

Pensieve header: A poly-time program to compute the $\frac{g}{0}$ invariant.

Reminders

1. Fill out "Graduate Course Participation Form" (see <http://drorbn.net/AcademicPensieve/Classes/17-1350-AKT/GCP.jpg>, in time).
2. Make sure that you have Mathematica and that you play with these programs!
3. Change meeting time?

Representing $g_0 = \langle h, e, l, f \rangle / ([e, l] = -e, [f, l] = f, [e, f] = h, [h, *] = 0)$

$$\rho_h = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \rho_e = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}; \rho_l = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \rho_f = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \rho_\theta = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix};$$

$B[x_?MatrixQ, y_?MatrixQ] := x.y - y.x;$

$\{B[\rho_e, \rho_l] == -\rho_e, B[\rho_f, \rho_l] == \rho_f, B[\rho_e, \rho_f] == \rho_h, B[\rho_h, \rho_e] == \rho_\theta, B[\rho_h, \rho_l] == \rho_\theta, B[\rho_h, \rho_f] == \rho_\theta\}$

$\{\text{True, True, True, True, True, True}\}$

Implementing g_0

```
PBWRule = {e → 1, l → 2, f → 3};
B[U@e, U@l] = -U@e; B[U@f, U@l] = U@f; B[U@e, U@f] = h U[];
```

```
$TD = 3; h /: h^d. /; d > $TD := 0;
```

```
x_ ≤ y_ := OrderedQ[{x, y} /. PBWRule]; x_ < y_ := ! OrderedQ[{y, x} /. PBWRule];
Simp[ε_] := Collect[ε, _U, Expand];
```

```
U_i[ε_] := ε /. {h → h_i, t → t_i, u U ⇒ Replace[u, x_ ⇒ x_i, 1]};
B[U[(x_)_i], U[(y_)_i]] := B[U[x_i], U[y_i]] = U_i[B[U@x, U@y]];
B[U[(x_)_i], U[(y_)_j]] /; i != j := 0;
B[x_, x_] = 0;
B[U[y_], U[x_]] := B[U[y], U[x]] = Simp[-B[U[x], U[y]]];
B[x_, y_] := x**y - y**x;
```

```
Unprotect[NonCommutativeMultiply];
NonCommutativeMultiply[x_] := x;
0**_ = _**0 = 0;
x**U[] := x; U[]**x_ := x;
(a_**x_U)**(b_**y_U) := If[ab === 0, 0, Simp[ab(x**y)]];
(a_**x_U)**y_ := Simp[a(x**y)]; x**(a_**y_U) := Simp[a(x**y)];
(x_Plus)**y_ := (#**y) & /@ x; x**(y_Plus) := (x**#) & /@ y;
```

```
U[xx___, x_] ** U[y_, yy___] := If[x ≤ y, U[xx, x, y, yy], U@xx ** (U@y ** U@x + B[U@x, U@y]) ** U@yy];
```

```
UU[L___, x^n_, r___] := UU[L, Sequence@@Table[x, {n}], r];
UU[L___, 1, r___] := UU[L, r];
UU[] = U[];
UU[L_, r___] := U[L] ** UU[r];
```

```

UProducts[{}, 0] = {UU[]};
UProducts[{}, n_Integer] /; n > 0 = {};
UProducts[{x_, xs___}, n_Integer] :=
  Sort@Flatten@Table[UU[x^k] ** u, {k, 0, n}, {u, UProducts[{xs}, n - k]}];
UProducts[xs_List, k_Integer, n_Integer] := UProducts[Flatten@Table[xj, {x, xs}, {j, k}], n];
UProducts[any_, {n_}] := Flatten@Table[UProducts[any, k], {k, 0, n}];

```

```

r_{i,j} := Simp[h (h_i UU[l_j] + UU[e_i, f_j])]

```

```

UExp[u_] := Module[{s, t, k},
  s = t = U[]; k = 0;
  While[k < 20 &amp; 0 != (t = t ** u), s += t / (++k)];
  Simp[s];
R_{i,j} := UExp[r_{i,j}];

```

```

m[i_, j_, k_][e_] := Simp[e /. {
  u_U := UU@@Join[DeleteCases[u, x_{i|j}], U@@Cases[u, x_{i} := x_k], U@@Cases[u, x_{j} := x_k]],
  h_{i|j} -> h_k}]

```

Ordering Symbols; The Invariant of the Trefoil

Theorem. $R = e^{h\otimes l + e\otimes f} = \mathcal{O}(\exp(hl + \frac{e^h - 1}{h} ef \mid e \otimes lf))$.

