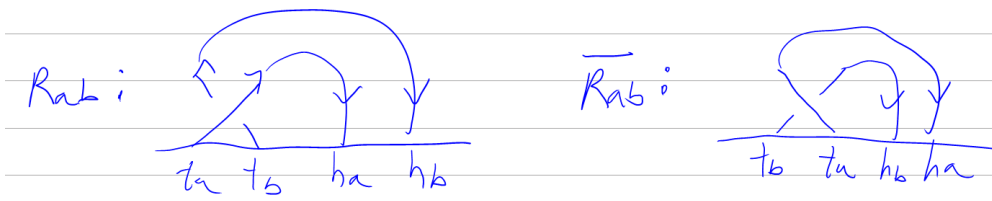


Pensieve header: Unitarity for Γ -calculus - finding the $\{\mathcal{L}\}_0$ for which $\bar{A} = \mathcal{L}_0 A$.

```
In[*]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\MetaCalculi"];
Once[<< KnotTheory`]
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.
Read more at <http://katlas.org/wiki/KnotTheory>.



```
In[*]:= R_{a,b}_ := \Gamma@<| \varsigma \to \{t_a, t_b, h_a, h_b\}, \omega \to 1, \sigma \to h_a + h_b T_a, \lambda \to \{t_a, t_b\} \cdot \begin{pmatrix} T_a & 1 - T_a \\ 0 & 1 \end{pmatrix} \cdot \{h_a, h_b\} |>;
\bar{R}_{a,b}_ := \Gamma@<| \varsigma \to \{t_b, t_a, h_b, h_a\}, \omega \to 1, \sigma \to h_a + h_b T_a^{-1}, \lambda \to \{t_a, t_b\} \cdot \begin{pmatrix} T_a^{-1} & 1 - T_a^{-1} \\ 0 & 1 \end{pmatrix} \cdot \{h_a, h_b\} |>;
```

```
In[*]:= \bar{R}_{1,2}
```

Out[*]=

$$\Gamma \left[\left\langle \varsigma \to \{t_2, t_1, h_2, h_1\}, \omega \to 1, \sigma \to h_1 + \frac{h_2}{T_1}, \lambda \to h_2 \left(t_2 + t_1 \left(1 - \frac{1}{T_1} \right) \right) + \frac{h_1 t_1}{T_1} \right\rangle \right]$$

```
In[*]:= \Gamma[\alpha_][\kappa_] := \alpha[\kappa];
\Gamma[\alpha_][S] := Union@Cases[\alpha[\varsigma], t_a_ \to a, \infty];
\Gamma[\alpha_][n] := Length[\Gamma[\alpha_][S]];
\Gamma[\alpha_][\Sigma] := (\partial_{h_a} \alpha[\sigma]) & /@ \Gamma[\alpha_][S];
\Gamma[\alpha_][A] := Outer[Factor[\partial_{\#1, \#2} \Gamma[\alpha_][\lambda]] &, Cases[\alpha[\varsigma], t_], Cases[\alpha[\varsigma], h_]]];
```

```
In[*]:= Table[\{\gamma@\varsigma, \gamma@\omega, \gamma@\sigma, \gamma@\lambda, \gamma@S, \gamma@\Sigma, \gamma@A // MatrixForm\}, \{\gamma, \{R_{1,2}, \bar{R}_{1,2}\}\}] // Transpose // MatrixForm
```

Out[*]//MatrixForm=

$$\begin{pmatrix} \begin{matrix} \{t_1, t_2, h_1, h_2\} \\ 1 \\ h_1 + h_2 T_1 \end{matrix} & \begin{matrix} \{t_2, t_1, h_2, h_1\} \\ 1 \\ h_1 + \frac{h_2}{T_1} \end{matrix} \\ h_2 \left(t_2 + t_1 \left(1 - T_1 \right) \right) + h_1 t_1 T_1 & h_2 \left(t_2 + t_1 \left(1 - \frac{1}{T_1} \right) \right) + \frac{h_1 t_1}{T_1} \\ \{1, 2\} & \{1, 2\} \\ \{1, T_1\} & \left\{ 1, \frac{1}{T_1} \right\} \\ \begin{pmatrix} T_1 & 1 - T_1 \\ 0 & 1 \end{pmatrix} & \begin{pmatrix} 1 & 0 \\ -\frac{1+T_1}{T_1} & \frac{1}{T_1} \end{pmatrix} \end{pmatrix}$$

```
In[*]:= rCollect[ $\gamma$ _I] :=  $\Gamma$ [ $\langle$  |  $\zeta \rightarrow \gamma @ \zeta, \omega \rightarrow$  Factor@ $\gamma @ \omega, \sigma \rightarrow$  Expand@ $\gamma @ \sigma,$ 
   $\lambda \rightarrow$  Total[CoefficientRules[ $\gamma @ \lambda, \gamma @ \zeta$ ] /. ( $ps\_ \rightarrow c\_$ )  $\Rightarrow$  Factor[ $c$ ] Times@@ ( $\gamma @ \zeta$ )ps] |  $\rangle$ ]
```

```
In[*]:= rCollect[ $\bar{R}_{1,2}$ ]
```

```
Out[*]=
```

$$\Gamma \left[\left\langle \left| \zeta \rightarrow \{t_2, t_1, h_2, h_1\}, \omega \rightarrow 1, \sigma \rightarrow h_1 + \frac{h_2}{T_1}, \lambda \rightarrow h_2 t_2 + \frac{h_1 t_1}{T_1} + \frac{h_2 t_1 (-1 + T_1)}{T_1} \right| \right\rangle \right]$$

```
In[*]:= ConservativeQ[ $\gamma$ _I] := Simplify[Expand[ $\gamma @ \lambda$  /.  $h\_ \rightarrow 1$ ] == Sum[ $t_a$ , { $a$ ,  $\gamma @ S$ }]]
```

```
In[*]:= ConservativeQ[ $R_{1,2}$ ]
```

```
Out[*]=
```

True

```
In[*]:= T* ^:=  $T^{-1}$ ;
 $\langle c\_ , d\_ \rangle_{c\_}$  := Expand@Module[{ $e$ ,  $f$ },
  Expand[ $c$  ( $d$  /. { $T \rightarrow T^*$ ,  $t_i \Rightarrow t_i^*$ ,  $h_i \Rightarrow h_i^*$ })] /.
  { $t_i^* t_i \rightarrow 0$ ,  $h_i^* h_i \rightarrow T - T^*$ , ( $f : t | h$ ) $j$ * ( $e : t | h$ ) $i$   $\Rightarrow$ 
  If[Position[ $\zeta$ ,  $e_i$ ][[1, 1]] < Position[ $\zeta$ ,  $f_j$ ][[1, 1],  $T - 1$ ,  $1 - T^*$ ]]
];
UnitaryQ[ $\gamma$ _I] := Module[{ $vs$ },
   $vs$  = Table[- $t_i + \partial_{t_i} \gamma @ \lambda$  /.  $T_ \rightarrow T$ , { $i$ ,  $\gamma @ S$ }]];
And@@Flatten@Table[Simplify[ $\langle vs[[i]$ ,  $vs[[j]] \rangle_{\gamma @ c}$  == 0], { $i$ ,  $\gamma @ n$ }, { $j$ ,  $\gamma @ n$ }]
];
```

