

```
In[ ]:= PP_ = Identity; $k = 0;  $\gamma = \gamma; \hbar;$ 
```

```
In[ ]:= Once[<< KnotTheory`];
```

Loading KnotTheory` version of February 2, 2020, 10:53:45.2097.
Read more at <http://katlas.org/wiki/KnotTheory>.

The “Speedy” Engine

Internal Utilities

Canonical Form:

```
In[ ]:= CCF[ $\mathcal{E}$ _] := ExpandDenominator@ExpandNumerator@Together[
    Expand[ $\mathcal{E}$ ] /. ex-ey- => ex+y /. ex- => eCCF[x]];
CF[ $\mathcal{E}$ _List] := CF/@ $\mathcal{E}$ ;
CF[ $\mathcal{S}$ _SeriesData] := MapAt[CF,  $\mathcal{S}$ , 3];
CF[ $\mathcal{E}$ _] := Module[
    {vs = Cases[ $\mathcal{E}$ , (y | b | t | a | x |  $\eta$  |  $\beta$  |  $\tau$  |  $\alpha$  |  $\xi$ )_,  $\infty$ ] U {y, b, t, a, x,  $\eta$ ,  $\beta$ ,  $\tau$ ,  $\alpha$ ,  $\xi$ }},
    Total[CoefficientRules[Expand[ $\mathcal{E}$ ], vs] /. (ps_ -> c_) => CCF[c] (Times@@vsps)
];
CF[ $\mathcal{E}$ _E] := CF/@ $\mathcal{E}$ ; CF[Esp[_][ $\mathcal{E}$ S_____]] := CF/@Esp[ $\mathcal{E}$ S];
```

The Kronecker δ :

```
In[ ]:= K $\delta$  /: K $\delta$ i_,j_ := If[i === j, 1, 0];
```

Equality, multiplication, and degree-adjustment of perturbed Gaussians; $\mathbb{E}[L, Q, P]$ stands for $e^{L+Q} P$:

```
In[ ]:= E /: E[L1_, Q1_, P1_] == E[L2_, Q2_, P2_] :=
    CF[L1 == L2] ^ CF[Q1 == Q2] ^ CF[Normal[P1 - P2] == 0];
E /: E[L1_, Q1_, P1_] E[L2_, Q2_, P2_] := E[L1 + L2, Q1 + Q2, P1 * P2];
E[L_, Q_, P_]$k_ := E[L, Q, Series[Normal@P, { $\epsilon$ , 0, $k}]];
```

Zip and Bind

Variables and their duals:

```
In[ ]:= {t*, b*, y*, a*, x*, z*} = { $\tau$ ,  $\beta$ ,  $\eta$ ,  $\alpha$ ,  $\xi$ ,  $\zeta$ };
{ $\tau^*$ ,  $\beta^*$ ,  $\eta^*$ ,  $\alpha^*$ ,  $\xi^*$ ,  $\zeta^*$ } = {t, b, y, a, x, z}; (u-i)* := (u*)i;
```

Upper to lower and lower to Upper:

```
In[ ]:=
U21 = { B_i^{p_-} -> e^{-p h \gamma b_i}, B^{p_-} -> e^{-p h \gamma b}, T_i^{p_-} -> e^{-p h t_i}, T^{p_-} -> e^{-p h t}, \mathcal{A}_i^{p_-} -> e^{p \gamma \alpha_i}, \mathcal{A}^{p_-} -> e^{p \gamma \alpha} };
12U = { e^{c_- \cdot b_i + d_-} -> B_i^{-c/(h \gamma)} e^d, e^{c_- \cdot b + d_-} -> B^{-c/(h \gamma)} e^d,
  e^{c_- \cdot t_i + d_-} -> T_i^{-c/h} e^d, e^{c_- \cdot t + d_-} -> T^{-c/h} e^d,
  e^{c_- \cdot \alpha_i + d_-} -> \mathcal{A}_i^{c/\gamma} e^d, e^{c_- \cdot \alpha + d_-} -> \mathcal{A}^{c/\gamma} e^d,
  e^{\mathcal{E}_-} -> e^{Expand@E} };
```

Derivatives in the presence of exponentiated variables:

```
In[ ]:=
D_b[f_] := \partial_b f - \hbar \gamma B \partial_B f; D_{b_i}[f_] := \partial_{b_i} f - \hbar \gamma B_i \partial_{B_i} f;
D_t[f_] := \partial_t f - \hbar T \partial_T f; D_{t_i}[f_] := \partial_{t_i} f - \hbar T_i \partial_{T_i} f;
D_\alpha[f_] := \partial_\alpha f + \gamma \mathcal{A} \partial_{\mathcal{A}} f; D_{\alpha_i}[f_] := \partial_{\alpha_i} f + \gamma \mathcal{A}_i \partial_{\mathcal{A}_i} f;
D_v[f_] := \partial_v f; D_{\{v, \emptyset\}}[f_] := f; D_{\{\}}[f_] := f; D_{\{v, n\_Integer\}}[f_] := D_v[D_{\{v, n-1\}}[f]];
D_{\{L\_List, Ls\_ \_\_\}}[f_] := D_{\{Ls\}}[D_L[f]];
```

Finite Zips:

```
In[ ]:=
collect[sd_SeriesData, \mathcal{L}_-] := MapAt[collect[#, \mathcal{L}_-] &, sd, 3];
collect[\mathcal{E}_-, \mathcal{L}_-] := Collect[\mathcal{E}_-, \mathcal{L}_-];
Zip_{\{\}}[P_-] := P;
Zip_{\mathcal{L}_s}[Ps_List] := Zip_{\mathcal{L}_s} /@ Ps;
Zip_{\{\mathcal{L}_-, \mathcal{L}_s\_ \_\_\}}[P_-] :=
  (collect[P // Zip_{\{\mathcal{L}_s\}}, \mathcal{L}_-] /. f_- \cdot \mathcal{L}^{d_-} -> (D_{\{\mathcal{L}_s, d\}}[f])) /. \mathcal{L}^* -> \emptyset /.
  ((\mathcal{L}^* /. {b -> B, t -> T, \alpha -> \mathcal{A}}) -> 1)
```

QZip implements the “Q-level zips” on $\mathbb{E}(L, Q, P) = e^{L+Q} P(\epsilon)$. Such zips regard the L variables as scalars.

$$\begin{aligned} \left\langle P(z_i, \zeta^j) e^{c + \eta^i z_i + y_j \zeta^j + q_i^j z_i \zeta^j} \right\rangle &= |\tilde{q}| \left\langle P(z_i, \zeta^j) e^{c + \eta^i z_i} \Big|_{z_i \rightarrow \tilde{q}_i^k (z_k + y_k)} \right\rangle \\ &= |\tilde{q}| e^{c + \eta^i \tilde{q}_i^k y_k} \left\langle P(\tilde{q}_i^k (z_k + y_k), \zeta^j + \eta^i \tilde{q}_i^j) \right\rangle. \end{aligned}$$

```
In[ ]:=
QZip_{\mathcal{L}_s\_List}@E[L_-, Q_-, P_-] := Module[{L, z, zs, c, ys, \eta s, qt, zrule, \mathcal{L}rule, out},
  zs = Table[\mathcal{L}^*, {\mathcal{L}_-, \mathcal{L}_s}];
  c = CF[Q /. Alternatives@@(\mathcal{L}_s \cup zs) -> \emptyset];
  ys = CF@Table[\partial_{\mathcal{L}_-} (Q /. Alternatives@@zs -> \emptyset), {\mathcal{L}_-, \mathcal{L}_s}];
  \eta s = CF@Table[\partial_z (Q /. Alternatives@@\mathcal{L}_s -> \emptyset), {z, zs}];
  qt = CF@Inverse@Table[K\delta_{z, \mathcal{L}^*} - \partial_{z, \mathcal{L}_-} Q, {\mathcal{L}_-, \mathcal{L}_s}, {z, zs}];
  zrule = Thread[zs -> CF[qt.(zs + ys)]];
  \mathcal{L}rule = Thread[\mathcal{L}_s -> \mathcal{L}_s + \eta s.qt];
  CF /@ E[L, c + \eta s.qt.y s, Det[qt] Zip_{\mathcal{L}_s}[P /. (zrule \cup \mathcal{L}rule)]];
];
```

LZip implements the “L-level zips” on $\mathbb{E}(L, Q, P) = P e^{L+Q}$. Such zips regard all of $P e^Q$ as a single “P”. Here the z ’s are b and α and the ζ ’s are β and a .