Gentle Proof, Presented Brutely.

MatrixForm /@ {MatrixExp[h ρl + e ρf], MatrixExp[h ρl].MatrixExp[$\frac{e^h - 1}{h}$ e ρf]}

$$\left\{ \begin{pmatrix} 1 & \frac{e^{-1+e^h}}{h} & 0 \\ 0 & e^h & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & \frac{e^{-1+e^h}}{h} & 0 \\ 0 & e^h & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

```

O[poly_, specs___] := Module[{vs, us, z},
  vs = Join@@(First /@ {specs});
  us = Join@@({specs} /. (l_ -> s_) := (l /. x_{i_} := x_s));
  Simp@Total[CoefficientRules[Normal@Series[poly, {h, 0, $TD}], vs] /. (p_ -> c_) := c UU@@(us^p)]
]

```

Debt. How does this work?

Timing[\$TD = 3; T1\$1 = O[Exp[h h l_1 + $\frac{e^h h - 1}{h}$ e_4 f_1 + h h l_5 + $\frac{e^h h - 1}{h}$ e_2 f_5 + h h l_3 + $\frac{e^h h - 1}{h}$ e_6 f_3],
 {l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6} -> 1] /. h_1 -> h]

$$\{0.078125, \left(1 - 2h\hbar + h^2\hbar^2 + \frac{2h^3\hbar^3}{3}\right) U[] +$$

$$\left(3h\hbar - 6h^2\hbar^2 + 3h^3\hbar^3\right) U[l_1] + \left(3\hbar - \frac{3h\hbar^2}{2} - \frac{3h^2\hbar^3}{2}\right) U[e_1, f_1] + \left(\frac{9h^2\hbar^2}{2} - 9h^3\hbar^3\right) U[l_1, l_1] +$$

$$\left(9h\hbar^2 - \frac{9h^2\hbar^3}{2}\right) U[e_1, l_1, f_1] + \frac{9}{2} h^3\hbar^3 U[l_1, l_1, l_1] + \left(\frac{9\hbar^2}{2} + \frac{9h\hbar^3}{2}\right) U[e_1, e_1, f_1, f_1] +$$

$$\frac{27}{2} h^2\hbar^3 U[e_1, l_1, l_1, f_1] + \frac{27}{2} h\hbar^3 U[e_1, e_1, l_1, f_1, f_1] + \frac{9}{2} \hbar^3 U[e_1, e_1, e_1, f_1, f_1, f_1] \}$$

The Big g₀ Lemma

$$1. \mathcal{O}(e^{Vl+\beta e} \mid |e) = \mathcal{O}(e^{Vl+e^V \beta e} \mid |e).$$

$$2. \mathcal{O}(e^{Vl+\beta f} \mid |f) = \mathcal{O}(e^{Vl+e^V \beta f} \mid |f).$$

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta e f} \mid fe) = \mathcal{O}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} \mid ef), \text{ with } v = (1 + h\delta)^{-1}.$$

Gentle Proofs of 1 & 2 and of 3 at $\delta=0$.

MatrixForm /@ {**MatrixExp**[$\gamma \rho 1$].**MatrixExp**[$\beta \rho e$], **MatrixExp**[$e^\gamma \beta \rho e$].**MatrixExp**[$\gamma \rho 1$]} }

$$\left\{ \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^\gamma & e^\gamma \beta \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^\gamma & e^\gamma \beta \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

MatrixForm /@ {**MatrixExp**[$\beta \rho f$].**MatrixExp**[$\gamma \rho 1$], **MatrixExp**[$\gamma \rho 1$].**MatrixExp**[$e^\gamma \beta \rho f$]} }

$$\left\{ \begin{pmatrix} 1 & e^\gamma \beta & 0 \\ 0 & e^\gamma & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & e^\gamma \beta & 0 \\ 0 & e^\gamma & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

MatrixForm /@ {**MatrixExp**[$\alpha \rho f$].**MatrixExp**[$\beta \rho e$], **MatrixExp**[$-\alpha \beta \rho h$].**MatrixExp**[$\beta \rho e$].**MatrixExp**[$\alpha \rho f$]} }

$$\left\{ \begin{pmatrix} 1 & \alpha & \alpha \beta \\ 0 & 1 & \beta \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & \alpha & \alpha \beta \\ 0 & 1 & \beta \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

Debt. Prove the full part 3!

