

Pensieve header: Verifying the adjoint action.

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SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\OneCo-1606\\V1"];
<< OneCo.m

AutoAd[τ_. a_{i,j}_][x_] := Module[{bas, β, k, f, t, guess, InitCond, DiffCond, sol},
  bas = ReplacePart[LBasis[{i, j}], 1 → β];
  n = 0; guess = Sum[f_{++n}[t] y, {y, bas}];
  InitCond = Table[
    0 == Coefficient[(guess /. t → 0) - x, y] /. {(c | u | w)_ → 0, ε → 0}, {y, bas}];
  DiffCond = Table[0 == Coefficient[D[guess, t] - b[Expand[τ a_{i,j}], guess], y] /.
    {(c | u | w)_ → 0, ε → 0}, {y, bas}];
  {sol} = DSolve[InitCond ∪ DiffCond, Table[f_k[t], {k, n}], t];
  guess /. sol /. t → 1
]

x = c_1
c_1

bas = ReplacePart[LBasis[{1, 2}], 1 → β]
{β, ε, c_1, c_2, u_1, u_2, w_1, w_2, ε c_1, ε c_2, ε u_1, ε u_2, ε w_1, u_1 w_1, u_2 w_1, ε w_2, u_1 w_2,
u_2 w_2, ε c_1^2, ε c_1 c_2, ε c_2^2, ε c_1 u_1, ε c_2 u_1, ε c_1 u_2, ε c_2 u_2, ε c_1 w_1, ε c_2 w_1, ε u_1 w_1,
ε u_2 w_1, ε c_1 w_2, ε c_2 w_2, ε u_1 w_2, ε u_2 w_2, ε c_1 u_1 w_1, ε c_2 u_1 w_1, ε u_1^2 w_1, ε c_1 u_2 w_1,
ε c_2 u_2 w_1, ε u_1 u_2 w_1, ε u_2^2 w_1, ε u_1 w_1^2, ε u_2 w_1^2, ε c_1 u_1 w_2, ε c_2 u_1 w_2, ε u_1^2 w_2,
ε c_1 u_2 w_2, ε c_2 u_2 w_2, ε u_1 u_2 w_2, ε u_2^2 w_2, ε u_1 w_1 w_2, ε u_2 w_1 w_2, ε u_1 w_2^2, ε u_2 w_2^2, ε u_1^2 w_2^2,
ε u_1 u_2 w_1^2, ε u_2^2 w_1^2, ε u_1^2 w_1 w_2, ε u_1 u_2 w_1 w_2, ε u_2^2 w_1 w_2, ε u_1^2 w_2^2, ε u_1 u_2 w_2^2, ε u_2^2 w_2^2}

