

Pensieve header: The Lashings Matrix.

```
In[1]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Projects\\APAI"];
```

```
In[2]:= Once[<< KnotTheory` ; << Rot.m];
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.

Read more at <http://katlas.org/wiki/KnotTheory>.

Loading Rot.m from <http://drorbn.net/APAI> to compute rotation numbers.

```
In[3]:= R1[s_, i_, j_] := s (g_{ji} (g_{j^+,j} + g_{j,j^+} - g_{ii}) - g_{ii} (g_{j,j^+} - 1) - 1/2);
ρ[K_] := ρ[K] = Module[{Cs, φ, n, A, s, i, j, k, Δ, G, ρ1},
  {Cs, φ} = Rot[K];
  n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  Cases[Cs, {s_, i_, j_} :> (A[[{i, j}], {i + 1, j + 1}] += {{-T^s T^s - 1}, {0, -1}})];
  Δ = T^{(-Total[φ]-Total[Cs[[All,1]])/2} Det[A];
  G = Inverse[A];
  ρ1 = Sum[R1 @@ Cs[[k]] - Sum[φ[[k]] (g_{kk} - 1/2),
    Factor@{Δ, Δ^2 ρ1 /. α_^+ :> α + 1 /. g_{α_,β_} :> G[[α, β]]}];
```

```
In[4]:= CompareMatrices[A_, B_] := Grid[
  MapThread[Column@*List, {A, B} /. 0 → "", 2],
  Frame → All, ItemSize → All
]
```

```
In[8]:= GMat[K_] := Module[{Cs, φ, n, A, k, s, i, j},
  {Cs, φ} = Rot[K];
  n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  For[k = 1, k ≤ n, k++, {s, i, j} = Cs[[k]];
    A[[{i, j}, {i + 1, j + 1}]] += {{-T^s T^s - 1, 0}, {0, -1}};
  ];
  Factor@Inverse[A];
];
```

```
MatrixForm[GMat[Knot[4, 1]]]
```

Out[8]//MatrixForm=

$$\begin{pmatrix} 1 & T & T^2 & T & 1 & T & T^2 & T & 1 \\ 0 & 1 & -\frac{T^2}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & -\frac{T(-1+2T)}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & 1 \\ 0 & 0 & -\frac{T^2}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & -\frac{T(-1+2T)}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & 1 \\ 0 & 0 & -\frac{(-1+T)T^2}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & -\frac{T(-1+2T)}{1-3T+T^2} & -\frac{T^3}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & 1 \\ 0 & 0 & -\frac{(-1+T)T^2}{1-3T+T^2} & -\frac{(-1+T)T}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & -\frac{T(-1+2T)}{1-3T+T^2} & -\frac{T^3}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & 1 \\ 0 & 0 & -\frac{(-1+T)T}{1-3T+T^2} & -\frac{-1+T}{1-3T+T^2} & -\frac{-1+T}{1-3T+T^2} & -\frac{-1+2T}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & 1 \\ 0 & 0 & -\frac{(-1+T)T}{1-3T+T^2} & -\frac{-1+T}{1-3T+T^2} & -\frac{-1+T}{1-3T+T^2} & -\frac{(-1+T)T}{1-3T+T^2} & -\frac{T^2}{1-3T+T^2} & -\frac{T}{1-3T+T^2} & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

```

LashMat[K_] := Module[{Cs, ϕ, n, A, α, β, k, s, i, j, Δ, G, g, k1, k2, s1, s2, i1, i2, j1, j2},
  {Cs, ϕ} = Rot[K]; n = Length[Cs];
  A = IdentityMatrix[2 n + 1];
  For[k = 1, k ≤ n, k++, {s, i, j} = Cs[[k]];
    A[[{i, j}, {i + 1, j + 1}]] += {{-T^s T^s - 1}, {0, -1}}];
  Δ = T^{(-Total[ϕ] - Total[Cs[[All, 1]]])/2} Det[A];
  G = Inverse[A];
  Factor[Table[
    {s1, i1, j1} = Cs[[k1]]; {s2, i2, j2} = Cs[[k2]];
    (g_{i1,j2} - T^{s1} g_{i1+1,j2} - T^{s2} (g_{i1,j2+1} - g_{i1+1,j2+1})) /. g_{α_,β_} :> G[[α, β]],
    {k1, n}, {k2, n}]]]
];

```

```

Column[MatrixForm /@ {LM = LashMat[Knot[8, 17]], Factor[LM /. T → T-1] / LMT}]

```

Out[=]

$$\begin{array}{cccccc}
 & \frac{(-1+T) T^2 (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^3 (1-T+2 T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T^3}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 (1-T+T^2)^2}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{T (-1+2 T-T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T) T^3}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T (-1+3 T-2 T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 (1-3 T+4 T^2-2 T^3+T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^2 T}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 (-1+2 T-3 T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T) (1-3 T+3 T^2-3 T^3+T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{T (1-4 T+4 T^2-3 T^3+T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^2 (1-T+T^2)^2}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 (1-2 T+4 T^2-3 T^3+T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^3 T (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T) T (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^2 (1-3 T+4 T^2-2 T^3+T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 (-1+2 T-T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^3 T (2-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^2 T^2}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T (-1+2 T-3 T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T (-1+T-2 T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^3 (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^2 (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T (-1+T-2 T^2+T^3)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^4 T}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{(-1+T)^3 T (1-T+T^2)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{T (1-3 T+5 T^2-6 T^3+2 T^4)}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^4 T^2}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1+T)^2 T^2}{1-4 T+8 T^2-11 T^3+8 T^4-4 T^5+T^6} & \frac{(-1)}{1-4} \\
 & \frac{1}{T} & \frac{(-1+T)^3 (2-T+T^2)}{-1+2 T-T^2+T^3} & -1 & -1 & -1 \\
 & \frac{T^2 (-1+T-2 T^2+T^3)}{(-1+T)^3 (1-T+2 T^2)} & \frac{1}{T} & -1 & -1 & -1 \\
 & -1 & -1 & -T & \frac{1-3 T+4 T^2-4 T^3+T^4}{(-1+T)^3 (1-T+T^2)} & -T \\
 & -1 & -1 & -T & -T & \frac{-1+2 T-T^2+T^3}{(-1+T)^3 (2-T+T^2)} \\
 & -1 & -1 & -T & \frac{(-1+T)^3 (1-T+2 T^2)}{T^2 (-1+T-2 T^2+T^3)} & -T \\
 & -1 & -1 & \frac{(-2+T) T^2 (-1+2 T-T^2+T^3)}{(-1+T)^2 (1-4 T+4 T^2-3 T^3+T^4)} & -T & \frac{(-1+T)^2 (-1+2 T-T^2+T^3)}{T (2-6 T+5 T^2-3 T^3+T^4)} \\
 & -\frac{1}{T} & -\frac{1}{T} & -1 & -1 & -1 \\
 & -\frac{1}{T} & -\frac{T (2-6 T+5 T^2-3 T^3+T^4)}{(-1+T)^2 (-1+2 T-T^2+T^3)} & -1 & -1 & -1
\end{array}$$