In[*]:=

```

LZip $\zeta_s$ _List@E[L_, Q_, P_] :=
Module[{ $\zeta$ , z, zs, Zs, c, ys,  $\eta$ s, lt, zrule, Zrule,  $\zeta$ rule, Q1, EEQ, EQ},
  zs = Table[ $\zeta^*$ , { $\zeta$ ,  $\zeta$ s}];
  Zs = zs /. {b  $\rightarrow$  B, t  $\rightarrow$  T,  $\alpha \rightarrow$  A};
  c = L /. Alternatives @@ ( $\zeta$ s  $\cup$  zs)  $\rightarrow$  0 /. Alternatives @@ Zs  $\rightarrow$  1;
  ys = Table[ $\partial_\zeta$  (L /. Alternatives @@ zs  $\rightarrow$  0), { $\zeta$ ,  $\zeta$ s}];
   $\eta$ s = Table[ $\partial_z$  (L /. Alternatives @@  $\zeta$ s  $\rightarrow$  0), {z, zs}];
  lt = Inverse@Table[K $\delta_{z, \zeta^*} - \partial_{z, \zeta} L$ , { $\zeta$ ,  $\zeta$ s}, {z, zs}];
  zrule = Thread[zs  $\rightarrow$  lt.(zs + ys)];
  Zrule = Join[zrule,
    zrule /. r_Rule  $\Rightarrow$  ((U = r[[1]] /. {b  $\rightarrow$  B, t  $\rightarrow$  T,  $\alpha \rightarrow$  A})  $\rightarrow$  (U /. U21 /. r // . l2U))];
   $\zeta$ rule = Thread[ $\zeta$ s  $\rightarrow$   $\zeta$ s +  $\eta$ s.lt];
  Q1 = Q /. (Zrule  $\cup$   $\zeta$ rule);
  EEQ[ps___] := EEQ[ps] =
    (CF[e-Q1 DThread[{zs, {ps}}][eQ1]] /. {Alternatives @@ zs  $\rightarrow$  0, Alternatives @@ Zs  $\rightarrow$  1});
  CF@E[c +  $\eta$ s.lt.y, Q1 /. {Alternatives @@ zs  $\rightarrow$  0, Alternatives @@ Zs  $\rightarrow$  1},
    Det[lt] (Zip $\zeta$ s [(EQ @@ zs) (P /. (Zrule  $\cup$   $\zeta$ rule))] /.
      Derivative[ps___][EQ][___]  $\Rightarrow$  EEQ[ps] /. _EQ  $\rightarrow$  1) ] ];

```

In[*]:=

```

B_{ } [L_, R_] := L R;
B_{is_} [L_IE, R_IE] := Module[{n},
  Times[
    L /. Table[{v : b | B | t | T | a | x | y}_i  $\rightarrow$  vn@i, {i, {is}}],
    R /. Table[{v :  $\beta$  |  $\tau$  |  $\alpha$  | A |  $\xi$  |  $\eta$ }_i  $\rightarrow$  vn@i, {i, {is}}]
  ] // LZipJoin@Table[{ $\beta$ n@i,  $\tau$ n@i, an@i}, {i, {is}}] // QZipJoin@Table[{ $\xi$ n@i, yn@i}, {i, {is}}] ];
B_{is_} [L_, R_] := B_{is} [L, R];

```

E morphisms with domain and range.

```

In[*]:=
Bis_List[E_{d1 \to r1}[L1_, Q1_, P1_], E_{d2 \to r2}[L2_, Q2_, P2_]] :=
  E_{(d1 \cup Complement[d2, is]) \to (r2 \cup Complement[r1, is])} @@ Bis[E[L1, Q1, P1], E[L2, Q2, P2]];
E_{d1 \to r1}[L1_, Q1_, P1_] // E_{d2 \to r2}[L2_, Q2_, P2_] :=
  B_{r1 \cap d2}[E_{d1 \to r1}[L1, Q1, P1], E_{d2 \to r2}[L2, Q2, P2]];
E_{d1 \to r1}[L1_, Q1_, P1_] \equiv E_{d2 \to r2}[L2_, Q2_, P2_] ^:=
  (d1 == d2) \wedge (r1 == r2) \wedge (E[L1, Q1, P1] \equiv E[L2, Q2, P2]);
E_{d1 \to r1}[L1_, Q1_, P1_] E_{d2 \to r2}[L2_, Q2_, P2_] ^:=
  E_{(d1 \cup d2) \to (r1 \cup r2)} @@ (E[L1, Q1, P1] E[L2, Q2, P2]);
E_{dr}[L_, Q_, P_]_{\$k} := E_{dr} @@ E[L, Q, P]_{\$k};
E_{[E_...]}[i_] := {E}[i];
R_{i,j} := E_{\{\} \to \{i,j\}}[\theta, (y_i - y_j) x_j, 1 + \epsilon (x_i y_i - x_j y_i - x_j y_j) +
  \epsilon^2 (\text{Sum}[r_{\text{If}[\#===i,0,1]\&\&k, \text{If}[\#===i,0,1]\&\&l} y_k x_l, \{k, \{i, j\}\}, \{1, \{i, j\}\}] +
  \text{Sum}[s_{\text{If}[\#===i,0,1]\&\&k, \text{If}[\#===i,0,1]\&\&l, \text{If}[\#===i,0,1]\&\&m, \text{If}[\#===i,0,1]\&\&n} y_k x_l y_m x_n,
  \{k, \{i, j\}\}, \{1, \{i, j\}\}, \{m, \{i, j\}\}, \{n, \{i, j\}\}]) + O[\epsilon^3]] /.
  {r_{1,0} \to 0, r_{1,1} \to 1, r_{0,0} \to -1, r_{0,1} \to 0, s_{0,0,0,0} \to \frac{1}{2}, s_{1,0,1,0} \to 0, s_{1,0,0,0} \to 1,
  s_{0,0,1,0} \to -1, s_{1,1,1,1} \to \frac{1}{2}, s_{1,1,1,0} \to 1, s_{1,0,1,1} \to -1, s_{0,0,1,1} \to 1, s_{0,1,0,1} \to 1, s_{0,1,1,0} \to -1,
  s_{1,0,0,1} \to 1, s_{1,1,0,0} \to -1, s_{0,0,0,1} \to -1, s_{0,1,0,0} \to -1, s_{0,1,1,1} \to 1, s_{1,1,0,1} \to \frac{-1}{2}}
  
```

“Define” Code

Define[lhs = rhs, ...] defines the lhs to be rhs, except that rhs is computed only once for each value of \$k. Fancy Mathematica not for the faint of heart. Most readers should ignore.

```

In[*]:=
SetAttributes[Define, HoldAll];
Define[def_, defs_] := (Define[def]; Define[defs]);
Define[op_{is_} = \epsilon_] := Module[{SD, ii, jj, kk, isp, nis, nisp, sis}, Block[{i, j, k},
  ReleaseHold[Hold[
    SD[op_{nisp, \$k_Integer}, Block[{i, j, k}, op_{isp, \$k} = \epsilon; op_{nis, \$k}]];
    SD[op_{isp}, op_{\{is\}, \$k}]; SD[op_{sis_}, op_{\{sis\}}];
  ] /. {SD \to SetDelayed,
  isp \to \{is\} /. {i \to i_, j \to j_, k \to k_},
  nis \to \{is\} /. {i \to ii, j \to jj, k \to kk},
  nisp \to \{is\} /. {i \to ii_, j \to jj_, k \to kk_}
  } ] ]
  
```

```

In[*]:=
Define[m_{i,j \to k} = E_{\{i,j\} \to \{k\}}[\theta, -\xi_i \eta_j + (\eta_i + \eta_j) y_k + (\xi_i + \xi_j) x_k, 1]]
  (*Heisenberg multiplication*)
  
```

```
In[*]:= AllMonomials[{}, 0] = {1};
AllMonomials[{}, d_Integer] /; d > 0 := {};
AllMonomials[{v_, vs___}, d_Integer] :=
  Join@@Table[vd-k AllMonomials[{vs}, k], {k, 0, d}];
AllMonomials[vs_List, {d_}] := Join@@Table[AllMonomials[vs, k], {k, 0, d}];
```

```
In[*]:= Basis[js_List, m_] := Flatten@Outer[Times,
  AllMonomials[Table[yj, {j, js}], m], AllMonomials[Table[xj, {j, js}], m]];
Basis[js_List, {m_}] := Flatten@Table[Basis[js, k], {k, 1, m}]
```

```
In[*]:= Basis[{i, j}, {2}]
```

```
Out[*]:= {xi yi, xj yi, xi yj, xj yj, xi2 yi2, xi xj yi2, xj2 yi2, xi2 yi yj, xi xj yi yj, xj2 yi yj, xi2 yj2, xi xj yj2, xj2 yj2}
```

```
In[*]:= GenericCombination[bas_, c_] := bas.Table[cj, {j, Length@bas}]
```

```
In[*]:= GenericCombination[Basis[{i, j}, {2}], c]
```

```
Out[*]:= c1 xi yi + c2 xj yi + c5 xi2 yi2 + c6 xi xj yi2 + c7 xj2 yi2 + c3 xi yj + c4 xj yj +
  c8 xi2 yi yj + c9 xi xj yi yj + c10 xj2 yi yj + c11 xi2 yj2 + c12 xi xj yj2 + c13 xj2 yj2
```