The Main g_0 Theorem.

Raw Version. The g_0 invariant of any S-component tangle T can be written in the form $Z(T) = \mathcal{O}(\omega e^{L+Q} \mid \prod_{i \in S} e_i l_i f_i)$, where ω is a scalar (meaning, a rational function in the variables h_i and their exponentials $t_i = e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients a_{ij} and where $Q = \sum b_{ij} e_i f_j$ is a balanced quadratic in the variables e_i and f_j with scalar coefficients b_{ij} . Furthermore, after setting $h_i = h$ and $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

Proof. Indeed,

$$0. R = e^{h\otimes l + e\otimes f} = \mathcal{O}(\exp(hl + \frac{e^h-1}{h} ef \mid e\otimes lf),$$

$$1. \mathcal{O}(e^{\gamma l + \beta e} \mid le) = \mathcal{O}(e^{\gamma l + e^\gamma \beta e} \mid el),$$

$$2. \mathcal{O}(e^{\gamma l + \beta f} \mid fl) = \mathcal{O}(e^{\gamma l + e^\gamma \beta f} \mid lf),$$

$$3. \mathcal{O}(e^{\beta e + \alpha f + \delta e f} \mid fe) = \mathcal{O}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} \mid ef), \text{ with } v = (1 + h\delta)^{-1},$$

and the rest is straight-forward.

old above / new below

```
CF[E[ $\omega$ _, L_, Q_]] := E[Simplify[ $\omega$ ], Simplify[L], Simplify[Q]];
E /: E[ $\omega 1$ _, L1_, Q1_] E[ $\omega 2$ _, L2_, Q2_] := CF@E[ $\omega 1 \omega 2$ , L1 + L2, Q1 + Q2];
E[ $\omega 1$ _, L1_, Q1_] E[ $\omega 2$ _, L2_, Q2_] := Simplify[ $\omega 1 == \omega 2 \wedge L1 == L2 \wedge Q1 == Q2$ ];
```

$$0. R = e^{h\otimes l + e\otimes f} = \mathcal{O}(\exp(hl + \frac{e^h-1}{h} ef \mid e\otimes lf):$$

$$\mathbb{E}[X_{i,j}^+] := \mathbb{E}[1, h_i l_j, h_i^{-1} (e^{h_i} - 1) e_i f_j];$$

$$\mathbb{E}[X_{i,j}^-] := \mathbb{E}[1, -h_i l_j, h_i^{-1} (e^{-h_i} - 1) e_i f_j];$$

$$\mathbb{E}[p_Times] := \mathbb{E} /@ p;$$

$$\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+]$$

$$\mathbb{E}\left[1, h_4 l_1 + h_6 l_3 + h_2 l_5, \frac{(-1 + e^{h_2}) e_2 f_5}{h_2} + \frac{(-1 + e^{h_4}) e_4 f_1}{h_4} + \frac{(-1 + e^{h_6}) e_6 f_3}{h_6}\right]$$

```
O[E[ $\omega$ _, L_, Q_], specs___] := O[ $\omega e^{L+Q} / . (x : e | h)_{i_-} \Rightarrow \hbar x_i$ , specs];
```

$$\text{Timing}[\$TD = 3; \text{T1}\$2 = \mathbf{0} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_ \rightarrow h]$$

$$\{0.078125, \left(1 - 2h\hbar + h^2\hbar^2 + \frac{2h^3\hbar^3}{3}\right) U[] +$$

$$\left(3h\hbar - 6h^2\hbar^2 + 3h^3\hbar^3\right) U[l_1] + \left(3\hbar - \frac{3h\hbar^2}{2} - \frac{3h^2\hbar^3}{2}\right) U[e_1, f_1] + \left(\frac{9h^2\hbar^2}{2} - 9h^3\hbar^3\right) U[l_1, l_1] +$$

$$\left(9h\hbar^2 - \frac{9h^2\hbar^3}{2}\right) U[e_1, l_1, f_1] + \frac{9}{2} h^3\hbar^3 U[l_1, l_1, l_1] + \left(\frac{9\hbar^2}{2} + \frac{9h\hbar^3}{2}\right) U[e_1, e_1, f_1, f_1] +$$

$$\frac{27}{2} h^2\hbar^3 U[e_1, l_1, l_1, f_1] + \frac{27}{2} h\hbar^3 U[e_1, e_1, l_1, f_1, f_1] + \frac{9}{2} \hbar^3 U[e_1, e_1, e_1, f_1, f_1, f_1]\}$$

