

Pensieve header: Exp relative to am, bm, cm, dm.

Follows code in Projects/SL2Portfolio/SL2PortfolioProgram.nb.

Startup

```
In[ ]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\SL2Portfolio2"];
(*Once[<< KnotTheory`];*)
Once[<< "../Profile/Profile.m"];
<< "Engine-Speedy.m";
<< "Objects.m";
$k = 3;
HL[ ] := Style[ , Background -> Green];
```

This is Profile.m of <http://www.drorbn.net/AcademicPensieve/Projects/Profile/>.

This version: April 2020. Original version: July 1994.

- » Warning: On Sep 4 2019 I swapped the operations ϵ and η . Some incompatibilities may arise in older notebooks.

Exponentials as needed.

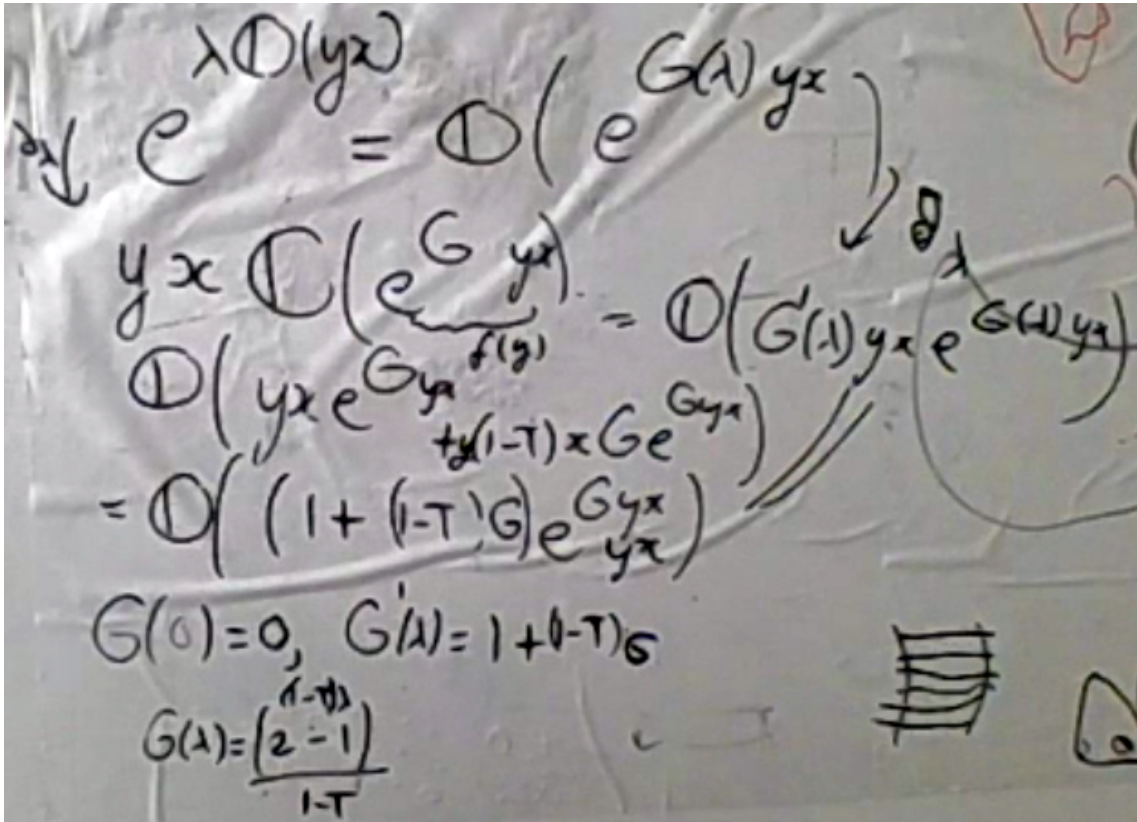
Task. Define $\text{Exp}_{m,i,k}[P]$ to compute $e^{\mathcal{O}(P)}$ to ϵ^k in the using the $\text{mm}_{i,j \rightarrow i}$ multiplication, where P is an ϵ -dependent near-docile element, giving the answer in E-form.