The docile R-matrix and its inverse

```
In[*]:= Once[DRules = {}];
```

```
In[*]:= Ri,j := E{i}→{i,j}[0, (yi - yj) (T - 1) xj,
  1 + ε GenericCombination[Basis[{i, j}, {2}], c] + O[ε]2] /. DRules
R̄i,j := E{i}→{i,j}[0, (yi - yj) (T-1 - 1) xj,
  1 + ε GenericCombination[Basis[{i, j}, {2}], d] + O[ε]2] /. DRules
CCi := E{i}→{i}[0, 0, √T + (α + β xi yi + γ xi2 yi2) ε + O[ε]2] /. DRules
CC̄i := E{i}→{i}[0, 0, (√T)-1 + (αi + βi xi yi + γi xi2 yi2) ε + O[ε]2] /. DRules
Kinki := CC3 R1,2 // m2,3→2 // m2,1→i
Kink̄i := CC3 R̄1,2 // m1,3→1 // m1,2→i
```

Requirements on R and CC to nail them down

```
In[*]:= (R1,2 R4,3 R5,6 // m1,4→1 // m2,5→2 // m3,6→3) ≡ (R2,3 R4,5 R1,6 // m1,4→1 // m2,5→2 // m3,6→3)
(R1,2 R̄3,4 // m1,3→1 // m2,4→2)
CC1 CC̄2 // m1,2→1
Kink1 ≡ (CC̄3 R1,2 // m1,3→1 // m1,2→1)
```

$$\begin{aligned}
 \text{Out[4]=} & \in C_3 X_2 Y_1 - T \in C_3 X_2 Y_1 + T \in C_1 X_3 Y_1 - T^2 \in C_1 X_3 Y_1 + \in C_2 X_3 Y_1 - T \in C_2 X_3 Y_1 + \in C_4 X_3 Y_1 - T \in C_4 X_3 Y_1 - \\
 & 2 \in C_5 X_1 X_2 Y_1^2 + 2 T \in C_5 X_1 X_2 Y_1^2 + \in C_8 X_2^2 Y_1^2 - 2 T \in C_8 X_2^2 Y_1^2 + T^2 \in C_8 X_2^2 Y_1^2 + \in C_{11} X_2^2 Y_1^2 - \\
 & 2 T \in C_{11} X_2^2 Y_1^2 + T^2 \in C_{11} X_2^2 Y_1^2 + 2 T \in C_5 X_1 X_3 Y_1^2 - 2 T^2 \in C_5 X_1 X_3 Y_1^2 + 2 \in C_7 X_2 X_3 Y_1^2 - 2 T \in C_7 X_2 X_3 Y_1^2 + \\
 & \in C_9 X_2 X_3 Y_1^2 - 2 T \in C_9 X_2 X_3 Y_1^2 + T^2 \in C_9 X_2 X_3 Y_1^2 + \in C_{12} X_2 X_3 Y_1^2 - 2 T \in C_{12} X_2 X_3 Y_1^2 + T^2 \in C_{12} X_2 X_3 Y_1^2 + \\
 & T^2 \in C_5 X_3^2 Y_1^2 - 2 T^3 \in C_5 X_3^2 Y_1^2 + T^4 \in C_5 X_3^2 Y_1^2 + T \in C_6 X_3^2 Y_1^2 - 2 T^2 \in C_6 X_3^2 Y_1^2 + T^3 \in C_6 X_3^2 Y_1^2 + \\
 & \in C_7 X_3^2 Y_1^2 - 4 T \in C_7 X_3^2 Y_1^2 + 3 T^2 \in C_7 X_3^2 Y_1^2 + \in C_{10} X_3^2 Y_1^2 - 2 T \in C_{10} X_3^2 Y_1^2 + T^2 \in C_{10} X_3^2 Y_1^2 + \in C_{13} X_3^2 Y_1^2 - \\
 & 2 T \in C_{13} X_3^2 Y_1^2 + T^2 \in C_{13} X_3^2 Y_1^2 - \in C_3 X_1 Y_2 + T \in C_3 X_1 Y_2 - \in C_3 X_2 Y_2 + 2 T \in C_3 X_2 Y_2 - T^2 \in C_3 X_2 Y_2 + \\
 & T \in C_3 X_3 Y_2 - T^2 \in C_3 X_3 Y_2 - \in C_8 X_1^2 Y_1 Y_2 + T \in C_8 X_1^2 Y_1 Y_2 - 2 \in C_8 X_1 X_2 Y_1 Y_2 + 4 T \in C_8 X_1 X_2 Y_1 Y_2 - \\
 & 2 T^2 \in C_8 X_1 X_2 Y_1 Y_2 + 2 T \in C_5 X_2^2 Y_1 Y_2 - 2 T^2 \in C_5 X_2^2 Y_1 Y_2 - \in C_8 X_2^2 Y_1 Y_2 + 4 T \in C_8 X_2^2 Y_1 Y_2 - \\
 & 4 T^2 \in C_8 X_2^2 Y_1 Y_2 + T^3 \in C_8 X_2^2 Y_1 Y_2 + 2 T \in C_8 X_1 X_3 Y_1 Y_2 - 2 T^2 \in C_8 X_1 X_3 Y_1 Y_2 + 2 T \in C_6 X_2 X_3 Y_1 Y_2 - \\
 & 2 T^2 \in C_6 X_2 X_3 Y_1 Y_2 - \in C_9 X_2 X_3 Y_1 Y_2 + 4 T \in C_9 X_2 X_3 Y_1 Y_2 - 3 T^2 \in C_9 X_2 X_3 Y_1 Y_2 + 2 \in C_{10} X_2 X_3 Y_1 Y_2 - \\
 & 2 T \in C_{10} X_2 X_3 Y_1 Y_2 + 2 T \in C_7 X_3^2 Y_1 Y_2 - 2 T^2 \in C_7 X_3^2 Y_1 Y_2 + T^2 \in C_8 X_3^2 Y_1 Y_2 - 2 T^3 \in C_8 X_3^2 Y_1 Y_2 + \\
 & T^4 \in C_8 X_3^2 Y_1 Y_2 + T \in C_9 X_3^2 Y_1 Y_2 - 2 T^2 \in C_9 X_3^2 Y_1 Y_2 + T^3 \in C_9 X_3^2 Y_1 Y_2 - \in C_{11} X_1^2 Y_2^2 + 2 T \in C_{11} X_1^2 Y_2^2 - \\
 & T^2 \in C_{11} X_1^2 Y_2^2 - 2 \in C_{11} X_1 X_2 Y_2^2 + 6 T \in C_{11} X_1 X_2 Y_2^2 - 6 T^2 \in C_{11} X_1 X_2 Y_2^2 + 2 T^3 \in C_{11} X_1 X_2 Y_2^2 - \\
 & \in C_{11} X_2^2 Y_2^2 + 4 T \in C_{11} X_2^2 Y_2^2 - 6 T^2 \in C_{11} X_2^2 Y_2^2 + 4 T^3 \in C_{11} X_2^2 Y_2^2 - T^4 \in C_{11} X_2^2 Y_2^2 + 2 T \in C_{11} X_1 X_3 Y_2^2 - \\
 & 2 T^2 \in C_{11} X_1 X_3 Y_2^2 + T \in C_{12} X_1 X_3 Y_2^2 - T^2 \in C_{12} X_1 X_3 Y_2^2 - \in C_{12} X_2 X_3 Y_2^2 + 4 T \in C_{12} X_2 X_3 Y_2^2 - \\
 & 4 T^2 \in C_{12} X_2 X_3 Y_2^2 + T^3 \in C_{12} X_2 X_3 Y_2^2 + 2 \in C_{13} X_2 X_3 Y_2^2 - 2 T \in C_{13} X_2 X_3 Y_2^2 + T^2 \in C_{11} X_3^2 Y_2^2 - \\
 & 2 T^3 \in C_{11} X_3^2 Y_2^2 + T^4 \in C_{11} X_3^2 Y_2^2 + T \in C_{12} X_3^2 Y_2^2 - 2 T^2 \in C_{12} X_3^2 Y_2^2 + T^3 \in C_{12} X_3^2 Y_2^2 + \in C_3 X_1 Y_3 - \\
 & T \in C_3 X_1 Y_3 - T \in C_3 X_2 Y_3 + T^2 \in C_3 X_2 Y_3 + \in C_8 X_1^2 Y_1 Y_3 - T \in C_8 X_1^2 Y_1 Y_3 - 2 T \in C_8 X_1 X_2 Y_1 Y_3 + \\
 & 2 T^2 \in C_8 X_1 X_2 Y_1 Y_3 + T^2 \in C_8 X_2^2 Y_1 Y_3 - T^3 \in C_8 X_2^2 Y_1 Y_3 + 2 T \in C_{11} X_2^2 Y_1 Y_3 - 2 T^2 \in C_{11} X_2^2 Y_1 Y_3 + \\
 & 2 T \in C_{12} X_2 X_3 Y_1 Y_3 - 2 T^2 \in C_{12} X_2 X_3 Y_1 Y_3 + 2 T \in C_{13} X_3^2 Y_1 Y_3 - 2 T^2 \in C_{13} X_3^2 Y_1 Y_3 - 2 T \in C_{11} X_1^2 Y_2 Y_3 + \\
 & 2 T^2 \in C_{11} X_1^2 Y_2 Y_3 - 4 T \in C_{11} X_1 X_2 Y_2 Y_3 + 8 T^2 \in C_{11} X_1 X_2 Y_2 Y_3 - 4 T^3 \in C_{11} X_1 X_2 Y_2 Y_3 - 2 T \in C_{11} X_2^2 Y_2 Y_3 + \\
 & 6 T^2 \in C_{11} X_2^2 Y_2 Y_3 - 6 T^3 \in C_{11} X_2^2 Y_2 Y_3 + 2 T^4 \in C_{11} X_2^2 Y_2 Y_3 - 2 T \in C_{12} X_1 X_3 Y_2 Y_3 + 2 T^2 \in C_{12} X_1 X_3 Y_2 Y_3 - \\
 & 2 T \in C_{12} X_2 X_3 Y_2 Y_3 + 4 T^2 \in C_{12} X_2 X_3 Y_2 Y_3 - 2 T^3 \in C_{12} X_2 X_3 Y_2 Y_3 - 2 T \in C_{13} X_3^2 Y_2 Y_3 + 2 T^2 \in C_{13} X_3^2 Y_2 Y_3 + \\
 & \in C_{11} X_1^2 Y_3^2 - T^2 \in C_{11} X_1^2 Y_3^2 - 2 T^2 \in C_{11} X_1 X_2 Y_3^2 + 2 T^3 \in C_{11} X_1 X_2 Y_3^2 - T^2 \in C_{11} X_2^2 Y_3^2 + 2 T^3 \in C_{11} X_2^2 Y_3^2 - \\
 & T^4 \in C_{11} X_2^2 Y_3^2 + T \in C_{12} X_1 X_3 Y_3^2 - T^2 \in C_{12} X_1 X_3 Y_3^2 - T^2 \in C_{12} X_2 X_3 Y_3^2 + T^3 \in C_{12} X_2 X_3 Y_3^2 = \emptyset
 \end{aligned}$$

