

Pensieve header: Exp relative to am, bm, cm, dm.

Follows code in Projects/SL2Portfolio/SL2PortfolioProgram.nb.

Startup

```
In[*]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\SL2Portfolio2"];
(*Once[<< KnotTheory`];*)
Once[<< "../Profile/Profile.m"];
<< "Engine-Speedy.m";
<< "Objects.m";
$k = 3;
HL[ε_] := Style[ε, Background → Green];
```

This is Profile.m of <http://www.drorbn.net/AcademicPensieve/Projects/Profile/>.

This version: April 2020. Original version: July 1994.

- » **Warning: On Sep 4 2019 I swapped the operations ϵ and η . Some incompatibilities may arise in older notebooks.**

Exponentials as needed.

Task. Define $\text{Exp}_{m,i,k}[P]$ to compute $e^{\mathcal{O}(P)}$ to ϵ^k in the using the $\text{mm}_{i,j \rightarrow i}$ multiplication, where P is an ϵ -dependent near-docile element, giving the answer in E-form.

Methodology. If $P_0 := P_{\epsilon=0}$ and $e^{\lambda \mathcal{O}(P)} = \mathcal{O}(e^{\lambda P_0} F(\lambda))$, then $F(\lambda = 0) = 1$ and we have:

$$\mathcal{O}(e^{\lambda P_0}(P_0 F(\lambda) + \partial_\lambda F)) = \mathcal{O}(\partial_\lambda e^{\lambda P_0} F(\lambda)) = \partial_\lambda \mathcal{O}(e^{\lambda P_0} F(\lambda)) = \partial_\lambda e^{\lambda \mathcal{O}(P)} = e^{\lambda \mathcal{O}(P)} \mathcal{O}(P) = \mathcal{O}(e^{\lambda P_0} F(\lambda)) \mathcal{O}(P).$$

This is a linear ODE for F . Setting inductively $F_k = F_{k-1} + \epsilon^k \varphi$ we find that $F_0 = 1$ and solve for φ .

```

In[ ]:= (* Bug: The first line is valid only if 0 (e^{P_0}) == e^{0(P_0)}. *)
Exp_{mm,i,0}[P_] := Module[{LQ = Normal@P /. e -> 0},
  E[LQ /. (x | y)_i -> 0, LQ /. (b | a | t)_i -> 0, 1]];
Exp_{mm,i,k}[P_] := Block[{$k = k},
  Module[{P0, lambda, phi, F, j, rhs, err = 0, pows, at0, atlambda},
    P0 = Normal@P /. e -> 0;
    F = Normal@Last@Exp_{mm,i,k-1}[lambda P];
    (*Unary*)While[
      If[err != 0,
        pows = Echo[First/@CoefficientRules[err, {y_i, b_i, a_i, x_i}]];
        F += Sum[e^k phi_{js}[lambda] Times@@{y_i, b_i, a_i, x_i}^{js}, {js, pows}];
        rhs = Normal@Last@mm_{i,j->i}[
          E_{i->{i}}[lambda P0 /. (x | y)_i -> 0, lambda P0 /. (b | a | t)_i -> 0, F]_k s_{i->j} @ E_{i->{i}}[0, 0, P]_k];
        err = CF[(D_lambda F) + P0 F - rhs];
        at0 = Table[phi_{js}[0] == 0, {js, pows}];
        atlambda = (# == 0) & /@ (pows /. CoefficientRules[err, {y_i, b_i, a_i, x_i}]);
        F = F /. DSolve[And@@(at0 | atlambda), Table[phi_{js}[lambda], {js, pows}], lambda][[1]]];
      rhs = Normal@Last@mm_{i,j->i}[
        E_{i->{i}}[lambda P0 /. (x | y)_i -> 0, lambda P0 /. (b | a | t)_i -> 0, F]_k s_{i->j} @ E_{i->{i}}[0, 0, P]_k];
      err = CF[(D_lambda F) + P0 F - rhs];
      err != 0];
    E_{i->{i}}[P0 /. (x | y)_i -> 0, P0 /. (b | a | t)_i -> 0, F + O[epsilon]^{k+1} /. lambda -> 1]]];
  ]

