

Aw-Calculus Programs for the WKO4 Paper

Pensieve header: Aw-calculus programs for the WKO4 paper.

“d” is “ht”: along tube strands, heads appear before tails.

Utilities

```

⟨{λ___}⟩ := ⟨λ⟩;
Support[⟨λ___⟩] := First /@ {λ};
λ \ key_ := DeleteCases[λ, key → _];
λ \ keys_List := Fold[#1 \ #2 &, λ, keys];
⟨λ___⟩_s := s /. {λ};
(λ_AngleBracket)[d_] := ⟨Table[u → λ_u[d], {u, Support[λ]}]⟩;
Crop[λ_AngleBracket, d_] := MapAt[Crop[#, d] &, λ, {All, 2}];
AngleBracket /: Plus[λs_AngleBracket] := ⟨Table[
  u → Total[#_ & /@ {λs}],
  {u, Union@@(Support[#] & /@ {λs})}
]⟩;
AngleBracket /: c_ * λ_AngleBracket := ⟨Table[
  u → Expand[c λ_u],
  {u, Support[λ]}
]⟩;
AngleBracket /: λ_AngleBracket // mor_LieMorphism := MapAt[mor, λ, {All, 2}];
λ_AngleBracket // DegreeScale[h_] := MapAt[DegreeScale[h], λ, {All, 2}];
deg /: (h_)^deg := DegreeScale[h];

```

Tangential Derivations, the Tree Bracket tb, div and j

```

TangentialDerivation[⟨λ___⟩] :=
  LieDerivation[{λ} /. (s_ → λs_) => (LW[s] → b[LW[s], λs])];
tb[λ1_AngleBracket, λ2_AngleBracket] /: Support[λ1] == Support[λ2] := ⟨Table[
  s →
    b[λ1_s, λ2_s] + TangentialDerivation[λ1][λ2_s] - TangentialDerivation[λ2][λ1_s],
  {s, Support[λ1]}
]⟩;
div[λ_AngleBracket] := Sum[div_s[λ_s], {s, Support[λ]}];
j[λ_AngleBracket] :=
  DerivationSeries[ $\frac{e^{\text{der}} - 1}{\text{der}}$ , TangentialDerivation[λ]][div[λ]];

```

Evaluating Lie Series in $\langle \dots \rangle$

```

LieMorphism[rules__Rule, keys_AngleBracket, br_] :=
  LieMorphism[{rules}, keys, br];
LieMorphism[rules_List, keys_AngleBracket, br_] := New[LieMorphism[mor],
  mor[Support] = First /@ rules;
  (mor[w_LW] /; Deg[w] == 1) := (mor[w] = w /. rules);
  mor[w_LW] := (mor[w] = br @@ (mor /@ LyndonFactorization[w]));
  mor[expr_] [d_] := Expand[expr /. w_LW :=> mor[w] [d]];
  mor[ls_LieSeries] := mor[ls] = Module[{ser},
    {
      Table[
        ReleaseHold[Hold[
          ser[] = Hold[AngleBracketFromLieMorphism[mor, ls, ss]];
          ser[d_Integer] := ser[d] =  $\left( \sum_{k=1}^d \text{mor}[ls[k]] [d] \right)_{ss}$ ;
          ss → LieSeries[ser]
        ] /. {ss → s, ser → Unique[LieSeriesInAngleBracket]}],
        {s, List@@keys}
      ]
    ]
  ];
BCH[x_, y_, keys_AngleBracket, br_] :=
  LieMorphism[{LW["x"] → x, LW["y"] → y}, keys, br][BCHBase];

```

The AT Presentation E_l of A^W

```

E1 /: E1[λ1_, ω1_] ∪ E1[λ2_, ω2_] /; Support[λ1] ∩ Support[λ2] == {} :=
  E1[λ1 ∪ λ2, ω1 + ω2];
E1 /: E1[λ1_, ω1_] ** E1[λ2_, ω2_] /; Support[λ1] == Support[λ2] :=
  E1[BCH[λ1, λ2, {1, 2}, tb], ω1 + DerivationExp[TangentialDerivation[λ1]][ω2]];
E1[λ_, ω_] // dA := E1[-λ, DerivationExp[TangentialDerivation[λ]][ω] - j[λ]];
E1[λ_, ω_] // dS := E1[
  -λ // (-1)deg,
  (DerivationExp[TangentialDerivation[λ]][ω] - j[λ]) // (-1)deg
];

```

The KBH Presentation E_s of A^W

```

Es /: Es[λ1_, ω1_] ∪ Es[λ2_, ω2_] /; Support[λ1] ∩ Support[λ2] == {} :=
  Es[λ1 ∪ λ2, ω1 + ω2];