$$\begin{aligned}
\text{Out[*]} = \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\mathbf{0}, \mathbf{0}, \mathbf{1} + \left((c_1 + d_1 + d_3 - T d_3) x_1 y_1 + \right. \right. \\
\frac{(-c_1 + T c_1 + c_2 + T d_2 + T d_4 - T^2 d_4) x_2 y_1}{T} + (c_5 + d_5 + d_8 - T d_8 + d_{11} - 2 T d_{11} + T^2 d_{11}) x_1^2 y_1^2 + \\
\frac{(-2 c_5 + 2 T c_5 + c_6 + T d_6 + T d_9 - T^2 d_9 + T d_{12} - 2 T^2 d_{12} + T^3 d_{12}) x_1 x_2 y_1^2}{T} + \\
\frac{(c_5 - 2 T c_5 + T^2 c_5 - c_6 + T c_6 + c_7 + T^2 d_7 + T^2 d_{10} - T^3 d_{10} + T^2 d_{13} - 2 T^3 d_{13} + T^4 d_{13}) x_2^2 y_1^2}{T^2} + \\
(c_3 + T d_3) x_1 y_2 + \frac{(-c_3 + T c_3 + c_4 + T^2 d_4) x_2 y_2}{T} + (c_8 + T d_8 + 2 T d_{11} - 2 T^2 d_{11}) x_1^2 y_1 y_2 + \\
\frac{(-2 c_8 + 2 T c_8 + c_9 + T^2 d_9 + 2 T^2 d_{12} - 2 T^3 d_{12}) x_1 x_2 y_1 y_2}{T} + \\
\frac{(c_8 - 2 T c_8 + T^2 c_8 - c_9 + T c_9 + c_{10} + T^3 d_{10} + 2 T^3 d_{13} - 2 T^4 d_{13}) x_2^2 y_1 y_2}{T^2} + \\
(c_{11} + T^2 d_{11}) x_1^2 y_2^2 + \frac{(-2 c_{11} + 2 T c_{11} + c_{12} + T^3 d_{12}) x_1 x_2 y_2^2}{T} + \\
\left. \frac{(c_{11} - 2 T c_{11} + T^2 c_{11} - c_{12} + T c_{12} + c_{13} + T^4 d_{13}) x_2^2 y_2^2}{T^2} \right) \epsilon + \mathbf{0}[\epsilon]^2]
\end{aligned}$$

$$\text{Out[*]} = \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\mathbf{0}, \mathbf{0}, \mathbf{1} + \left(\frac{\alpha}{\sqrt{T}} + \sqrt{T} \alpha i + \frac{\beta x_1 y_1}{\sqrt{T}} + \sqrt{T} \beta i x_1 y_1 + \frac{(\gamma + T \gamma i) x_1^2 y_1^2}{\sqrt{T}} \right) \epsilon + \mathbf{0}[\epsilon]^2 \right]$$

$$\begin{aligned}
\text{Out[*]} = \frac{1}{T^3} \left(T^2 \alpha \epsilon - T^3 \alpha i \epsilon - T \beta \epsilon + T^2 \beta \epsilon + 2 \gamma \epsilon - 4 T \gamma \epsilon + 2 T^2 \gamma \epsilon - T^{3/2} \epsilon c_2 + T^{5/2} \epsilon c_3 + 2 \sqrt{T} \epsilon c_7 - \right. \\
2 T^{5/2} \epsilon c_{11} + T \beta \epsilon x_1 y_1 - T^4 \beta i \epsilon x_1 y_1 - 4 \gamma \epsilon x_1 y_1 + 4 T \gamma \epsilon x_1 y_1 + T^{5/2} \epsilon c_1 x_1 y_1 - T^{7/2} \epsilon c_1 x_1 y_1 + \\
T^{3/2} \epsilon c_2 x_1 y_1 - T^{5/2} \epsilon c_2 x_1 y_1 + T^{5/2} \epsilon c_3 x_1 y_1 - T^{7/2} \epsilon c_3 x_1 y_1 + T^{3/2} \epsilon c_4 x_1 y_1 - T^{5/2} \epsilon c_4 x_1 y_1 - \\
2 T^{3/2} \epsilon c_6 x_1 y_1 - 4 \sqrt{T} \epsilon c_7 x_1 y_1 + 2 T^{7/2} \epsilon c_8 x_1 y_1 - T^{3/2} \epsilon c_9 x_1 y_1 + T^{5/2} \epsilon c_9 x_1 y_1 - \\
2 \sqrt{T} \epsilon c_{10} x_1 y_1 + 4 T^{7/2} \epsilon c_{11} x_1 y_1 + 2 T^{5/2} \epsilon c_{12} x_1 y_1 + \gamma \epsilon x_1^2 y_1^2 - T^5 \gamma i \epsilon x_1^2 y_1^2 + T^{5/2} \epsilon c_5 x_1^2 y_1^2 - \\
T^{9/2} \epsilon c_5 x_1^2 y_1^2 + T^{3/2} \epsilon c_6 x_1^2 y_1^2 - T^{7/2} \epsilon c_6 x_1^2 y_1^2 + \sqrt{T} \epsilon c_7 x_1^2 y_1^2 - T^{5/2} \epsilon c_7 x_1^2 y_1^2 + T^{5/2} \epsilon c_8 x_1^2 y_1^2 - \\
T^{9/2} \epsilon c_8 x_1^2 y_1^2 + T^{3/2} \epsilon c_9 x_1^2 y_1^2 - T^{7/2} \epsilon c_9 x_1^2 y_1^2 + \sqrt{T} \epsilon c_{10} x_1^2 y_1^2 - T^{5/2} \epsilon c_{10} x_1^2 y_1^2 + T^{5/2} \epsilon c_{11} x_1^2 y_1^2 - \\
T^{9/2} \epsilon c_{11} x_1^2 y_1^2 + T^{3/2} \epsilon c_{12} x_1^2 y_1^2 - T^{7/2} \epsilon c_{12} x_1^2 y_1^2 + \sqrt{T} \epsilon c_{13} x_1^2 y_1^2 - T^{5/2} \epsilon c_{13} x_1^2 y_1^2 \Big) = \mathbf{0}
\end{aligned}$$

```

In[ ]:= eqns = Join[
  Thread[CoefficientRules[Coefficient[
    (R1,2 R4,3 R5,6 // m1,4→1 // m2,5→2 // m3,6→3) [[3]] - (R2,3 R4,5 R1,6 // m1,4→1 // m2,5→2 // m3,6→3) [[
    3]] // Normal, ε], {x1, x2, x3, y1, y2, y3}] [[ ; ; , 2]] == 0],
  Thread[CoefficientRules[Coefficient[(R1,2 R̄3,4 // m1,3→1 // m2,4→2) [[3]] // Normal, ε],
    {x1, x2, y1, y2}] [[ ; ; , 2]] == 0],
  Thread[CoefficientRules[Coefficient[(CC1 C̄C2 // m1,2→1) [[3]] // Normal, ε], {x1, y1}] [[
    ; ; , 2]] == 0],
  Thread[CoefficientRules[Coefficient[(Kink1) [[3]] - (C̄C3 R1,2 // m1,3→1 // m1,2→1) [[3]] // Normal,
    ε], {x1, y1}] [[ ; ; , 2]] == 0]
]

