

# Aw-Calculus Programs for the WKO4 Paper

Pensieve header: Aw-calculus programs for the WKO4 paper.

“d” is “ht”: along tube strands, heads appear before tails.

## Utilities

```

⟨{λ___}⟩ := ⟨λ⟩;
Support[⟨λ___⟩] := First /@ {λ};
λ \ key_ := DeleteCases[λ, key → _];
λ \ keys_List := Fold[#1 \ #2 &, λ, keys];
⟨λ___⟩_s := s /. {λ};
(λ_AngleBracket)[d_] := ⟨Table[u → λ_u[d], {u, Support[λ]}]⟩;
Crop[λ_AngleBracket, d_] := MapAt[Crop[#, d] &, λ, {All, 2}];
AngleBracket /:
  λ1_AngleBracket ≡ λ2_AngleBracket /; Support[λ1] == Support[λ2] :=
  ⟨Table[s → λ1_s ≡ λ2_s, {s, Support[λ1]}]⟩
AngleBracket /: Plus[λs__AngleBracket] := ⟨Table[
  u → Total[#_ & /@ {λs}],
  {u, Union@@(Support[#] & /@ {λs})}
]⟩;
AngleBracket /: c_ * λ_AngleBracket := ⟨Table[
  u → Expand[c λ_u],
  {u, Support[λ]}
]⟩;
AngleBracket /: λ_AngleBracket // DerivationSeries[f_, ld_LieDerivation] :=
  MapAt[DerivationSeries[f, ld], λ, {All, 2}];
AngleBracket /: λ_AngleBracket // mor_LieMorphism := MapAt[mor, λ, {All, 2}];
AngleBracket /: Integrate[λ_AngleBracket, {s_, s0_, s1_}] :=
  ⟨Table[u → Integrate[λ_u, {s, s0, s1}], {u, Support[λ]}]⟩;
AngleBracket /: CC[⟨λ___⟩] := CC[LW /@ First /@ {λ}, Last /@ {λ}];
λ_AngleBracket // DegreeScale[h_] := MapAt[DegreeScale[h], λ, {All, 2}];
deg /: (h_)^deg := DegreeScale[h];

```

## Tangential Derivations, the Tangential Bracket $tb$ , $div$ and $j$

```

TangentialDerivation[⟨λ__⟩] :=
  LieDerivation[{λ} /. (s_ → λs_) ⇒ (LW[s] → b[LW[s], λs])];
tb[λ1_AngleBracket, λ2_AngleBracket] /. Support[λ1] == Support[λ2] := ⟨Table[
  s →
    b[λ1_s, λ2_s] + TangentialDerivation[λ1][λ2_s] - TangentialDerivation[λ2][λ1_s],
  {s, Support[λ1]}
]⟩;
div[λ_AngleBracket] := Sum[div_s[λ_s], {s, Support[λ]}];
j[λ_AngleBracket] :=
  DerivationSeries[ $\frac{e^{der} - 1}{der}$ , TangentialDerivation[λ]][div[λ]];

```

## Evaluating Lie Series in ⟨...⟩

```

LieMorphism[rules_Rule, keys_AngleBracket, br_] :=
  LieMorphism[{rules}, keys, br];
LieMorphism[rules_List, keys_AngleBracket, br_] := New[LieMorphism[mor],
  mor[Support] = First /@ rules;
  (mor[w_LW] /. Deg[w] == 1) := (mor[w] = w /. rules);
  mor[w_LW] := (mor[w] = br @@ (mor /@ LyndonFactorization[w]));
  mor[expr_][d_] := Expand[expr /. w_LW ⇒ mor[w][d]];
  mor[ls_LieSeries] := mor[ls] = Module[{ser},
    ⟨Table[
      ReleaseHold[Hold[
        ser[] = Hold[AngleBracketFromLieMorphism[mor, ls, ss]];
        ser[d_Integer] := ser[d] =  $\left(\sum_{k=1}^d \text{mor}[ls[k]][d]\right)_{ss}$ ;
        ss → LieSeries[ser]
      ] /. {ss → s, ser → Unique[LieSeriesInAngleBracket]}],
      {s, List@@keys}
    ]⟩
  ];
BCH[x_, y_, keys_AngleBracket, br_] :=
  LieMorphism[{LW["x"] → x, LW["y"] → y}, keys, br][BCHBase];
adSeries[f_, λ1_AngleBracket, br_][λ2_AngleBracket] /.
  Support[λ1] == Support[λ2] :=
  LieMorphism[{LW["x"] → λ1, LW["y"] → λ2}, ⟨Support[λ1]⟩, br][
  adSeries[f, LW["x"]][LW["y"]]];