Methodology. If $P_0 := P_{\epsilon=0}$ and $e^{\lambda \mathcal{O}(P)} = \mathcal{O}(e^{\lambda P_0} F(\lambda))$, then $F(\lambda = 0) = 1$ and we have:

$$\mathcal{O}(e^{\lambda P_0}(P_0 F(\lambda) + \partial_\lambda F)) = \mathcal{O}(\partial_\lambda e^{\lambda P_0} F(\lambda)) = \partial_\lambda \mathcal{O}(e^{\lambda P_0} F(\lambda)) = \partial_\lambda e^{\lambda \mathcal{O}(P)} = e^{\lambda \mathcal{O}(P)} \mathcal{O}(P) = \mathcal{O}(e^{\lambda P_0} F(\lambda)) \mathcal{O}(P).$$

This is a linear ODE for F . Setting inductively $F_k = F_{k-1} + \epsilon^k \varphi$ we find that $F_0 = 1$ and solve for φ .

```
(* Bug: The first line is valid only if  $\mathcal{O}(e^{P_0}) = e^{\mathcal{O}(P_0)}$ . *)
Exp_{mm_,i_,0}[P_] := Module[{LQ = Normal@P /.  $\epsilon \rightarrow 0$ },
  E[LQ /. (x | y)_i -> 0, LQ /. (b | a | t)_i -> 0, 1] ];
```



$mm = dm; i = 1; P0 = b_1 a_1 + y_1 x_1;$

$G =$

\$k=0, Example 1

$In[*]:= mm = dm; P0 = y_i x_i;$

$In[*]:= \mathbb{E}G = \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] b_\theta a_\theta, QG[\lambda] y_\theta x_\theta, 1 + O[\epsilon]]$

$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] a_\theta b_\theta, QG[\lambda] x_\theta y_\theta, 1 + O[\epsilon]^1]$

$In[*]:= (\mathbb{E}_{\{\} \rightarrow \{i\}} [\theta, \theta, P0 + O[\epsilon]] \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] b_\theta a_\theta, QG[\lambda] y_\theta x_\theta, 1 + O[\epsilon]]) // mm_{i, \theta \rightarrow \theta}$

$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] a_\theta b_\theta, QG[\lambda] x_\theta y_\theta, \frac{(QG[\lambda] - QG[\lambda] B_\theta + \hbar B_\theta^{\frac{LG[\lambda]}}{\hbar}) x_\theta y_\theta}{\hbar} + O[\epsilon]^1]$

$In[*]:= \mathbb{E}_{\{\} \rightarrow \{i\}} [\theta, \theta, P0 + O[\epsilon]] \mathbb{E}_{\{\} \rightarrow \{\theta\}} [\theta, QG[\lambda] y_\theta x_\theta, 1 + O[\epsilon]] // mm_{i, \theta \rightarrow \theta}$

$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{\theta\}} [\theta, QG[\lambda] x_\theta y_\theta, \frac{(\hbar + QG[\lambda] - QG[\lambda] B_\theta) x_\theta y_\theta}{\hbar} + O[\epsilon]^1]$

$In[*]:= \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] b_\theta a_\theta, QG[\lambda] y_\theta x_\theta, \partial_\lambda (LG[\lambda] b_\theta a_\theta + QG[\lambda] y_\theta x_\theta) + O[\epsilon]]$

$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{\theta\}} [LG[\lambda] a_\theta b_\theta, QG[\lambda] x_\theta y_\theta, (a_\theta b_\theta LG'[\lambda] + x_\theta y_\theta QG'[\lambda]) + O[\epsilon]^1]$

In[*]:= sol = DSolve[QG'[λ] == $\frac{(\hbar + QG[\lambda] - QG[\lambda] B_\theta)}{\hbar} \wedge QG[0] == 0, QG[\lambda], \lambda]$

Out[*]:= $\left\{ \left\{ QG[\lambda] \rightarrow \frac{e^{\frac{\lambda - \lambda B_\theta}{\hbar}} \left(-1 + e^{\frac{\lambda(-1+B_\theta)}{\hbar}} \right) \hbar}{-1 + B_\theta} \right\} \right\}$

In[*]:= Simplify[QG[λ] /. sol]

Out[*]:= $\left\{ \frac{\hbar - e^{\frac{\lambda - \lambda B_\theta}{\hbar}} \hbar}{-1 + B_\theta} \right\}$