```


$$\begin{aligned}
\text{Out[*]} = & \left\{ -c_8 + T c_8 = 0, c_8 - T c_8 = 0, -c_{11} + 2 T c_{11} - T^2 c_{11} = 0, -2 T c_{11} + 2 T^2 c_{11} = 0, \right. \\
& c_{11} - T^2 c_{11} = 0, -2 c_5 + 2 T c_5 = 0, -2 c_8 + 4 T c_8 - 2 T^2 c_8 = 0, -2 T c_8 + 2 T^2 c_8 = 0, \\
& -2 c_{11} + 6 T c_{11} - 6 T^2 c_{11} + 2 T^3 c_{11} = 0, -4 T c_{11} + 8 T^2 c_{11} - 4 T^3 c_{11} = 0, -2 T^2 c_{11} + 2 T^3 c_{11} = 0, \\
& 2 T c_5 - 2 T^2 c_5 = 0, 2 T c_8 - 2 T^2 c_8 = 0, 2 T c_{11} - 2 T^2 c_{11} + T c_{12} - T^2 c_{12} = 0, -2 T c_{12} + 2 T^2 c_{12} = 0, \\
& T c_{12} - T^2 c_{12} = 0, -c_3 + T c_3 = 0, c_3 - T c_3 = 0, c_8 - 2 T c_8 + T^2 c_8 + c_{11} - 2 T c_{11} + T^2 c_{11} = 0, \\
& 2 T c_5 - 2 T^2 c_5 - c_8 + 4 T c_8 - 4 T^2 c_8 + T^3 c_8 = 0, T^2 c_8 - T^3 c_8 + 2 T c_{11} - 2 T^2 c_{11} = 0, \\
& -c_{11} + 4 T c_{11} - 6 T^2 c_{11} + 4 T^3 c_{11} - T^4 c_{11} = 0, -2 T c_{11} + 6 T^2 c_{11} - 6 T^3 c_{11} + 2 T^4 c_{11} = 0, \\
& -T^2 c_{11} + 2 T^3 c_{11} - T^4 c_{11} = 0, 2 c_7 - 2 T c_7 + c_9 - 2 T c_9 + T^2 c_9 + c_{12} - 2 T c_{12} + T^2 c_{12} = 0, \\
& 2 T c_6 - 2 T^2 c_6 - c_9 + 4 T c_9 - 3 T^2 c_9 + 2 c_{10} - 2 T c_{10} = 0, 2 T c_{12} - 2 T^2 c_{12} = 0, \\
& -c_{12} + 4 T c_{12} - 4 T^2 c_{12} + T^3 c_{12} + 2 c_{13} - 2 T c_{13} = 0, -2 T c_{12} + 4 T^2 c_{12} - 2 T^3 c_{12} = 0, \\
& -T^2 c_{12} + T^3 c_{12} = 0, c_3 - T c_3 = 0, -c_3 + 2 T c_3 - T^2 c_3 = 0, -T c_3 + T^2 c_3 = 0, \\
& T^2 c_5 - 2 T^3 c_5 + T^4 c_5 + T c_6 - 2 T^2 c_6 + T^3 c_6 + c_7 - 4 T c_7 + 3 T^2 c_7 + c_{10} - 2 T c_{10} + T^2 c_{10} + c_{13} - \\
& 2 T c_{13} + T^2 c_{13} = 0, 2 T c_7 - 2 T^2 c_7 + T^2 c_8 - 2 T^3 c_8 + T^4 c_8 + T c_9 - 2 T^2 c_9 + T^3 c_9 = 0, \\
& 2 T c_{13} - 2 T^2 c_{13} = 0, T^2 c_{11} - 2 T^3 c_{11} + T^4 c_{11} + T c_{12} - 2 T^2 c_{12} + T^3 c_{12} = 0, \\
& -2 T c_{13} + 2 T^2 c_{13} = 0, T c_1 - T^2 c_1 + c_2 - T c_2 + c_4 - T c_4 = 0, T c_3 - T^2 c_3 = 0, \\
& c_5 + d_5 + d_8 - T d_8 + d_{11} - 2 T d_{11} + T^2 d_{11} = 0, c_8 + T d_8 + 2 T d_{11} - 2 T^2 d_{11} = 0, \\
& c_{11} + T^2 d_{11} = 0, 2 c_5 - \frac{2 c_5}{T} + \frac{c_6}{T} + d_6 + d_9 - T d_9 + d_{12} - 2 T d_{12} + T^2 d_{12} = 0, \\
& 2 c_8 - \frac{2 c_8}{T} + \frac{c_9}{T} + T d_9 + 2 T d_{12} - 2 T^2 d_{12} = 0, 2 c_{11} - \frac{2 c_{11}}{T} + \frac{c_{12}}{T} + T^2 d_{12} = 0, c_1 + d_1 + d_3 - T d_3 = 0, \\
& c_3 + T d_3 = 0, c_5 + \frac{c_5}{T^2} - \frac{2 c_5}{T} - \frac{c_6}{T^2} + \frac{c_6}{T} + \frac{c_7}{T^2} + d_7 + d_{10} - T d_{10} + d_{13} - 2 T d_{13} + T^2 d_{13} = 0, \\
& c_8 + \frac{c_8}{T^2} - \frac{2 c_8}{T} - \frac{c_9}{T^2} + \frac{c_9}{T} + \frac{c_{10}}{T^2} + T d_{10} + 2 T d_{13} - 2 T^2 d_{13} = 0, \\
& c_{11} + \frac{c_{11}}{T^2} - \frac{2 c_{11}}{T} - \frac{c_{12}}{T^2} + \frac{c_{12}}{T} + \frac{c_{13}}{T^2} + T^2 d_{13} = 0, c_1 - \frac{c_1}{T} + \frac{c_2}{T} + d_2 + d_4 - T d_4 = 0, \\
& c_3 - \frac{c_3}{T} + \frac{c_4}{T} + T d_4 = 0, \frac{\gamma}{\sqrt{T}} + \sqrt{T} \gamma i = 0, \frac{\beta}{\sqrt{T}} + \sqrt{T} \beta i = 0, \frac{\alpha}{\sqrt{T}} + \sqrt{T} \alpha i = 0, \\
& \frac{\gamma}{T^3} - T^2 \gamma i + \frac{c_5}{\sqrt{T}} - T^{3/2} c_5 + \frac{c_6}{T^{3/2}} - \sqrt{T} c_6 + \frac{c_7}{T^{5/2}} - \frac{c_7}{\sqrt{T}} + \frac{c_8}{\sqrt{T}} - T^{3/2} c_8 + \frac{c_9}{T^{3/2}} - \sqrt{T} c_9 + \frac{c_{10}}{T^{5/2}} - \frac{c_{10}}{\sqrt{T}} + \\
& \frac{c_{11}}{\sqrt{T}} - T^{3/2} c_{11} + \frac{c_{12}}{T^{3/2}} - \sqrt{T} c_{12} + \frac{c_{13}}{T^{5/2}} - \frac{c_{13}}{\sqrt{T}} = 0, \frac{\beta}{T^2} - T \beta i - \frac{4 \gamma}{T^3} + \frac{4 \gamma}{T^2} + \frac{c_1}{\sqrt{T}} - \sqrt{T} c_1 + \frac{c_2}{T^{3/2}} - \frac{c_2}{\sqrt{T}} + \\
& \frac{c_3}{\sqrt{T}} - \sqrt{T} c_3 + \frac{c_4}{T^{3/2}} - \frac{c_4}{\sqrt{T}} - \frac{2 c_6}{T^{3/2}} - \frac{4 c_7}{T^{5/2}} + 2 \sqrt{T} c_8 - \frac{c_9}{T^{3/2}} + \frac{c_9}{\sqrt{T}} - \frac{2 c_{10}}{T^{5/2}} + 4 \sqrt{T} c_{11} + \frac{2 c_{12}}{\sqrt{T}} = 0, \\
& \left. \frac{\alpha}{T} - \alpha i - \frac{\beta}{T^2} + \frac{\beta}{T} + \frac{2 \gamma}{T^3} - \frac{4 \gamma}{T^2} + \frac{2 \gamma}{T} - \frac{c_2}{T^{3/2}} + \frac{c_3}{\sqrt{T}} + \frac{2 c_7}{T^{5/2}} - \frac{2 c_{11}}{\sqrt{T}} = 0 \right\}
\end{aligned}$$

In[*]:= **Solve**[eqns, { α , β , γ , αi , βi , γi } \cup **Table**[c_j, {j, 13}] \cup **Table**[d_j, {j, 13}]]

Solve: Equations may not give solutions for all "solve" variables.