T1\$1 == T1\$2

True

- $\mathbf{0}(e^{\gamma l + \beta e} | le) = \mathbf{0}(e^{\gamma l + e^{\gamma} \beta e} | el),$
- $\mathbf{0}(e^{\gamma l + \beta f} | fl) = \mathbf{0}(e^{\gamma l + e^{\gamma} \beta f} | lf):$

```
NO_{(x:f|e)_i_l_j}[\mathbb{E}[\omega_-, L_-, Q_-]] := CF[\mathbb{E}[\omega, L, e^{\gamma} \alpha x_i + (Q /. x_i \to \theta) /. {\gamma \to \partial_{l_j} L, \alpha \to \partial_{x_i} Q}]]];
ANO_{(x:f|e)_i_l_j}[\mathbb{E}[\omega_-, L_-, Q_-]] := CF[\mathbb{E}[\omega, L, e^{-\gamma} \alpha x_i + (Q /. x_i \to \theta) /. {\gamma \to \partial_{l_j} L, \alpha \to \partial_{x_i} Q}]]];
```

$\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{ANO}_{e_2 l_3}$

$$\mathbb{E}\left[1, h_4 l_1 + h_6 l_3 + h_2 l_5, \frac{e^{-h_6} (-1 + e^{h_2})}{h_2} e_2 f_5 + \frac{(-1 + e^{h_4})}{h_4} e_4 f_1 + \frac{(-1 + e^{h_6})}{h_6} e_6 f_3\right]$$

$$\mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{ANO}_{e_2 l_3}, \{l_1, f_1, l_3, e_2, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] ==$$

$$\mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1]$$

True

$$\mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{ANO}_{e_2 l_3}, \{l_3, e_2\} \rightarrow 1] == \mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{e_2, l_3\} \rightarrow 1]$$

True

$$(\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{ANO}_{e_2 l_3} // \text{NO}_{e_2 l_3}) == \mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+]$$

True

- $\mathbf{0}(e^{\beta e + \alpha f + \delta e f} | fe) = \mathbf{0}(v e^{v(-\alpha \beta h + \beta e + \alpha f + \delta e f)} | ef),$ with $v = (1 + h\delta)^{-1}$:

```
NO_{f_i e_j \to k}[\mathbb{E}[\omega_-, L_-, Q_-]] := CF[
  \mathbb{E}[v \omega, L, v(-\alpha \beta h_k + \beta e_k + \alpha f_k + \delta e_k f_k) + (Q /. f_i | e_j \to \theta)]
  /. v \to (1 + h_k \delta)^{-1} /. {\alpha \to \partial_{f_i} Q /. e_j \to \theta, \beta \to \partial_{e_j} Q /. f_i \to \theta, \delta \to \partial_{f_i e_j} Q}
];
```

$\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{NO}_{f_3 e_4 \to 7}$

$$\mathbb{E}\left[1, h_4 l_1 + h_6 l_3 + h_2 l_5, \frac{1}{h_2 h_4 h_6} \left(\left((-1 + e^{h_4}) e_7 f_1 h_2 + (-1 + e^{h_2}) e_2 f_5 h_4\right) h_6 + (-1 + e^{h_6}) e_6 h_2 (f_7 h_4 - (-1 + e^{h_4}) f_1 h_7)\right)\right]$$

$$\mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // \text{NO}_{f_3 e_4 \to 7}, \{l_1, f_1, e_2, l_3, e_7, f_7, l_5, f_5, e_6\} \rightarrow 1] ==$$

$$\mathbf{0}[\mathbb{E}[X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_ \rightarrow h$$

