

Bufallo Handout planning

September 5, 2017 8:17 AM

Bufallo

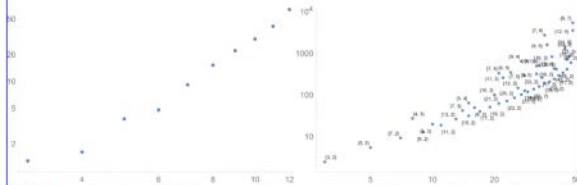
Full version: w/β/β/17

The Dogma is Wrong

Abstract. It has long been known that there are knot invariants associated to semi-simple Lie algebras, and there has long been a dogma as for how to extract them: “quantize and use representation theory”. We present an alternative and better procedure: “centrally extend, approximate by solvable, and learn how to re-order exponentials in a universal enveloping algebra”. While equivalent to the old invariants via a complicated process, our invariants are in practice stronger, faster to compute (poly-time vs. exp-time), and clearly carry topological information.

KiW 43 Abstract (ωεβ/kiw). Whether or not you like the formulas on this page, they describe the strongest truly computable knot invariant we know.

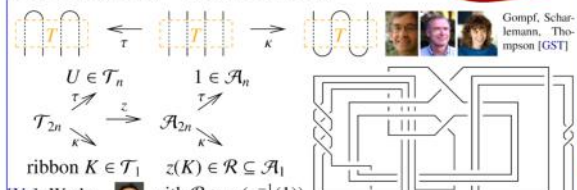
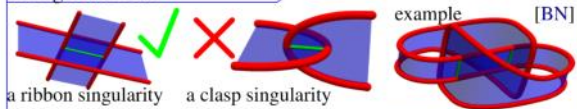
Experimental Analysis (ωεβ/Exp). Log-log plots of computation time (sec) vs. crossing number, for all knots with up to 12 crossings (mean times) and for all torus knots with up to 48 crossings:



Power. On the 250 knots with at most 10 crossings, the pair (ω, ρ_1) attains 250 distinct values, while (Khovanov, HOMFLY-PT) attains only 249 distinct values. To 11 crossings the numbers are (802, 788, 772) and to 12 they are (2978, 2883, 2786).

Genus. Up to 12 crossings, always ρ_1 is symmetric under $t \leftrightarrow t^{-1}$. With ρ_1^+ denoting the positive-degree part of ρ_1 , always $\deg \rho_1^+ \leq 2g - 1$, where g is the 3-genus of K (equality for 2530 knots). This gives a lower bound on g in terms of ρ_1 (conjectural, but undoubtedly true). This bound is often weaker than the Alexander bound, yet for 10 of the 12-xing Alexander failures it does give the right answer.

Ribbon Knots.



[Vo]: Works with $\mathcal{R} := \kappa(\tau^{-1}(1))$
 $A^+ = -r^8 + 2r^7 - r^6 - 2r^4 + 5r^3 - 2r^2 - 7r + 13$
 $\rho_1^+ = 5r^{15} - 18r^{14} + 33r^{13} - 32r^{12} + 2r^{11} + 42r^{10} - 62r^9 - 8r^8 + 166r^7 - 242r^6 + 108r^5 + 132r^4 - 226r^3 + 148r^2 - 11r - 36$
 Faster is better, leaner is meaner!

Ordering Symbols. \odot (poly | specs) plants the variables of poly in $S(\otimes_j \mathfrak{g})$ on several tensor copies of $\mathcal{U}(\mathfrak{g})$ according to specs. E.g.,
 $\odot(a_1^3 y_1 a_2 e^{y_3} x_3^9 | x_3 a_1 \otimes y_1 y_3 a_2) = x^9 a^3 \otimes y e^y a \in \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$
 This enables the description of elements of $\hat{\mathcal{U}}(\mathfrak{g})^{\otimes S}$ using commutative polynomials / power series.

Follows Rozansky [Ro1, Ro2, Ro3] and Overbay [Ov], joint with van der Veen. Preliminary writeup [BV1], fuller writeup [BV2]. More at ωεβ/talks.