```

```

In[ ]:= Exp_{dm,1,2}[xi (x1 + e y1)]
» {{1, 0, 0, 0}, {0, 0, 0, 0}}
» {{2, 0, 0, 0}, {1, 0, 0, 1}, {1, 0, 0, 0}, {0, 0, 1, 0}, {0, 0, 0, 1}, {0, 0, 0, 0}}

```

$$\begin{aligned}
 \text{Out[]} = & E_{i \rightarrow \{1\}} \left[0, \xi x_1, 1 + \left(-\frac{\xi^2 (-1 + B_1)}{2 \hbar} + \xi y_1 \right) \epsilon + \right. \\
 & \left. \left(\frac{\xi^4 (-1 + B_1)^2}{8 \hbar^2} + \frac{1}{2} \xi^2 a_1 B_1 - \frac{1}{6} \gamma \xi^3 (-1 + 3 B_1) x_1 - \frac{\xi^3 (-1 + B_1) y_1}{2 \hbar} + \frac{1}{2} \gamma \xi^2 \hbar x_1 y_1 + \frac{1}{2} \xi^2 y_1^2 \right) \epsilon^2 + \right. \\
 & \left. O[\epsilon]^3 \right]
 \end{aligned}$$

```

In[ ]:= dS_1[E_{i->{1}}[0, 0, #]] & /@ {y1, x1}

```

$$\begin{aligned}
 \text{Out[]} = & \left\{ E_{i \rightarrow \{1\}} \left[0, 0, -\frac{y_1}{B_1} + \frac{\gamma \hbar y_1 \epsilon}{B_1} - \frac{(\gamma^2 \hbar^2 y_1) \epsilon^2}{2 B_1} + \frac{\gamma^3 \hbar^3 y_1 \epsilon^3}{6 B_1} + O[\epsilon]^4 \right], \right. \\
 & \left. E_{i \rightarrow \{1\}} \left[0, 0, -x_1 - \hbar a_1 x_1 \epsilon - \frac{1}{2} (\hbar^2 a_1^2 x_1) \epsilon^2 - \frac{1}{6} (\hbar^3 a_1^3 x_1) \epsilon^3 + O[\epsilon]^4 \right] \right\}
 \end{aligned}$$

`In[*]:= Timing@{lhs = $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \xi_1 \mathbf{x}_1, \mathbf{1}] // \mathbf{dS}_1,$
 rhs = $\text{Exp}_{\text{dm},1,\$k}[\xi_1 \text{Last@}\mathbf{dS}_1[\mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \mathbf{0}, \mathbf{x}_1]]] /. \{\{1\} \rightarrow \{1\}\}; \text{HL}[lhs \equiv rhs]}$`

» $\{\{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{1}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{2}\}\}$

» $\{\{\mathbf{0}, \mathbf{0}, \mathbf{2}, \mathbf{2}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{2}, \mathbf{1}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{3}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{2}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{4}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{3}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{2}\}\}$

» $\{\{\mathbf{0}, \mathbf{0}, \mathbf{3}, \mathbf{3}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{3}, \mathbf{2}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{3}, \mathbf{1}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{2}, \mathbf{4}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{2}, \mathbf{3}\},$
 $\{\mathbf{0}, \mathbf{0}, \mathbf{2}, \mathbf{2}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{5}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{4}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{3}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{2}\},$
 $\{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{6}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{5}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{4}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{3}\}, \{\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{2}\}\}$

