

A POLY-TIME KNOT POLYNOMIAL VIA SOLVABLE APPROXIMATION

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ABSTRACT. We construct the first poly-time-computable knot polynomial since Alexander’s [Al, 1928] by using some new commutator-calculus techniques and a Lie algebra \mathfrak{g}_1 which is at the same time solvable and an approximation of the simple Lie algebra sl_2 .

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1. INTRODUCTION

An excellent classical paper in mathematics would state a great theorem in the first couple pages of the introduction, describe its significance in section 2, and then present its proof in the remaining sections. We cannot match that; as a “theorem”, our result is that a certain algorithm works well. We cannot even state the theorem without describing the algorithm, and a wordy description of the algorithm would either be lengthy and unmotivated, or would take up a whole paper. So instead of a wordy description we provide a complete implementation, right below in Figure 1.1, along with one usage example. Once it is established that the algorithm fits in less than a page of code, we move on to explain why we think it is valuable, and more importantly, how it arises from a traditional construction applied to a non-traditional Lie algebra which enables a non-traditional computational technique.

Theorem 1.1. *The program in Figure 1.1 computes z_1 , a polynomial invariant of knots, in time polynomial in the crossing number.*

computations below

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A Demo Program for z_1

```

DPx-→Dα,y-→Dβ[P-][f-] := (* means P[∂α,∂β][f] *)
Total[CoefficientRules[P, {x, y}] /.
  ({m-, n-} → c-) ⇒ c D[f, {α, m}, {β, n}]];
CF[IE[ω-, L-, Q-, P-]] := Expand/@Together/@
  E[ω /. b ⇒ Log[t], L, Q /. b ⇒ Log[t],
  P /. b ⇒ Log[t]];
E /: E[ω1, L1, Q1, P1] E[ω2, L2, Q2, P2] :=
  CF@E[ω1 ω2, L1 + L2, ω2 Q1 + ω1 Q2, ω24 P1 + ω14 P2];
Nui- cj-→R-[E[ω-, L-, Q-, P-]] :=
  With[{q = e-y β uk + γ ck}, CF[
    E[ω, γ ck + (L /. cj → θ), ω e-y β uk + (Q /. ui → θ),
    e-q DPcj→Dγ,ui→Dβ[P][eq] /.
    {γ → ∂cjL, β → ω-1 ∂uiQ}]];
Nui- cj-→R-[E[ω-, L-, Q-, P-]] :=
  With[{q = ey α wk + γ ck}, CF[
    E[ω, γ ck + (L /. cj → θ), ω ey α wk + (Q /. wi → θ),
    e-q DPcj→Dγ,wi→Dα[P][eq] /.
    {γ → ∂cjL, α → ω-1 ∂wiQ}]];
Nuwi- uj-→R-[E[ω-, L-, Q-, P-]] :=
  With[{q = (1 - t) μ-1 α β + μ-1 β uk + μ-1 δ uk wk + μ-1 α wk},
  CF[
    E[μ ω, L, μ ω q + μ (Q /. wi | uj → θ),
    μ4 e-q DPwi→Dα,uj→Dβ[P][eq] + ω4 Δ[k]] /.
    μ → 1 + (t - 1) δ /.
    {α → ω-1 (∂wiQ /. uj → θ), β → ω-1 (∂ujQ /. wi → θ),
    δ → ω-1 ∂wi,ujQ}]];
mi-,j-→R-[Z-] := Module[{x, y, z},
  Z // Nui- cj-→x // Nuwx uj-→y //
  ReplaceAll[{cx|y → cx, wj → wy}] // Nuui cx→x //
  ReplaceAll[Z-[i|j|x|y → zk] // CF]

```

FIGURE 1.1. A demo program computing z_1 , some initial data, and a sample run on the 0-framed trefoil knot. The program is written in *Mathematica* [Wo] and is available at [BNVDV].

The invariant z_1 is in fact quite strong — explicit computations show that it separates more knots in the standard knot tables than the Alexander polynomial, the Jones polynomial, the HOMFLY-PT polynomial, and Khovanov homology (even when these are combined)! See the table in Section 5.

This is exciting news. The main reason is self-evident — z_1 is the first poly-time computable polynomial invariants of knots since the Alexander polynomial, discovered nearly 90 years ago [Al, 1928]. A further reason is explained in Section 6 — it seems that z_1 has a

