

HW6 on web!

Reminders  $\mathfrak{g}$ : metrized f.d. Lie algebra,  $R$ : Representation thereof.

Thm  $\exists W_{\mathfrak{g}, R}: \mathfrak{A} \rightarrow \mathbb{F}$

$$\mathfrak{g} = \langle X_\alpha \rangle_{\alpha=1}^{\dim \mathfrak{g}} \quad R = \langle e_\alpha \rangle_{\alpha=1}^{\dim R}$$

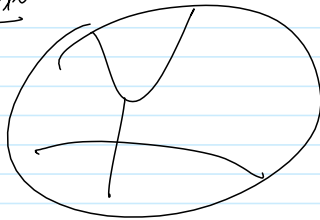
$$[X_\alpha, X_\beta] = f_{\alpha\beta}^\gamma X_\gamma \quad \langle X_\alpha, X_\beta \rangle = t_{\alpha\beta} \quad t_{\alpha\beta} t^{\beta\gamma} = \delta_\alpha^\gamma$$

$$X_\alpha e_\beta = \rho_\alpha^\beta e_\beta$$

$$f_{\alpha\beta\gamma} = \langle [X_\alpha, X_\beta], X_\gamma \rangle = f_{\alpha\beta}^\delta t_{\delta\gamma}$$

on  
board

Example



Thm This is well defined on diag.

- PF 1. Phys way.
- 2. Tens. calc. way.
- 3. hands on.

Thm Satisfies AS, IHX, STU.

done  
line.

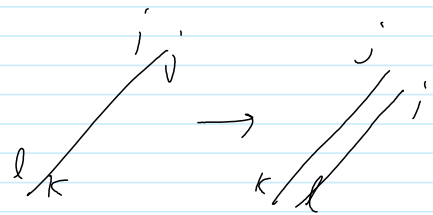
The glw calculation  $a \leftrightarrow (ij)$

$$X_{ij} = i \begin{pmatrix} & & j \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \end{pmatrix} \quad X_{ij} X_{kl} = \delta_{jk} X_{il}$$

$$[X_{ij}, X_{kl}] = \delta_{jk} X_{il} - \delta_{il} X_{kj}$$

$$t_{(ij)(kl)} = \text{tr } X_{ij} X_{kl} = \delta_{jk} \delta_{il}$$

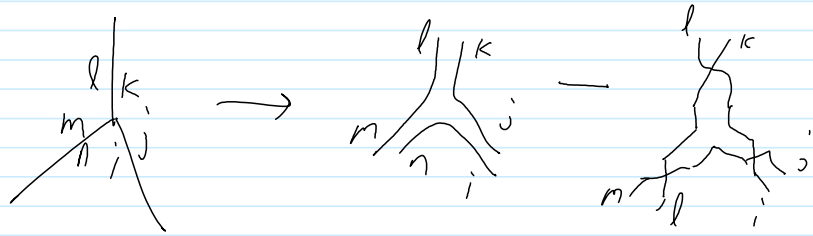
$f_{(ij)(kl)} = \text{same}$ , indeed



$$t_{ij,kl} t^{kl,mn} = \sum_{k,l} \delta_{jk} \delta_{il} \delta^{kn} \delta^{lm} = \delta_{jn} \dim$$

$$F_{ii,kl,mn} = \langle [X_{ii}, X_{kl}], X_{mn} \rangle = \langle \delta_{ik} X_{il} - \delta_{il} X_{ki}, X_{mn} \rangle$$

$$= d_{jk} f_{lm} d_{in} - d_{il} d_{jm} d_{kn}$$



$$r_{(ij)k}^l = d_{jk} f_i^l$$