```

## The AT Presentation $E_I$ of $A^W$

```

E1 /: E1[λ1_, ω1_] ∪ E1[λ2_, ω2_] /; Support[λ1] ∩ Support[λ2] == {} :=
  E1[λ1 ∪ λ2, ω1 + ω2];
E1 /: E1[λ1_, ω1_] ** E1[λ2_, ω2_] /; Support[λ1] == Support[λ2] :=
  E1[BCH[λ1, λ2, <Support[λ1]>, tb],
    ω1 + DerivationExp[TangentialDerivation[λ1]][ω2]];
E1[λ_, ω_] // dA := E1[-λ, DerivationExp[TangentialDerivation[λ]][ω] - j[λ]];
E1[λ_, ω_] // dS := E1[
  -λ // (-1)deg,
  (DerivationExp[TangentialDerivation[λ]][ω] - j[λ]) // (-1)deg
];

```

## The KBH Presentation $E_S$ of $A^W$

```

Es /: Es[λ1_, ω1_] ∪ Es[λ2_, ω2_] /; Support[λ1] ∩ Support[λ2] == {} :=
  Es[λ1 ∪ λ2, ω1 + ω2];

to[us_List → vs_List][ser_LieSeries | ser_CWSeries | ser_AngleBracket] :=
  ser // LieMorphism[Thread[(LW/@us) → (LW/@vs)]];
to[u_, v_] := to[{u} → {v}];
to[us_List → vs_List][ξ_Es] := to[us → vs] /@ ξ;
ho[xs_List → ys_List][λ_AngleBracket] :=
  Union[λ \ xs, <Thread[ys → Table[λ_x, {x, xs}]]>];
ho[x_, y_] := ho[{x} → {y}];
ho[xs_List → ys_List][Es[λ_, ω_]] := Es[λ // ho[xs → ys], ω];
do[as_List → bs_List][ξ_] := ξ // to[as → bs] // ho[as → bs];
do[a_, b_][ξ_] := ξ // to[a, b] // ho[a, b];

tm[u_, v_, w_][λ_AngleBracket] := λ // LieMorphism[LW@u → LW@w, LW@v → LW@w];
tm[u_, v_, w_][Es[λ_, ω_]] := LieMorphism[LW@u → LW@w, LW@v → LW@w] /@ Es[λ, ω];
hm[x_, y_, z_][λ_AngleBracket] := Union[λ \ {x, y}, <z → BCH[λ_x, λ_y]>];
hm[x_, y_, z_][Es[λ_, ω_]] := Es[λ // hm[x, y, z], ω];
tha[u_LW, x_][λ_AngleBracket] := λ // RC_u[λ_x];
tha[u_LW, x_][Es[λ_, ω_]] := Es[λ // tha[u, x], (ω + J_u[λ_x]) // RC_u[λ_x]];
dm[a_, b_, c_][ξ_] := ξ // tha[LW@a, b] // tm[LW@a, LW@b, LW@c] // hm[a, b, c];
dm[a_, b_, rest_, c_][ξ_] := ξ // dm[b, rest, b] // dm[a, b, c];

Es /: Es[λ1_, ω1_] ** Es[λ2_, ω2_] /; Support[λ1] == Support[λ2] := Module[
  {supp, temps, ξ},
  supp = Support[λ1];
  temps = Complement[Characters["0123456789abcdefghijklmnopqrstuvwxyz"],
    ToString /@ supp][[1 ;; Length@supp]];
  ξ = Es[λ1, ω1] ∪ (Es[λ2, ω2] // do[supp → temps]);
  MapThread[(ξ = ξ // dm[#1, #2, #1]) &, {supp, temps}] // Last
];

```

```

tA[u_][expr_] := expr;
hA[x_][Es[λ_, ω_]] := Es[Union[λ \ x, ⟨x → -λ_x⟩], ω];
dA[a_][μ_] := μ // hA[a] // tha[LW@a, a];
dA[a_, rest_][μ_] := μ // dA[a] // dA[rest];
Es[λ_, ω_] // dA := Es[λ, ω] // (dA @@ Support[λ])

tS[u_][λ_AngleBracket] :=
  <Table[x → LieMorphism[LW@u → -LW@u][λ_x], {x, Support[λ]}]>;
tS[u_][Es[λ_, ω_]] := Es[λ // tS[u], ω // LieMorphism[LW@u → -LW@u]];
hS[x_][Es[λ_, ω_]] := Es[Union[λ \ x, ⟨x → -λ_x⟩], ω];
dS[a_][μ_] := μ // tS[a] // hS[a] // tha[LW@a, a];
dS[a_, rest_][μ_] := μ // dS[a] // dS[rest];
Es[λ_, ω_] // dS := Es[λ, ω] // (dS @@ Support[λ])