§k>0

```
In[*]:= Expmm,i,k[P_] := Block[{$k = k},
Module[{P0, λ, φ, F, j, rhs, err = 0, pows, at0, atλ},
P0 = Normal@P /. e → 0;
F = Normal@Last@Expmm,i,k-1[λ P];
(*Unary*) While [
If[err != 0,
pows = Echo[First/@CoefficientRules[err, {yi, bi, ai, xi}]];
F += Sum[ek φjs[λ] Times@@{yi, bi, ai, xi}js, {js, pows}];
rhs = Normal@Last@mmi,j→i[
 $\mathbb{E}_{\{\} \rightarrow \{i\}}[\lambda P0 /. (x | y)_i \rightarrow 0, \lambda P0 /. (b | a | t)_i \rightarrow 0, F]_k s_{i \rightarrow j} @ \mathbb{E}_{\{\} \rightarrow \{i\}}[0, 0, P]_k$ ];
err = CF[(∂λF) + P0 F - rhs];
at0 = Table[φjs[0] == 0, {js, pows}];
atλ = (# == 0) & /@ (pows /. CoefficientRules[err, {yi, bi, ai, xi}]);
F = F /. DSolve[And@@(at0 ∪ atλ), Table[φjs[λ], {js, pows}], λ][[1]]
];
rhs = Normal@Last@mmi,j→i[
 $\mathbb{E}_{\{\} \rightarrow \{i\}}[\lambda P0 /. (x | y)_i \rightarrow 0, \lambda P0 /. (b | a | t)_i \rightarrow 0, F]_k s_{i \rightarrow j} @ \mathbb{E}_{\{\} \rightarrow \{i\}}[0, 0, P]_k$ ];
err = CF[(∂λF) + P0 F - rhs];
err != 0
];
 $\mathbb{E}_{\{\} \rightarrow \{i\}}[P0 /. (x | y)_i \rightarrow 0, P0 /. (b | a | t)_i \rightarrow 0, F + 0[e]^{k+1} /. \lambda \rightarrow 1]$ 
]
```

In[*]:= Exp_{dm,1,2}[ξ(x₁ + e y₁)]

» $\{\{1, 0, 0, 0\}, \{0, 0, 0, 0\}\}$

» $\{\{2, 0, 0, 0\}, \{1, 0, 0, 1\}, \{1, 0, 0, 0\}, \{0, 0, 1, 0\}, \{0, 0, 0, 1\}, \{0, 0, 0, 0\}\}$

$$\text{Out[*]} = \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\mathbf{0}, \xi \mathbf{x}_1, \mathbf{1} + \left(-\frac{\xi^2 (-1 + \mathbf{B}_1)}{2 \hbar} + \xi \mathbf{y}_1 \right) \epsilon + \left(\frac{\xi^4 (-1 + \mathbf{B}_1)^2}{8 \hbar^2} + \frac{1}{2} \xi^2 \mathbf{a}_1 \mathbf{B}_1 - \frac{1}{6} \gamma \xi^3 (-1 + 3 \mathbf{B}_1) \mathbf{x}_1 - \frac{\xi^3 (-1 + \mathbf{B}_1) \mathbf{y}_1}{2 \hbar} + \frac{1}{2} \gamma \xi^2 \hbar \mathbf{x}_1 \mathbf{y}_1 + \frac{1}{2} \xi^2 \mathbf{y}_1^2 \right) \epsilon^2 + \mathbf{0}[\epsilon]^3 \right]$$

In[*] = $\mathbf{dS}_1[\mathbb{E}_{\{\} \rightarrow \{1\}}[\mathbf{0}, \mathbf{0}, \#]] \& /@ \{\mathbf{y}_1, \mathbf{x}_1\}$

$$\text{Out[*]} = \left\{ \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\mathbf{0}, \mathbf{0}, -\frac{\mathbf{y}_1}{\mathbf{B}_1} + \frac{\gamma \hbar \mathbf{y}_1 \epsilon}{\mathbf{B}_1} - \frac{(\gamma^2 \hbar^2 \mathbf{y}_1) \epsilon^2}{2 \mathbf{B}_1} + \frac{\gamma^3 \hbar^3 \mathbf{y}_1 \epsilon^3}{6 \mathbf{B}_1} + \mathbf{0}[\epsilon]^4 \right], \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\mathbf{0}, \mathbf{0}, -\mathbf{x}_1 - \hbar \mathbf{a}_1 \mathbf{x}_1 \epsilon - \frac{1}{2} (\hbar^2 \mathbf{a}_1^2 \mathbf{x}_1) \epsilon^2 - \frac{1}{6} (\hbar^3 \mathbf{a}_1^3 \mathbf{x}_1) \epsilon^3 + \mathbf{0}[\epsilon]^4 \right] \right\}$$