Initial Data

```

Δ[k-] := (1 - t) (α2 β2 + 4 α β δ μ + 2 δ2 μ2) / 2 +
  2 μ2 (α β + δ μ) ck - β (2 μ - 1) (α β + 2 δ μ) uk +
  2 β δ μ2 ck uk - β2 δ (3 μ - 1) uk2 / 2 + α (α β + 2 δ μ) wk +
  2 α δ μ2 ck wk - 2 (t - 1) δ2 (α β + δ μ) uk wk +
  2 δ2 μ2 ck uk wk - β δ2 (2 μ - 1) uk2 wk + α2 δ (1 + μ) wk2 / 2 +
  α δ2 uk wk2 - (t - 1) δ4 uk2 wk2 / 2;
Ri-,j-+ := E[1, bi cj, ui wj,
  -ci (t - 1)2 / 2 - ci2 (t - 1)2 / 2 + ci cj (t2 - t - 2) / 2 -
  cj ui wi / 2 + ci (1 - t) ui wi - ui2 wi2 / 2 + ui wj +
  cj t ui wj / 2 + ci (t - 2) t ui wj + ci (1 + t) uj wj / 2 +
  (t - 1) ui2 wi wj - (t - 2) t ui2 wj2 / 2];
Ri-,j-- := E[1, -bi cj, -t-1 ui wj,
  ci (t - 1)2 / 2 + ci2 (t - 1)2 / 2 + ci cj (2 + t - t2) / 2 +
  cj ui wi / 2 + ci (t - 1) ui wi + ui2 wi2 / 2 +
  (1 - t-1) ui wj / 2 + ci (2 t - 5 + 3 t-1) ui wj / 2 +
  cj (t-1 + 1 - t) ui wj / 2 - ci (t + 1) uj wj / 2 +
  (2 - 3 t-1) ui2 wi wj / 2 + (1 + 2 t-2 - 3 t-1) ui2 wj2 / 2 -
  t-1 (1 + t) ui uj wj2 / 2];
uri- := E[t-1/4, θ, θ, ci t / 4 + ui wi / 8];
nri- := E[t1/4, θ, θ, -ci t3 / 4 - t2 ui wi / 8];
uli- := E[t1/4, θ, θ, ci t (4 + t) / 4 - t2 ui wi / 8];
nli- := E[t-1/4, θ, θ, -ci (1 + 4 t-1) / 4 + ui wi / 8];

```

The Trefoil

```

z = R1,14+ R5,2- nr3 ul4 R19,6+ R7,10- nl8 ur9 R11,20+ nr12 ul13
  R15,18- nl16 ur17;
(Do[z = z // m1,k→1, {k, 2, 20}]; z = z /. a-1 ⇒ a)
E[-1 + 1/t + t, θ, θ,
  -16 + 9c/2 - 2c/t4 + 1/t3 + 11c/2t3 - 4/t2 - 8c/t2 + 10/t + 4c/t + 18t -
  10ct - 14t2 + 8ct2 + 7t3 - 3ct3/2 - 2t4 - 2ct4 +
  2ct5 - ct6/2 - 4uw + 2uw/t4 - 7uw/2t3 + 9uw/2t2 + uw/2t +
  6t2uw - 2t2uw - 1/2 t3uw + 3/2 t4uw - 1/2 t5uw]

```

better chance than anything else we know to detect potential counterexamples to the ribbon-slice conjecture. Finally, z_1 is founded on some new Lie-theoretic techniques, it seems to be possible to generalize it in several directions, and many questions are raised. See Section 7.

Our z_1 can be considered as a perturbation of another invariant, z_0 , which is somewhat weaker yet in many ways it is more valuable. It is computed by a shorter program (see Figure 3.1) which runs faster, and it has a proven topological significance. The main reason z_0 is not the main character of this paper is that it is already well known: restricted to knots z_0 is the Alexander polynomial and considered on pure tangles (see Section 3) it is equivalent to the “ β -calculus” of [BNS, BN2], which in itself is mostly equivalent [Ha] to Archibald’s calculus [Ar] and is a mild extension of the Burau-Gassner theory of [LD, KLW, CT, CC].

As we shall see in Section 4, z_1 arises from a certain Lie algebra \mathfrak{g}_1 , and as we shall see in Section 3, z_0 arises from a certain Lie algebra \mathfrak{g}_0 . Within this introduction we only wish to define these two Lie algebras and explain how they arise as “(solvable) approximations of sl_2 ”.

Definition 1.2. Over the field \mathbb{Q} of rational numbers, let \mathfrak{g}_0 be the 4-dimensional Lie algebra generated by elements b, c, u , and w , such that b is central, $[c, u] = u$, $[c, w] = -w$, and $[u, w] = b$:

$$\mathfrak{g}_0 := \mathbb{Q}\langle b, c, u, w \rangle / ([b, -] = 0, [c, u] = u, [c, w] = -w, [u, w] = b).$$

We grade \mathfrak{g}_0 by declaring that $\deg(b, c, u, w) = (1, 0, 1, 0)$.

Note that \mathfrak{g}_0 is solvable: Indeed

$$\mathfrak{g}_0 \supset \langle b, u, w \rangle \supset \langle b \rangle \supset \{0\}$$

is a tower of ideals of \mathfrak{g}_0 whose consecutive quotients are Abelian.