k = 0;
guess = Sum[f_{++k}[t] y, {y, bas}]
β f_1[t] + ε f_2[t] + c_1 f_3[t] + c_2 f_4[t] + u_1 f_5[t] + u_2 f_6[t] + w_1 f_7[t] + w_2 f_8[t] + ε c_1 f_9[t] +
ε c_2 f_{10}[t] + ε u_1 f_{11}[t] + ε u_2 f_{12}[t] + ε w_1 f_{13}[t] + u_1 w_1 f_{14}[t] + u_2 w_1 f_{15}[t] + ε w_2 f_{16}[t] +
u_1 w_2 f_{17}[t] + u_2 w_2 f_{18}[t] + ε c_1^2 f_{19}[t] + ε c_1 c_2 f_{20}[t] + ε c_2^2 f_{21}[t] + ε c_1 u_1 f_{22}[t] +
ε c_2 u_1 f_{23}[t] + ε c_1 u_2 f_{24}[t] + ε c_2 u_2 f_{25}[t] + ε c_1 w_1 f_{26}[t] + ε c_2 w_1 f_{27}[t] +
ε u_1 w_1 f_{28}[t] + ε u_2 w_1 f_{29}[t] + ε c_1 w_2 f_{30}[t] + ε c_2 w_2 f_{31}[t] + ε u_1 w_2 f_{32}[t] +
ε u_2 w_2 f_{33}[t] + ε c_1 u_1 w_1 f_{34}[t] + ε c_2 u_1 w_1 f_{35}[t] + ε u_1^2 w_1 f_{36}[t] + ε c_1 u_2 w_1 f_{37}[t] +
ε c_2 u_2 w_1 f_{38}[t] + ε u_1 u_2 w_1 f_{39}[t] + ε u_2^2 w_1 f_{40}[t] + ε u_1 w_1^2 f_{41}[t] + ε u_2 w_1^2 f_{42}[t] +
ε c_1 u_1 w_2 f_{43}[t] + ε c_2 u_1 w_2 f_{44}[t] + ε u_1^2 w_2 f_{45}[t] + ε c_1 u_2 w_2 f_{46}[t] + ε c_2 u_2 w_2 f_{47}[t] +
ε u_1 u_2 w_2 f_{48}[t] + ε u_2^2 w_2 f_{49}[t] + ε u_1 w_1 w_2 f_{50}[t] + ε u_2 w_1 w_2 f_{51}[t] + ε u_1 w_2^2 f_{52}[t] +
ε u_2 w_2^2 f_{53}[t] + ε u_1^2 w_1^2 f_{54}[t] + ε u_1 u_2 w_1^2 f_{55}[t] + ε u_2^2 w_1^2 f_{56}[t] + ε u_1^2 w_1 w_2 f_{57}[t] +
ε u_1 u_2 w_1 w_2 f_{58}[t] + ε u_2^2 w_1 w_2 f_{59}[t] + ε u_1^2 w_2^2 f_{60}[t] + ε u_1 u_2 w_2^2 f_{61}[t] + ε u_2^2 w_2^2 f_{62}[t]

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(guess /. t -> 0) - x

$$\begin{aligned}
 & -c_1 + \beta f_1[0] + \epsilon f_2[0] + c_1 f_3[0] + c_2 f_4[0] + u_1 f_5[0] + u_2 f_6[0] + w_1 f_7[0] + w_2 f_8[0] + \\
 & \epsilon c_1 f_9[0] + \epsilon c_2 f_{10}[0] + \epsilon u_1 f_{11}[0] + \epsilon u_2 f_{12}[0] + \epsilon w_1 f_{13}[0] + u_1 w_1 f_{14}[0] + \\
 & u_2 w_1 f_{15}[0] + \epsilon w_2 f_{16}[0] + u_1 w_2 f_{17}[0] + u_2 w_2 f_{18}[0] + \epsilon c_1^2 f_{19}[0] + \epsilon c_1 c_2 f_{20}[0] + \\
 & \epsilon c_2^2 f_{21}[0] + \epsilon c_1 u_1 f_{22}[0] + \epsilon c_2 u_1 f_{23}[0] + \epsilon c_1 u_2 f_{24}[0] + \epsilon c_2 u_2 f_{25}[0] + \epsilon c_1 w_1 f_{26}[0] + \\
 & \epsilon c_2 w_1 f_{27}[0] + \epsilon u_1 w_1 f_{28}[0] + \epsilon u_2 w_1 f_{29}[0] + \epsilon c_1 w_2 f_{30}[0] + \epsilon c_2 w_2 f_{31}[0] + \epsilon u_1 w_2 f_{32}[0] + \\
 & \epsilon u_2 w_2 f_{33}[0] + \epsilon c_1 u_1 w_1 f_{34}[0] + \epsilon c_2 u_1 w_1 f_{35}[0] + \epsilon u_1^2 w_1 f_{36}[0] + \epsilon c_1 u_2 w_1 f_{37}[0] + \\
 & \epsilon c_2 u_2 w_1 f_{38}[0] + \epsilon u_1 u_2 w_1 f_{39}[0] + \epsilon u_2^2 w_1 f_{40}[0] + \epsilon u_1 w_1^2 f_{41}[0] + \epsilon u_2 w_1^2 f_{42}[0] + \\
 & \epsilon c_1 u_1 w_2 f_{43}[0] + \epsilon c_2 u_1 w_2 f_{44}[0] + \epsilon u_1^2 w_2 f_{45}[0] + \epsilon c_1 u_2 w_2 f_{46}[0] + \epsilon c_2 u_2 w_2 f_{47}[0] + \\
 & \epsilon u_1 u_2 w_2 f_{48}[0] + \epsilon u_2^2 w_2 f_{49}[0] + \epsilon u_1 w_1 w_2 f_{50}[0] + \epsilon u_2 w_1 w_2 f_{51}[0] + \epsilon u_1 w_2^2 f_{52}[0] + \\
 & \epsilon u_2 w_2^2 f_{53}[0] + \epsilon u_1^2 w_1^2 f_{54}[0] + \epsilon u_1 u_2 w_1^2 f_{55}[0] + \epsilon u_2^2 w_1^2 f_{56}[0] + \epsilon u_1^2 w_1 w_2 f_{57}[0] + \\
 & \epsilon u_1 u_2 w_1 w_2 f_{58}[0] + \epsilon u_2^2 w_1 w_2 f_{59}[0] + \epsilon u_1^2 w_2^2 f_{60}[0] + \epsilon u_1 u_2 w_2^2 f_{61}[0] + \epsilon u_2^2 w_2^2 f_{62}[0]
 \end{aligned}$$