$$\text{Out[*]} = \left\{ \left\{ \alpha \rightarrow \frac{c_2}{2\sqrt{T}}, \alpha i \rightarrow -\frac{c_2}{2T^{3/2}}, \beta \rightarrow -\frac{c_9}{\sqrt{T}}, \beta i \rightarrow \frac{c_9}{T^{3/2}}, \gamma \rightarrow 0, \gamma i \rightarrow 0, c_3 \rightarrow 0, c_4 \rightarrow -T c_1 - c_2, \right. \right.$$

$$c_5 \rightarrow 0, c_7 \rightarrow -\frac{1}{2}(1-T)c_9, c_8 \rightarrow 0, c_{10} \rightarrow -T c_6 - \frac{1}{2}(-1+3T)c_9, c_{11} \rightarrow 0, c_{12} \rightarrow 0,$$

$$c_{13} \rightarrow 0, d_1 \rightarrow -c_1, d_2 \rightarrow -\frac{c_2}{T^2}, d_3 \rightarrow 0, d_4 \rightarrow \frac{c_1}{T} + \frac{c_2}{T^2}, d_5 \rightarrow 0, d_6 \rightarrow -\frac{c_6}{T} - \frac{(-1+T)c_9}{T^2},$$

$$\left. \left. d_7 \rightarrow -\frac{(1-T)c_9}{2T^3}, d_8 \rightarrow 0, d_9 \rightarrow -\frac{c_9}{T^2}, d_{10} \rightarrow \frac{c_6}{T^2} - \frac{(-1-T)c_9}{2T^3}, d_{11} \rightarrow 0, d_{12} \rightarrow 0, d_{13} \rightarrow 0 \right\} \right\}$$

In[*]:= **{DRules} = Solve**[eqns, { α , β , γ , αi , βi , γi } \cup **Table**[c_j, {j, 13}] \cup **Table**[d_j, {j, 13}]]

Solve: Equations may not give solutions for all "solve" variables.

$$\text{Out[*]} = \left\{ \left\{ \alpha \rightarrow \frac{c_2}{2\sqrt{T}}, \alpha i \rightarrow -\frac{c_2}{2T^{3/2}}, \beta \rightarrow -\frac{c_9}{\sqrt{T}}, \beta i \rightarrow \frac{c_9}{T^{3/2}}, \gamma \rightarrow 0, \gamma i \rightarrow 0, c_3 \rightarrow 0, c_4 \rightarrow -T c_1 - c_2, \right. \right.$$

$$c_5 \rightarrow 0, c_7 \rightarrow -\frac{1}{2}(1-T)c_9, c_8 \rightarrow 0, c_{10} \rightarrow -T c_6 - \frac{1}{2}(-1+3T)c_9, c_{11} \rightarrow 0, c_{12} \rightarrow 0,$$

$$c_{13} \rightarrow 0, d_1 \rightarrow -c_1, d_2 \rightarrow -\frac{c_2}{T^2}, d_3 \rightarrow 0, d_4 \rightarrow \frac{c_1}{T} + \frac{c_2}{T^2}, d_5 \rightarrow 0, d_6 \rightarrow -\frac{c_6}{T} - \frac{(-1+T)c_9}{T^2},$$

$$\left. \left. d_7 \rightarrow -\frac{(1-T)c_9}{2T^3}, d_8 \rightarrow 0, d_9 \rightarrow -\frac{c_9}{T^2}, d_{10} \rightarrow \frac{c_6}{T^2} - \frac{(-1-T)c_9}{2T^3}, d_{11} \rightarrow 0, d_{12} \rightarrow 0, d_{13} \rightarrow 0 \right\} \right\}$$

In[*]:= **{R_{i,j}, $\bar{R}_{i,j}$, CC_i, \bar{CC}_i }**

$$\text{Out[*]} = \left\{ \mathbb{E}_{\{\} \rightarrow \{i,j\}} \left[0, (-1+T) x_j (y_i - y_j), \right. \right.$$

$$1 + \left(c_1 x_i y_i + c_2 x_j y_i + c_6 x_i x_j y_i^2 - \frac{1}{2}(1-T)c_9 x_j^2 y_i^2 + (-T c_1 - c_2) x_j y_j + \right.$$

$$\left. \left. c_9 x_i x_j y_i y_j + \left(-T c_6 - \frac{1}{2}(-1+3T)c_9 \right) x_j^2 y_i y_j \right) \epsilon + \mathcal{O}[\epsilon]^2 \right],$$

$$\mathbb{E}_{\{\} \rightarrow \{i,j\}} \left[0, \left(-1 + \frac{1}{T} \right) x_j (y_i - y_j), 1 + \left(-c_1 x_i y_i - \frac{c_2 x_j y_i}{T^2} + \left(-\frac{c_6}{T} - \frac{(-1+T)c_9}{T^2} \right) x_i x_j y_i^2 - \right. \right.$$

$$\left. \left. \frac{(1-T)c_9 x_j^2 y_i^2}{2T^3} + \left(\frac{c_1}{T} + \frac{c_2}{T^2} \right) x_j y_j - \frac{c_9 x_i x_j y_i y_j}{T^2} + \left(\frac{c_6}{T^2} - \frac{(-1-T)c_9}{2T^3} \right) x_j^2 y_i y_j \right) \epsilon + \mathcal{O}[\epsilon]^2 \right],$$

$$\mathbb{E}_{\{\} \rightarrow \{i\}} \left[0, 0, \sqrt{T} + \left(\frac{c_2}{2\sqrt{T}} - \frac{c_9 x_i y_i}{\sqrt{T}} \right) \epsilon + \mathcal{O}[\epsilon]^2 \right], \mathbb{E}_{\{\} \rightarrow \{i\}} \left[0, 0, \right.$$

$$\left. \frac{1}{\sqrt{T}} + \left(-\frac{c_2}{2T^{3/2}} + \frac{c_9 x_i y_i}{T^{3/2}} \right) \epsilon + \mathcal{O}[\epsilon]^2 \right] \right\}$$

$$\text{In[*]} := \{R_{i,j}, \bar{R}_{i,j}, CC_i, \bar{CC}_i\} /. \{c_{1|2|6} \rightarrow \theta, c_9 \rightarrow 1\}$$

$$\begin{aligned} \text{Out[*]} := & \left\{ E_{\{\} \rightarrow \{i,j\}} \left[\theta, (-1 + T) x_j (y_i - y_j), 1 + \left(-\frac{1}{2} (1 - T) x_j^2 y_i^2 + x_i x_j y_i y_j + \frac{1}{2} (1 - 3T) x_j^2 y_i y_j \right) \epsilon + O[\epsilon]^2 \right], \right. \\ & E_{\{\} \rightarrow \{i,j\}} \left[\theta, \left(-1 + \frac{1}{T} \right) x_j (y_i - y_j), \right. \\ & \left. 1 + \left(-\frac{(-1 + T) x_i x_j y_i^2}{T^2} - \frac{(1 - T) x_j^2 y_i^2}{2 T^3} - \frac{x_i x_j y_i y_j}{T^2} - \frac{(-1 - T) x_j^2 y_i y_j}{2 T^3} \right) \epsilon + O[\epsilon]^2 \right], \\ & \left. E_{\{\} \rightarrow \{i\}} \left[\theta, \theta, \sqrt{T} - \frac{x_i y_i \epsilon}{\sqrt{T}} + O[\epsilon]^2 \right], E_{\{\} \rightarrow \{i\}} \left[\theta, \theta, \frac{1}{\sqrt{T}} + \frac{x_i y_i \epsilon}{T^{3/2}} + O[\epsilon]^2 \right] \right\} \end{aligned}$$

$$\begin{aligned} \text{In[*]} := & (R_{1,2} R_{4,3} R_{5,6} // m_{1,4 \rightarrow 1} // m_{2,5 \rightarrow 2} // m_{3,6 \rightarrow 3}) \equiv (R_{2,3} R_{4,5} R_{1,6} // m_{1,4 \rightarrow 1} // m_{2,5 \rightarrow 2} // m_{3,6 \rightarrow 3}) \\ & (R_{1,2} \bar{R}_{3,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2}) \\ & CC_1 \bar{CC}_2 // m_{1,2 \rightarrow 1} \\ \text{Kink}_1 \equiv & (\bar{CC}_3 R_{1,2} // m_{1,3 \rightarrow 1} // m_{1,2 \rightarrow 1}) \end{aligned}$$

Out[*] = True

$$\text{Out[*]} = E_{\{\} \rightarrow \{1,2\}} [\theta, \theta, 1 + O[\epsilon]^2]$$

$$\text{Out[*]} = E_{\{\} \rightarrow \{1\}} [\theta, \theta, 1 + O[\epsilon]^2]$$

Out[*] = True

OC fails

$$\text{In[*]} := (R_{1,2} R_{4,3} // m_{1,4 \rightarrow 1}) \equiv (R_{1,3} R_{4,2} // m_{1,4 \rightarrow 1}) // \text{Simplify}$$

$$\text{Out[*]} = (-1 + T) \epsilon y_1 (c_1 (x_2 - x_3) + c_9 x_2 x_3 (-y_2 + y_3)) = \theta$$