```
In[*]:= UnitaryQ /@ { $R_{1,2}$ ,  $\bar{R}_{1,2}$ }
```

```
Out[*]=
```

{True, True}

```
In[*]:= rForm[ $\gamma$ _I] := Module[{ $M$ },
   $M$  =  $\gamma$ [ $A$ ] // Transpose;
  PrependTo[ $M$ ,  $t_{\#}$  & /@  $\gamma$ [ $S$ ]];
   $M$  = Join[
    {Prepend[ $h_{\#}$  & /@  $\gamma$ [ $S$ ],  $\gamma$ [ $\omega$ ]]},
    Transpose[ $M$ ],
    {Prepend[ $\gamma$ [ $\Sigma$ ], If[TrueQ[ConservativeQ@ $\gamma \wedge$  UnitaryQ@ $\gamma$ ],  $\blacksquare$ ,  $\blacksquare$ ]]}
  ];
  Column[{ $\gamma$ [ $\zeta$ ], MatrixForm[ $M$ ]}]
];
rForm[ $else\_$ ] :=  $else$  /.  $\gamma\_I \Rightarrow$  rForm[ $\gamma$ ];
Format[ $\gamma\_I$ , StandardForm] := rForm[ $\gamma$ ];
```

In[*]:= $\{R_{1,2}, \bar{R}_{1,2}\}$

Out[*]=

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, h_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & T_1 & 1 - T_1 \\ t_2 & 0 & 1 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix}, \begin{matrix} \{t_2, t_1, h_2, h_1\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 1 & 0 \\ t_2 & \frac{-1+T_1}{T_1} & \frac{1}{T_1} \\ \blacksquare & 1 & \frac{1}{T_1} \end{pmatrix} \end{matrix} \right\}$$

In[*]:= $dm_{i_j \rightarrow k_}[\gamma_T] := \text{Module}[\{a, b, c, d, \theta, \epsilon, \phi, \psi, \Xi, \mu\},$

$$\begin{pmatrix} a & b & \theta \\ c & d & \epsilon \\ \phi & \psi & \Xi \end{pmatrix} = \begin{pmatrix} \partial_{t_i, h_i} \gamma @ \lambda & \partial_{t_i, h_j} \gamma @ \lambda & \partial_{t_i} \gamma @ \lambda \\ \partial_{t_j, h_i} \gamma @ \lambda & \partial_{t_j, h_j} \gamma @ \lambda & \partial_{t_j} \gamma @ \lambda \\ \partial_{h_i} \gamma @ \lambda & \partial_{h_j} \gamma @ \lambda & \gamma @ \lambda \end{pmatrix} /. (t | h)_{i|j} \rightarrow \theta;$$

$rCollect[\Gamma[\langle |$

$c \rightarrow \text{DeleteCases}[\gamma @ c, h_i | t_j] /. \{t_i \rightarrow t_k, h_j \rightarrow h_k\},$

$\omega \rightarrow (\mu = 1 - c) \gamma @ \omega,$

$\sigma \rightarrow h_k (\partial_{h_i} \sigma) (\partial_{h_j} \sigma) + (\sigma /. h_{i|j} \rightarrow \theta),$

$\lambda \rightarrow \{t_k, 1\} \cdot \left(\begin{matrix} b + ad / \mu & \theta + a \epsilon / \mu \\ \psi + d \phi / \mu & \Xi + \epsilon \phi / \mu \end{matrix} \right) \cdot \{h_k, 1\}$

$| \rangle] /. \{T_i \rightarrow T_k, T_j \rightarrow T_k\}$

$];$

In[*]:= $\Gamma /: \text{RotateLeft}[\Gamma[\alpha_], n_]\ := \Gamma @ \text{ReplacePart}[\alpha, \text{Key} @ c \rightarrow \text{RotateLeft}[\alpha @ c, n]]$

In[*]:= $\{\text{Table}[\text{RotateLeft}[R_{1,2}, k], \{k, 0, 3\}], \text{Table}[\text{RotateLeft}[\bar{R}_{1,2}, k], \{k, 0, 3\}]\}$

Out[*]=

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, h_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & T_1 & 1 - T_1 \\ t_2 & 0 & 1 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix}, \begin{matrix} \{t_2, h_1, h_2, t_1\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 0 & 1 \\ t_2 & T_1 & 1 - T_1 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix}, \begin{matrix} \{h_1, h_2, t_1, t_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & T_1 & 1 - T_1 \\ t_2 & 0 & 1 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix}, \begin{matrix} \{h_2, t_1, t_2, h_1\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 1 - T_1 & T_1 \\ t_2 & 1 & 0 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_2, t_1, h_2, h_1\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 1 & 0 \\ t_2 & \frac{-1+T_1}{T_1} & \frac{1}{T_1} \\ \blacksquare & 1 & \frac{1}{T_1} \end{pmatrix} \end{matrix}, \begin{matrix} \{t_1, h_2, h_1, t_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & \frac{-1+T_1}{T_1} & \frac{1}{T_1} \\ t_2 & 1 & 0 \\ \blacksquare & 1 & \frac{1}{T_1} \end{pmatrix} \end{matrix}, \begin{matrix} \{h_2, h_1, t_2, t_1\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 1 & 0 \\ t_2 & \frac{-1+T_1}{T_1} & \frac{1}{T_1} \\ \blacksquare & 1 & \frac{1}{T_1} \end{pmatrix} \end{matrix}, \begin{matrix} \{h_1, t_2, t_1, h_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & 0 & 1 \\ t_2 & \frac{1}{T_1} & \frac{-1+T_1}{T_1} \\ \blacksquare & 1 & \frac{1}{T_1} \end{pmatrix} \end{matrix} \right\}$$

```

In[*]:=  $\Gamma$  /: Insert[ $\gamma1_\Gamma$ ,  $\gamma2_\Gamma$ ,  $k_$ ] :=  $\Gamma$ @<|
   $\zeta$  → Flatten[Insert[ $\gamma1_\zeta$ ,  $\gamma2_\zeta$ ,  $k$ ]],
   $\omega$  →  $\gamma1_\omega \gamma2_\omega$ ,
   $\sigma$  →  $\gamma1_\sigma + \gamma2_\sigma$ ,
   $\lambda$  →  $\gamma1_\lambda + \gamma2_\lambda$ 
  |>
 $\Gamma$  /: Insert[ $\gamma2_\Gamma$ ,  $k_$ ][ $\gamma1_\Gamma$ ] := Insert[ $\gamma1$ ,  $\gamma2$ ,  $k$ ]

```