InitCond =

Table[0 == Coefficient[(guess /. t -> 0) - x, y] /. {(c | u | w) -> 0, \epsilon -> 0}, {y, bas}]

$$\begin{aligned}
 & \{0 == f_1[0], 0 == f_2[0], 0 == -1 + f_3[0], 0 == f_4[0], 0 == f_5[0], 0 == f_6[0], \\
 & 0 == f_7[0], 0 == f_8[0], 0 == f_9[0], 0 == f_{10}[0], 0 == f_{11}[0], 0 == f_{12}[0], 0 == f_{13}[0], \\
 & 0 == f_{14}[0], 0 == f_{15}[0], 0 == f_{16}[0], 0 == f_{17}[0], 0 == f_{18}[0], 0 == f_{19}[0], 0 == f_{20}[0], \\
 & 0 == f_{21}[0], 0 == f_{22}[0], 0 == f_{23}[0], 0 == f_{24}[0], 0 == f_{25}[0], 0 == f_{26}[0], 0 == f_{27}[0], \\
 & 0 == f_{28}[0], 0 == f_{29}[0], 0 == f_{30}[0], 0 == f_{31}[0], 0 == f_{32}[0], 0 == f_{33}[0], 0 == f_{34}[0], \\
 & 0 == f_{35}[0], 0 == f_{36}[0], 0 == f_{37}[0], 0 == f_{38}[0], 0 == f_{39}[0], 0 == f_{40}[0], 0 == f_{41}[0], \\
 & 0 == f_{42}[0], 0 == f_{43}[0], 0 == f_{44}[0], 0 == f_{45}[0], 0 == f_{46}[0], 0 == f_{47}[0], 0 == f_{48}[0], \\
 & 0 == f_{49}[0], 0 == f_{50}[0], 0 == f_{51}[0], 0 == f_{52}[0], 0 == f_{53}[0], 0 == f_{54}[0], 0 == f_{55}[0], \\
 & 0 == f_{56}[0], 0 == f_{57}[0], 0 == f_{58}[0], 0 == f_{59}[0], 0 == f_{60}[0], 0 == f_{61}[0], 0 == f_{62}[0]\}
 \end{aligned}$$

