right) := \left\{ \begin{matrix} \text{SPQ } S \\ \text{on } \langle g_i \rangle \end{matrix} \right\}$ .

**Theorem 4.**  $\{S(\text{cyclic sets})\}$  is a planar algebra, with compositions  $S(D)((S_i)) := \phi_*^D(\psi_D^*(\bigoplus_i S_i))$ , where  $\psi_D: \langle f_i \rangle \rightarrow \langle g_{\alpha i} \rangle$  maps every face of  $D$  to the sum of the input gaps adjacent to it and  $\phi^D: \langle f_i \rangle \rightarrow \langle g_i \rangle$  maps every face to the sum of the output gaps adjacent to it. So for our  $D$ ,  $\psi_D$  is  $f_1 \mapsto g_{34}, f_2 \mapsto g_{31} + g_{14} + g_{24} + g_{33}, f_3 \mapsto g_{32}, f_4 \mapsto g_{11}, f_5 \mapsto g_{13} + g_{21}, f_6 \mapsto g_{23}, f_7 \mapsto g_{12} + g_{22}$  and  $\phi^D$  is  $f_1 \mapsto g_1, f_2 \mapsto g_2 + g_6, f_3 \mapsto 0, f_4 \mapsto g_3, f_5 \mapsto 0, f_6 \mapsto g_5, f_7 \mapsto g_4$ .



**Theorem 5.**  $TL$  and  $Kas$ , defined on  $X$  and  $\bar{X}$  as before, extend to planar algebra morphisms  $\{\text{tangles}\} \rightarrow \{S\}$ .



**Proof of Theorem 1'.** Fix  $W$  and consider triples  $(V, S, \phi: V \rightarrow W)$  where  $S = (s, D, Q)$  is an SPQ on  $V$ . Say that two triples are "push-equivalent",  $(V_1, S_1, \phi_1) \sim (V_2, S_2, \phi_2)$  if for every quadratic  $U$  on  $W$ ,

$$\sigma_{V_1}(S_1 + \phi_1^*U) = \sigma_{V_2}(S_2 + \phi_2^*U).$$

Given our  $(V, S, \phi)$ , we need to show: *bad manners!*

1. There is an SPQ  $S'$  on  $W$  such that  $(V, S, \phi) \sim (W, S', I)$ .
2. If  $(W, S', I) \sim (W, S'', I)$  then  $S' = S''$ .

Property 2 is easy (Exercises 1, 2). Property 1 follows from the following three claims, each of which is easy.

**Claim 1.** If  $v \in \ker \phi \cap D(S)$ , and  $\lambda := Q(v) \neq 0$ , then  $(V, S, \phi) \sim (V/\langle v \rangle, (s + \text{sign}(\lambda), V/\langle v \rangle, Q - \frac{Q(-, v) \otimes Q(v, -)}{|\lambda|^2}), \phi/\langle v \rangle)$ .

So wlog  $Q|_{\ker \phi} = 0$  (meaning,  $Q|_{\ker \phi \otimes \ker \phi} = 0$ ).  $\square$

**Claim 2.** If  $Q|_{\ker \phi} = 0$  and  $v \in \ker \phi \cap D(S)$ , let  $V' = \ker Q(v, -)$  and then  $(V, S, \phi) \sim (V', S|_{V'}, \phi|_{V'})$  so wlog  $Q|_{V \otimes \ker \phi + \ker \phi \otimes V} = 0$ .  $\square$

**Claim 3.** If  $Q|_{V \otimes \ker \phi + \ker \phi \otimes V} = 0$  then  $S = \phi^*S'$  for some SPQ  $S'$  on  $\text{im } \phi$  and then  $(V, S, \phi) \sim (W, S', I)$ .  $\square \square$

**Proof of Theorem 2.** The functoriality of pullbacks needs no proof. Now assume  $V_0 \xrightarrow{\alpha} V_1 \xrightarrow{\beta} V_2$  and that  $S$  is an SPQ on  $V_0$ . Then for every SPQ  $U$  on  $V_2$  we have, using reciprocity three times, that  $\sigma(\beta_*\alpha_*S + U) = \sigma(\alpha_*S + \beta^*U) = \sigma(S + \alpha^*\beta^*U) = \sigma(S + (\beta\alpha)^*U) = \sigma((\beta\alpha)_*S + U)$ . Hence  $\beta_*\alpha_*S = (\beta\alpha)_*S$ .  $\square$

**Proof of Theorem 3.**

**Proof of Theorem 4.**

**Proof of Theorem 5.**

**Homework.**

**Exercise 1.** Show that if two SPQ's  $S_1$  and  $S_2$  on  $V$  satisfy  $\sigma(S_1 + U) = \sigma(S_2 + U)$  for every quadratic  $U$  on  $V$ , then they have the same shift and the same domains.

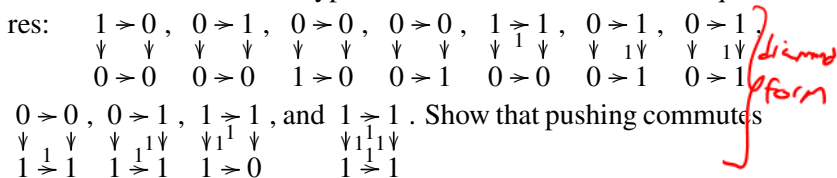
**Exercise 2.** Show that if two full quadratics  $Q_1$  and  $Q_2$  satisfy  $\sigma(Q_1 + U) = \sigma(Q_2 + U)$  for every  $U$ , then  $Q_1 = Q_2$ .

