

Pensieve header: Exp relative to am, bm, cm, dm.

Follows code in Projects/SL2Portfolio/SL2PortfolioProgram.nb.

Startup

In[*]:=

```
SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\SL2Portfolio2"];
(*Once[<< KnotTheory`];*)
Once[<< "../Profile/Profile.m"];];
<< "Engine-Speedy.m";
<< "Objects.m";
$k = 3;
HL[ε_] := Style[ε, Background -> Green];
```

This is Profile.m of <http://www.drorbn.net/AcademicPensieve/Projects/Profile/>.

This version: June 2018. Original version: July 1994.

Exponentials as needed.

Task. Define $\text{Exp}_{m,i,k}[P]$ to compute $e^{\mathcal{O}(P)}$ to ϵ^k in the using the $m_{i,j \rightarrow i}$ multiplication, where P is an ϵ -dependent near-docile element, giving the answer in \mathbf{E} -form.

Methodology. If $P_0 := P_{\epsilon=0}$ and $e^{\lambda \mathcal{O}(P)} = \mathcal{O}(e^{\lambda P_0} F(\lambda))$, then $F(\lambda = 0) = 1$ and we

have:

$$\mathcal{O}(e^{\lambda P_0}(P_0 F(\lambda) + \partial_\lambda F)) = \mathcal{O}(\partial_\lambda e^{\lambda P_0} F(\lambda)) = \partial_\lambda \mathcal{O}(e^{\lambda P_0} F(\lambda)) = \partial_\lambda e^{\lambda \mathcal{O}(P)} = e^{\lambda \mathcal{O}(P)} \mathcal{O}(P) = \mathcal{O}(e^{\lambda P_0} F(\lambda)) \mathcal{O}(P).$$

This is a linear ODE for F . Setting inductively $F_k = F_{k-1} + \epsilon^k \varphi$ we find that $F_0 = 1$ and solve for φ .

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In[ ]:= (* Bug: The first line is valid only if  $\mathbb{0}(\mathbb{e}^{P_0}) == \mathbb{e}^{\mathbb{0}(P_0)}$ . *)
Exp_{m,i,0}[P_] := Module[{LQ = Normal@P /.  $\epsilon \rightarrow \mathbb{0}$ },
  E[LQ /. (x | y)_i  $\rightarrow \mathbb{0}$ , LQ /. (b | a | t)_i  $\rightarrow \mathbb{0}, 1$ ]];
Exp_{m,i,k}[P_] := Block[{$k = k},
  Module[{P0,  $\lambda$ ,  $\varphi$ ,  $\varphi_s$ , F, j, rhs, eqn, pows, at0, at $\lambda$ },
    P0 = Normal@P /.  $\epsilon \rightarrow \mathbb{0}$ ;
    F = Normal@Last@Exp_{m,i,k-1}[\lambda P];
    While[
      rhs = Normal@Last@m_{i,j} [
        E_{i} [  $\lambda P_0$  /. (x | y)_i  $\rightarrow \mathbb{0}$ ,  $\lambda P_0$  /. (b | a | t)_i  $\rightarrow \mathbb{0}, F$  ]_k s_{i} @ E_{i} [  $\mathbb{0}, \mathbb{0}, P$  ]_k ];
      eqn = CF[( $\partial_\lambda F$ ) + P0 F - rhs];
      eqn !=  $\mathbb{0}$ ,
      (*do*) pows = Echo[First@CoefficientRules[eqn, {y_i, b_i, a_i, x_i}]];
      F += Sum[ $\epsilon^k \varphi_{js}[\lambda]$  Times@@ {y_i, b_i, a_i, x_i}^{js}, {js, pows}];
      rhs = Normal@Last@m_{i,j} [
        E_{i} [  $\lambda P_0$  /. (x | y)_i  $\rightarrow \mathbb{0}$ ,  $\lambda P_0$  /. (b | a | t)_i  $\rightarrow \mathbb{0}, F$  ]_k s_{i} @ E_{i} [  $\mathbb{0}, \mathbb{0}, P$  ]_k ];
      eqn = CF[( $\partial_\lambda F$ ) + P0 F - rhs];
       $\varphi_s$  = Table[ $\varphi_{js}[\lambda]$ , {js, pows}];
      at0 = Table[ $\varphi_{js}[\mathbb{0}] == \mathbb{0}$ , {js, pows}];
      at $\lambda$  = (# ==  $\mathbb{0}$ ) & /@ (pows /. CoefficientRules[eqn, {y_i, b_i, a_i, x_i}]);
      F = F /. DSolve[And@@ (at0  $\cup$  at $\lambda$ ),  $\varphi_s, \lambda$ ][[1]]
    ];
    E_{i} [  $P_0$  /. (x | y)_i  $\rightarrow \mathbb{0}$ ,  $P_0$  /. (b | a | t)_i  $\rightarrow \mathbb{0}, F + \mathbb{0}[\epsilon]^{k+1} /. \lambda \rightarrow 1$  ]
  ]
]

```