DiffCond = Table[

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0 == Coefficient[D[guess, t] - b[a1,2, guess], y] /. {(c | u | w) -> 0, e -> 0}, {y, bas}]
{0 == f1'[t], 0 == f2'[t], 0 == f3'[t], 0 == f4'[t], 0 == b2 f6[t] + f5'[t], 0 == -b1 f6[t] + f6'[t],
0 == f7'[t], 0 == -b1 f7[t] + b1 f8[t] + f8'[t], 0 == f9'[t], 0 == f10'[t],
0 == b2 f12[t] - b2 f24[t] + b2 f25[t] + f11'[t], 0 == -b1 f12[t] + f12'[t], 0 == f13'[t],
0 == b2 f15[t] + f14'[t], 0 == -b1 f15[t] + f15'[t], 0 == -b1 f13[t] + b1 f16[t] + f16'[t],
0 == f3[t] - f4[t] - b1 f14[t] + b1 f17[t] + b2 f18[t] + f17'[t], 0 == -b1 f15[t] + f18'[t],
0 == f19'[t], 0 == f20'[t], 0 == f21'[t], 0 == b2 f24[t] + f22'[t],
0 == f5[t] - 2 f6[t] + b2 f25[t] + f23'[t], 0 == f6[t] - b1 f24[t] + f24'[t],
0 == -b1 f25[t] + f25'[t], 0 == f26'[t], 0 == -f7[t] + f27'[t],
0 == b2 f29[t] - b2 f37[t] + b2 f38[t] + f28'[t], 0 == f15[t] - b1 f29[t] + f29'[t],
0 == 2 f7[t] - f8[t] - b1 f26[t] + b1 f30[t] + f30'[t], 0 == -b1 f27[t] + b1 f31[t] + f31'[t],
0 == f9[t] - f10[t] - 2 f14[t] + f17[t] - f19[t] + f20[t] - f21[t] - b1 f28[t] + b1 f32[t] +
b2 f33[t] - b2 f46[t] + b2 f47[t] + f32'[t], 0 == -b1 f29[t] + f33'[t], 0 == b2 f37[t] + f34'[t],
0 == -2 f15[t] + b2 f38[t] + f35'[t], 0 == b2 f39[t] + f36'[t], 0 == f15[t] - b1 f37[t] + f37'[t],
0 == -f15[t] - b1 f38[t] + f38'[t], 0 == -b1 f39[t] + 2 b2 f40[t] + f39'[t],
0 == -2 b1 f40[t] + f40'[t], 0 == b2 f42[t] + f41'[t], 0 == -b1 f42[t] + f42'[t],
0 == 2 f14[t] - f17[t] + 2 f19[t] - f20[t] - b1 f34[t] + b1 f43[t] + b2 f46[t] + f43'[t],
0 == f17[t] - 2 f18[t] + f20[t] - 2 f21[t] - b1 f35[t] + b1 f44[t] + b2 f47[t] + f44'[t],
0 == f22[t] - f23[t] - b1 f36[t] + b1 f45[t] + b2 f48[t] + f45'[t],
0 == 2 f15[t] - b1 f37[t] + f46'[t], 0 == -b1 f38[t] + f47'[t],
0 == f24[t] - f25[t] - b1 f39[t] + 2 b2 f49[t] + f48'[t], 0 == -b1 f40[t] - b1 f49[t] + f49'[t],
0 == f26[t] - f27[t] - 2 b1 f41[t] + b1 f50[t] + b2 f51[t] + f50'[t],
0 == -2 b1 f42[t] + f51'[t], 0 == f30[t] - f31[t] - b1 f50[t] + 2 b1 f52[t] + b2 f53[t] + f52'[t],
0 == -b1 f51[t] + b1 f53[t] + f53'[t], 0 == b2 f55[t] + f54'[t],
0 == -b1 f55[t] + 2 b2 f56[t] + f55'[t], 0 == -2 b1 f56[t] + f56'[t],
0 == f34[t] - f35[t] - 2 b1 f54[t] + b1 f57[t] + b2 f58[t] + f57'[t],
0 == f37[t] - f38[t] - 2 b1 f55[t] + 2 b2 f59[t] + f58'[t], 0 == -2 b1 f56[t] - b1 f59[t] + f59'[t],
0 == f43[t] - f44[t] - b1 f57[t] + 2 b1 f60[t] + b2 f61[t] + f60'[t],
0 == f46[t] - f47[t] - b1 f58[t] + b1 f61[t] + 2 b2 f62[t] + f61'[t], 0 == -b1 f59[t] + f62'[t]}