**Exercise 3.** By taking  $U = 0$  in the reciprocity statement, prove that always  $\sigma(\phi_*S) = \sigma(S)$ . But that seems wrong, if  $\phi = 0$ . What saves the day?

**Exercise 4.** By taking  $S = 0$  in the reciprocity statement, prove that always  $\sigma(\phi^*U) = \sigma(U)$ . But wait, this is nonsense! What went wrong?

**Exercise 5.** Show that always,  $\phi_*\phi^*S = S|_{\text{im } \phi}$ .

**Exercise 6.** There are 11 types of irreducible commutative squares:



**Solutions / Hints.**

**Hint 1.** On a vector in the domain of one but not the other, take an outrageous value for  $U$ , that will raise or lower the signature. *improve*

**Hint 2.** WLOG,  $Q_1$  is diagonal and  $Q_1 = 0$ .

**Hint 3.** The "shift" part of  $0_*S$  is  $\sigma(S)$ . *LaTeX*

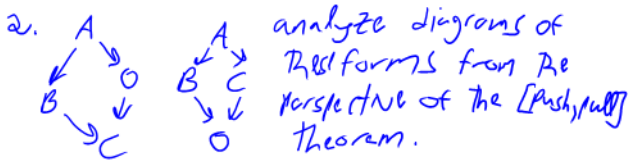
**Hint 4.**  $\phi_*S$  isn't 0, it's the *partial* quadratic "0 on  $\text{im } \phi$ " (and indeed,  $\sigma(\phi^*U) = \sigma(U)$  if  $\phi$  is surjective).

**Hint 5.** It's enough to test that against  $U$  with  $\mathcal{D}(U) = \text{im } \phi$ .

**Hint 6.** The exceptions are  $\begin{smallmatrix} 01 & 00 & 01 \\ 00 & 10 & 11 \end{smallmatrix}$ , and  $\begin{smallmatrix} 11 \\ 10 \end{smallmatrix}$ . *dimmed form*

*Add to the HW section:*

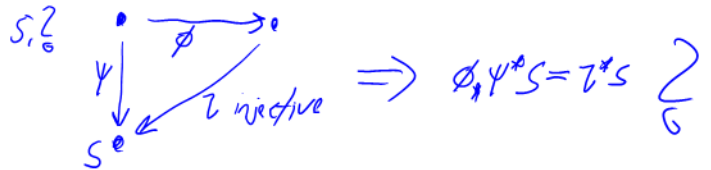
1. Any lemma that's no longer needed.



3. Does [push, pull] hold for



4. Understand from the perspective of the "list" of the proof box.



6. *claim*  $\pi_*\alpha^*S = \beta_*S$  if



*proof*  $\sigma(\pi_*\alpha^*S + U) = \sigma(\alpha^*S + \pi^*U) = \sigma(\alpha^*S + \alpha^*\beta^*U) = \sigma(S + \beta^*U) = \sigma(\beta_*S + U)$  for every  $U$ , and so  $\beta_*S = \pi_*\alpha^*S$

7. *claim*  $S \circ \alpha \rightarrow 0$  If  $\alpha$  is 1-1, then  $\alpha^*\alpha_*S = S$

Proof of Thm 3.

Def.  $V_3$  is called admissible if  $\delta^* \beta_* = \nu_* \mu^*$

Lemma 1  $\begin{matrix} IVF \\ \downarrow \\ V \\ \downarrow \\ IVF \end{matrix}$  is admissible  
Lemma 2 TFAE  
 1. Admissible  
 2. "mirror admissible,  $\beta^* \gamma_* = \mu_* \nu^*$   
 3. The pairing condition.

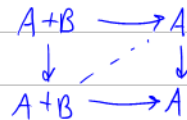
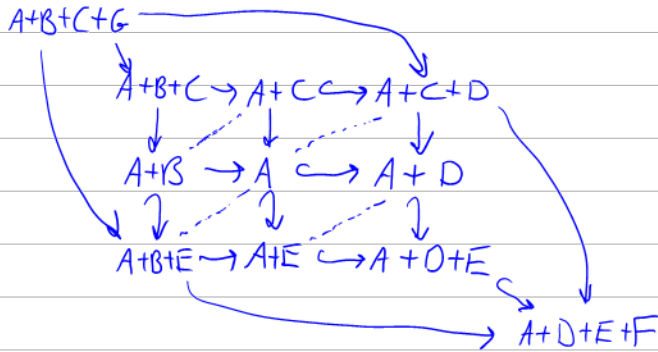
Lemma 3 IF  $\begin{matrix} V_3 \rightarrow V_2 \\ \downarrow \downarrow \\ V_1 \rightarrow V_0 \end{matrix}$  is admissible, Then so is  $\begin{matrix} V_3 \rightarrow V_2 \\ \downarrow \downarrow \\ V_1 \rightarrow V_0 \oplus A \end{matrix}$

Lemma 4 For any  $V \rightarrow W$ ,  $\begin{matrix} V \rightarrow V \oplus A \\ \downarrow \downarrow \\ W \rightarrow W \oplus A \end{matrix}$  and  $\begin{matrix} V \oplus A \rightarrow W \oplus A \\ \downarrow \downarrow \\ V \rightarrow W \end{matrix}$  are admissible.