```

In[ ]:= Exp_{dm,1,2}[\xi (x_1 +  $\epsilon$  y_1)]
"
{ {1, 0, 0, 0}, {0, 0, 0, 0} }
"
{ {2, 0, 0, 0}, {1, 0, 0, 1}, {1, 0, 0, 0}, {0, 0, 1, 0}, {0, 0, 0, 1}, {0, 0, 0, 0} }

```

$$\text{Out[]} = E_{i \rightarrow \{1\}} \left[\mathbb{0}, \xi x_1, 1 + \left(-\frac{\xi^2 (-1 + B_1)}{2 \hbar} + \xi y_1 \right) \epsilon + \left(\frac{\xi^4 (-1 + B_1)^2}{8 \hbar^2} + \frac{1}{2} \xi^2 a_1 B_1 - \frac{1}{6} \gamma \xi^3 (-1 + 3 B_1) x_1 - \frac{\xi^3 (-1 + B_1) y_1}{2 \hbar} + \frac{1}{2} \gamma \xi^2 \hbar x_1 y_1 + \frac{1}{2} \xi^2 y_1^2 \right) \epsilon^2 + \mathbb{0}[\epsilon]^3 \right]$$

```

In[ ]:= dS_1[E_{i \rightarrow \{1\}} [0, 0, #]] & /@ {y_1, x_1}

```

$$\text{Out[]} = \left\{ E_{i \rightarrow \{1\}} \left[\mathbb{0}, \mathbb{0}, -\frac{y_1}{B_1} + \frac{\gamma \hbar y_1 \epsilon}{B_1} - \frac{(\gamma^2 \hbar^2 y_1) \epsilon^2}{2 B_1} + \frac{\gamma^3 \hbar^3 y_1 \epsilon^3}{6 B_1} + \mathbb{0}[\epsilon]^4 \right], E_{i \rightarrow \{1\}} \left[\mathbb{0}, \mathbb{0}, -x_1 - \hbar a_1 x_1 \epsilon - \frac{1}{2} (\hbar^2 a_1^2 x_1) \epsilon^2 - \frac{1}{6} (\hbar^3 a_1^3 x_1) \epsilon^3 + \mathbb{0}[\epsilon]^4 \right] \right\}$$

```

In[ ]:= Timing@{lhs = E_{i \rightarrow \{1\}} [0,  $\xi_1 x_1, 1$ ] // dS_1, rhs = Exp_{dm,1,$k}[\xi_1 Last@dS_1[E_{i \rightarrow \{1\}} [0, 0, x_1]]] /. {{i} -> {1}}; HL[lhs == rhs]}

```

```

" {{0, 0, 1, 1}, {0, 0, 0, 2}}
" {{0, 0, 2, 2}, {0, 0, 2, 1}, {0, 0, 1, 3}, {0, 0, 1, 2}, {0, 0, 0, 4}, {0, 0, 0, 3}, {0, 0, 0, 2}}
" {{0, 0, 3, 3}, {0, 0, 3, 2}, {0, 0, 3, 1}, {0, 0, 2, 4}, {0, 0, 2, 3},
  {0, 0, 2, 2}, {0, 0, 1, 5}, {0, 0, 1, 4}, {0, 0, 1, 3}, {0, 0, 1, 2},
  {0, 0, 0, 6}, {0, 0, 0, 5}, {0, 0, 0, 4}, {0, 0, 0, 3}, {0, 0, 0, 2}}

```

Out[*]= {3.53125,

$$\begin{aligned} & \left\{ \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\theta, -x_1 \xi_1, 1 + \left(-\hbar a_1 x_1 \xi_1 - \frac{1}{2} \gamma \hbar x_1^2 \xi_1^2 \right) \epsilon + \left(-\frac{1}{2} \hbar^2 a_1^2 x_1 \xi_1 + \frac{1}{4} \gamma^2 \hbar^2 x_1^2 \xi_1^2 - \gamma \hbar^2 a_1 x_1^2 \xi_1^2 + \right. \right. \right. \\ & \quad \left. \left. \frac{1}{2} \hbar^2 a_1^2 x_1^2 \xi_1^2 - \frac{1}{2} \gamma^2 \hbar^2 x_1^3 \xi_1^3 + \frac{1}{2} \gamma \hbar^2 a_1 x_1^3 \xi_1^3 + \frac{1}{8} \gamma^2 \hbar^2 x_1^4 \xi_1^4 \right) \epsilon^2 + \right. \\ & \quad \left. \left(-\frac{1}{6} \hbar^3 a_1^3 x_1 \xi_1 - \frac{1}{12} \gamma^3 \hbar^3 x_1^2 \xi_1^2 + \frac{1}{2} \gamma^2 \hbar^3 a_1 x_1^2 \xi_1^2 - \gamma \hbar^3 a_1^2 x_1^2 \xi_1^2 + \frac{1}{2} \hbar^3 a_1^3 x_1^2 \xi_1^2 + \right. \right. \\ & \quad \left. \left. \frac{2}{3} \gamma^3 \hbar^3 x_1^3 \xi_1^3 - \frac{7}{4} \gamma^2 \hbar^3 a_1 x_1^3 \xi_1^3 + \frac{5}{4} \gamma \hbar^3 a_1^2 x_1^3 \xi_1^3 - \frac{1}{6} \hbar^3 a_1^3 x_1^3 \xi_1^3 - \frac{19}{24} \gamma^3 \hbar^3 x_1^4 \xi_1^4 + \gamma^2 \hbar^3 a_1 x_1^4 \xi_1^4 - \right. \right. \\ & \quad \left. \left. \frac{1}{4} \gamma \hbar^3 a_1^2 x_1^4 \xi_1^4 + \frac{1}{4} \gamma^3 \hbar^3 x_1^5 \xi_1^5 - \frac{1}{8} \gamma^2 \hbar^3 a_1 x_1^5 \xi_1^5 - \frac{1}{48} \gamma^3 \hbar^3 x_1^6 \xi_1^6 \right) \epsilon^3 + O[\epsilon]^4 \right], \text{True} \} \end{aligned}$$