Definition 1.3. Over the ring $R := \mathbb{Q}[\epsilon]/(\epsilon^2 = 0)$, let \mathfrak{g}_1 be the 4-dimensional Lie algebra generated by elements b, c, u , and w , such that b is central, $[c, u] = u$, $[c, w] = -w$, and $[u, w] = b - 2\epsilon c$:

$$\mathfrak{g}_1 := R\langle b, c, u, w \rangle / ([b, -] = 0, [c, u] = u, [c, w] = -w, [u, w] = b - 2\epsilon c).$$

We grade R and \mathfrak{g}_1 by declaring that $\deg(b, c, u, w, \epsilon) = (1, 0, 1, 0, 1)$.

Note that over \mathbb{Q} , \mathfrak{g}_1 is an 8-dimensional solvable Lie algebra: Indeed

$$\mathfrak{g}_1 \supset \langle b, u, w, \epsilon b, \epsilon c, \epsilon u, \epsilon w \rangle \supset \langle b, \epsilon b, \epsilon c, \epsilon u, \epsilon w \rangle \supset 0$$

is a tower of ideals of $\mathfrak{g}_1/\mathbb{Q}$ whose consecutive quotients are Abelian.

For the purposes of this paper, we do not need to know that \mathfrak{g}_0 and \mathfrak{g}_1 are related to the classical Lie algebra sl_2 , and hence the next few paragraphs¹ can safely be skipped. Yet these paragraphs say that “there’s more where \mathfrak{g}_0 and \mathfrak{g}_1 came from”, and strongly suggest that there’s more where our z_0 and z_1 come from.

Let \mathfrak{g} be an arbitrary semi-simple Lie algebra over \mathbb{Q} , and let $\mathfrak{g} = \mathfrak{n}^+ \oplus \mathfrak{h} \oplus \mathfrak{n}^-$ be
MORE.

2. ALGEBRAS, YANG-BAXTER ELEMENTS AND SPINNERS, INVARIANTS

MORE.

¹Trigger warning: Borel and Cartan subalgebras, Lie bialgebras, Drinfel’d doubles.

A Demo Program for z_0

```

CF[ω-.E[Q-]] := Simplify[ω] E[Simplify[Q]];
E /: E[Q1-] E[Q2-] := CF@E[Q1 + Q2];
Nui cj →k[ω-.E[Q-]] :=
  CF[ω E[e-γ β uk + γ ck + (Q / . cj | ui → 0)] / .
    {γ → ∂cj Q, β → ∂ui Q}];
Nwi cj →k[ω-.E[Q-]] :=
  CF[ω E[eγ α wk + γ ck + (Q / . cj | wi → 0)] / .
    {γ → ∂cj Q, α → ∂wi Q}];
Nwi uj →k[ω-.E[Q-]] :=
  CF[
    v ω E[-b v α β + v β uk + v δ uk wk + v α wk +
      (Q / . wi | uj → 0)] / . v → (1 + b δ)-1 / .
    {α → ∂wi Q / . uj → 0, β → ∂uj Q / . wi → 0, δ → ∂wi, uj Q}];
mi-, j- →k[ω-.E[Q-]] :=
  CF[Module[{x},
    (ω E[Q] // Nwi cj →x // Nui cx →x // Nwx uj →x) / .
    {ci → ck, wj → wk, y-x → yk}]]

```

Initial Data

$$R_{i-,j-}^+ := \mathbb{E} \left[\mathbf{b} c_j + \mathbf{b}^{-1} (\mathbf{e}^{\mathbf{b}} - \mathbf{1}) u_i w_j \right];$$

$$R_{i-,j-}^- := \mathbb{E} \left[-\mathbf{b} c_j + \mathbf{b}^{-1} (\mathbf{e}^{-\mathbf{b}} - \mathbf{1}) u_i w_j \right];$$

The Knot 8_{17}

$$\mathbf{z} = R_{12,1}^- R_{2,7}^- R_{8,3}^- R_{4,11}^- R_{16,5}^+ R_{6,13}^+ R_{14,9}^+ R_{10,15}^+;$$

$$\text{Do}[\mathbf{z} = \mathbf{z} // \mathbf{m}_{1,n \rightarrow 1}, \{\mathbf{n}, 2, 16\}];$$

$$\text{CF}@\mathbf{z} / . \omega_{-}.E[Q_{-}] \Rightarrow \omega^{-1} / . \mathbf{b} \rightarrow \text{Log}[\mathbf{t}]$$

$$\frac{-1-4t+8t^2-11t^3+8t^4-4t^5+t^6}{t^3}$$

FIGURE 3.1. A demo program computing z_0 , some initial data, and a sample run on the knot 8_{17} . The program is written in *Mathematica* [Wo] and is available at [BNVDV].

3. THE LIE ALGEBRA \mathfrak{g}_0 , THE INVARIANT z_0 , AND THE ALEXANDER POLYNOMIAL

4. THE LIE ALGEBRA \mathfrak{g}_1 AND THE INVARIANT z_1

MORE.

5. COMPUTING z_1

MORE.

6. AN ASIDE ON RIBBON KNOTS

MORE.

7. QUESTIONS

MORE.

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