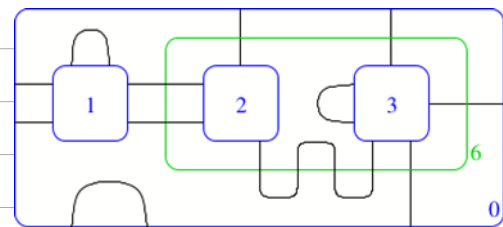
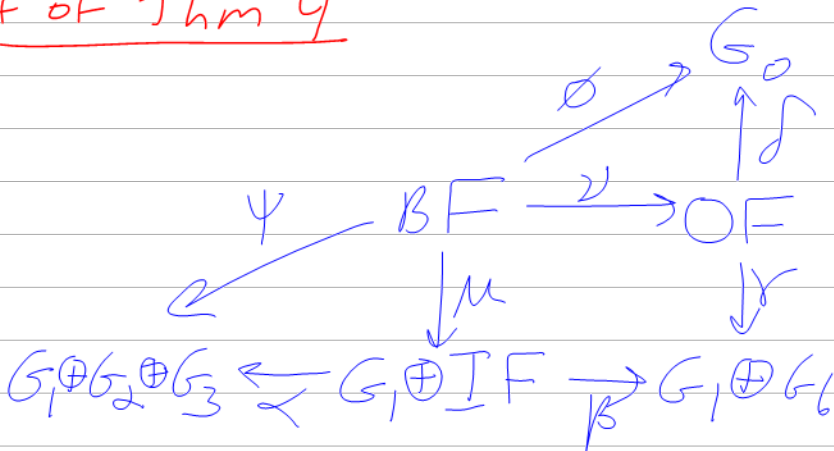
Lemma 5 IF  $\begin{matrix} V_3 \\ \downarrow \downarrow \\ V_1 \rightarrow V_0 \end{matrix}$  is admissible, Then so are  $\begin{matrix} V_3 \oplus A \\ \downarrow \downarrow \\ V_1 \rightarrow V_0 \oplus A \end{matrix}$  and  $\begin{matrix} V_3 \oplus A \\ \downarrow \downarrow \\ V_1 \rightarrow V_0 \oplus A \end{matrix}$

And now the proof of The Theorem...

$$\begin{matrix} A+B+C \\ E+A+B & A+C+D \\ E+A+D+F \end{matrix}$$



pf of Thm 4



**Implementation** (sources: <http://drorbn.net/icerm23/ap>). I like it most when the implementation matches the math perfectly. We failed here.

Once[<< KnotTheory`];

Loading KnotTheory` version

of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

**Utilities.** The step function, algebraic numbers, canonical forms.

$\theta[x\_]$  /; NumericQ[x] := UnitStep[x]

```
 $\omega 2[v\_][p\_]$  := Module[{q = Expand[p], n, c},
  If[q == 0, 0,
    c = Coefficient[q,  $\omega$ , n = Exponent[q,  $\omega$ ]];
     $c v^n + \omega 2[v][q - c(\omega + \omega^{-1})^n]$ ];
```

```
sign[ $\mathcal{E}$ _] := Module[{n, d, v, p, rs, e, k},
  {n, d} = NumeratorDenominator[ $\mathcal{E}$ ];
  {n, d} /=  $\omega^{\text{Exponent}[n, \omega]/2 + \text{Exponent}[n, \omega, \text{Min}]/2}$ ;
  p = Factor[ $\omega 2[v]@n * \omega 2[v]@d / . v \rightarrow 4 u^2 - 2$ ];
  rs = Solve[p == 0, u, Reals];
  If[rs == {}, Sign[p /. u -> 0],
    rs = Union@{u /. rs};
    Sign[(-1)e=Exponent[p, u] Coefficient[p, u, e]] + Sum[
      k = 0;
      While[{d = RootReduce[ $\partial_{\{u, ++k\}} p / . u \rightarrow r$ ]} == 0];
      If[EvenQ[k], 0, 2 Sign[d]] *  $\theta[u - r]$ ,
      {r, rs}]]
]
```

SetAttributes[B, Orderless];

```
CF[b_B] := RotateLeft[#, First@Ordering[#] - 1] & /@
DeleteCases[b, {}]
```

```
CF[ $\mathcal{E}$ _] := Module[{ $\gamma$ s = Union@Cases[ $\mathcal{E}$ ,  $\gamma$ _ |  $\bar{\gamma}$ _,  $\infty$ ]},
  Total[CoefficientRules[ $\mathcal{E}$ ,  $\gamma$ s] /.
    (ps_ -> c_) := Factor[c]  $\times$  Times@@ $\gamma$ sps]]
```

CF[{}] = {};

CF[C\_List] :=

```
Module[{ $\gamma$ s = Union@Cases[C,  $\gamma$ _,  $\infty$ ],  $\gamma$ },
  CF /@ DeleteCases[0] [
    RowReduce[Table[ $\partial_{\gamma} r$ , {r, C}, { $\gamma$ ,  $\gamma$ s}]] .  $\gamma$ s ]
```

( $\mathcal{E}$ \_)<sup>\*</sup> :=  $\mathcal{E} / . \{\bar{\gamma} \rightarrow \gamma, \gamma \rightarrow \bar{\gamma}, \omega \rightarrow \omega^{-1}, c\_Complex \rightarrow c^*\}$ ;

r\_Rule<sup>+</sup> := {r, r<sup>\*</sup>}

RulesOf[ $\gamma_i$  + rest\_] := ( $\gamma_i \rightarrow -rest$ )<sup>+</sup>;

```
CF[PQ[C_, q_]] := Module[{nC = CF[C]},
  PQ[nC, CF[q /. Union@@RulesOf /@nC]] ]
```

