

Pensieve header: The Kerler Algebra and the Alexander polynomial. Closely related to arXiv://math/0008204.

```
In[ ]:= SetDirectory["C:\\drorbn\\AcademicPensieve\\Classes\\21-1350-KnotTheory"];
<< Common.m
```

```
In[ ]:= MT = 
$$\begin{pmatrix} & a & b & c & d & ka & kb & kc & kd \\ a & a & b & 0 & 0 & ka & kb & 0 & 0 \\ b & 0 & 0 & a & b & 0 & 0 & -ka & -kb \\ c & c & d & 0 & 0 & -kc & -kd & 0 & 0 \\ d & 0 & 0 & c & d & 0 & 0 & kc & kd \\ ka & ka & kb & 0 & 0 & a & b & 0 & 0 \\ kb & 0 & 0 & ka & kb & 0 & 0 & -a & -b \\ kc & kc & kd & 0 & 0 & -c & -d & 0 & 0 \\ kd & 0 & 0 & kc & kd & 0 & 0 & c & d \end{pmatrix};$$

```

```
 $\mathcal{E}_- // m_{i,j \rightarrow k} := \text{Expand}[\mathcal{E}] /. \text{Flatten@Table}[MT[[\alpha, 1]]_i MT[[1, \beta]]_j \rightarrow$ 
 $(MT[[\alpha, \beta]] /. v : (a | b | c | d | ka | kb | kc | kd) \Rightarrow v_k), \{\alpha, 2, 9\}, \{\beta, 2, 9\}];$ 
```

```
 $\eta_{i_-} :=$ 
 $a_i +$ 
 $d_i;$ 
```

```
In[ ]:= Flatten@Table[MT[[\alpha, 1]]_i MT[[1, \beta]]_j \rightarrow
(MT[[\alpha, \beta]] /. v : (a | b | c | d | ka | kb | kc | kd) \Rightarrow v_k), \{\alpha, 2, 9\}, \{\beta, 2, 9\}]
```

```
Out[ ]:= {a_i a_j \to a_k, a_i b_j \to b_k, a_i c_j \to 0, a_i d_j \to 0, a_i ka_j \to ka_k, a_i kb_j \to kb_k, a_i kc_j \to 0,
a_i kd_j \to 0, a_j b_i \to 0, b_i b_j \to 0, b_i c_j \to a_k, b_i d_j \to b_k, b_i ka_j \to 0, b_i kb_j \to 0, b_i kc_j \to -ka_k,
b_i kd_j \to -kb_k, a_j c_i \to c_k, b_j c_i \to d_k, c_i c_j \to 0, c_i d_j \to 0, c_i ka_j \to -kc_k, c_i kb_j \to -kd_k,
c_i kc_j \to 0, c_i kd_j \to 0, a_j d_i \to 0, b_j d_i \to 0, c_j d_i \to c_k, d_i d_j \to d_k, d_i ka_j \to 0, d_i kb_j \to 0,
d_i kc_j \to kc_k, d_i kd_j \to kd_k, a_j ka_i \to ka_k, b_j ka_i \to kb_k, c_j ka_i \to 0, d_j ka_i \to 0, ka_i ka_j \to a_k,
ka_i kb_j \to b_k, ka_i kc_j \to 0, ka_i kd_j \to 0, a_j kb_i \to 0, b_j kb_i \to 0, c_j kb_i \to ka_k, d_j kb_i \to kb_k,
ka_j kb_i \to 0, kb_i kb_j \to 0, kb_i kc_j \to -a_k, kb_i kd_j \to -b_k, a_j kc_i \to kc_k, b_j kc_i \to kd_k,
c_j kc_i \to 0, d_j kc_i \to 0, ka_j kc_i \to -c_k, kb_j kc_i \to -d_k, kc_i kc_j \to 0, kc_i kd_j \to 0, a_j kd_i \to 0,
b_j kd_i \to 0, c_j kd_i \to kc_k, d_j kd_i \to kd_k, ka_j kd_i \to 0, kb_j kd_i \to 0, kc_j kd_i \to c_k, kd_i kd_j \to d_k}
```

```
In[ ]:= KBasis[i_] := {a_i, b_i, c_i, d_i, ka_i, kb_i, kc_i, kd_i};
KBasis[i_, is_] := Flatten@Outer[Times, KBasis[i], KBasis[is]]
```

```
In[ ]:= KBasis[1]
```

```
Out[ ]:= {a_1, b_1, c_1, d_1, ka_1, kb_1, kc_1, kd_1}
```

In[]:= **KBasis** [5, 6]