```

```

tσ[us_List → vs_List][ser_LieSeries | ser_CWSeries | ser_AngleBracket] :=
  ser // LieMorphism[Thread[(LW/@us) → (LW/@vs)]];
tσ[u_, v_] := tσ[{u} → {v}];
tσ[us_List → vs_List][ξ_Es] := tσ[us → vs] /@ ξ;
hσ[xs_List → ys_List][λ_AngleBracket] :=
  Union[λ \ xs, ⟨Thread[ys → Table[λ_x, {x, xs}]]⟩];
hσ[x_, y_] := hσ[{x} → {y}];
hσ[xs_List → ys_List][Es[λ_, ω_]] := Es[λ // hσ[xs → ys], ω];
dσ[as_List → bs_List][ξ_] := ξ // tσ[as → bs] // hσ[as → bs];
dσ[a_, b_][ξ_] := ξ // tσ[a, b] // hσ[a, b];

tm[u_, v_, w_][λ_AngleBracket] := λ // LieMorphism[LW@u → LW@w, LW@v → LW@w];
tm[u_, v_, w_][Es[λ_, ω_]] := LieMorphism[LW@u → LW@w, LW@v → LW@w] /@ Es[λ, ω];
hm[x_, y_, z_][λ_AngleBracket] := Union[λ \ {x, y}, ⟨z → BCH[λ_x, λ_y]⟩];
hm[x_, y_, z_][Es[λ_, ω_]] := Es[λ // hm[x, y, z], ω];
tha[u_LW, x_][λ_AngleBracket] := λ // RC_u[λ_x];
tha[u_LW, x_][Es[λ_, ω_]] := Es[λ // tha[u, x], (ω + J_u[λ_x]) // RC_u[λ_x]];
dm[a_, b_, c_][ξ_] := ξ // tha[LW@a, b] // tm[LW@a, LW@b, LW@c] // hm[a, b, c];
dm[a_, b_, rest_, c_][ξ_] := ξ // dm[b, rest, b] // dm[a, b, c];

Es /: Es[λ1_, ω1_] ** Es[λ2_, ω2_] /; Support[λ1] == Support[λ2] := Module[
  {supp, temps, ξ},
  supp = Support[λ1];
  temps = Complement[Characters["0123456789abcdefghijklmnopqrstuvwxyz"],
    ToString /@ supp][[1 ;; Length@supp]];
  ξ = Es[λ1, ω1] ∪ (Es[λ2, ω2] // dσ[supp → temps]);
  MapThread[(ξ = ξ // dm[#1, #2, #1]) &, {supp, temps}] // Last
];

tA[u_][expr_] := expr;
hA[x_][Es[λ_, ω_]] := Es[Union[λ \ x, ⟨x → -λ_x⟩], ω];
dA[a_][μ_] := μ // hA[a] // tha[LW@a, a];
dA[a_, rest_][μ_] := μ // dA[a] // dA[rest];
Es[λ_, ω_] // dA := Es[λ, ω] // (dA @@ Support[λ])

tS[u_][λ_AngleBracket] :=
  ⟨Table[x → LieMorphism[LW@u → -LW@u][λ_x], {x, Support[λ]}]⟩;
tS[u_][Es[λ_, ω_]] := Es[λ // tS[u], ω // LieMorphism[LW@u → -LW@u]];
hS[x_][Es[λ_, ω_]] := Es[Union[λ \ x, ⟨x → -λ_x⟩], ω];
dS[a_][μ_] := μ // tS[a] // hS[a] // tha[LW@a, a];
dS[a_, rest_][μ_] := μ // dS[a] // dS[rest];
Es[λ_, ω_] // dS := Es[λ, ω] // (dS @@ Support[λ])

```

The $E_l \leftrightarrow E_s$ Conversions

```

Γ[-1, λ_AngleBracket, _] := <Table[s → MakeLieSeries[0], {s, Support[λ]}]>;
Γ[n_, λ_AngleBracket, t_] := Γ[n, λ, t] = Module[{τ, Γ0},
  Γ0 = Γ[n-1, λ, τ];
  {Table[
    s → ∫₀ᵗ (λ_s // DerivationExp[-τ TangentialDerivation[λ]] //
      adSeries[ $\frac{\text{ad}}{e^{\text{ad}} - 1}$ , Γ0_s]) dτ,
    {s, Support[λ]}
  ]}
];
Γ[λ_AngleBracket, t_] := Γ[λ, t] = <Table[
  s → New[LieSeries[ser],
    With[{s = s}, ser[d_Integer] := ser[d] = (Γ[d-1, λ, t]_s)[d]];
  ],
  {s, Support[λ]}
]>;
Γ[λ_AngleBracket] := Γ[λ, 1];
Γi[λ_AngleBracket] := Γi[λ] = <Table[With[{s = s},
  s → New[LieSeries[ser],
    ser[d_Integer] := ser[d] = λ_s[d] - Γ[Crop[Γi[λ], d-1]]_s[d]
  ]],
  {s, Support[λ]}
]>;
Γ /: Γ⁻¹ = Γi;
Es[El[λ_, ω_]] := Es[Γ[λ], ω];
El[Es[λ_, ω_]] := El[Γ⁻¹[λ], ω];

```