Happy Birthday Anton [BV2] ωεβ:=http://drorbn.net/talks/

Theorem ([BNG], conjectured [MM], elucidated [Ro1]). Let $J_d(K)$ be the coloured Jones polynomial of K , in the d -dimensional representation of sl_2 . Writing

$$\left. \frac{(q^{1/2} - q^{-1/2}) J_d(K)}{q^{d/2} - q^{-d/2}} \right|_{q=e^h} = \sum_{j,m \geq 0} a_{jm}(K) d^j h^m,$$

“below diagonal” coefficients vanish, $a_{jm}(K) = 0$ if $j > m$, and “on diagonal” coefficients give the inverse of the Alexander polynomial: $(\sum_{m=0}^{\infty} a_{mm}(K) h^m) \cdot \omega(K)(e^h) = 1$.

Above diagonal we have Rozansky’s Theorem [Ro3, (1.2)]:

$$J_d(K)(q) = \frac{q^d - q^{-d}}{(q - q^{-1}) \omega(K)(q^d)} \left(1 + \sum_{k=1}^{\infty} \frac{(q-1)^k \rho_k(K)(q^d)}{\omega^{2k}(K)(q^d)} \right).$$

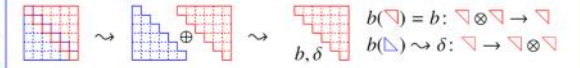
The Yang-Baxter Technique. Given an algebra U (typically $\mathcal{U}(\mathfrak{g})$ or $\hat{\mathcal{U}}(\mathfrak{g})$) and elements $R = \sum a_i \otimes b_i \in U \otimes U$ and $C \in U$, form $Z = \sum_{i,j,k} C a_i b_j a_k C^2 b_i a_j b_k C$.

Problem. Extract information from Z . The Dogma. Use representation theory. In principle finite, but slow.

The Loyal Opposition. For certain algebras, work in a homomorphic poly-dimensional “space of formulas”. $m_k^i \circ \{ \mathcal{F}_S \} \xrightarrow{\mathbb{E}} \{ U^{\otimes S} \} \xleftarrow{m_k^i}$

The (fake) moduli of Lie algebras on V , a quadratic variety in $(V^{\otimes 2} \otimes V)$ is on the right. We care about $sl_{17}^k := sl_{17}^k / (\epsilon^{k+1} = 0)$.

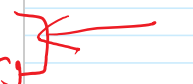
Recomposing gl_n . Half is enough! $gl_n \oplus \mathfrak{a}_n = \mathcal{D}(\nabla, b, \delta)$:



Now define $gl_n^\epsilon := \mathcal{D}(\nabla, b, \epsilon \delta)$. Schematically, this is $\nabla, \nabla] = \nabla, [\nabla, \Delta] = \epsilon \Delta$, and $\nabla, \Delta] = \Delta + \epsilon \nabla$. In detail, it is

$$\begin{aligned} [x_{ij}, x_{kl}] &= \delta_{jk} x_{il} - \delta_{il} x_{kj} & [y_{ij}, y_{kl}] &= \epsilon \delta_{jk} y_{il} - \epsilon \delta_{il} y_{kj} \\ [x_{ij}, y_{kl}] &= \delta_{jk} (\epsilon \delta_{j < k} x_{il} + \delta_{il} (b_j + \epsilon a_j) / 2 + \delta_{i > l} y_{il}) \\ &\quad - \delta_{il} (\epsilon \delta_{k < j} x_{kj} + \delta_{kj} (b_j + \epsilon a_j) / 2 + \delta_{k > j} y_{kj}) \\ [a_i, x_{jk}] &= (\delta_{ij} - \delta_{ik}) x_{jk} & [b_i, x_{jk}] &= \epsilon (\delta_{ij} - \delta_{ik}) x_{jk} \\ [a_i, y_{jk}] &= (\delta_{ij} - \delta_{ik}) y_{jk} & [b_i, y_{jk}] &= \epsilon (\delta_{ij} - \delta_{ik}) y_{jk} \end{aligned}$$