R2 braid-like

$$\begin{aligned} \text{In[*]} := & R_{1,2} \bar{R}_{3,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2} \\ & \bar{R}_{1,2} R_{3,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2} \end{aligned}$$

$$\text{Out[*]} = E_{\{\} \rightarrow \{1,2\}} [\theta, \theta, 1 + O[\epsilon]^2]$$

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'naked' R2 cyclic (!!):

$$\begin{aligned} \text{In[*]} := & R_{3,2} \bar{R}_{1,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2} \\ & R_{1,4} \bar{R}_{3,2} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2} \end{aligned}$$

$$\text{Out[*]} = E_{\{\} \rightarrow \{1,2\}} \left[\theta, \theta, 1 + \frac{(c_9 - T c_9) x_2 y_1 \epsilon}{T^2} + O[\epsilon]^2 \right]$$

$$\text{Out[*]} = E_{\{\} \rightarrow \{1,2\}} \left[\theta, \theta, 1 + \frac{(c_9 - T c_9) x_2 y_1 \epsilon}{T} + O[\epsilon]^2 \right]$$

Proper R2 cyclic:

$$\begin{aligned} \text{In}[*]:= & \left(\text{CC}_3 \text{R}_{5,2} \overline{\text{R}}_{1,4} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{1,5 \rightarrow 1} // \text{m}_{2,4 \rightarrow 2} \right) \equiv \text{CC}_1 \mathbb{E}_{\{\} \rightarrow \{2\}} \left[\theta, \theta, 1 + \mathcal{O}[\epsilon]^2 \right] \\ & \left(\overline{\text{CC}}_4 \text{R}_{1,6} \overline{\text{R}}_{3,2} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{2,4 \rightarrow 2} // \text{m}_{2,6 \rightarrow 2} \right) \equiv \overline{\text{CC}}_2 \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\theta, \theta, 1 + \mathcal{O}[\epsilon]^2 \right] \end{aligned}$$

Out[*]= True

Out[*]= True

R3:

$$\text{In}[*]:= \left(\text{R}_{1,2} \text{R}_{4,3} \text{R}_{5,6} // \text{m}_{1,4 \rightarrow 1} // \text{m}_{2,5 \rightarrow 2} // \text{m}_{3,6 \rightarrow 3} \right) \equiv \left(\text{R}_{2,3} \text{R}_{4,5} \text{R}_{1,6} // \text{m}_{1,4 \rightarrow 1} // \text{m}_{2,5 \rightarrow 2} // \text{m}_{3,6 \rightarrow 3} \right)$$

Out[*]= True

Pairwise equality of the four kinks:

$$\begin{aligned} \text{In}[*]:= & \text{Kink}_1 \equiv \left(\overline{\text{CC}}_3 \text{R}_{1,2} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{1,2 \rightarrow 1} \right) \\ & \overline{\text{Kink}}_1 \equiv \left(\overline{\text{CC}}_3 \overline{\text{R}}_{1,2} // \text{m}_{2,3 \rightarrow 2} // \text{m}_{2,1 \rightarrow 1} \right) \end{aligned}$$

Out[*]= True

Out[*]= True

Trefoils?:

$$\begin{aligned} \text{In}[*]:= & \overline{\text{Kink}}_8 \overline{\text{Kink}}_9 \overline{\text{Kink}}_{10} \overline{\text{CC}}_7 \text{R}_{1,4} \text{R}_{5,2} \text{R}_{3,6} // \text{m}_{1,2 \rightarrow 1} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{1,7 \rightarrow 1} // \text{m}_{1,4 \rightarrow 1} // \text{m}_{1,5 \rightarrow 1} // \text{m}_{1,6 \rightarrow 1} // \\ & \text{m}_{1,8 \rightarrow 1} // \text{m}_{1,9 \rightarrow 1} // \text{m}_{1,10 \rightarrow 1} \\ & \overline{\text{Kink}}_8 \overline{\text{Kink}}_9 \overline{\text{Kink}}_{10} \text{CC}_7 \text{R}_{4,1} \text{R}_{2,5} \text{R}_{6,3} // \text{m}_{1,2 \rightarrow 1} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{1,7 \rightarrow 1} // \text{m}_{1,4 \rightarrow 1} // \text{m}_{1,5 \rightarrow 1} // \text{m}_{1,6 \rightarrow 1} // \\ & \text{m}_{1,8 \rightarrow 1} // \text{m}_{1,9 \rightarrow 1} // \text{m}_{1,10 \rightarrow 1} \end{aligned}$$

$$\text{Out}[*]= \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\theta, \theta, \frac{T}{1 - T + T^2} + \frac{(c_2 - T c_2 + T^3 c_2 - T^4 c_2 - T c_9 + 2 T^2 c_9 - 3 T^3 c_9 + 2 T^4 c_9) \epsilon}{1 - 3 T + 6 T^2 - 7 T^3 + 6 T^4 - 3 T^5 + T^6} + \mathcal{O}[\epsilon]^2 \right]$$

$$\text{Out}[*]= \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\theta, \theta, \frac{T}{1 - T + T^2} + \frac{(c_2 - T c_2 + T^3 c_2 - T^4 c_2 - T c_9 + 2 T^2 c_9 - 3 T^3 c_9 + 2 T^4 c_9) \epsilon}{1 - 3 T + 6 T^2 - 7 T^3 + 6 T^4 - 3 T^5 + T^6} + \mathcal{O}[\epsilon]^2 \right]$$

Unfortunately? This docile invariant does not see the difference between the mirror trefoils. Perhaps it is actually determined by Alexander.

$$\text{In}[*]:= \text{Kink}_8 \text{Kink}_9 \text{Kink}_{10} \text{CC}_4 \overline{\text{R}}_{1,5} \overline{\text{R}}_{6,2} \overline{\text{R}}_{3,7} // \text{m}_{1,2 \rightarrow 1} // \text{m}_{1,3 \rightarrow 1} // \text{m}_{1,4 \rightarrow 1} // \text{m}_{1,5 \rightarrow 1} // \text{m}_{1,6 \rightarrow 1} // \text{m}_{1,7 \rightarrow 1} // \\ \text{m}_{1,8 \rightarrow 1} // \text{m}_{1,9 \rightarrow 1} // \text{m}_{1,10 \rightarrow 1}$$

$$\text{Out}[*]= \mathbb{E}_{\{\} \rightarrow \{1\}} \left[\theta, \theta, \frac{T}{1 - T + T^2} + \frac{(c_2 - T c_2 + T^3 c_2 - T^4 c_2 - 2 c_9 + 3 T c_9 - 2 T^2 c_9 + T^3 c_9) \epsilon}{1 - 3 T + 6 T^2 - 7 T^3 + 6 T^4 - 3 T^5 + T^6} + \mathcal{O}[\epsilon]^2 \right]$$

```

In[*]:= RVK[pd_PD] := Module[{n, xs, x, rots, front = {0}, k},
  n = Length@pd; rots = Table[0, {2 n}];
  xs = Cases[pd, x_X => {
    {Xp[x[[4]], x[[1]]] PositiveQ@x,
    {Xm[x[[2]], x[[1]]] True
  }];
  For[k = 0, k < 2 n, ++k, If[k == 0 ∨ FreeQ[front, -k],
    front = Flatten[front /. k → (xs /. {
      Xp[k + 1, L_] | Xm[L_, k + 1] => {L, k + 1, 1 - L},
      Xp[L_, k + 1] | Xm[k + 1, L_] => (++)rots[[L]; {1 - L, k + 1, L}
    })],
    Cases[front, k | -k] /. {k, -k} => --rots[[k + 1]];
  ];
  RVK[xs, rots ] ];
RVK[K_] := RVK[PD[K]];

```

```

In[*]:= rot[i_, 0] := E_{i}→{i}[0, 0, 1];
rot[i_, n_] := Module[{j},
  rot[i, n] = If[n > 0, rot[i, n - 1] CCj, rot[i, n + 1]  $\overline{CC}_j$ ] // mi,j→i];

```

In[]:=

```

Z[K_] := Z[RVK@K];
Z[rvk_RVK] := (*Z[rvk] =*)
Module[{todo, n, rots, ξ, done, st, cx, ξ1, i, j, k, k1, k2, k3},
  {todo, rots} = List@@rvk;
  AppendTo[rots, 0];
  n = Length[todo];
  ξ = E_{i→{0}}[0, 0, 1];
  done = {0};
  st = Range[0, 2 n + 1];
  While[{ } != ($M = todo),
    {cx} = MaximalBy[todo, Length[done ∩ {#[[1]], #[[2]], #[[1]] - 1, #[[2]] - 1}] &, 1];
    {i, j} = List@@cx;
    ξ1 = Switch[Head[cx],
      Xp, (R_{i,j} Kink_k) // m_{j,k→j},
      Xm, (R_{i,j} Kink_k) // m_{j,k→j}
    ];
    ξ1 = (rot[k, rots[[i]] ξ1) // m_{k,i→i}; rots[[i]] = 0;
    ξ1 = (ξ1 rot[k, rots[[i+1]]) // m_{i,k→i}; rots[[i+1]] = 0;
    ξ1 = (rot[k, rots[[j]] ξ1) // m_{k,j→j}; rots[[j]] = 0;
    ξ1 = (ξ1 rot[k, rots[[j+1]]) // m_{j,k→j}; rots[[j+1]] = 0;
    ξ *= ξ1;
    If[MemberQ[done, i], ξ = ξ // m_{i,i+1→i}; st = st /. st[[i+2]] → st[[i+1]];
    If[MemberQ[done, i-1], ξ = ξ // m_{st[[i],i→st[[i]]}; st = st /. st[[i+1]] → st[[i]];
    If[MemberQ[done, j], ξ = ξ // m_{j,j+1→j}; st = st /. st[[j+2]] → st[[j+1]];
    If[MemberQ[done, j-1], ξ = ξ // m_{st[[j],j→st[[j]]}; st = st /. st[[j+1]] → st[[j]];
    done = done ∪ {i-1, i, j-1, j};
    todo = DeleteCases[todo, cx]
  ];
  CF /@ (ξ (* /. {X_0→X, Y_0→Y, a_0→a}*))
]