Out[]:= { a₅ a₆, a₅ b₆, a₅ c₆, a₅ d₆, a₅ ka₆, a₅ kb₆, a₅ kc₆, a₅ kd₆, a₆ b₅, b₅ b₆, b₅ c₆, b₅ d₆, b₅ ka₆, b₅ kb₆, b₅ kc₆, b₅ kd₆, a₆ c₅, b₆ c₅, c₅ c₆, c₅ d₆, c₅ ka₆, c₅ kb₆, c₅ kc₆, c₅ kd₆, a₆ d₅, b₆ d₅, c₆ d₅, d₅ d₆, d₅ ka₆, d₅ kb₆, d₅ kc₆, d₅ kd₆, a₆ ka₅, b₆ ka₅, c₆ ka₅, d₆ ka₅, ka₅ ka₆, ka₅ kb₆, ka₅ kc₆, ka₅ kd₆, a₆ kb₅, b₆ kb₅, c₆ kb₅, d₆ kb₅, ka₆ kb₅, kb₅ kb₆, kb₅ kc₆, kb₅ kd₆, a₆ kc₅, b₆ kc₅, c₆ kc₅, d₆ kc₅, ka₆ kc₅, kb₆ kc₅, kc₅ kc₆, kc₅ kd₆, a₆ kd₅, b₆ kd₅, c₆ kd₅, d₆ kd₅, ka₆ kd₅, kb₆ kd₅, kc₆ kd₅, kd₅ kd₆ }

Associativity of m:

In[]:= **Short** [l_{hs} = **KBasis** [1, 2, 3] // m_{1,2→1} // m_{1,3→1}]
 r_{hs} = **KBasis** [1, 2, 3] // m_{2,3→2} // m_{1,2→1} ;
 l_{hs} == r_{hs}

Out[]//Short= { a₁, b₁, 0, 0, ka₁, <<502>>, d₁, 0, 0, kc₁, kd₁ }

Out[]:= True

Units:

In[]:= { (η₁ **KBasis** [2] // m_{1,2→1}) == **KBasis** [1], (η₁ **KBasis** [2] // m_{2,1→1}) == **KBasis** [1] }
 Out[]:= { True, True }

In[]:= $R_{i,j} := T^{-1/2} (a_i ka_j - T a_i kd_j + (T - 1) b_j kc_i + d_i ka_j + T d_i kd_j) ;$
 $\bar{R}_{i,j} := T^{1/2} (a_i ka_j - T^{-1} a_i kd_j + (T^{-1} - 1) b_j kc_i + d_i ka_j + T^{-1} d_i kd_j) ;$
 $C_{i-} := T^{-1/2} (ka_i + kd_i) ; \bar{C}_{i-} := T^{1/2} (ka_i + kd_i) ;$

Reidemeister 3:

In[]:= **Short** [l_{hs} = R_{1,2} R_{4,3} R_{5,6} // m_{1,4→1} // m_{2,5→2} // m_{3,6→3}]
 r_{hs} = R_{2,3} R_{1,4} R_{5,6} // m_{1,5→1} // m_{2,6→2} // m_{3,4→3} ;
 l_{hs} == r_{hs}

Out[]//Short= $\frac{a_1 a_3 ka_2}{T^{3/2}} + \ll 27 \gg$

Out[]:= True

Reidemeister 2b:

In[]:= **Short** [l_{hs} = R_{1,2} $\bar{R}_{3,4}$ // m_{1,3→1} // m_{2,4→2}]
 r_{hs} = η₁ η₂ // **Expand** ;
 l_{hs} == r_{hs}

Out[]//Short= a₁ a₂ + a₂ d₁ + a₁ d₂ + d₁ d₂

Out[]:= True

Naive Reidemeister 2c:

```
In[ ]:= Short [lhs = R1,2 R̄3,4 // m1,3→1 // m4,2→2]
rhs = η1 η2 // Expand;
Simplify[lhs - rhs]
```

```
Out[ ]:= a1 a2 + a2 d1 + <<1>> + <<1>> - 2 kb2 kc1 + 2 T kb2 kc1
```

```
Out[ ]:= 2 × (-1 + T) kb2 kc1
```

Corrected Reidemeister 2c:

```
In[ ]:= lhs = R1,4 R̄5,2 C̄3 // m2,4→2 // m1,3→1 // m1,5→1
rhs = C̄1 η2 // Expand;
lhs == rhs
```

```
Out[ ]:= √T a2 ka1 + √T d2 ka1 + √T a2 kd1 + √T d2 kd1
```

```
Out[ ]:= True
```