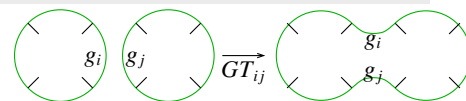
CF[ $\Sigma_b$ [ $\sigma$ \_, pq\_]] :=  $\Sigma_{CF[b]}$ [ $\sigma$ , CF[pq]]

## Pretty-Printing.

```
Format[ $\Sigma_{b,B}[\sigma_, PQ[C_, q_]]$ ] := Module[{ $\gamma$ s},
   $\gamma$ s =  $\gamma$ # & /@ Join@@b;
  Column[{TraditionalForm@ $\sigma$ ,
    TableForm[Join[
      Prepend[""] /@ Table[TraditionalForm[ $\partial_c r$ ],
        {r, C}, {c,  $\gamma$ s}],
      {Prepend[""] [
        Join@@
          (b /. {L_, m___, r_} =>
            {DisplayForm@RowBox[{"(", L}],
              m, DisplayForm@RowBox[{r, ")"}]}) / .
            i_Integer =>  $\gamma_i$  ]}],
      MapThread[Prepend,
        {Table[TraditionalForm[ $\partial_{r,c} q$ ], {r,  $\gamma$ s*},
          {c,  $\gamma$ s}],  $\gamma$ s*}],
      TableAlignments -> Center]
    ], Center] ];
```

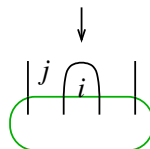
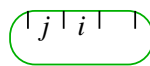
## The Face-Centric Core.

```
 $\Sigma_{b1}[\sigma_1, PQ[C1_, q1_]] \oplus \Sigma_{b2}[\sigma_2, PQ[C2_, q2_]]$  ^:=
  CF@ $\Sigma_{\text{Join}[b1, b2]}$ [ $\sigma_1 + \sigma_2, PQ[C1 \cup C2, q1 + q2]$ ];
```



GT for Gap Touch:

```
GTi,j@ $\Sigma_B$ [{li___, i_, ri___}, {lj___, j_, rj___}, bs___][ $\sigma$ _,
  PQ[C_, q_]] :=
  CF@ $\Sigma_B$ [{ri, li, j, rj, lj, i}, bs][ $\sigma$ _, PQ[C  $\cup$  { $\gamma_i - \gamma_j$ }, q]]
```



cor·don (kôr'dn)  
n.



1. A line of people, military posts, or ships stationed around an area to enclose or guard it: a *police cordon*.
2. A rope, line, tape, or similar border stretched around an area, usually by the police, indicating that access is restricted.

$$s \begin{pmatrix} 0 & \phi C_{\text{rest}} \\ \bar{\phi}^T & \lambda \theta \\ \bar{C}_{\text{rest}}^T & \bar{\theta}^T A_{\text{rest}} \end{pmatrix} \rightarrow \begin{cases} \exists p \phi_p \neq 0 & \text{use } \phi_p \text{ to kill its row and} \\ \phi = 0, \lambda \neq 0 & \text{column, drop a } \begin{pmatrix} 01 \\ 10 \end{pmatrix} \text{ summand} \\ \phi = 0, \lambda = 0 & \text{use } \lambda \text{ to kill } \theta, \text{ let } s += \text{sign}(\lambda) \\ & \text{append } \theta \text{ to } C_{\text{rest}}. \end{cases}$$

```
Cordoni@ $\Sigma_B$ [{li___, i_, ri___}, bs___][ $\sigma$ _, PQ[C_, q_]] :=
```

```
Module[{ $\phi = \partial_{\gamma_i} C$ ,  $\lambda = \partial_{\bar{\gamma}_i, \gamma_i} q$ , n $\sigma = \sigma$ , nC, nq, p},
  {p} = FirstPosition[({# != 0} & /@  $\phi$ , True, {0})];
  {nC, nq} = Which[
    p > 0, {C, q} /. ( $\gamma_i \rightarrow -C[[p]] / \phi[[p]]$ )+ /. ( $\gamma_i \rightarrow \theta$ )+,
     $\lambda \neq 0$ , (n $\sigma += \text{sign}[\lambda]$ ;
      {C, q /. ( $\gamma_i \rightarrow -(\partial_{\bar{\gamma}_i} q) / \lambda$ )+ /. ( $\gamma_i \rightarrow \theta$ )+}),
     $\lambda == 0$ , {C  $\cup$  { $\partial_{\bar{\gamma}_i} q$ }, q /. ( $\gamma_i \rightarrow \theta$ )+];
  CF@ $\Sigma_B$ [Most@{ri, li}, bs][n $\sigma$ ,
    PQ[nC, nq] /. ( $\gamma_{\text{Last}@{ri, li}} \rightarrow \gamma_{\text{First}@{ri, li}}$ )+ ] ]
```



**Strand Operations.** c for contract, mc for magnetic contract:

$$C_{i,j}@t : \Sigma_B[\{li\_ , i, ri\_ \}, \{ \_, j, \_ \}, \_ ] [ \_ ] := t // GT_{j, First\{ri, li\}} // Cordon_j$$

$$C_{i,j}@t : \Sigma_B[\{ \_, i, j, \_ \}, \_ ] [ \_ ] := Cordon_j @ t$$

$$C_{i,j}@t : \Sigma_B[\{ j, \_, i, \_ \}, \_ ] [ \_ ] := Cordon_j @ t$$

$$C_{i,j}@t : \Sigma_B[\{ \_, j, i, \_ \}, \_ ] [ \_ ] := Cordon_i @ t$$

$$C_{i,j}@t : \Sigma_B[\{ i, \_, j, \_ \}, \_ ] [ \_ ] := Cordon_i @ t$$

$$mc[\mathcal{E}_] := \mathcal{E} //$$

$$t : \Sigma_B[\{ \_, i, \_ \}, \{ \_, j, \_ \}, \_ ] [ \_ ] | \Sigma_B[\{ \_, i, j, \_ \}, \_ ] [ \_ ] | \Sigma_B[\{ j, \_, i, \_ \}, \_ ] [ \_ ] / ; i + j == 0 \Rightarrow C_{i,j}@t$$