In[*] = $\mathbf{Timing}@\{\mathbf{lhs} = \mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \xi_1 \mathbf{x}_1, \mathbf{1}] // \mathbf{dS}_1, \mathbf{rhs} = \mathbf{Exp}_{\mathbf{dm}, 1, \mathbf{\$k}}[\xi_1 \mathbf{Last}@\mathbf{dS}_1[\mathbb{E}_{\{\} \rightarrow \{1\}}[\mathbf{0}, \mathbf{0}, \mathbf{x}_1]]] /. \{\{\} \rightarrow \{1\}\}; \mathbf{HL}[\mathbf{lhs} \equiv \mathbf{rhs}]\}$

» $\{\{0, 0, 1, 1\}, \{0, 0, 0, 2\}\}$

» $\{\{0, 0, 2, 2\}, \{0, 0, 2, 1\}, \{0, 0, 1, 3\}, \{0, 0, 1, 2\}, \{0, 0, 0, 4\}, \{0, 0, 0, 3\}, \{0, 0, 0, 2\}\}$

» $\{\{0, 0, 3, 3\}, \{0, 0, 3, 2\}, \{0, 0, 3, 1\}, \{0, 0, 2, 4\}, \{0, 0, 2, 3\}, \{0, 0, 2, 2\}, \{0, 0, 1, 5\}, \{0, 0, 1, 4\}, \{0, 0, 1, 3\}, \{0, 0, 1, 2\}, \{0, 0, 0, 6\}, \{0, 0, 0, 5\}, \{0, 0, 0, 4\}, \{0, 0, 0, 3\}, \{0, 0, 0, 2\}\}$

$$\text{Out[*]} = \left\{ 5.67188, \left\{ \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\mathbf{0}, -\mathbf{x}_1 \xi_1, \mathbf{1} + \left(-\hbar \mathbf{a}_1 \mathbf{x}_1 \xi_1 - \frac{1}{2} \gamma \hbar \mathbf{x}_1^2 \xi_1^2 \right) \epsilon + \left(-\frac{1}{2} \hbar^2 \mathbf{a}_1^2 \mathbf{x}_1 \xi_1 + \frac{1}{4} \gamma^2 \hbar^2 \mathbf{x}_1^2 \xi_1^2 - \gamma \hbar^2 \mathbf{a}_1 \mathbf{x}_1^2 \xi_1^2 + \frac{1}{2} \hbar^2 \mathbf{a}_1^2 \mathbf{x}_1^2 \xi_1^2 - \frac{1}{2} \gamma^2 \hbar^2 \mathbf{x}_1^3 \xi_1^3 + \frac{1}{2} \gamma \hbar^2 \mathbf{a}_1 \mathbf{x}_1^3 \xi_1^3 + \frac{1}{8} \gamma^2 \hbar^2 \mathbf{x}_1^4 \xi_1^4 \right) \epsilon^2 + \left(-\frac{1}{6} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1 \xi_1 - \frac{1}{12} \gamma^3 \hbar^3 \mathbf{x}_1^2 \xi_1^2 + \frac{1}{2} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^2 \xi_1^2 - \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^2 \xi_1^2 + \frac{1}{2} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1^2 \xi_1^2 + \frac{2}{3} \gamma^3 \hbar^3 \mathbf{x}_1^3 \xi_1^3 - \frac{7}{4} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^3 \xi_1^3 + \frac{5}{4} \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^3 \xi_1^3 - \frac{1}{6} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1^3 \xi_1^3 - \frac{19}{24} \gamma^3 \hbar^3 \mathbf{x}_1^4 \xi_1^4 + \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^4 \xi_1^4 - \frac{1}{4} \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^4 \xi_1^4 + \frac{1}{4} \gamma^3 \hbar^3 \mathbf{x}_1^5 \xi_1^5 - \frac{1}{8} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^5 \xi_1^5 - \frac{1}{48} \gamma^3 \hbar^3 \mathbf{x}_1^6 \xi_1^6 \right) \epsilon^3 + \mathbf{0}[\epsilon]^4 \right], \mathbf{True} \right\}$$

In[*] = $\mathbf{Timing}@\{\mathbf{lhs} = \mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \eta_1 \mathbf{y}_1, \mathbf{1}] // \mathbf{dS}_1, \mathbf{rhs} = \mathbf{Exp}_{\mathbf{dm}, 1, \mathbf{\$k}}[\eta \mathbf{Last}@\mathbf{dS}_1[\mathbb{E}_{\{\} \rightarrow \{1\}}[\mathbf{0}, \mathbf{0}, \mathbf{y}_1]]] /. \{\eta \rightarrow \eta_1, \{\} \rightarrow \{1\}\}, \mathbf{HL}[\mathbf{lhs} \equiv \mathbf{rhs}]\}$