C̄C̄:

```
In[ ]:= C1 C̄2 // m1,2→1
```

```
Out[ ]:= a1 + d1
```

Reidemeister 1s:

```
In[ ]:= { (C̄2 R1,3 // m1,2→1 // m1,3→1) == η1, (C̄2 R̄3,1 // m1,2→1 // m1,3→1) == η1,
(C̄2 R̄1,3 // m1,2→1 // m1,3→1) == η1, (C̄2 R3,1 // m1,2→1 // m1,3→1) == η1 }
```

```
Out[ ]:= {True, True, True, True}
```

The whirl:

```
In[ ]:= Expand [ (C̄1 C̄2 R3,4 C5 C6 // m1,3→1 // m1,5→1 // m2,4→2 // m2,6→2) == R1,2 ]
```

```
Out[ ]:= True
```

RVK and Z

```
In[ ]:= Knot [8, 17] // PD
```

KnotTheory: Loading precomputed data in PD4Knots`.

```
Out[ ]:= PD [X [6, 2, 7, 1], X [14, 8, 15, 7], X [8, 3, 9, 4], X [2, 13, 3, 14],
X [12, 5, 13, 6], X [4, 9, 5, 10], X [16, 12, 1, 11], X [10, 16, 11, 15]]
```

RVK, rot, Z modified from 2016-09/OneSmidgen.nb. See also in AP/Projects/SL2Invariant/.

Some details of the code below are at <http://drorbn.net/bbs/show?shot=Dror-160920-151350.jpg>.

```
In[ ]:= RVK::usage =
```

```
"RVK[xs, rots] represents a Rotational Virtual Knot with a list of n Xp/Xm crossings
xs and a length 2n list of rotation numbers rots. Crossing
sites are indexed 1 through 2n, and rots[[k]] is the rotation
between site k-1 and site k. RVK is also a casting operator
converting to the RVK presentation from other knot presentations.";
```

```

In[ ]:= RVK[pd_PD] := Module[{n, xs, x, rots, front = {0}, k},
  n = Length@pd; rots = Table[0, {2 n}];
  xs = Cases[pd, x_X :=> {
    Xp[x[[4]], x[[1]] PositiveQ@x,
    Xm[x[[2]], x[[1]] True
  }];
  For[k = 0, k < 2 n, ++k, If[k == 0 ∨ FreeQ[front, -k],
    front = Flatten@Replace[front, k → (xs /. {
      Xp[k + 1, L_] | Xm[L_, k + 1] :=> {L, k + 1, 1 - L},
      Xp[L_, k + 1] | Xm[k + 1, L_] :=> (++)rots[[L]]; {1 - L, k + 1, L},
      _Xp | _Xm :=> {}
    }), {1}],
    Cases[front, k | -k] /. {k, -k} :=> --rots[[k + 1]];
  ]];
  RVK[xs, rots] ];
RVK[K_] := RVK[PD[K]];

In[ ]:= roti[n_] := roti[n] = {
  ηi n == 0
  Cξ roti[n - 1] // mi,ξ→i n > 0
  C̄ξ roti[n + 1] // mi,ξ→i n < 0
};

In[ ]:= Z[K_] := Z[RVK@K];
Z[rvk_RVK] := Module[{ξ, done, st, c, χ, i, j, k},
  ξ = 1; done = {}; st = Range[2 Length[rvk[[1]]]];
  Do[
    {i, j} = List@@c;
    χ = c /. {_Xp :=> Ri,j, _Xm :=> R̄i,j};
    Do[χ = (rot0[rvk[[2, k]]] χ) // m0,k→k, {k, {i, j}}];
    ξ *= χ;
  Do[
    If[MemberQ[done, k + 1], ξ = ξ // mk,k+1→k; st = st /. k + 1 → k];
    If[MemberQ[done, k - 1], ξ = ξ // mst[[k-1],k→st[[k-1]]; st = st /. k → st[[k - 1]],
    {k, {i, j}}];
    done = done ∪ {i, j},
    {c, rvk[[1]]}
  ];
  Factor@ξ
];

In[ ]:= K = Knot[8, 17]; Factor@Alexander[K][T]
z = Z[K]

In[ ]:= Timing@Union@Table[Simplify[Alexander[K][T] η1 == Z[K]], {K, AllKnots[{3, 10}]}]

In[ ]:= ZF[K_] := Z@ThinPosition@K;

In[ ]:= Timing@Union@Table[Simplify[Alexander[K][T] η1 == ZF[K]], {K, AllKnots[{3, 10}]}]

In[ ]:= Timing[ZF[GST48]]

```