**The Crossings** (and empty strands).

$$Kas@P_{i,j} := CF@ \Sigma_B[\{i,j\}] [\theta, PQ[\{\}, \theta]] ;$$

$$TL@P_{i,j} := CF@ \Sigma_B[\{i,j\}] [\theta, PQ[\{\}, \theta]]$$

$$Kas[x : X[i_, j_, k_, l_]] :=$$

$$Kas@If[PositiveQ[x], X_{-i,j,k,-l}, \bar{X}_{-j,k,l,-i}] ;$$

$$Kas[(x : X | \bar{X})_{fs\_}] := Module[\{v = 2u^2 - 1, p, \gamma s, m\},$$

$$\gamma s = \gamma_{\#} \& /@ \{fs\}; p = (x === X);$$

$$m = If[p, \begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}, -\begin{pmatrix} v & u & 1 & u \\ u & 1 & u & 1 \\ 1 & u & v & u \\ u & 1 & u & 1 \end{pmatrix}];$$

$$CF@ \Sigma_B[\{fs\}] [If[p, -1, 1], PQ[\{\}, \gamma s^* . m . \gamma s]]]$$

$$TL[x : X[i_, j_, k_, l_]] :=$$

$$TL@If[PositiveQ[x], X_{-i,j,k,-l}, \bar{X}_{-j,k,l,-i}] ;$$

$$TL[(x : X | \bar{X})_{fs\_}] := Module[\{t = 1 - \omega, r, \gamma s, m\},$$

$$r = t + t^*; \gamma s = \gamma_{\#} \& /@ \{fs\};$$

$$m = If[x === X,$$

$$\begin{pmatrix} -r & -t & 2t & t^* \\ -t^* & \theta & t^* & \theta \\ 2t^* & t & -r & -t^* \\ t & \theta & -t & \theta \end{pmatrix}, \begin{pmatrix} r & -t & -2t^* & t^* \\ -t^* & \theta & t^* & \theta \\ -2t & t & r & -t^* \\ t & \theta & -t & \theta \end{pmatrix}];$$

$$CF@ \Sigma_B[\{fs\}] [\theta, PQ[\{\}, \gamma s^* . m . \gamma s]]]$$

**Evaluation on Tangles and Knots.**

$$Kas[K_] := Fold[mc[\#1 \oplus \#2] \&, \Sigma_B[] [\theta, PQ[\{\}, \theta]], List@@ (Kas /@ PD@K)] ;$$

$$KasSig[K_] := Expand[Kas[K][[1]] / 2]$$

$$TL[K_] :=$$

$$Fold[mc[\#1 \oplus \#2] \&, \Sigma_B[] [\theta, PQ[\{\}, \theta]],$$

$$List@@ (TL /@ PD@K)] / .$$

$$\theta[c\_ + u] / ; Abs[c] \ge 1 \Rightarrow \theta[c] ;$$

$$TLSig[K_] := TL[K][[1]]$$

**Reidemeister 3.**

$$R3L = PD[X_{-2,5,4,-1}, X_{-3,7,6,-5}]$$

$$X_{-6,9,8,-4} ;$$

$$R3R = PD[X_{-3,5,4,-2}, X_{-4,6,8,-1}]$$

$$X_{-5,7,9,-6} ;$$

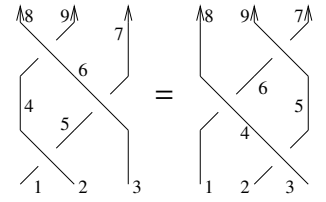
$$\{TL@R3L == TL@R3R, Kas@R3L == Kas@R3R\}$$

$$\{True, True\}$$

**Kas@R3L**

$$2\theta(u - \frac{1}{2}) - 2\theta(u + \frac{1}{2}) - 2$$

	$\gamma_3$	$\gamma_7$	$\gamma_9$	$\gamma_8$	$\gamma_{-1}$	$\gamma_{-2}$
$\bar{\gamma}_3$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$
$\bar{\gamma}_7$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2(2u^2-1)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$
$\bar{\gamma}_9$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$
$\bar{\gamma}_8$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$
$\bar{\gamma}_{-1}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2(2u^2-1)}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$
$\bar{\gamma}_{-2}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$-\frac{2u}{(2u-1)(2u+1)}$	$-\frac{1}{(2u-1)(2u+1)}$	$\frac{u(4u^2-3)}{(2u-1)(2u+1)}$	$\frac{2u^2(4u^2-3)}{(2u-1)(2u+1)}$