`Out[*]:= {3.53125,`

$$\left\{ \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\mathbf{0}, -\mathbf{x}_1 \xi_1, \mathbf{1} + \left(-\hbar \mathbf{a}_1 \mathbf{x}_1 \xi_1 - \frac{1}{2} \gamma \hbar \mathbf{x}_1^2 \xi_1^2 \right) \epsilon + \left(-\frac{1}{2} \hbar^2 \mathbf{a}_1^2 \mathbf{x}_1 \xi_1 + \frac{1}{4} \gamma^2 \hbar^2 \mathbf{x}_1^2 \xi_1^2 - \gamma \hbar^2 \mathbf{a}_1 \mathbf{x}_1^2 \xi_1^2 + \right. \right.$$

$$\left. \frac{1}{2} \hbar^2 \mathbf{a}_1^2 \mathbf{x}_1^2 \xi_1^2 - \frac{1}{2} \gamma^2 \hbar^2 \mathbf{x}_1^3 \xi_1^3 + \frac{1}{2} \gamma \hbar^2 \mathbf{a}_1 \mathbf{x}_1^3 \xi_1^3 + \frac{1}{8} \gamma^2 \hbar^2 \mathbf{x}_1^4 \xi_1^4 \right) \epsilon^2 +$$

$$\left(-\frac{1}{6} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1 \xi_1 - \frac{1}{12} \gamma^3 \hbar^3 \mathbf{x}_1^2 \xi_1^2 + \frac{1}{2} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^2 \xi_1^2 - \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^2 \xi_1^2 + \frac{1}{2} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1^2 \xi_1^2 + \right.$$

$$\left. \frac{2}{3} \gamma^3 \hbar^3 \mathbf{x}_1^3 \xi_1^3 - \frac{7}{4} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^3 \xi_1^3 + \frac{5}{4} \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^3 \xi_1^3 - \frac{1}{6} \hbar^3 \mathbf{a}_1^3 \mathbf{x}_1^3 \xi_1^3 - \frac{19}{24} \gamma^3 \hbar^3 \mathbf{x}_1^4 \xi_1^4 + \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^4 \xi_1^4 - \right.$$

$$\left. \frac{1}{4} \gamma \hbar^3 \mathbf{a}_1^2 \mathbf{x}_1^4 \xi_1^4 + \frac{1}{4} \gamma^3 \hbar^3 \mathbf{x}_1^5 \xi_1^5 - \frac{1}{8} \gamma^2 \hbar^3 \mathbf{a}_1 \mathbf{x}_1^5 \xi_1^5 - \frac{1}{48} \gamma^3 \hbar^3 \mathbf{x}_1^6 \xi_1^6 \right) \epsilon^3 + \mathcal{O}[\epsilon^4], \text{true} \left. \right\}$$

`In[*]:= Timing@{lhs = $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \eta_1 \mathbf{y}_1, \mathbf{1}] // \mathbf{dS}_1,$
 rhs = $\text{Exp}_{\text{dm},1,\$k}[\eta_1 \text{Last@}\mathbf{dS}_1[\mathbb{E}_{\{1\} \rightarrow \{1\}}[\mathbf{0}, \mathbf{0}, \mathbf{y}_1]]] /. \{\eta \rightarrow \eta_1, \{1\} \rightarrow \{1\}\}, \text{HL}[lhs \equiv rhs]}$`

» $\{\{2, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{1, \mathbf{0}, \mathbf{0}, \mathbf{0}\}\}$

» $\{\{4, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{3, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{2, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{1, \mathbf{0}, \mathbf{0}, \mathbf{0}\}\}$

» $\{\{6, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{5, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{4, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{3, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{2, \mathbf{0}, \mathbf{0}, \mathbf{0}\}, \{1, \mathbf{0}, \mathbf{0}, \mathbf{0}\}\}$

`Out[*]:= {3.29688,`

$$\left\{ \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\mathbf{0}, -\frac{\mathbf{y}_1 \eta_1}{\mathbf{B}_1}, \right. \right.$$

$$1 + \left(\frac{\gamma \hbar \mathbf{y}_1 \eta_1}{\mathbf{B}_1} - \frac{\gamma \hbar \mathbf{y}_1^2 \eta_1^2}{2 \mathbf{B}_1^2} \right) \epsilon + \left(-\frac{\gamma^2 \hbar^2 \mathbf{y}_1 \eta_1}{2 \mathbf{B}_1} + \frac{7 \gamma^2 \hbar^2 \mathbf{y}_1^2 \eta_1^2}{4 \mathbf{B}_1^2} - \frac{\gamma^2 \hbar^2 \mathbf{y}_1^3 \eta_1^3}{\mathbf{B}_1^3} + \frac{\gamma^2 \hbar^2 \mathbf{y}_1^4 \eta_1^4}{8 \mathbf{B}_1^4} \right) \epsilon^2 +$$