The Main sl_2 Theorem. Let $\mathfrak{g}^\epsilon = \langle t, y, a, x \rangle / ([t, \cdot] = 0, [a, x] = x, [a, y] = -y, [x, y] = t - 2\epsilon a)$ and let $\mathfrak{g}_k = \mathfrak{g}^\epsilon / (\epsilon^{k+1} = 0)$. The \mathfrak{g}_k -invariant of any S -component tangle K can be written in the form $Z(K) = \odot (\omega \otimes^{L+Q+P} : \otimes_{i \in S} y_i a_i x_i)$, where ω is a scalar (a rational function in the variables t_i and their exponentials $T_i := e^{t_i}$), where $L = \sum l_{ij} t_i a_j$ is a quadratic in t_i and a_j with integer coefficients l_{ij} , where $Q = \sum q_{ij} y_i x_j$ is a quadratic in the variables y_i and x_j with scalar coefficients q_{ij} , and where P is a polynomial in $\{\epsilon, y_i, a_i, x_i\}$ (with scalar coefficients) whose ϵ^d -term is of degree at most $2d+2$ in $\{y_i, \sqrt{a_i}, x_i\}$. Furthermore, after setting $t_i = t$ and $T_i = T$ for all i , the invariant $Z(K)$ is poly-time computable.



The PBW Problem. In $\mathcal{U}(\mathfrak{g}^e)$, bring $Z = y^3 a^2 x^2 \cdot y^2 a^2 x$ to yax -order. In other words, find $g \in Z[\epsilon, t, y, a, x]$ such that $Z = \mathcal{O}(f = y^3 y_2^2 a_1^2 x_2^2 : y_1 a_1 x_1 y_2 a_2 x_2) = \mathcal{O}(g : yax)$.

Solution, Part 1. In $\mathcal{U}(\mathfrak{g}^e)$ we have

$$X_{\tau_1, \eta_1, \alpha_1, \xi_1, \tau_2, \eta_2, \alpha_2, \xi_2} := e^{\tau_1 t} e^{\eta_1 y} e^{\alpha_1 a} e^{\xi_1 x} e^{\tau_2 t} e^{\eta_2 y} e^{\alpha_2 a} e^{\xi_2 x} = e^{\tau t} e^{\eta y} e^{\alpha a} e^{\xi x} =: Y_{\tau, \eta, \alpha, \xi},$$

where τ, η, α, ξ are ugly functions of $\tau_1, \eta_1, \alpha_1, \xi_1$:

$$\tau = \tau_1 + \tau_2 - \frac{\log(1 - \epsilon \eta_2 \xi_1)}{\epsilon} = \tau_1 + \tau_2 + \eta_2 \xi_1 + \frac{\epsilon}{2} \eta_2^2 \xi_1^2 + \dots,$$

$$\eta = \eta_1 + \frac{e^{-\alpha_1} \eta_2}{(1 - \epsilon \eta_2 \xi_1)} = \eta_1 + e^{-\alpha_1} \eta_2 + \epsilon e^{-\alpha_1} \eta_2^2 \xi_1 + \dots,$$

$$\alpha = \alpha_1 + \alpha_2 + 2 \log(1 - \epsilon \eta_2 \xi_1) = \alpha_1 + \alpha_2 - 2\epsilon \eta_2 \xi_1 + \dots,$$

$$\xi = \frac{e^{-\alpha_2} \xi_1}{(1 - \epsilon \eta_2 \xi_1)} + \xi_2 = e^{-\alpha_2} \xi_1 + \xi_2 + \epsilon e^{-\alpha_2} \eta_2 \xi_1^2 + \dots$$

Note 1. This defines a mapping $\Phi: \mathbb{R}^8_{\tau_1, \eta_1, \alpha_1, \xi_1, \tau_2, \eta_2, \alpha_2, \xi_2} \rightarrow \mathbb{R}^4_{\tau, \eta, \alpha, \xi}$.