**Reidemeister 2.**

$$TL@PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}]$$

$$\theta$$

	1	0	-1	0
$\bar{\gamma}_{-2}$	0	0	0	0
$\bar{\gamma}_6$	0	0	0	0
$\bar{\gamma}_5$	0	0	0	0
$\bar{\gamma}_{-1}$	0	0	0	0

$$\{TL@PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}] == GT_{5,-2}@TL@PD[P_{-1,5}, P_{-2,6}], Kas@PD[X_{-2,4,3,-1}, \bar{X}_{-4,6,5,-3}] == GT_{5,-2}@Kas@PD[P_{-1,5}, P_{-2,6}]\}$$

$$\{True, True\}$$

**Reidemeister 1.**

$$\{TL@PD[X_{-3,3,2,-1}] == TL@P_{-1,2},$$

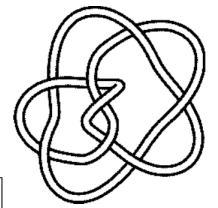
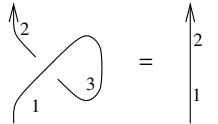
$$Kas@PD[X_{-3,3,2,-1}] == Kas@P_{-1,2}\}$$

$$\{True, True\}$$

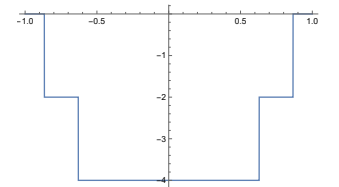
**A Knot.**

$$f = TLSig[Knot[8, 5]]$$

$$2\theta\left[-\frac{\sqrt{3}}{2} + u\right] - 2\theta\left[\frac{\sqrt{3}}{2} + u\right] - 2\theta\left[u - \text{ArcTan}[-0.630957344480193]\right] + 2\theta\left[u - \text{ArcTan}[0.630957344480193]\right]$$



$$Plot[f, \{u, -1, 1\}]$$

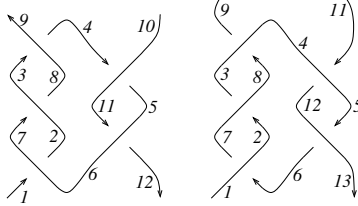


# The Conway-Kinoshita-Terasaka Tangles.



$$T1 = PD[\bar{X}_{-6,2,7,-1}, \bar{X}_{-2,8,3,-7}, \bar{X}_{-8,4,9,-3}, X_{-11,6,12,-5}, X_{-4,11,5,-10}];$$

$$T2 = PD[X_{-6,2,7,-1}, X_{-2,8,3,-7}, X_{-8,4,9,-3}, \bar{X}_{-12,6,13,-5}, \bar{X}_{-4,12,5,-11}, \bar{X}_{-10,15,11,-14}, \bar{X}_{-15,10,16,-9}];$$



## Column@{TL [T1], Kas [T1]}

$$-2\theta(u - \frac{\sqrt{3}}{2}) + 2\theta(u + \frac{\sqrt{3}}{2}) - 1$$

$\bar{Y}_{-10}$	$Y_9$	$Y_{-1}$	$Y_{12}$
$\frac{0}{\omega}$	$1 - \omega$	$0$	$\frac{\omega - 1}{\omega}$
$\frac{\omega - 1}{\omega}$	$\frac{2\omega}{\omega^2 - \omega + 1}$	$\frac{\omega - 1}{\omega}$	$-\frac{2\omega}{\omega^2 - \omega + 1}$
$0$	$\frac{1 - \omega}{\omega}$	$0$	$\frac{1 - \omega}{\omega}$
$-\frac{\omega - 1}{\omega}$	$-\frac{2\omega}{\omega^2 - \omega + 1}$	$\frac{\omega - 1}{\omega}$	$\frac{2\omega}{\omega^2 - \omega + 1}$

$\bar{Y}_{-10}$	$Y_9$	$Y_{-1}$	$Y_{12}$
$2(u-1)(u+1)(4u^2-3)$	$0$	$-2(u-1)(u+1)(4u^2-3)$	$0$
$0$	$\frac{1}{2(4u^2-3)}$	$0$	$-\frac{1}{2(4u^2-3)}$
$-2(u-1)(u+1)(4u^2-3)$	$0$	$2(u-1)(u+1)(4u^2-3)$	$0$
$0$	$-\frac{1}{2(4u^2-3)}$	$0$	$\frac{1}{2(4u^2-3)}$

## Column@{TL [T2], Kas [T2]}

$\bar{Y}_{-14}$	$Y_{16}$	$Y_{-1}$	$Y_{13}$
$0$	$1 - \omega$	$0$	$\frac{\omega - 1}{\omega}$
$\frac{\omega - 1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4 - 3\omega^3 + 5\omega^2 - 3\omega + 1}$	$-\frac{\omega - 1}{\omega}$	$\frac{2(\omega-1)^2\omega}{\omega^4 - 3\omega^3 + 5\omega^2 - 3\omega + 1}$
$0$	$\frac{\omega - 1}{\omega}$	$0$	$\frac{1 - \omega}{\omega}$
$-\frac{\omega - 1}{\omega}$	$\frac{2(\omega-1)^2\omega}{\omega^4 - 3\omega^3 + 5\omega^2 - 3\omega + 1}$	$\frac{\omega - 1}{\omega}$	$-\frac{2(\omega-1)^2\omega}{\omega^4 - 3\omega^3 + 5\omega^2 - 3\omega + 1}$