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```
{sol} = DSolve[InitCond ∪ DiffCond, Table[fi[t], {i, k}], t]
{ {f1[t] → 0, f2[t] → 1, f3[t] → 0, f8[t] → 0, f9[t] → 0, f13[t] → 0, f14[t] → 0,
  f16[t] → -  $\frac{e^{-t b_1} (-1 + e^{t b_1})}{b_1}$ , f17[t] → 0, f18[t] → 0, f19[t] → 0, f20[t] → 0, f27[t] → 0,
  f28[t] → 0, f31[t] →  $\frac{e^{-t b_1} (-1 + e^{t b_1} - t b_1)}{b_1^2}$ , f32[t] → 0, f33[t] → 0, f34[t] → 0,
  f36[t] → 0, f37[t] → 0, f42[t] → -  $\frac{e^{-t b_1} (-1 + e^{t b_1} - t b_1)}{b_1^2}$ , f43[t] →  $\frac{e^{-t b_1} (-1 + e^{t b_1} - t b_1)}{b_1^2}$ ,
  f45[t] → 0, f46[t] → 0, f53[t] → 0, f54[t] → 0, f55[t] → 0, f56[t] → 0, f57[t] → 0,
  f58[t] → 0, f59[t] →  $\frac{e^{-2 t b_1} (-1 + e^{2 t b_1} - 2 e^{t b_1} t b_1)}{b_1^3}$ , f60[t] → 0, f61[t] → 0,
  f4[t] → 0, f5[t] → 0, f10[t] → 0, f11[t] → 0, f21[t] → 0, f22[t] → 0, f23[t] → 0,
  f24[t] → 0, f35[t] → 0, f38[t] → 0, f39[t] → 0, f44[t] → 0, f47[t] → 0, f48[t] → 0,
  f6[t] → 0, f7[t] → 0, f25[t] → 0, f26[t] → 0, f29[t] → 0, f30[t] → 0, f40[t] → 0,
  f41[t] → 0, f49[t] → 0, f50[t] → 0, f51[t] → 0, f52[t] → 0, f12[t] → 0, f15[t] → 0 } }
```

guess /. sol

$$c_1 - \frac{e^{-t b_1} (-1 + e^{t b_1}) u_1 w_2}{b_1} + \frac{e^{-t b_1} \in (-1 + e^{t b_1} - t b_1) u_1 w_2}{b_1^2} - \frac{e^{-t b_1} \in (-1 + e^{t b_1} - t b_1) c_1 u_1 w_2}{b_1^2} +$$

$$\frac{e^{-t b_1} \in (-1 + e^{t b_1} - t b_1) c_2 u_1 w_2}{b_1^2} + \frac{e^{-2 t b_1} \in (-1 + e^{2 t b_1} - 2 e^{t b_1} t b_1) u_1^2 w_2^2}{b_1^3}$$

AutoAd[τ a_{i,j}][c_i]

$$c_i - \frac{e^{-\tau b_i} (-1 + e^{\tau b_i}) u_i w_j}{b_i} + \frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) u_i w_j}{b_i^2} - \frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) c_i u_i w_j}{b_i^2} +$$

$$\frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) c_j u_i w_j}{b_i^2} + \frac{e^{-2 \tau b_i} \in (-1 + e^{2 \tau b_i} - 2 e^{\tau b_i} \tau b_i) u_i^2 w_j^2}{b_i^3}$$

AutoAd[τ a_{i,j}][c_j]

$$c_j + \frac{e^{-\tau b_i} (-1 + e^{\tau b_i}) u_i w_j}{b_i} - \frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) u_i w_j}{b_i^2} + \frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) c_i u_i w_j}{b_i^2} -$$

$$\frac{e^{-\tau b_i} \in (-1 + e^{\tau b_i} - \tau b_i) c_j u_i w_j}{b_i^2} - \frac{e^{-2 \tau b_i} \in (-1 + e^{2 \tau b_i} - 2 e^{\tau b_i} \tau b_i) u_i^2 w_j^2}{b_i^3}$$

AutoAd[τ a_{i,j}][u_i]

$$u_i - \in \tau c_j u_i - \frac{e^{-\tau b_i} \in (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) u_i^2 w_j}{b_i^2}$$

AutoAd[$\tau a_{i,j}$][u_j]

$$\begin{aligned}