Proof. \mathfrak{g}^e has a 2D representation ρ :

$$\rho t = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}; \rho y = \begin{pmatrix} 0 & 0 \\ -\epsilon & 0 \end{pmatrix};$$

$$\rho a = \begin{pmatrix} (1 + 1/\epsilon) / 2 & 0 \\ 0 & -(1 - 1/\epsilon) / 2 \end{pmatrix}; \rho x = \begin{pmatrix} 0 & 1 \\ \theta & 0 \end{pmatrix};$$

$$\text{Simplify}[\{\rho a \cdot \rho x - \rho x \cdot \rho a = \rho x, \rho a \cdot \rho y - \rho y \cdot \rho a = -\rho y, \rho x \cdot \rho y - \rho y \cdot \rho x = \rho t - 2\epsilon \rho a\}]$$

(True, True, True)

It is enough to verify the desired identity in ρ :

ME = MatrixExp;

Simplify[

$$\text{ME}[\tau_1 \rho t] \cdot \text{ME}[\eta_1 \rho y] \cdot \text{ME}[\alpha_1 \rho a] \cdot \text{ME}[\xi_1 \rho x] \cdot \text{ME}[\tau_2 \rho t] \cdot \text{ME}[\eta_2 \rho y] \cdot \text{ME}[\alpha_2 \rho a] \cdot \text{ME}[\xi_2 \rho x] = \text{ME}[\tau_0 \rho t] \cdot \text{ME}[\eta_0 \rho y] \cdot \text{ME}[\alpha_0 \rho a] \cdot \text{ME}[\xi_0 \rho x] / \left\{ \begin{aligned} \tau_0 &\rightarrow -\frac{\log(1 - \epsilon \eta_2 \xi_1)}{\epsilon} + \tau_1 + \tau_2, \eta_0 \rightarrow \eta_1 + \frac{e^{-\alpha_1} \eta_2}{1 - \epsilon \eta_2 \xi_1}, \\ \alpha_0 &\rightarrow 2 \text{Log}[1 - \epsilon \eta_2 \xi_1] + \alpha_1 + \alpha_2, \xi_0 \rightarrow \frac{e^{-\alpha_2} \xi_1}{1 - \epsilon \eta_2 \xi_1} + \xi_2 \end{aligned} \right\}]$$

True

Solution, Part 2. But now, with $D_f = f(z \mapsto \partial_z) =$

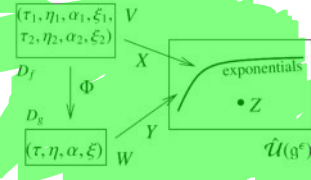
$$\partial_{\eta_1}^3 \partial_{\alpha_1}^2 \partial_{\xi_1}^2 \partial_{\eta_2}^2 \partial_{\alpha_2}^2 \partial_{\xi_2}^2,$$

$$Z = D_f X_{\tau_1, \eta_1, \alpha_1, \xi_1, \tau_2, \eta_2, \alpha_2, \xi_2} \Big|_{y=x=0} = D_f Y_{\tau, \eta, \alpha, \xi} \Big|_{y=x=0} = \mathcal{O}(D_f e^{\tau t} e^{\eta y} e^{\alpha a} e^{\xi x} \Big|_{y=x=0} : yax) = \mathcal{O}(g : yax);$$

$$\text{Expand}[\partial_{(\eta_1, 3)} \partial_{(\alpha_1, 2)} \partial_{(\xi_1, 2)} \partial_{(\eta_2, 2)} \partial_{(\alpha_2, 2)} \partial_{(\xi_2, 2)} \text{Exp} \left[\begin{aligned} &(-\frac{\log(1 - \epsilon \eta_2 \xi_1)}{\epsilon} + \tau_1 + \tau_2) t + \left(\eta_1 + \frac{e^{-\alpha_1} \eta_2}{1 - \epsilon \eta_2 \xi_1} \right) y + \\ &(2 \text{Log}[1 - \epsilon \eta_2 \xi_1] + \alpha_1 + \alpha_2) a + \left(\frac{e^{-\alpha_2} \xi_1}{1 - \epsilon \eta_2 \xi_1} + \xi_2 \right) x \end{aligned} \right] / . (\tau | \eta | \alpha | \xi)_{1|2 \rightarrow 0}]$$