```

## The $E_l \leftrightarrow E_s$ Conversions

```

Γ[-1, λ_AngleBracket, _] := <Table[s → MakeLieSeries[0], {s, Support[λ]}>;
Γ[n_, λ_AngleBracket, t_] := Γ[n, λ, t] = Module[{τ, Γ0},
  Γ0 = Γ[n-1, λ, τ];
  <Table[
    s → ∫₀ᵗ (λ_s // DerivationExp[-τ TangentialDerivation[λ]] //
      adSeries[ $\frac{\text{ad}}{e^{\text{ad}} - 1}$ , Γ0_s]) dτ,
    {s, Support[λ]}
  ]>
];
Γ[λ_AngleBracket, t_] := Γ[λ, t] = <Table[
  s → New[LieSeries[ser],
    With[{s = s}, ser[d_Integer] := ser[d] = (Γ[d-1, λ, t]_s)[d]]],
  {s, Support[λ]}
]>;
Γ[λ_AngleBracket] := Γ[λ, 1];
Γi[λ_AngleBracket] := Γi[λ] = <Table[With[{s = s},
  s → New[LieSeries[ser],
    ser[d_Integer] := ser[d] = λ_s[d] - Γ[Crop[Γi[λ], d-1]]_s[d]]],
  {s, Support[λ]}
]>;
Γ /: Γ⁻¹ = Γi;
Es[El[λ_, ω_]] := Es[Γ[λ], ω];
El[Es[λ_, ω_]] := El[Γ⁻¹[λ], ω];

```

```

 $\Lambda[-1, \lambda\_AngleBracket, \_ ] := \langle Table[s \rightarrow MakeLieSeries[0], \{s, Support[\lambda]\}] \rangle;$ 
 $\Lambda[n, \lambda\_AngleBracket, t\_ ] := \Lambda[n, \lambda, t] = Module[\{\tau, \Lambda0\},$ 
   $\Lambda0 = \Lambda[n-1, \lambda, \tau];$ 
  (* I'm confused why the first
  two options below do not give the same answer *)
   $\int_0^t \left( \lambda // DerivationExp[TangentialDerivation[\Lambda0]] //$ 
     $adSeries\left[\frac{ad}{e^{ad}-1}, \Lambda0, tb\right] \right) d\tau$ 
  (* $\epsilon_1 \int_0^t (\lambda // CC[\epsilon_2 \tau \lambda] // adSeries\left[\frac{\epsilon_3 ad}{e^{\epsilon_3 ad}-1}, \epsilon_4 \Lambda0, tb\right]) d\tau$ *)
  (* $\epsilon_1 \int_0^t (\lambda // DerivationExp[\epsilon_2 TangentialDerivation[\Lambda0]] //$ 
     $adSeries\left[\frac{\epsilon_3 ad}{e^{\epsilon_3 ad}-1}, \epsilon_4 \Lambda0, tb\right]) d\tau$ *)
  (* $\epsilon_1 \int_0^t (\lambda // DerivationExp[\epsilon_2 \tau TangentialDerivation[\lambda]] //$ 
     $adSeries\left[\frac{\epsilon_3 ad}{e^{\epsilon_3 ad}-1}, \epsilon_4 \Lambda0, tb\right]) d\tau$ *)
   $];$ 
 $\Lambda[\lambda\_AngleBracket, t\_ ] := \Lambda[\lambda, t] = \langle Table[$ 
   $s \rightarrow New[LieSeries[ser],$ 
   $With[\{s = s\}, ser[d\_Integer] := ser[d] = (\Lambda[d-1, \lambda, t]_s)[d]];$ 
   $],$ 
   $\{s, Support[\lambda]\}$ 
 $]\rangle;$ 
 $\Lambda[\lambda\_AngleBracket] := \Lambda[\lambda, 1];$ 

(* $\Lambda[\lambda\_AngleBracket] :=$ 
   $Module[\{\tau\}, \int_0^1 (\lambda // DerivationExp[\tau TangentialDerivation[\lambda]] //$ 
     $adSeries\left[\frac{ad}{e^{ad}-1}, -\tau \lambda, tb\right]) d\tau$ *)

```