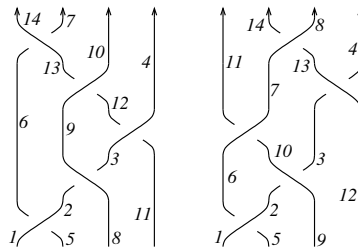
  

$\bar{Y}_{-14}$	$Y_{16}$	$Y_{-1}$	$Y_{13}$
$\frac{1}{2}(-16u^4 + 28u^2 - 13)$	$0$	$\frac{1}{2}(16u^4 - 28u^2 + 13)$	$0$
$0$	$-\frac{2(u-1)(u+1)}{16u^4 - 28u^2 + 13}$	$0$	$\frac{2(u-1)(u+1)}{16u^4 - 28u^2 + 13}$
$\frac{1}{2}(16u^4 - 28u^2 + 13)$	$0$	$\frac{1}{2}(-16u^4 + 28u^2 - 13)$	$0$
$0$	$\frac{2(u-1)(u+1)}{16u^4 - 28u^2 + 13}$	$0$	$-\frac{2(u-1)(u+1)}{16u^4 - 28u^2 + 13}$

## Examples with non-trivial co-dimension.

$$B1 = PD[X_{-5,2,6,-1}, \bar{X}_{-8,3,9,-2}, X_{-11,4,12,-3}, X_{-12,10,13,-9}, \bar{X}_{-13,7,14,-6}];$$

$$B2 = PD[X_{-5,2,6,-1}, \bar{X}_{-9,3,10,-2}, X_{-10,7,11,-6}, \bar{X}_{-12,4,13,-3}, X_{-13,8,14,-7}];$$



## Column@{TL [B1], Kas [B1]}

$\bar{Y}_{-11}$	$Y_4$	$Y_{10}$	$Y_7$	$Y_{14}$	$Y_{-1}$	$Y_{-5}$	$Y_{-8}$
$0$	$0$	$0$	$0$	$\frac{\omega - 1}{\omega^2}$	$0$	$-\frac{\omega - 1}{\omega^2}$	$0$
$0$	$0$	$0$	$0$	$-\frac{\omega - 1}{\omega^2}$	$0$	$\frac{\omega - 1}{\omega^2}$	$0$
$0$	$0$	$0$	$0$	$\frac{(\omega - 1)^2}{\omega^2}$	$0$	$-\frac{(\omega - 1)^2}{\omega^2}$	$0$
$0$	$-(\omega - 1)\omega$	$\omega - 1$	$(\omega - 1)^2$	$0$	$-\frac{\omega - 1}{\omega}$	$\frac{\omega - 1}{\omega}$	$0$
$0$	$0$	$0$	$0$	$\omega - 1$	$0$	$1 - \omega$	$0$
$0$	$(\omega - 1)\omega$	$1 - \omega$	$-(\omega - 1)^2$	$1 - \omega$	$\frac{\omega - 1}{\omega}$	$\frac{(\omega - 1)^2}{\omega}$	$0$
$0$	$0$	$0$	$0$	$0$	$0$	$0$	$0$

$\bar{Y}_{-11}$	$Y_4$	$Y_{10}$	$Y_7$	$Y_{14}$	$Y_{-1}$	$Y_{-5}$	$Y_{-8}$
$0$	$0$	$0$	$0$	$0$	$0$	$0$	$0$
$0$	$0$	$0$	$-1$	$-u$	$0$	$u$	$1$
$0$	$0$	$0$	$-u$	$1 - 2u^2$	$0$	$2u^2 - 1$	$0$
$0$	$-1$	$-u$	$2u^2 - 3$	$-u$	$-1$	$0$	$1$
$0$	$-u$	$1 - 2u^2$	$-u$	$-1$	$-u$	$-2(u-1)(u+1)$	$0$
$0$	$0$	$0$	$-1$	$-u$	$0$	$0$	$1$
$0$	$u$	$2u^2 - 1$	$0$	$-2(u-1)(u+1)$	$u$	$4u^2 - 3$	$0$
$0$	$1$	$u$	$1$	$u$	$1$	$0$	$1 - 2u^2$

## Column@{TL [B2], Kas [B2]}

$\bar{Y}_{-12}$	$Y_4$	$Y_8$	$Y_{14}$	$Y_{11}$	$Y_{-1}$	$Y_{-5}$	$Y_{-9}$
$\frac{(\omega - 1)^2}{\omega^2}$	$\omega - 1$	$-2(\omega - 1)$	$\frac{2(\omega - 1)^2}{\omega}$	$\frac{2(\omega - 1)^2}{\omega}$	$0$	$-\frac{2(\omega - 1)^2}{\omega}$	$-\frac{(\omega - 1)(2\omega - 1)}{\omega}$
$0$	$0$	$0$	$0$	$0$	$0$	$0$	$0$
$0$	$1 - \omega$	$0$	$-\frac{(\omega - 1)(2\omega - 1)}{\omega}$	$-\frac{2(\omega - 1)^2}{\omega}$	$0$	$\frac{2(\omega - 1)^2}{\omega}$	$\frac{2(\omega - 1)(\omega - 1)}{\omega}$
$0$	$0$	$0$	$\frac{2(\omega - 1)^2}{\omega}$	$-\frac{(\omega - 1)(2\omega - 1)}{\omega}$	$0$	$-\frac{2(\omega - 1)^2}{\omega}$	$-\frac{2(\omega - 1)(\omega - 1)}{\omega}$
$-2(\omega - 1)\omega$	$0$	$2(\omega - 1)\omega$	$-(\omega - 1)(2\omega - 1)$	$\frac{(\omega - 1)^2}{\omega}$	$-\frac{\omega - 1}{\omega}$	$\frac{2(\omega - 1)^2}{\omega}$	$2(\omega - 1)^2$
$0$	$0$	$0$	$0$	$\omega - 1$	$0$	$1 - \omega$	$0$
$2(\omega - 1)\omega$	$0$	$-2(\omega - 1)\omega$	$2(\omega - 1)\omega$	$-2(\omega - 1)$	$\frac{\omega - 1}{\omega}$	$\frac{(\omega - 1)^2}{\omega}$	$-(\omega - 1)(2\omega - 1)$
$-\frac{(\omega - 1)(2\omega - 1)}{\omega}$	$0$	$\frac{2(\omega - 1)(2\omega - 1)}{\omega}$	$-\frac{2(\omega - 1)(2\omega - 1)}{\omega}$	$\frac{2(\omega - 1)^2}{\omega}$	$0$	$-\frac{2(\omega - 1)(2\omega - 1)}{\omega}$	$\frac{2(\omega - 1)^2}{\omega}$