True

The Stitching Formula

```
m_{i,j \to k}[_Z_] := Module[{x, z}, CF[(Z // NO_{f_i e_j \to x} // NO_{l_i e_x} // NO_{f_x l_j}) /. z_{-i|j|x} \to z_k]]]
```

$$\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1}$$

$$\mathbb{E} \left[1, h_4 l_1 + h_6 l_3 + h_1 l_5, \frac{1}{h_1 h_4 h_6} \right. \\ \left. \left((-1 + e^{h_6}) e_6 f_3 h_1 h_4 + \left((-1 + e^{h_4}) e_4 (f_1 - (-1 + e^{h_1}) f_5) h_1 + e^{h_4} (-1 + e^{h_1}) e_1 f_5 h_4 \right) h_6 \right) \right]$$

$$\mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1}, \{e_1, l_1, f_1, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] == \\ \mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_- \rightarrow h$$

True

$$\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}$$

$$\mathbb{E} \left[1, h_4 l_1 + h_6 l_1 + h_1 l_5, \frac{1}{h_1 h_4 h_6} \right. \\ \left. \left((-1 + e^{h_6}) e_6 f_1 h_1 h_4 + \left((-1 + e^{h_4}) e_4 (e^{h_6} f_1 - (-1 + e^{h_1}) f_5) h_1 + e^{h_4} (-1 + e^{h_1}) e_1 f_5 h_4 \right) h_6 \right) \right]$$

$$\mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1}, \{e_1, l_1, f_1, e_4, l_5, f_5, e_6\} \rightarrow 1] == \\ \mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_- \rightarrow h$$

True

$$\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1} // m_{1,4 \rightarrow 1}$$

$$\mathbb{E} \left[\frac{1}{1 + e^{h_6} (-1 + e^{h_1})}, h_6 l_1 + h_1 (l_1 + l_5), \right. \\ \left. \left((-1 + e^{h_6}) e_6 (f_1 + (-1 + e^{h_1})^2 f_5) h_1 + e^{h_1} (-1 + e^{h_1}) e_1 (e^{2h_6} f_1 + f_5) h_6 \right) / \left((1 - e^{h_6} + e^{h_1+h_6}) h_1 h_6 \right) \right]$$

$$\mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1} // m_{1,4 \rightarrow 1}, \{e_1, l_1, f_1, l_5, f_5, e_6\} \rightarrow 1] == \\ \mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_- \rightarrow h$$

True

$$\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1} // m_{1,4 \rightarrow 1} // m_{1,5 \rightarrow 1} // m_{1,6 \rightarrow 1}$$

$$\mathbb{E} \left[\frac{e^{-h_1}}{1 - e^{h_1} + e^{2h_1}}, 3 h_1 l_1, \frac{(-1 + e^{3h_1}) e_1 f_1}{h_1} \right]$$

$$\mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+] // m_{1,2 \rightarrow 1} // m_{1,3 \rightarrow 1} // m_{1,4 \rightarrow 1} // m_{1,5 \rightarrow 1} // m_{1,6 \rightarrow 1}, \{e_1, l_1, f_1\} \rightarrow 1] == \\ \mathbb{O} [\mathbb{E} [X_{4,1}^+ X_{2,5}^+ X_{6,3}^+], \{l_1, f_1, e_2, l_3, f_3, e_4, l_5, f_5, e_6\} \rightarrow 1] /. h_- \rightarrow h$$

True

The Main g_0 Theorem, Polished Version

Polished Version. With $\bar{e} = \frac{(e^h - 1)}{h} e$, the g_0 invariant of any S-component tangle T can be written in the form

$Z(T) = \mathcal{O}(\omega^{-1} e^{L + \omega^{-1} Q} \mid \prod_{i \in S} \bar{e}_i l_i f_i)$, where ω is a scalar (meaning, a **polynomial** in the variables $t_i = e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients a_{ij} and where $Q = \sum b_{ij} \bar{e}_i f_j$ is a balanced quadratic in the variables \bar{e}_i and f_j with scalar coefficients b_{ij} . Furthermore, after setting $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

Debt. Implement (and verify!).

Just a Computation

$$\text{With} \left[\left\{ \psi = v e^{(t e f - \alpha \beta h + \alpha f + \beta e)} \right. \right. \\ \left. \left. / . v \rightarrow (1 + t h)^{-1} \right\}, \text{Simplify} @ \left\{ \partial_t \psi - \partial_{\alpha, \beta} \psi, \psi \right. \right. \\ \left. \left. / . t \rightarrow \theta \right\} \right] \\ \left\{ \theta, e^{f \alpha + e \beta - h \alpha \beta} \right\}$$