```

In[*]:= ComposeList[{Insert[R3,4, 5], Insert[R5,6, 9], dm2,3→2, dm1,4→1, dm1,5→1, dm2,6→2, dm2,1→2},
  R1,2]

```

Out[]=

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, h_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & T_1 & 1 - T_1 \\ t_2 & 0 & 1 \\ \blacksquare & 1 & T_1 \end{pmatrix} \end{matrix} \right\}, \left\{ \begin{matrix} \{t_1, t_2, h_1, h_2, t_3, t_4, h_3, h_4\} \\ \begin{pmatrix} 1 & h_1 & h_2 & h_3 & h_4 \\ t_1 & T_1 & 1 - T_1 & 0 & 0 \\ t_2 & 0 & 1 & 0 & 0 \\ t_3 & 0 & 0 & T_3 & 1 - T_3 \\ t_4 & 0 & 0 & 0 & 1 \\ \blacksquare & 1 & T_1 & 1 & T_3 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, h_2, t_3, t_4, h_3, h_4, t_5, t_6, h_5, h_6\} \\ \begin{pmatrix} 1 & h_1 & h_2 & h_3 & h_4 & h_5 & h_6 \\ t_1 & T_1 & 1 - T_1 & 0 & 0 & 0 & 0 \\ t_2 & 0 & 1 & 0 & 0 & 0 & 0 \\ t_3 & 0 & 0 & T_3 & 1 - T_3 & 0 & 0 \\ t_4 & 0 & 0 & 0 & 1 & 0 & 0 \\ t_5 & 0 & 0 & 0 & 0 & T_5 & 1 - T_5 \\ t_6 & 0 & 0 & 0 & 0 & 0 & 1 \\ \blacksquare & 1 & T_1 & 1 & T_3 & 1 & T_5 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, t_4, h_2, h_4, t_5, t_6, h_5, h_6\} \\ \begin{pmatrix} 1 & h_1 & h_2 & h_4 & h_5 & h_6 \\ t_1 & T_1 & -((-1 + T_1) T_2) & (-1 + T_1) (-1 + T_2) & 0 & 0 \\ t_2 & 0 & T_2 & 1 - T_2 & 0 & 0 \\ t_4 & 0 & 0 & 1 & 0 & 0 \\ t_5 & 0 & 0 & 0 & T_5 & 1 - T_5 \\ t_6 & 0 & 0 & 0 & 0 & 1 \\ \blacksquare & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_1, t_2, h_2, h_1, t_5, t_6, h_5, h_6\} \\ \begin{pmatrix} 1 & h_1 & h_2 & h_5 & h_6 \\ t_1 & -((-1 + T_1) T_2) & 1 - T_2 + T_1 T_2 & 0 & 0 \\ t_2 & T_2 & 1 - T_2 & 0 & 0 \\ t_5 & 0 & 0 & T_5 & 1 - T_5 \\ t_6 & 0 & 0 & 0 & 1 \\ \blacksquare & 0 & 0 & 0 & 0 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_1, t_2, h_2, t_6, h_1, h_6\} \\ \begin{pmatrix} 1 & h_1 & h_2 & h_6 \\ t_1 & -((-1 + T_1) T_2) & T_1 (1 - T_2 + T_1 T_2) & -((-1 + T_1) (1 - T_2 + T_1 T_2)) \\ t_2 & T_2 & -T_1 (-1 + T_2) & (-1 + T_1) (-1 + T_2) \\ t_6 & 0 & 0 & 1 \\ \blacksquare & 0 & 0 & 0 \end{pmatrix} \end{matrix} \right\},$$

$$\left\{ \begin{matrix} \{t_1, t_2, h_1, h_2\} \\ \begin{pmatrix} 1 & h_1 & h_2 \\ t_1 & T_1 (1 - T_2 + T_1 T_2) & -((-1 + T_1) (1 + T_1 T_2)) \\ t_2 & -T_1 (-1 + T_2) & 1 - T_1 + T_1 T_2 \\ \blacksquare & 0 & 0 \end{pmatrix} \end{matrix} \right\}, \left\{ \begin{matrix} \{t_2, h_2\} \\ \begin{pmatrix} T_2 (1 - T_2 + T_2^2) & h_2 \\ t_2 & 1 \\ \blacksquare & 0 \end{pmatrix} \end{matrix} \right\}$$

```
In[*]:= c0 = {t2, h2, t6, h6};
S0 = Cases[c0, t_i_ -> i]
```

```
Out[*]=
{2, 6}
```

```
In[*]:= Table[-t_i + Sum[a_i,k h_k, {k, S0}], {i, S0}]
```

```
Out[*]=
{-t2 + h2 a2,2 + h6 a2,6, -t6 + h2 a6,2 + h6 a6,6}
```

```
In[*]:= us = Flatten@Table[u_i,j, {i, S0}, {j, S0}]
```

```
Out[*]=
{u2,2, u2,6, u6,2, u6,6}
```

```
In[*]:= eqns = Flatten@
```

```
Table[{-t_i + Sum[a_i,k h_k, {k, S0}], -t_j + Sum[u_j,k h_k, {k, S0}]}_c0 == 0, {i, S0}, {j, S0}]
```

```
Out[*]=
```

$$\left\{ \begin{aligned} & -a_{2,2} + \frac{a_{2,2}}{T} - a_{2,6} + \frac{a_{2,6}}{T} + u_{2,2} - T u_{2,2} - \frac{a_{2,2} u_{2,2}}{T} + T a_{2,2} u_{2,2} + \\ & a_{2,6} u_{2,2} - \frac{a_{2,6} u_{2,2}}{T} + u_{2,6} - T u_{2,6} - a_{2,2} u_{2,6} + T a_{2,2} u_{2,6} - \frac{a_{2,6} u_{2,6}}{T} + T a_{2,6} u_{2,6} = 0, \\ & -1 + T + a_{2,2} - T a_{2,2} - a_{2,6} + \frac{a_{2,6}}{T} + u_{6,2} - T u_{6,2} - \frac{a_{2,2} u_{6,2}}{T} + T a_{2,2} u_{6,2} + a_{2,6} u_{6,2} - \\ & \frac{a_{2,6} u_{6,2}}{T} + u_{6,6} - T u_{6,6} - a_{2,2} u_{6,6} + T a_{2,2} u_{6,6} - \frac{a_{2,6} u_{6,6}}{T} + T a_{2,6} u_{6,6} = 0, \\ & 1 - \frac{1}{T} - a_{6,2} + \frac{a_{6,2}}{T} - a_{6,6} + \frac{a_{6,6}}{T} - u_{2,2} + \frac{u_{2,2}}{T} - \frac{a_{6,2} u_{2,2}}{T} + T a_{6,2} u_{2,2} + a_{6,6} u_{2,2} - \\ & \frac{a_{6,6} u_{2,2}}{T} + u_{2,6} - T u_{2,6} - a_{6,2} u_{2,6} + T a_{6,2} u_{2,6} - \frac{a_{6,6} u_{2,6}}{T} + T a_{6,6} u_{2,6} = 0, \\ & a_{6,2} - T a_{6,2} - a_{6,6} + \frac{a_{6,6}}{T} - u_{6,2} + \frac{u_{6,2}}{T} - \frac{a_{6,2} u_{6,2}}{T} + T a_{6,2} u_{6,2} + a_{6,6} u_{6,2} - \frac{a_{6,6} u_{6,2}}{T} + \\ & u_{6,6} - T u_{6,6} - a_{6,2} u_{6,6} + T a_{6,2} u_{6,6} - \frac{a_{6,6} u_{6,6}}{T} + T a_{6,6} u_{6,6} = 0 \end{aligned} \right\}$$