$$\left(\frac{\gamma^3 \hbar^3 \mathbf{y}_1 \eta_1}{6 \mathbf{B}_1} - \frac{25 \gamma^3 \hbar^3 \mathbf{y}_1^2 \eta_1^2}{12 \mathbf{B}_1^2} + \frac{23 \gamma^3 \hbar^3 \mathbf{y}_1^3 \eta_1^3}{6 \mathbf{B}_1^3} - \frac{49 \gamma^3 \hbar^3 \mathbf{y}_1^4 \eta_1^4}{24 \mathbf{B}_1^4} + \frac{3 \gamma^3 \hbar^3 \mathbf{y}_1^5 \eta_1^5}{8 \mathbf{B}_1^5} - \frac{\gamma^3 \hbar^3 \mathbf{y}_1^6 \eta_1^6}{48 \mathbf{B}_1^6} \right) \epsilon^3 +$$

$$\mathcal{O}[\epsilon^4], \mathbb{E}_{\{1\} \rightarrow \{1\}} \left[\mathbf{0}, -\frac{\mathbf{y}_1 \eta_1}{\mathbf{B}_1}, \right.$$

$$1 - \frac{(\gamma \hbar (-2 \mathbf{B}_1 \mathbf{y}_1 \eta_1 + \mathbf{y}_1^2 \eta_1^2)) \epsilon}{2 \mathbf{B}_1^2} + \frac{\gamma^2 \hbar^2 (-4 \mathbf{B}_1^3 \mathbf{y}_1 \eta_1 + 14 \mathbf{B}_1^2 \mathbf{y}_1^2 \eta_1^2 - 8 \mathbf{B}_1 \mathbf{y}_1^3 \eta_1^3 + \mathbf{y}_1^4 \eta_1^4) \epsilon^2}{8 \mathbf{B}_1^4} -$$

$$\frac{(\gamma^3 \hbar^3 (-8 \mathbf{B}_1^5 \mathbf{y}_1 \eta_1 + 100 \mathbf{B}_1^4 \mathbf{y}_1^2 \eta_1^2 - 184 \mathbf{B}_1^3 \mathbf{y}_1^3 \eta_1^3 + 98 \mathbf{B}_1^2 \mathbf{y}_1^4 \eta_1^4 - 18 \mathbf{B}_1 \mathbf{y}_1^5 \eta_1^5 + \mathbf{y}_1^6 \eta_1^6)) \epsilon^3}{48 \mathbf{B}_1^6} +$$

$$\left. \left. \mathcal{O}[\epsilon^4], \text{true} \right\} \right\}$$

```
In[*]:= Timing@{lhs =  $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, \xi_1 x_1, 1]$  //  $\mathbf{CS}_1$ ,
  rhs =  $\text{Exp}_{\text{cm},1,\$k}[\xi_1 \text{Last}@ $\mathbf{CS}_1[\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, \theta, x_1]]]$  /. {} -> {1}; HL[lhs == rhs]}$ 
```

```
Out[*]:= {3.67188, { $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, -x_1 \xi_1, 1 + O[\epsilon]^4]$ , True}}
```

```
In[*]:= Timing@{lhs =  $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, \eta_1 y_1, 1]$  //  $\mathbf{CS}_1$ ,
  rhs =  $\text{Exp}_{\text{cm},1,\$k}[\eta_1 \text{Last}@ $\mathbf{CS}_1[\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, \theta, y_1]]]$  /. {} -> {1}; HL[lhs == rhs]}$ 
```

```
Out[*]:= {0.296875, { $\mathbb{E}_{\{1\} \rightarrow \{1\}}[\theta, -y_1 \eta_1, 1 + O[\epsilon]^4]$ , True}}
```