- » $\{\{2, 0, 0, 0\}, \{1, 0, 0, 0\}\}$
- » $\{\{4, 0, 0, 0\}, \{3, 0, 0, 0\}, \{2, 0, 0, 0\}, \{1, 0, 0, 0\}\}$
- » $\{\{6, 0, 0, 0\}, \{5, 0, 0, 0\}, \{4, 0, 0, 0\}, \{3, 0, 0, 0\}, \{2, 0, 0, 0\}, \{1, 0, 0, 0\}\}$

$$\begin{aligned}
\text{Out}[*]= & \left\{ 5.15625, \left\{ \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\theta, -\frac{y_1 \eta_1}{B_1}, \right. \right. \right. \\
& 1 + \left(\frac{\gamma \hbar y_1 \eta_1}{B_1} - \frac{\gamma \hbar y_1^2 \eta_1^2}{2 B_1^2} \right) \epsilon + \left(-\frac{\gamma^2 \hbar^2 y_1 \eta_1}{2 B_1} + \frac{7 \gamma^2 \hbar^2 y_1^2 \eta_1^2}{4 B_1^2} - \frac{\gamma^2 \hbar^2 y_1^3 \eta_1^3}{B_1^3} + \frac{\gamma^2 \hbar^2 y_1^4 \eta_1^4}{8 B_1^4} \right) \epsilon^2 + \\
& \left. \left(\frac{\gamma^3 \hbar^3 y_1 \eta_1}{6 B_1} - \frac{25 \gamma^3 \hbar^3 y_1^2 \eta_1^2}{12 B_1^2} + \frac{23 \gamma^3 \hbar^3 y_1^3 \eta_1^3}{6 B_1^3} - \frac{49 \gamma^3 \hbar^3 y_1^4 \eta_1^4}{24 B_1^4} + \frac{3 \gamma^3 \hbar^3 y_1^5 \eta_1^5}{8 B_1^5} - \frac{\gamma^3 \hbar^3 y_1^6 \eta_1^6}{48 B_1^6} \right) \epsilon^3 + \right. \\
& \left. 0[\epsilon]^4 \right\}, \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\theta, -\frac{y_1 \eta_1}{B_1}, \right. \\
& 1 - \frac{(\gamma \hbar (-2 B_1 y_1 \eta_1 + y_1^2 \eta_1^2)) \epsilon}{2 B_1^2} + \frac{\gamma^2 \hbar^2 (-4 B_1^3 y_1 \eta_1 + 14 B_1^2 y_1^2 \eta_1^2 - 8 B_1 y_1^3 \eta_1^3 + y_1^4 \eta_1^4) \epsilon^2}{8 B_1^4} - \\
& \left. \frac{(\gamma^3 \hbar^3 (-8 B_1^5 y_1 \eta_1 + 100 B_1^4 y_1^2 \eta_1^2 - 184 B_1^3 y_1^3 \eta_1^3 + 98 B_1^2 y_1^4 \eta_1^4 - 18 B_1 y_1^5 \eta_1^5 + y_1^6 \eta_1^6)) \epsilon^3}{48 B_1^6} + \right. \\
& \left. 0[\epsilon]^4, \text{True} \right\} \}
\end{aligned}$$

$$\begin{aligned}
\text{In}[*]= & \text{Timing} @ \{ \text{lhs} = \mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, \xi_1 x_1, 1] // \text{CS}_1, \\
& \text{rhs} = \text{Exp}_{\text{cm}, 1, \$k} [\xi_1 \text{Last} @ \text{CS}_1 [\mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, \theta, x_1]]] /. \{ \} \rightarrow \{1\}; \text{HL} [\text{lhs} \equiv \text{rhs}] \}
\end{aligned}$$

$$\text{Out}[*]= \{ 5.78125, \{ \mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, -x_1 \xi_1, 1 + 0[\epsilon]^4], \text{True} \} \}$$

$$\begin{aligned}
\text{In}[*]= & \text{Timing} @ \{ \text{lhs} = \mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, \eta_1 y_1, 1] // \text{CS}_1, \\
& \text{rhs} = \text{Exp}_{\text{cm}, 1, \$k} [\eta_1 \text{Last} @ \text{CS}_1 [\mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, \theta, y_1]]] /. \{ \} \rightarrow \{1\}; \text{HL} [\text{lhs} \equiv \text{rhs}] \}
\end{aligned}$$

$$\text{Out}[*]= \{ 0.484375, \{ \mathbb{E}_{\{1\} \rightarrow \{1\}} [\theta, -y_1 \eta_1, 1 + 0[\epsilon]^4], \text{True} \} \}$$