 & - \frac{(-1 + e^{\tau b_i}) b_j u_i}{b_i} - \frac{\epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) b_j u_i}{b_i^2} + \frac{\epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) b_j c_i u_i}{b_i^2} + \\
 & \frac{\epsilon (-2 b_i + 2 e^{\tau b_i} b_i - b_j + e^{\tau b_i} b_j - \tau b_i b_j) c_j u_i}{b_i^2} + e^{\tau b_i} u_j - e^{\tau b_i} \epsilon \tau c_i u_j - \frac{1}{b_i^3} \\
 & e^{-\tau b_i} \epsilon (-b_i + 2 e^{\tau b_i} b_i - e^{2 \tau b_i} b_i + 2 e^{\tau b_i} b_j - 2 e^{2 \tau b_i} b_j + e^{\tau b_i} \tau b_i b_j + e^{2 \tau b_i} \tau b_i b_j) u_i^2 w_j + \\
 & \frac{\epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) u_i u_j w_j}{b_i^2}
 \end{aligned}$$

AutoAd[$\tau a_{i,j}$][w_i]

$$\begin{aligned}
 & w_i + \epsilon \tau c_j w_i + e^{-\tau b_i} (-1 + e^{\tau b_i}) w_j - \\
 & \frac{e^{-\tau b_i} \epsilon (-1 + e^{\tau b_i} + \tau b_i) c_i w_j}{b_i} + \frac{e^{-\tau b_i} \epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) c_j w_j}{b_i} + \\
 & \frac{e^{-\tau b_i} \epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) u_i w_i w_j}{b_i^2} + \frac{e^{-2 \tau b_i} (1 + e^{\tau b_i}) \epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) u_i w_j^2}{b_i^2}
 \end{aligned}$$

AutoAd[$\tau a_{i,j}$][w_j]

$$e^{-\tau b_i} w_j + e^{-\tau b_i} \epsilon \tau c_i w_j - \frac{e^{-2 \tau b_i} \epsilon (1 - e^{\tau b_i} + e^{\tau b_i} \tau b_i) u_i w_j^2}{b_i^2}$$

AutoAd[β]

0

b[AutoAd[u_i], AutoAd[w_i]] + 2 ϵ AutoAd[c_i] // Expand

b_i

b[AutoAd[u_j], AutoAd[w_j]] + 2 ϵ AutoAd[c_j] // Expand

b_j

Table[Expand[R0[1, 1, 2][y_k] - AutoAd[$a_{1,2}$][y_k]], { y , { c , u , w }}, { k , 3}]

{0, 0, c_3 }, {0, 0, u_3 }, {0, 0, w_3 }

b[c_1 , w_1]

$-w_1$

Ad[$\tau a_{1,2}$][b[c_1 , w_1]]

$$\begin{aligned}
 & -w_1 - \epsilon \tau c_2 w_1 - e^{-\tau b_1} (-1 + e^{\tau b_1}) w_2 + \\
 & \frac{e^{-\tau b_1} \epsilon (-1 + e^{\tau b_1} + \tau b_1) c_1 w_2}{b_1} - \frac{e^{-\tau b_1} \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) c_2 w_2}{b_1} - \\
 & \frac{e^{-\tau b_1} \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) u_1 w_1 w_2}{b_1^2} - \frac{e^{-2 \tau b_1} (1 + e^{\tau b_1}) \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) u_1 w_2^2}{b_1^2}
 \end{aligned}$$

Ad[$\tau (b_1 c_2 - \epsilon c_1 c_2 + u_1 w_2)$] [w_1]

$$w_1 + \epsilon \tau c_2 w_1 + e^{-\tau b_1} (-1 + e^{\tau b_1}) w_2 -$$

$$\frac{e^{-\tau b_1} \epsilon (-1 + e^{\tau b_1} + \tau b_1) c_1 w_2}{b_1} + \frac{e^{-\tau b_1} \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) c_2 w_2}{b_1} +$$

$$\frac{e^{-\tau b_1} \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) u_1 w_1 w_2}{b_1^2} + \frac{e^{-2\tau b_1} (1 + e^{\tau b_1}) \epsilon (1 - e^{\tau b_1} + e^{\tau b_1} \tau b_1) u_1 w_2^2}{b_1^2}$$