```
In[*]:= {sol} = Solve[eqns, us]
```

```
Out[*]=
```

$$\left\{ \begin{aligned} u_{2,2} & \rightarrow - \left((T - a_{2,6} - T a_{6,2} + a_{2,6} a_{6,2} - T a_{6,6} - a_{2,2} a_{6,6}) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + T a_{6,2} - \right. \\ & \left. a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) \right), \\ u_{2,6} & \rightarrow - \left((-T + T a_{2,2} + T a_{6,2} + T a_{2,6} a_{6,2} + T a_{6,6} - T a_{2,2} a_{6,6}) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + \right. \\ & \left. T a_{6,2} - a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) \right), \\ u_{6,2} & \rightarrow (T (T - T a_{2,2} - a_{2,6} - T a_{2,6} a_{6,2} - T a_{6,6} + T a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + \\ & T a_{6,2} - a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}), \\ u_{6,6} & \rightarrow - \left((-T + T a_{2,2} + a_{2,6} + T a_{6,2} - a_{2,6} a_{6,2} + a_{2,2} a_{6,6}) / (T - T^2 + T^2 a_{2,2} - a_{2,6} - T a_{6,2} + \right. \\ & \left. a_{2,6} a_{6,2} + T a_{2,6} a_{6,2} + T^2 a_{2,6} a_{6,2} + T^2 a_{6,6} - a_{2,2} a_{6,6} - T a_{2,2} a_{6,6} - T^2 a_{2,2} a_{6,6}) \right) \end{aligned} \right\}$$

```
In[*]:= Flatten@Table[ui,j → Factor[ui,j /. sol], {i, S}, {j, S}]
```

```
Out[*]=
```

$$\left\{ \begin{aligned} u_{2,2} &\rightarrow - \left((-T + a_{2,6} + T a_{6,2} - a_{2,6} a_{6,2} + T a_{6,6} + a_{2,2} a_{6,6}) / (T - T^2 + T^2 a_{2,2} - a_{2,6} - T a_{6,2} + \right. \\ &\quad \left. a_{2,6} a_{6,2} + T a_{2,6} a_{6,2} + T^2 a_{2,6} a_{6,2} + T^2 a_{6,6} - a_{2,2} a_{6,6} - T a_{2,2} a_{6,6} - T^2 a_{2,2} a_{6,6}) \right), \\ u_{2,6} &\rightarrow (T (1 - a_{2,2} - a_{6,2} - a_{2,6} a_{6,2} - a_{6,6} + a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + T a_{6,2} - \\ &\quad a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}), \\ u_{6,2} &\rightarrow (T (T - T a_{2,2} - a_{2,6} - T a_{2,6} a_{6,2} - T a_{6,6} + T a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + \\ &\quad T a_{6,2} - a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}), \\ u_{6,6} &\rightarrow (-T + T a_{2,2} + a_{2,6} + T a_{6,2} - a_{2,6} a_{6,2} + a_{2,2} a_{6,6}) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + T a_{6,2} - \\ &\quad a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) \end{aligned} \right\}$$

```
In[*]:= Sum[Factor[ui,j /. sol] ti hj, {i, S}, {j, S}] // Together
```

```
Out[*]=
```

$$\begin{aligned} &(T h_2 t_2 - T h_6 t_2 - T^2 h_2 t_6 + T h_6 t_6 + T h_6 t_2 a_{2,2} + T^2 h_2 t_6 a_{2,2} - T h_6 t_6 a_{2,2} - \\ &\quad h_2 t_2 a_{2,6} + T h_2 t_6 a_{2,6} - h_6 t_6 a_{2,6} - T h_2 t_2 a_{6,2} + T h_6 t_2 a_{6,2} - T h_6 t_6 a_{6,2} + h_2 t_2 a_{2,6} a_{6,2} + \\ &\quad T h_6 t_2 a_{2,6} a_{6,2} + T^2 h_2 t_6 a_{2,6} a_{6,2} + h_6 t_6 a_{2,6} a_{6,2} - T h_2 t_2 a_{6,6} + T h_6 t_2 a_{6,6} + \\ &\quad T^2 h_2 t_6 a_{6,6} - h_2 t_2 a_{2,2} a_{6,6} - T h_6 t_2 a_{2,2} a_{6,6} - T^2 h_2 t_6 a_{2,2} a_{6,6} - h_6 t_6 a_{2,2} a_{6,6}) / \\ &(T - T^2 + T^2 a_{2,2} - a_{2,6} - T a_{6,2} + a_{2,6} a_{6,2} + T a_{2,6} a_{6,2} + T^2 a_{2,6} a_{6,2} + \\ &\quad T^2 a_{6,6} - a_{2,2} a_{6,6} - T a_{2,2} a_{6,6} - T^2 a_{2,2} a_{6,6}) \end{aligned}$$

```
In[*]:=  $\mathcal{L}0[\zeta\_]$  := Module[{S, us, eqns, sol},
  S = Cases[\zeta, ti → i];
  us = Flatten@Table[ui,j, {i, S}, {j, S}];
  eqns = Flatten@
    Table[{-ti + Sum[ai,k hk, {k, S}], -tj + Sum[uj,k hk, {k, S}]}ζ == 0, {i, S}, {j, S}];
  {sol} = Solve[eqns, us];
  Sum[Factor[ui,j /. sol] ti hj, {i, S}, {j, S}]
]
```

