

1617-257 Fri Jan 6, Hour 37: Back to the 257 atmosphere, volumes

December 5, 2016 8:56 AM

(nothing on TT2)

Agenda: Get back to the 257 atmosphere.

Read along: Re-read sections 16-20, esp. 20.

Riddle along: Is there a distance-decreasing function  $f: [0,1]^2 \rightarrow \mathbb{R}^2$  (meaning,  $d(f(x), f(y)) < d(x, y)$ , using the Euclidean metric) such that  $\text{length}(Bd(f([0,1]^2))) > 4$ ?

Thm given  $(A) \xrightarrow{g} (B) \xrightarrow{f} \mathbb{R}^k, \int_B f = \int_A (f \circ g) \cdot |\det Dg|$

Corollary. Let  $P(v_1, \dots, v_n)$  be the parallelepiped in  $\mathbb{R}^n$  spanned by  $v_1, \dots, v_n$ :

$$P(v_1, \dots, v_n) = \{ \sum a_i v_i : 0 \leq a_i \leq 1 \}$$

Geometric interp.

Then  $\text{vol}(P(v_1, \dots, v_n)) = |\det(v_1 | \dots | v_n)|$  of det's  $\nabla$  on board

Proof of corollary. Let  $g: \mathbb{R}_x^n \rightarrow \mathbb{R}_y^n$  be  $g(x_1, \dots, x_n) = \sum x_i v_i$ . Then  $Dg = g$

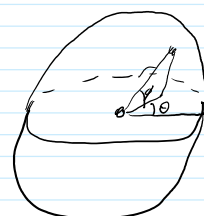
so  $|\det Dg| = |\det(v_1 | \dots | v_n)|$ . Also,  $P(v_1, \dots, v_n) = g([0,1]^n)$  so

$$\text{vol}(P(v_1, \dots, v_n)) = \int_{P(v_1, \dots, v_n)} 1 = \int_{[0,1]^n} |\det(v_1, \dots, v_n)| = |\det(v_1 | \dots | v_n)|. \quad \square$$

Exercise. Compute the volume of  $B^3 = \{x \in \mathbb{R}^3 : |x| \leq 1\}$ .

Sol'n use  $g(r, \theta, \phi) = (r \cos \theta \cos \phi, r \sin \theta \cos \phi, r \sin \theta)$

$$J = \begin{vmatrix} \cos \theta \cos \phi & -r \sin \theta \cos \phi & -r \cos \theta \sin \phi \\ \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta & 0 & r \cos \theta \end{vmatrix} = \sin^2 \theta \cos \phi \cdot r^2 + r \cos^3 \theta \cdot r = r^3 \cos \theta$$



$\theta$ : longitude [east-west]  
 $\phi$ : latitude [north-south]  
 Toronto = (67.1, 79, 43)

$$\text{So } \text{vol}(B^3) = \int_0^1 dr \int_0^{2\pi} d\theta \int_{-\pi/2}^{\pi/2} d\phi r^3 \cos \theta = \int_0^1 r^3 dr \cdot 4\pi = \frac{4}{3}\pi$$

Def:  $h: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is an "isometry" if  $\forall x, y \quad d(h(x), h(y)) = d(x, y)$  (Euc)

Thm  $h$  is an isometry iff it is of the form

$$h(x) = p + Ax, \text{ where } A \in M_{nn} \text{ satisfies } A^T A = I$$

Comments 1. Such  $h$  is "volume preserving".

2. Such  $h$  is a "rotation followed by translation".

done line

[A l.t. is a "rotation" if  $A^T A = I$ ; alt., if it is "orthogonal", meaning its columns form an "orthonormal basis"]

3. Rotation matrices  $O(n) := \{A: A^T A = I\}$  form a "group":

0.  $A, B \in O(n) \Rightarrow A \cdot B \in O(n)$ .

1.  $(AB)C = A(BC)$

$$2. \exists I \in O(n) \text{ s.t. } AI = IA = A.$$

$$3. \forall A \in O(n) \exists B \in O(n) \text{ } AB = BA = I \quad [\text{use, e.g. } \det(A) = \pm 1]$$

proof of thm  $\Leftarrow$ : easy (though write in full...;  $\|x\|^2 = x^T \cdot x$ ...)

$\Rightarrow$  steps: 1. WLOG,  $h(0) = 0$ .

2.  $h$  preserves norms.

3. using  $\|x+y\|^2 = \dots$ ,  $h$  preserves dot products.

4. set  $A = (h(e_1) | \dots | h(e_n))$ ; then  $A \in O(n)$ .

5. claim  $h(\sum x_i e_i) = \sum x_i h(e_i)$  so  $h(x) = Ax$

pf Let  $\Delta = h(\sum x_i e_i) - \sum x_i h(e_i)$ . Then  $\langle \Delta, h(e_j) \rangle = 0$ ,

so  $\Delta A e_j = 0$  so  $\Delta A = 0$  so  $\Delta = 0$ .