$1$	$\frac{1}{2\omega}$	$0$	$-\frac{1}{2\omega}$	$0$	$-\frac{1}{2\omega}$	$0$	$\frac{1}{2\omega}$
$\bar{Y}_{-12}$	$Y_4$	$Y_8$	$Y_{14}$	$Y_{11}$	$Y_{-1}$	$Y_{-5}$	$Y_{-9}$
$0$	$0$	$0$	$0$	$0$	$0$	$0$	$0$
$0$	$\frac{(2\omega - 1)(2\omega - 1)(2\omega^2 - 1)}{4\omega^2(4\omega^2 - 3)}$	$\frac{2\omega^2 - 1}{2\omega}$	$\frac{1}{4\omega^2(4\omega^2 - 3)}$	$0$	$-\frac{(2\omega - 1)(2\omega - 1)}{4\omega^2(4\omega^2 - 3)}$	$-\frac{1}{4\omega^2(4\omega^2 - 3)}$	$\frac{8\omega^4 - 6\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$
$0$	$-\frac{2\omega^2 - 1}{2\omega}$	$-2(u - 1)(u + 1)$	$-\frac{1}{2\omega}$	$0$	$0$	$0$	$\frac{1}{2\omega}$
$0$	$\frac{2\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$	$\frac{2\omega^2 - 1}{2\omega}$	$\frac{(2\omega - 1)(16\omega^4 - 16\omega^2 - 1)}{4\omega^2(4\omega^2 - 3)}$	$0$	$-\frac{8\omega^4 - 10\omega^2 - 1}{2\omega(4\omega^2 - 3)}$	$\frac{1}{4\omega^2(4\omega^2 - 3)}$	$\frac{16\omega^4 - 16\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$
$0$	$-\frac{(2\omega - 1)(2\omega - 1)}{4\omega^2(4\omega^2 - 3)}$	$-\frac{1}{2\omega}$	$\frac{8\omega^4 - 10\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$	$0$	$\frac{8\omega^4 - 10\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$	$\frac{8\omega^4 - 10\omega^2 - 1}{2\omega(4\omega^2 - 3)}$	$\frac{16\omega^4 - 16\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$
$0$	$-\frac{1}{2\omega(4\omega^2 - 3)}$	$0$	$\frac{8\omega^4 - 10\omega^2 - 1}{2\omega(4\omega^2 - 3)}$	$0$	$\frac{8\omega^4 - 10\omega^2 - 1}{2\omega(4\omega^2 - 3)}$	$\frac{2(\omega - 1)(\omega - 1)(2\omega - 1)}{4\omega^2 - 3}$	$\frac{8\omega^4 - 6\omega^2 - 1}{2\omega(4\omega^2 - 3)}$
$0$	$\frac{8\omega^4 - 6\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$	$\frac{1}{2\omega}$	$\frac{1}{4\omega^2(4\omega^2 - 3)}$	$0$	$\frac{16\omega^4 - 16\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$	$\frac{8\omega^4 - 6\omega^2 - 1}{2\omega(4\omega^2 - 3)}$	$\frac{32\omega^4 - 64\omega^2 - 1}{4\omega^2(4\omega^2 - 3)}$

$\begin{pmatrix} A & B \\ C & U \end{pmatrix} \xrightarrow{\det(A)} \begin{pmatrix} I & A^{-1}B \\ C & U \end{pmatrix} \xrightarrow{1} \begin{pmatrix} I & A^{-1}B \\ 0 & U - CA^{-1}B \end{pmatrix}$ . Roughly,  $\det(A)$  is "det on ker",  $-CA^{-1}B$  is "a pushforward of  $\begin{pmatrix} A & B \\ C & U \end{pmatrix}$ ".  
so  $\det \begin{pmatrix} A & B \\ C & U \end{pmatrix} = \det(A) \det(U - CA^{-1}B)$ . (what if  $\mathbb{A}A^{-1}$ ?)

**Questions.** 1. Does this have a topological meaning? 2. Is there a version of the Kashaev Conjecture for tangles? 3. Find all solutions of R123 in our "algebra". 4. Braids and the Burau representation. 5. Recover the work in "Prior Art". 6. Are there any concordance properties? 7. What is the "SPQ group"? 8. The jumping points of signatures are the roots of the Alexander polynomial. Does this generalize to tangles? 9. Which of the three Cordon cases is the most common? 10. Are there interesting examples of tangles for which rels is non-trivial? 11. Is the  $pq$  part determined by  $\Gamma$ -calculus? 12. Is the  $pq$  part determined by finite type invariants? 13. Does it work with closed components / links? 14. Strand-doubling formulas? 15. A multivariable version? 16. Mutation invariance? 17. Ribbon knots? 18. Are there "face-virtual knots"? 19. Does the pushforward story extend to ranks? To formal Gaussian measures? To super Gaussian measures?

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