```
In[*]:=  $\mathcal{L}0[\{t_2, h_2, t_6, h_6\}]$ 
```

```
Out[*]=
```

$$\begin{aligned} &- \left((h_2 t_2 (-T + a_{2,6} + T a_{6,2} - a_{2,6} a_{6,2} + T a_{6,6} + a_{2,2} a_{6,6})) / (T - T^2 + T^2 a_{2,2} - a_{2,6} - T a_{6,2} + \right. \\ &\quad \left. a_{2,6} a_{6,2} + T a_{2,6} a_{6,2} + T^2 a_{2,6} a_{6,2} + T^2 a_{6,6} - a_{2,2} a_{6,6} - T a_{2,2} a_{6,6} - T^2 a_{2,2} a_{6,6}) \right) + \\ &(h_6 t_6 (-T + T a_{2,2} + a_{2,6} + T a_{6,2} - a_{2,6} a_{6,2} + a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + T a_{6,2} - \\ &\quad a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) + \\ &(T h_6 t_2 (1 - a_{2,2} - a_{6,2} - a_{2,6} a_{6,2} - a_{6,6} + a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + T a_{6,2} - \\ &\quad a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) + \\ &(T h_2 t_6 (T - T a_{2,2} - a_{2,6} - T a_{2,6} a_{6,2} - T a_{6,6} + T a_{2,2} a_{6,6})) / (-T + T^2 - T^2 a_{2,2} + a_{2,6} + \\ &\quad T a_{6,2} - a_{2,6} a_{6,2} - T a_{2,6} a_{6,2} - T^2 a_{2,6} a_{6,2} - T^2 a_{6,6} + a_{2,2} a_{6,6} + T a_{2,2} a_{6,6} + T^2 a_{2,2} a_{6,6}) \end{aligned}$$

```
In[*]:= L0[{t2, t6, h2, h6}]
Out[*]=
- ((h2 t2 (-T + a2,6 + T a6,2 - a2,6 a6,2 + T a6,6 + a2,2 a6,6)) / (T a2,2 - T^2 a2,6 - T a6,2 +
  a2,6 a6,2 + T a2,6 a6,2 + T^2 a2,6 a6,2 + T^2 a6,6 - a2,2 a6,6 - T a2,2 a6,6 - T^2 a2,2 a6,6)) -
(h2 t6 (-T^2 + T a2,2 + T a2,6 - T a6,2 + T^2 a6,2 + a2,6 a6,2 + T^2 a6,6 - a2,2 a6,6)) /
(-T a2,2 + T^2 a2,6 + T a6,2 - a2,6 a6,2 - T a2,6 a6,2 -
  T^2 a2,6 a6,2 - T^2 a6,6 + a2,2 a6,6 + T a2,2 a6,6 + T^2 a2,2 a6,6) +
(T h6 t6 (-T + a2,2 + a2,6 + T a6,2 - a2,6 a6,2 + a2,2 a6,6)) / (-T a2,2 + T^2 a2,6 + T a6,2 -
  a2,6 a6,2 - T a2,6 a6,2 - T^2 a2,6 a6,2 - T^2 a6,6 + a2,2 a6,6 + T a2,2 a6,6 + T^2 a2,2 a6,6) +
(h6 t2 (T - a2,2 - a2,6 + T a2,6 - T a6,2 - T a2,6 a6,2 - T a6,6 + T a2,2 a6,6)) / (-T a2,2 + T^2 a2,6 +
  T a6,2 - a2,6 a6,2 - T a2,6 a6,2 - T^2 a2,6 a6,2 - T^2 a6,6 + a2,2 a6,6 + T a2,2 a6,6 + T^2 a2,2 a6,6)
```

```
In[*]:= L0_{\lambda_} := Factor[L0[c] /. a_{i,j} -> \partial_{t_i, h_j} \lambda]
```

```
In[*]:= \gamma\theta = \bar{R}_{12,1} // Insert[RotateLeft[\bar{R}_{2,7}, 1], 4] // dm_{1,2 \to 1} // Insert[RotateLeft[R_{6,13}, 1], 7] //
  dm_{12,13 \to 12} // dm_{6,7 \to 6} // Insert[\bar{R}_{8,3}, 5] // dm_{1,3 \to 1} // dm_{6,8 \to 6} // Insert[R_{14,9}, 6] //
  dm_{12,14 \to 12} // dm_{6,9 \to 6} // Insert[RotateLeft[\bar{R}_{4,11}, 1], 4] // dm_{1,4 \to 1} // dm_{11,12 \to 11}
```

```
Out[*]=
{t1, h1, t11, h11, h6, t6}
(
  -1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11 / T1^2 T6 T11
  t1
  t6
  t11
  0
  h1
  (1-T1+T1 T6) T11 / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  (1-T1+T1 T6) (-1+T11) / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  T1 (-1+T6) T6 T11 / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  0
  h6
  (-1+T1) (1-T1+T1 T6) / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  T1^2 T6 T11 / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  (-1+T6) T11 (-1+2 T1-T1^2+T11-2 T1) / (-1+2 T1-T1^2-T1 T6+T1^2 T6+T11-2 T1 T11+T1^2 T11+T1 T6 T11)
  0
)
```