```

In[]:= NewBit[K_] := Module[{Alex = Alexander[K][T]},

$$T^3 \frac{Alex^3}{T-1} \text{Coefficient}[Z[K][[3]], \epsilon] // \text{Factor}]$$

In[]:= NewBit /@ AllKnots[{3, 5}]

KnotTheory: Loading precomputed data in PD4Knots`.

$$\text{Out[]:= } \left\{ -c_2 - T^3 c_2 + 2 c_9 - T c_9 + T^2 c_9, - \left((1 + T) (1 - 3 T + T^2) (c_2 - c_9) \right), \right. \\
 \left. - \frac{2 c_2 - T c_2 + 2 T^2 c_2 + 2 T^5 c_2 - T^6 c_2 + 2 T^7 c_2 - 4 c_9 + 3 T c_9 - 5 T^2 c_9 + 3 T^3 c_9 - 3 T^4 c_9 + T^5 c_9 - T^6 c_9}{T^2}, \right. \\
 \left. -4 c_2 + 2 T c_2 + 2 T^2 c_2 - 4 T^3 c_2 + 9 c_9 - 11 T c_9 + 7 T^2 c_9 - T^3 c_9 \right\}$$

In[]:= (*Two knots with equal Alexander, new bit does not agree*)

Alexander[Knot[6, 1]] == Alexander[Knot[9, 46]]
 eq = (NewBit[Knot[6, 1]] == NewBit[Knot[9, 46]]);
 eq /. c₉ → 0
 eq /. c₂ → 0

Out[]:= True

Out[]:= True

Out[]:= 5 c₉ - 11 T c₉ - T² c₉ + 3 T³ c₉ == 7 c₉ - 21 T c₉ + 9 T² c₉ + T³ c₉

In[]:= Factor[NewBit /@AllKnots[{3, 7}] /. c₂ → 0]

Out[]:=
$$\left\{ (2 - T + T^2) c_9, (1 + T) (1 - 3 T + T^2) c_9, \frac{(4 - 3 T + 5 T^2 - 3 T^3 + 3 T^4 - T^5 + T^6) c_9}{T^2}, \right.$$

$$- \left((-9 + 11 T - 7 T^2 + T^3) c_9 \right), (5 - 11 T - T^2 + 3 T^3) c_9,$$

$$\frac{(3 - 12 T + 16 T^2 - 12 T^3 + 4 T^4 - 2 T^6 + T^7) c_9}{T^2}, \frac{(1 + T) (2 - 3 T + 2 T^2) (1 - 3 T + 5 T^2 - 3 T^3 + T^4) c_9}{T^2},$$

$$\frac{(6 - 5 T + 9 T^2 - 7 T^3 + 9 T^4 - 6 T^5 + 6 T^6 - 3 T^7 + 3 T^8 - T^9 + T^{10}) c_9}{T^4},$$

$$- \left((-23 + 36 T - 24 T^2 + 5 T^3) c_9 \right), \frac{(-1 + 7 T - 13 T^2 + 24 T^3 - 32 T^4 + 35 T^5 - 27 T^6 + 17 T^7) c_9}{T^2},$$

$$4 (-2 + 11 T - 17 T^2 + 10 T^3) c_9, - \frac{(-17 + 41 T - 65 T^2 + 65 T^3 - 49 T^4 + 25 T^5 - 9 T^6 + T^7) c_9}{T^2},$$

$$\frac{(3 - 22 T + 53 T^2 - 53 T^3 + 25 T^4 - T^5 - 4 T^6 + T^7) c_9}{T^2},$$

$$\left. \frac{(2 - 13 T + 27 T^2 - 9 T^3 - 31 T^4 + 33 T^5 - 13 T^6 + 2 T^7) c_9}{T^2} \right\}$$

In[]:= m_{i,j→k}

lhs = m_{1,2→1} // m_{1,3→1}

rhs = m_{2,3→2} // m_{1,2→1}

lhs == rhs

Out[]:= E_{{i,j}→{k}} [0, y_k (η_i + η_j) - η_j ξ_i + x_k (ξ_i + ξ_j), 1]

Out[]:= E_{{1,2,3}→{1}} [0, y₁ η₁ + y₁ η₂ + y₁ η₃ + x₁ ξ₁ - η₂ ξ₁ - η₃ ξ₁ + x₁ ξ₂ - η₃ ξ₂ + x₁ ξ₃, 1]

Out[]:= E_{{1,2,3}→{1}} [0, y₁ η₁ + y₁ η₂ + y₁ η₃ + x₁ ξ₁ - η₂ ξ₁ - η₃ ξ₁ + x₁ ξ₂ - η₃ ξ₂ + x₁ ξ₃, 1]

Out[]:= True

In[]:= R_{i,j} /. {c_{1|2|6} → 0, c₉ → 1}

Out[]:= E_{{i}→{i,j}} [0, (-1 + T) x_j (y_i - y_j), 1 + $\left(-\frac{1}{2} (1 - T) x_j^2 y_i^2 + x_i x_j y_i y_j + \frac{1}{2} (1 - 3 T) x_j^2 y_i y_j \right) \epsilon + 0[\epsilon]^2$]

$$In[*]:= \mathbf{R}_{1,2} \overline{\mathbf{R}}_{3,4} /. \{c_{1|2|6} \rightarrow \mathbf{0}, c_9 \rightarrow \mathbf{1}\}$$

$$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{1,2,3,4\}} \left[\mathbf{0}, (-1 + \tau) x_2 (y_1 - y_2) + \left(-1 + \frac{1}{\tau}\right) x_4 (y_3 - y_4), \right. \\ \left. 1 + \left(-\frac{1}{2} (1 - \tau) x_2^2 y_1^2 + x_1 x_2 y_1 y_2 + \frac{1}{2} (1 - 3\tau) x_2^2 y_1 y_2 - \right. \right. \\ \left. \left. \frac{(-1 + \tau) x_3 x_4 y_3^2}{\tau^2} - \frac{(1 - \tau) x_4^2 y_3^2}{2 \tau^3} - \frac{x_3 x_4 y_3 y_4}{\tau^2} - \frac{(-1 - \tau) x_4^2 y_3 y_4}{2 \tau^3} \right) \epsilon + \mathbf{0}[\epsilon]^2 \right]$$

$$In[*]:= \left(\mathbf{R}_{1,2} \overline{\mathbf{R}}_{3,4} \right) // m_{1,3 \rightarrow 1} /. \{c_{1|2|6} \rightarrow \mathbf{0}, c_9 \rightarrow \mathbf{1}\}$$

$$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{1,2,4\}} \left[\mathbf{0}, (-1 + \tau) x_2 y_1 + \frac{(1 - \tau) x_4 y_1}{\tau} + (1 - \tau) x_2 y_2 + \frac{(-1 + \tau) x_4 y_4}{\tau}, \right. \\ \left. 1 + \left(\frac{1}{2} (-1 + \tau) x_2^2 y_1^2 + \frac{(1 - \tau) x_1 x_4 y_1^2}{\tau^2} + \frac{(-1 + \tau) x_4^2 y_1^2}{2 \tau^3} + x_1 x_2 y_1 y_2 + \right. \right. \\ \left. \left. \frac{1}{2} (1 - 3\tau) x_2^2 y_1 y_2 + \frac{(-1 + \tau) x_2 x_4 y_1 y_2}{\tau} - \frac{x_1 x_4 y_1 y_4}{\tau^2} + \frac{(1 + \tau) x_4^2 y_1 y_4}{2 \tau^3} \right) \epsilon + \mathbf{0}[\epsilon]^2 \right]$$

$$In[*]:= \mathbf{R}_{1,2} \overline{\mathbf{R}}_{3,4} // m_{1,3 \rightarrow 1} // m_{2,4 \rightarrow 2}$$

$$Out[*]:= \mathbb{E}_{\{\} \rightarrow \{1,2\}} \left[\mathbf{0}, \mathbf{0}, 1 + \mathbf{0}[\epsilon]^2 \right]$$