

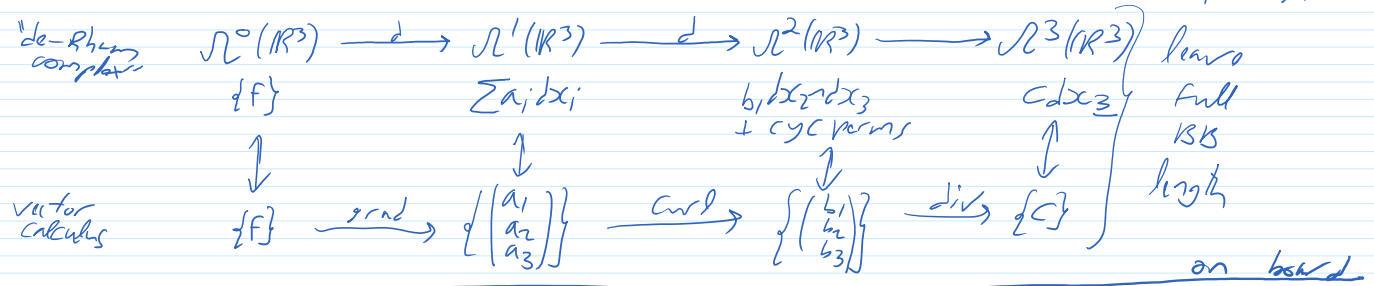
Dror Bar-Natan: Academic Pensieve: Classes: 1617-257b-AnalysisII:

1617-257 Wed Mar 29, hour 68: Stokes' theorem in low dimensions

February 15, 2017 12:58 PM

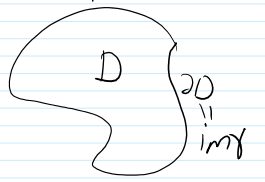
Read along: Sec 37-38. Eval rate: 28/93. HW18 due; HW19 (last!) on web by midnight. Makeup class tomorrow at 5PM at MP 134, video will be available

Thm If M^k is compact and oriented and $w \in \mathcal{L}^{k-1}(M)$, then $\int_M dw = \int_{\partial M} w$



Example. $M = [0,1]_x$, $w = f \implies \int_0^1 f' = f(1) - f(0)$

Example $M = D \subset \mathbb{R}^2$, $w = P dx + Q dy$, $dw = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy$



$$\int_{\partial D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy = \int_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy = \int_a^b (P(t) \dot{y}_1 + Q(t) \dot{y}_2) dt$$

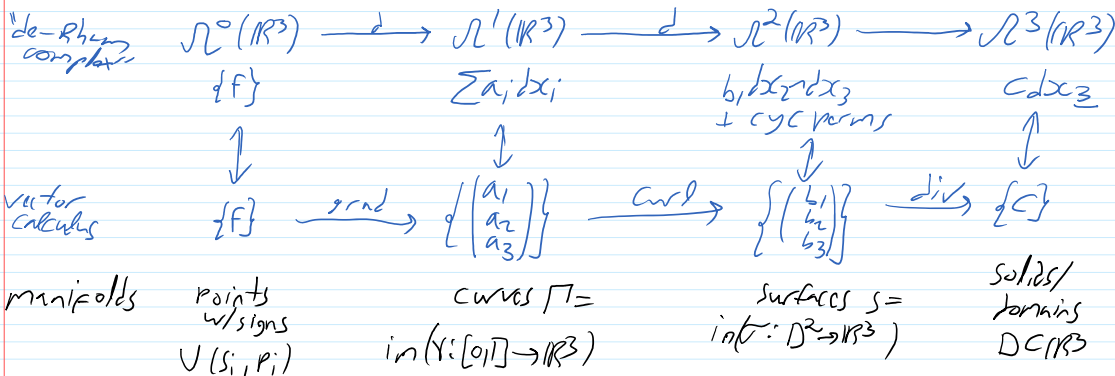
$\gamma: [a,b] \rightarrow \mathbb{R}^2 = \begin{pmatrix} x \\ y \end{pmatrix}$ "Green's theorem"

Let $F = \begin{pmatrix} Q \\ -P \end{pmatrix}$; get $\int_D \text{div}(F) = \int_D F_1 \dot{y}_2 - F_2 \dot{y}_1 = \int_a^b \begin{pmatrix} F_1 \\ F_2 \end{pmatrix} \cdot \begin{pmatrix} \dot{y}_2 \\ -\dot{y}_1 \end{pmatrix} = \int F \cdot \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \dot{\gamma} = \int F \cdot \vec{n}$ the divergence theorem.

Example: Use for $w = \frac{1}{2}(x dy - y dx)$

Example: The Planimeter.

Continue in \mathbb{R}^3 :



integration

$$\int_M w$$

$$\sum S_i f(p_i)$$

$$\int_0^1 \vec{x} \cdot \dot{\gamma} = \int_n \vec{x} \cdot \vec{T} dV$$

$$\int_S b \cdot \vec{n} dV$$

$$\int_C$$

ch. 12.1

Stokes'

Stokes'

done line

↑
Stokes:

$$\int_0^1 (\text{grad } f) \cdot \dot{\gamma} = f(\gamma(1)) - f(\gamma(0))$$

Stokes:

$$\int_S (\text{curl } a) \cdot \vec{n} \, dV = \int_{\partial S} \vec{a} \cdot \vec{T} \, dV$$

Stokes:

$$\int_D \text{div } b = \int_{\partial D} b \cdot \vec{n} \, dV$$

Aside

$$\begin{aligned} \sigma^*(b_1 dx_2 dx_3 + \text{cyclic perms}) &= \left(b_1 dx_2 dx_3 \left(\frac{\partial x_1}{\partial x_2} \sigma_1, \frac{\partial x_1}{\partial x_3} \sigma_2 \right) + \text{c.p.} \right) dx_1 dy_1 \\ &= (b_1 (\partial_x \sigma_2 - \partial_y \sigma_3) + \text{c.p.}) dx_1 dy_1 = b \cdot [(\partial_x \sigma) \times (\partial_y \sigma)] dx_1 dy_1 = b \cdot \vec{n} \cdot \text{Vol}(\partial_x \sigma, \partial_y \sigma) \end{aligned}$$