```
In[*]:= lhs = L0_{\gamma\theta}[c] [\gamma\theta[\lambda] /. T_ -> T]
```

```
Out[*]=
1 / T^2 (-3 + 4 T - 3 T^2 + T^3)
(-T^2 h1 t1 + T^3 h1 t1 - T^4 h1 t1 + T h6 t1 - 4 T^2 h6 t1 + 5 T^3 h6 t1 - 3 T^4 h6 t1 + T^5 h6 t1 - T h11 t1 +
  2 T^2 h11 t1 - 2 T^3 h11 t1 + T^4 h11 t1 - T h1 t6 + T^2 h1 t6 - 2 h6 t6 + 6 T h6 t6 - 10 T^2 h6 t6 + 8 T^3 h6 t6 -
  4 T^4 h6 t6 + T^5 h6 t6 + 2 h11 t6 - 5 T h11 t6 + 6 T^2 h11 t6 - 4 T^3 h11 t6 + T^4 h11 t6 - T^2 h1 t11 +
  2 T^3 h1 t11 - 2 T^4 h1 t11 + T^5 h1 t11 + T h6 t11 - 2 T^2 h6 t11 + 2 T^3 h6 t11 - T^4 h6 t11 - T h11 t11)
```


In[*]:= rhs = Factor[$\gamma_0[\lambda] / . T_ \rightarrow T^{-1}$]

Out[*]=

$$\frac{1}{T^2 (-3 + 4 T - 3 T^2 + T^3)}$$

$$\begin{aligned} & (-T^2 h_1 t_1 + T^3 h_1 t_1 - T^4 h_1 t_1 + T h_6 t_1 - 4 T^2 h_6 t_1 + 5 T^3 h_6 t_1 - 3 T^4 h_6 t_1 + T^5 h_6 t_1 - T h_{11} t_1 + \\ & 2 T^2 h_{11} t_1 - 2 T^3 h_{11} t_1 + T^4 h_{11} t_1 - T h_1 t_6 + T^2 h_1 t_6 - 2 h_6 t_6 + 6 T h_6 t_6 - 10 T^2 h_6 t_6 + 8 T^3 h_6 t_6 - \\ & 4 T^4 h_6 t_6 + T^5 h_6 t_6 + 2 h_{11} t_6 - 5 T h_{11} t_6 + 6 T^2 h_{11} t_6 - 4 T^3 h_{11} t_6 + T^4 h_{11} t_6 - T^2 h_1 t_{11} + \\ & 2 T^3 h_1 t_{11} - 2 T^4 h_1 t_{11} + T^5 h_1 t_{11} + T h_6 t_{11} - 2 T^2 h_6 t_{11} + 2 T^3 h_6 t_{11} - T^4 h_6 t_{11} - T h_{11} t_{11}) \end{aligned}$$

In[*]:= lhs == rhs

Out[*]=

True

In[*]:= Together[$\mathcal{L}_0@ \{t_1, h_1, t_{11}, h_{11}, h_6, t_6\}$]

Out[*]=

$$\begin{aligned} & (T h_6 t_1 - T^2 h_6 t_1 - T h_{11} t_1 + T^2 h_{11} t_1 - T h_6 t_6 + T^2 h_6 t_6 + T h_{11} t_6 - T^2 h_{11} t_6 - T h_6 t_1 a_{1,1} + T^2 h_6 t_1 a_{1,1} + \\ & T h_{11} t_1 a_{1,1} - T^2 h_{11} t_1 a_{1,1} - T^2 h_6 t_6 a_{1,1} + T^2 h_{11} t_6 a_{1,1} + T h_6 t_{11} a_{1,1} - T h_{11} t_{11} a_{1,1} + T h_1 t_1 a_{1,6} - \\ & T^2 h_1 t_1 a_{1,6} + T^2 h_1 t_6 a_{1,6} + T h_6 t_6 a_{1,6} - T^2 h_6 t_6 a_{1,6} - T h_{11} t_6 a_{1,6} - T^2 h_1 t_{11} a_{1,6} + T h_{11} t_{11} a_{1,6} - \\ & h_1 t_1 a_{1,11} + T h_1 t_1 a_{1,11} - T h_1 t_6 a_{1,11} + T h_6 t_6 a_{1,11} + T h_1 t_{11} a_{1,11} - T h_6 t_{11} a_{1,11} - h_{11} t_{11} a_{1,11} + \\ & T h_{11} t_{11} a_{1,11} + T^2 h_6 t_1 a_{6,1} - T^2 h_{11} t_1 a_{6,1} - T^2 h_6 t_{11} a_{6,1} + T^2 h_{11} t_{11} a_{6,1} - T h_6 t_1 a_{1,6} a_{6,1} + \\ & T^2 h_6 t_1 a_{1,6} a_{6,1} + T h_{11} t_1 a_{1,6} a_{6,1} - T^2 h_6 t_6 a_{1,6} a_{6,1} + T^3 h_6 t_6 a_{1,6} a_{6,1} + T^2 h_{11} t_6 a_{1,6} a_{6,1} + \\ & T^3 h_1 t_{11} a_{1,6} a_{6,1} + T h_6 t_{11} a_{1,6} a_{6,1} - T h_{11} t_{11} a_{1,6} a_{6,1} - T^2 h_{11} t_{11} a_{1,6} a_{6,1} - T h_6 t_1 a_{1,11} a_{6,1} - \\ & T^2 h_6 t_6 a_{1,11} a_{6,1} - T^2 h_1 t_{11} a_{1,11} a_{6,1} + T h_6 t_{11} a_{1,11} a_{6,1} + T^2 h_6 t_{11} a_{1,11} a_{6,1} - T^2 h_{11} t_{11} a_{1,11} a_{6,1} - \\ & T^2 h_1 t_1 a_{6,6} - T h_6 t_1 a_{6,6} + T^2 h_6 t_1 a_{6,6} + T h_{11} t_1 a_{6,6} + T h_6 t_6 a_{6,6} - 2 T^2 h_6 t_6 a_{6,6} + T^3 h_6 t_6 a_{6,6} - \\ & T h_{11} t_6 a_{6,6} + T^2 h_{11} t_6 a_{6,6} + T^3 h_1 t_{11} a_{6,6} - T^2 h_{11} t_{11} a_{6,6} + T h_6 t_1 a_{1,1} a_{6,6} - T^2 h_6 t_1 a_{1,1} a_{6,6} - \\ & T h_{11} t_1 a_{1,1} a_{6,6} + T^2 h_6 t_6 a_{1,1} a_{6,6} - T^3 h_6 t_6 a_{1,1} a_{6,6} - T^2 h_{11} t_6 a_{1,1} a_{6,6} - T^3 h_1 t_{11} a_{1,1} a_{6,6} - \\ & T h_6 t_{11} a_{1,1} a_{6,6} + T h_{11} t_{11} a_{1,1} a_{6,6} + T^2 h_{11} t_{11} a_{1,1} a_{6,6} + h_1 t_1 a_{1,11} a_{6,6} + T h_1 t_6 a_{1,11} a_{6,6} - \\ & T h_1 t_{11} a_{1,11} a_{6,6} - T^2 h_1 t_{11} a_{1,11} a_{6,6} + T h_6 t_{11} a_{1,11} a_{6,6} + h_{11} t_{11} a_{1,11} a_{6,6} + T h_1 t_1 a_{6,11} - \\ & T h_6 t_1 a_{6,11} + T h_6 t_6 a_{6,11} - T^2 h_6 t_6 a_{6,11} - T^2 h_1 t_{11} a_{6,11} + T^2 h_6 t_{11} a_{6,11} + T h_{11} t_{11} a_{6,11} - \\ & T^2 h_{11} t_{11} a_{6,11} + T h_6 t_1 a_{1,1} a_{6,11} + T^2 h_6 t_6 a_{1,1} a_{6,11} + T^2 h_1 t_{11} a_{1,1} a_{6,11} - T h_6 t_{11} a_{1,1} a_{6,11} - \\ & T^2 h_6 t_{11} a_{1,1} a_{6,11} + T^2 h_{11} t_{11} a_{1,1} a_{6,11} - h_1 t_1 a_{1,6} a_{6,11} - T h_1 t_6 a_{1,6} a_{6,11} + T h_1 t_{11} a_{1,6} a_{6,11} + \\ & T^2 h_1 t_{11} a_{1,6} a_{6,11} - T h_6 t_{11} a_{1,6} a_{6,11} - h_{11} t_{11} a_{1,6} a_{6,11} - T h_6 t_1 a_{11,1} + T h_{11} t_1 a_{11,1} + T h_6 t_6 a_{11,1} - \\ & T h_{11} t_6 a_{11,1} - T h_1 t_1 a_{1,6} a_{11,1} + T^2 h_1 t_1 a_{1,6} a_{11,1} - T^2 h_{11} t_1 a_{1,6} a_{11,1} - T^2 h_1 t_6 a_{1,6} a_{11,1} - \\ & T h_6 t_6 a_{1,6} a_{11,1} + T h_{11} t_6 a_{1,6} a_{11,1} + T^2 h_{11} t_6 a_{1,6} a_{11,1} - T h_{11} t_{11} a_{1,6} a_{11,1} + h_1 t_1 a_{1,11} a_{11,1} - \\ & T h_1 t_1 a_{1,11} a_{11,1} + T^2 h_6 t_1 a_{1,11} a_{11,1} + T h_{11} t_1 a_{1,11} a_{11,1} - T^2 h_{11} t_1 a_{1,11} a_{11,1} + T h_1 t_6 a_{1,11} a_{11,1} - \\ & T h_6 t_6 a_{1,11} a_{11,1} - T^2 h_6 t_6 a_{1,11} a_{11,1} + T^2 h_{11} t_6 a_{1,11} a_{11,1} + T h_6 t_{11} a_{1,11} a_{11,1} + h_{11} t_{11} a_{1,11} a_{11,1} - \\ & T h_{11} t_{11} a_{1,11} a_{11,1} + T^2 h_1 t_1 a_{6,6} a_{11,1} + T h_6 t_1 a_{6,6} a_{11,1} - T h_{11} t_1 a_{6,6} a_{11,1} - T^2 h_{11} t_1 a_{6,6} a_{11,1} - \\ & T h_6 t_6 a_{6,6} a_{11,1} + T^2 h_6 t_6 a_{6,6} a_{11,1} + T h_{11} t_6 a_{6,6} a_{11,1} + T^2 h_{11} t_{11} a_{6,6} a_{11,1} - h_1 t_1 a_{1,11} a_{6,6} a_{11,1} - \\ & T^2 h_6 t_1 a_{1,11} a_{6,6} a_{11,1} - T h_{11} t_1 a_{1,11} a_{6,6} a_{11,1} - T h_1 t_6 a_{1,11} a_{6,6} a_{11,1} - T^3 h_6 t_6 a_{1,11} a_{6,6} a_{11,1} - \\ & T^2 h_{11} t_6 a_{1,11} a_{6,6} a_{11,1} - T^3 h_1 t_{11} a_{1,11} a_{6,6} a_{11,1} - T h_6 t_{11} a_{1,11} a_{6,6} a_{11,1} - h_{11} t_{11} a_{1,11} a_{6,6} a_{11,1} - \\ & T h_1 t_1 a_{6,11} a_{11,1} + T h_6 t_1 a_{6,11} a_{11,1} + T^2 h_6 t_1 a_{6,11} a_{11,1} - T^2 h_{11} t_1 a_{6,11} a_{11,1} - T h_6 t_6 a_{6,11} a_{11,1} - \\ & T^2 h_6 t_{11} a_{6,11} a_{11,1} - T h_{11} t_{11} a_{6,11} a_{11,1} + T^2 h_{11} t_{11} a_{6,11} a_{11,1} + h_1 t_1 a_{1,6} a_{6,11} a_{11,1} + \\ & T^2 h_6 t_1 a_{1,6} a_{6,11} a_{11,1} + T h_{11} t_1 a_{1,6} a_{6,11} a_{11,1} + T h_1 t_6 a_{1,6} a_{6,11} a_{11,1} + T^3 h_6 t_6 a_{1,6} a_{6,11} a_{11,1} + \\ & T^2 h_{11} t_6 a_{1,6} a_{6,11} a_{11,1} + T^3 h_1 t_{11} a_{1,6} a_{6,11} a_{11,1} + T h_6 t_{11} a_{1,6} a_{6,11} a_{11,1} + h_{11} t_{11} a_{1,6} a_{6,11} a_{11,1} + \end{aligned}$$

$$\begin{aligned}
 & T^2 h_1 t_1 a_{11,6} - T^2 h_{11} t_1 a_{11,6} - T^2 h_1 t_6 a_{11,6} + T^2 h_{11} t_6 a_{11,6} + T h_1 t_1 a_{1,1} a_{11,6} - T^2 h_1 t_1 a_{1,1} a_{11,6} + \\
 & T^2 h_{11} t_1 a_{1,1} a_{11,6} + T^2 h_1 t_6 a_{1,1} a_{11,6} + T h_6 t_6 a_{1,1} a_{11,6} - T h_{11} t_6 a_{1,1} a_{11,6} - T^2 h_{11} t_6 a_{1,1} a_{11,6} + \\
 & T h_{11} t_{11} a_{1,1} a_{11,6} - T^2 h_1 t_1 a_{1,11} a_{11,6} + T h_1 t_6 a_{1,11} a_{11,6} + T^2 h_1 t_6 a_{1,11} a_{11,6} - T^2 h_6 t_6 a_{1,11} a_{11,6} - \\
 & T h_{11} t_6 a_{1,11} a_{11,6} - T^2 h_1 t_{11} a_{1,11} a_{11,6} - T^2 h_1 t_1 a_{6,1} a_{11,6} - T h_6 t_1 a_{6,1} a_{11,6} + T h_{11} t_1 a_{6,1} a_{11,6} + \\
 & T^2 h_{11} t_1 a_{6,1} a_{11,6} + T h_6 t_6 a_{6,1} a_{11,6} - T^2 h_6 t_6 a_{6,1} a_{11,6} - T h_{11} t_6 a_{6,1} a_{11,6} - T^2 h_{11} t_{11} a_{6,1} a_{11,6} + \\
 & h_1 t_1 a_{1,11} a_{6,1} a_{11,6} + T^2 h_6 t_1 a_{1,11} a_{6,1} a_{11,6} + T h_{11} t_1 a_{1,11} a_{6,1} a_{11,6} + T h_1 t_6 a_{1,11} a_{6,1} a_{11,6} + \\
 & T^3 h_6 t_6 a_{1,11} a_{6,1} a_{11,6} + T^2 h_{11} t_6 a_{1,11} a_{6,1} a_{11,6} + T^3 h_1 t_{11} a_{1,11} a_{6,1} a_{11,6} + T h_6 t_{11} a_{1,11} a_{6,1} a_{11,6} + \\
 & h_{11} t_{11} a_{1,11} a_{6,1} a_{11,6} - T h_1 t_1 a_{6,11} a_{11,6} - T^2 h_1 t_1 a_{6,11} a_{11,6} + T^2 h_6 t_1 a_{6,11} a_{11,6} + \\
 & T h_{11} t_1 a_{6,11} a_{11,6} + T h_1 t_6 a_{6,11} a_{11,6} - T^2 h_6 t_6 a_{6,11} a_{11,6} + T^3 h_6 t_6 a_{6,11} a_{11,6} - T h_{11} t_6 a_{6,11} a_{11,6} + \\