$$2 a^4 t^2 x y^3 + 4 t x^2 y^4 - 16 a t x^2 y^4 + 24 a^2 t x^2 y^4 - 16 a^3 t x^2 y^4 + 4 a^4 t x^2 y^4 + 16 x^3 y^5 - 32 a x^3 y^5 + 24 a^2 x^3 y^5 - 8 a^3 x^3 y^5 + a^4 x^3 y^5 + 2 a^4 t x y^3 \epsilon - 8 a^5 t x y^3 \epsilon + 8 x^2 y^4 \epsilon - 40 a x^2 y^4 \epsilon + 80 a^2 x^2 y^4 \epsilon - 80 a^3 x^2 y^4 \epsilon + 40 a^4 x^2 y^4 \epsilon - 8 a^5 x^2 y^4 \epsilon - 4 a^5 x y^3 \epsilon^2 + 8 a^6 x y^3 \epsilon^2$$

Note 2. Replacing $f \rightarrow D_f$ (and likewise $g \rightarrow D_g$), we find that $D_g = \Phi_* D_f$.



Note 3. The two great evils of mathematics are non-commutativity and non-linearity. We traded one for the other.

Note 4. We could have done similarly with $e^{\tau t} e^{\eta y} e^{\alpha a} e^{\xi x} = e^{\tau t + \eta y + \alpha a + \xi x}$, and with $S(e^{\tau t} e^{\eta y} e^{\alpha a} e^{\xi x})$, $\Delta(e^{\tau t} e^{\eta y} e^{\alpha a} e^{\xi x})$, $\prod_{i=1}^5 e^{\tau_i t} e^{\eta_i y} e^{\alpha_i a} e^{\xi_i x}$.

Fact. $R_{12} \rightarrow \exp(\partial_{\tau_1} \partial_{\alpha_2} + \partial_{y_1} \partial_{x_2})(1 + \sum_{d \geq 1} \epsilon^d p_d)$, where the p_d are computable polynomials of a-priori bounded degrees.

Moral. We need to understand the pushforwards via maps like Φ of (formally ∞ -order) "differential operators at 0", that in themselves are perturbed Gaussians. This turns out to be the same problem as "0-dimensional QFT" (except no integration is ever needed), and if $\epsilon^{k+1} = 0$, it is explicitly soluble.

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dog·ma

(dɔg'mə, dɔg' -) The Free Dictionary, [oeft/TFD](#)

- n. pl. dog·mas or dog·ma·ta (-mə-tə)
1. A doctrine or a corpus of doctrines relating to matters such as morality and faith, set forth in an authoritative manner by a religion.
 2. A principle or statement of ideas, or a group of such principles or statements, especially when considered to be authoritative or accepted uncritically: "Much education consists in the instilling of unfounded dogmas in place of a spirit of inquiry" (Bertrand Russell).

diagram	n'_k	Alexander's ω^+	genus / ribbon	diagram	n'_k	Alexander's ω^+	genus / ribbon
	Today's / Rozansky's ρ'_k	unknotting number / amphicheiral			Today's / Rozansky's ρ'_k	unknotting number / amphicheiral	
	$0'_1$	1	0 / ✓		$3'_1$	$t - 1$	1 / ✗
	$4'_1$	$3 - t$	1 / ✗		$5'_1$	$t^2 - t + 1$	2 / ✗
	0		1 / ✓		$2t^3 + 3t$		2 / ✗
	$5'_2$	$2t - 3$	1 / ✗		$6'_1$	$5 - 2t$	1 / ✓
	$5t - 4$		1 / ✗		$t - 4$		1 / ✗

more at web/...