```

In[*]= Timing@{lhs = E_{1} -> {1} [theta, eta_1 y_1, 1] // ds_1,
  rhs = Exp_{dm,1,$k} [eta_1 Last@ds_1 [E_{1} -> {1} [theta, 0, y_1]]] /. {eta -> eta_1, {} -> {1}}, HL[lhs == rhs]}

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" {{2, 0, 0, 0}, {1, 0, 0, 0}}
" {{4, 0, 0, 0}, {3, 0, 0, 0}, {2, 0, 0, 0}, {1, 0, 0, 0}}
" {{6, 0, 0, 0}, {5, 0, 0, 0}, {4, 0, 0, 0}, {3, 0, 0, 0}, {2, 0, 0, 0}, {1, 0, 0, 0}}

```

Out[*]= {3.29688, {E_{1} -> {1} [theta, -frac{y_1 eta_1}{B_1},

$$\begin{aligned} & 1 + \left(\frac{\gamma \hbar y_1 \eta_1}{B_1} - \frac{\gamma \hbar y_1^2 \eta_1^2}{2 B_1^2} \right) \epsilon + \left(-\frac{\gamma^2 \hbar^2 y_1 \eta_1}{2 B_1} + \frac{7 \gamma^2 \hbar^2 y_1^2 \eta_1^2}{4 B_1^2} - \frac{\gamma^2 \hbar^2 y_1^3 \eta_1^3}{B_1^3} + \frac{\gamma^2 \hbar^2 y_1^4 \eta_1^4}{8 B_1^4} \right) \epsilon^2 + \\ & \left(\frac{\gamma^3 \hbar^3 y_1 \eta_1}{6 B_1} - \frac{25 \gamma^3 \hbar^3 y_1^2 \eta_1^2}{12 B_1^2} + \frac{23 \gamma^3 \hbar^3 y_1^3 \eta_1^3}{6 B_1^3} - \frac{49 \gamma^3 \hbar^3 y_1^4 \eta_1^4}{24 B_1^4} + \frac{3 \gamma^3 \hbar^3 y_1^5 \eta_1^5}{8 B_1^5} - \frac{\gamma^3 \hbar^3 y_1^6 \eta_1^6}{48 B_1^6} \right) \epsilon^3 + \\ & O[\epsilon]^4, \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\theta, -\frac{y_1 \eta_1}{B_1}, \right. \\ & \left. 1 - \frac{(\gamma \hbar (-2 B_1 y_1 \eta_1 + y_1^2 \eta_1^2)) \epsilon}{2 B_1^2} + \frac{1}{8 B_1^4} \gamma^2 \hbar^2 (-4 B_1^3 y_1 \eta_1 + 14 B_1^2 y_1^2 \eta_1^2 - 8 B_1 y_1^3 \eta_1^3 + y_1^4 \eta_1^4) \epsilon^2 - \right. \\ & \left. \frac{1}{48 B_1^6} (\gamma^3 \hbar^3 (-8 B_1^5 y_1 \eta_1 + 100 B_1^4 y_1^2 \eta_1^2 - 184 B_1^3 y_1^3 \eta_1^3 + 98 B_1^2 y_1^4 \eta_1^4 - 18 B_1 y_1^5 \eta_1^5 + y_1^6 \eta_1^6)) \epsilon^3 + \right. \\ & \left. O[\epsilon]^4, \text{True} \} \right\} \end{aligned}$$

```

In[*]= Timing@{lhs = E_{1} -> {1} [theta, xi_1 x_1, 1] // cs_1,
  rhs = Exp_{cm,1,$k} [xi_1 Last@cs_1 [E_{1} -> {1} [theta, 0, x_1]]] /. {} -> {1}; HL[lhs == rhs]}

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Out[*]= {3.67188, {E_{1} -> {1} [theta, -x_1 xi_1, 1 + O[epsilon]^4], True}}

```

In[*]= Timing@{lhs = E_{1} -> {1} [theta, eta_1 y_1, 1] // cs_1,
  rhs = Exp_{cm,1,$k} [eta_1 Last@cs_1 [E_{1} -> {1} [theta, 0, y_1]]] /. {} -> {1}; HL[lhs == rhs]}

```

Out[*]= {0.296875, {E_{1} -> {1} [theta, -y_1 eta_1, 1 + O[epsilon]^4], True}}