 & T^2 h_{11} t_6 a_{6,11} a_{11,6} + T^3 h_1 t_{11} a_{6,11} a_{11,6} - h_1 t_1 a_{1,1} a_{6,11} a_{11,6} - T^2 h_6 t_1 a_{1,1} a_{6,11} a_{11,6} - \\
 & T h_{11} t_1 a_{1,1} a_{6,11} a_{11,6} - T h_1 t_6 a_{1,1} a_{6,11} a_{11,6} - T^3 h_6 t_6 a_{1,1} a_{6,11} a_{11,6} - T^2 h_{11} t_6 a_{1,1} a_{6,11} a_{11,6} - \\
 & T^3 h_1 t_{11} a_{1,1} a_{6,11} a_{11,6} - T h_6 t_{11} a_{1,1} a_{6,11} a_{11,6} - h_{11} t_{11} a_{1,1} a_{6,11} a_{11,6} - T h_1 t_1 a_{11,11} + \\
 & T^2 h_6 t_1 a_{11,11} + T h_{11} t_1 a_{11,11} - T^2 h_{11} t_1 a_{11,11} + T h_1 t_6 a_{11,11} - T^2 h_6 t_6 a_{11,11} - T h_{11} t_6 a_{11,11} + \\
 & T^2 h_{11} t_6 a_{11,11} - h_1 t_1 a_{1,1} a_{11,11} + T h_1 t_1 a_{1,1} a_{11,11} - T^2 h_6 t_1 a_{1,1} a_{11,11} - T h_{11} t_1 a_{1,1} a_{11,11} + \\
 & T^2 h_{11} t_1 a_{1,1} a_{11,11} - T h_1 t_6 a_{1,1} a_{11,11} + T h_6 t_6 a_{1,1} a_{11,11} + T^2 h_6 t_6 a_{1,1} a_{11,11} - T^2 h_{11} t_6 a_{1,1} a_{11,11} - \\
 & T h_6 t_{11} a_{1,1} a_{11,11} - h_{11} t_{11} a_{1,1} a_{11,11} + T h_{11} t_{11} a_{1,1} a_{11,11} + T^2 h_1 t_1 a_{1,6} a_{11,11} - T h_1 t_6 a_{1,6} a_{11,11} - \\
 & T^2 h_1 t_6 a_{1,6} a_{11,11} + T^2 h_6 t_6 a_{1,6} a_{11,11} + T h_{11} t_6 a_{1,6} a_{11,11} + T^2 h_1 t_{11} a_{1,6} a_{11,11} + T h_1 t_1 a_{6,1} a_{11,11} - \\
 & T h_6 t_1 a_{6,1} a_{11,11} - T^2 h_6 t_1 a_{6,1} a_{11,11} + T^2 h_{11} t_1 a_{6,1} a_{11,11} + T h_6 t_6 a_{6,1} a_{11,11} + T^2 h_6 t_{11} a_{6,1} a_{11,11} + \\
 & T h_{11} t_{11} a_{6,1} a_{11,11} - T^2 h_{11} t_{11} a_{6,1} a_{11,11} - h_1 t_1 a_{1,6} a_{6,1} a_{11,11} - T^2 h_6 t_1 a_{1,6} a_{6,1} a_{11,11} - \\
 & T h_{11} t_1 a_{1,6} a_{6,1} a_{11,11} - T h_1 t_6 a_{1,6} a_{6,1} a_{11,11} - T^3 h_6 t_6 a_{1,6} a_{6,1} a_{11,11} - T^2 h_{11} t_6 a_{1,6} a_{6,1} a_{11,11} - \\
 & T^3 h_1 t_{11} a_{1,6} a_{6,1} a_{11,11} - T h_6 t_{11} a_{1,6} a_{6,1} a_{11,11} - h_{11} t_{11} a_{1,6} a_{6,1} a_{11,11} + T h_1 t_1 a_{6,6} a_{11,11} + \\
 & T^2 h_1 t_1 a_{6,6} a_{11,11} - T^2 h_6 t_1 a_{6,6} a_{11,11} - T h_{11} t_1 a_{6,6} a_{11,11} - T h_1 t_6 a_{6,6} a_{11,11} + T^2 h_6 t_6 a_{6,6} a_{11,11} - \\
 & T^3 h_6 t_6 a_{6,6} a_{11,11} + T h_{11} t_6 a_{6,6} a_{11,11} - T^2 h_{11} t_6 a_{6,6} a_{11,11} - T^3 h_1 t_{11} a_{6,6} a_{11,11} + h_1 t_1 a_{1,1} a_{6,6} a_{11,11} + \\
 & T^2 h_6 t_1 a_{1,1} a_{6,6} a_{11,11} + T h_{11} t_1 a_{1,1} a_{6,6} a_{11,11} + T h_1 t_6 a_{1,1} a_{6,6} a_{11,11} + T^3 h_6 t_6 a_{1,1} a_{6,6} a_{11,11} + \\
 & T^2 h_{11} t_6 a_{1,1} a_{6,6} a_{11,11} + T^3 h_1 t_{11} a_{1,1} a_{6,6} a_{11,11} + T h_6 t_{11} a_{1,1} a_{6,6} a_{11,11} + h_{11} t_{11} a_{1,1} a_{6,6} a_{11,11}) / \\
 & (T a_{1,6} - T^2 a_{1,6} - a_{1,11} + T a_{1,11} + T^3 a_{1,6} a_{6,1} - T^2 a_{1,11} a_{6,1} - T^2 a_{6,6} + T^3 a_{6,6} - T^3 a_{1,1} a_{6,6} + \\
 & a_{1,11} a_{6,6} + T a_{6,11} - T^2 a_{6,11} + T^2 a_{1,1} a_{6,11} - a_{1,6} a_{6,11} - T a_{1,6} a_{11,1} + a_{1,11} a_{11,1} + T^2 a_{6,6} a_{11,1} - \\
 & a_{1,11} a_{6,6} a_{11,1} - T a_{1,11} a_{6,6} a_{11,1} - T^2 a_{1,11} a_{6,6} a_{11,1} - T^3 a_{1,11} a_{6,6} a_{11,1} - T a_{6,11} a_{11,1} + a_{1,6} a_{6,11} a_{11,1} + \\
 & T a_{1,6} a_{6,11} a_{11,1} + T^2 a_{1,6} a_{6,11} a_{11,1} + T^3 a_{1,6} a_{6,11} a_{11,1} + T a_{1,1} a_{11,6} - T^2 a_{1,11} a_{11,6} - T^2 a_{6,1} a_{11,6} + \\
 & a_{1,11} a_{6,1} a_{11,6} + T a_{1,11} a_{6,1} a_{11,6} + T^2 a_{1,11} a_{6,1} a_{11,6} + T^3 a_{1,11} a_{6,1} a_{11,6} + T^3 a_{6,11} a_{11,6} - \\
 & a_{1,1} a_{6,11} a_{11,6} - T a_{1,1} a_{6,11} a_{11,6} - T^2 a_{1,1} a_{6,11} a_{11,6} - T^3 a_{1,1} a_{6,11} a_{11,6} - a_{1,1} a_{11,11} + T^2 a_{1,6} a_{11,11} + \\
 & T a_{6,1} a_{11,11} - a_{1,6} a_{6,1} a_{11,11} - T a_{1,6} a_{6,1} a_{11,11} - T^2 a_{1,6} a_{6,1} a_{11,11} - T^3 a_{1,6} a_{6,1} a_{11,11} - \\
 & T^3 a_{6,6} a_{11,11} + a_{1,1} a_{6,6} a_{11,11} + T a_{1,1} a_{6,6} a_{11,11} + T^2 a_{1,1} a_{6,6} a_{11,11} + T^3 a_{1,1} a_{6,6} a_{11,11})
 \end{aligned}$$