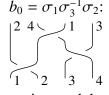
A NOTE ON THE UNITARITY PROPERTY OF THE GASSNER INVARIANT

DROR BAR-NATAN

ABSTRACT. We give a 3-page description of the Gassner invariant / representation of braids / pure braids, along with a description of its unitarity property.

The unitarity of the Gassner representation [Ga] of the pure braid group was discussed by many authors (e.g. [Lo, Ab, KLW]) and from several points of view, yet without exposing how utterly simple the formulas turn out to be. When the present author needed quick and easy formulas, he couldn't find them. This note is written in order to rectify this situation. I was heavily influenced by a similar discussion of the unitarity of the Burau representation in [KT, Section 3.1.2].

Let *n* be a natural number. The braid group B_n on *n* strands is the group with $b_0 = \sigma_1 \sigma_3^{-1} \sigma_2$: generators σ_i , for $1 \le i \le n$ thank with relations $\sigma_i \sigma_j = \sigma_j \sigma_i$ when |i - j| > 1 and $\sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1}$ when $1 \le i \le n-2$. The standard way to depict braids, namely elements of B_n , appears on the right. Braids are made of strands that are indexed 1 through n at the bottom. The generator σ_i denotes a positive crossing



between the strand at position #i as counted just below the horizontal level of that crossing, and the strand just to its right. Note that with the strands indexed at the bottom, the two strands participating in a crossing corresponding to σ_i may have arbitrary indices, depending on the permutation induced by the braids below the level of that crossing.

Let t be a formal variable and let $U_i(t) = U_{n,i}(t)$ denote the $n \times n$ identity matrix with its 2×2 block at rows i and i+1 and columns i and i+1 replaced by $\begin{pmatrix} 1-t & 1 \\ t & 0 \end{pmatrix}$. Let $U_i^{-1}(t)$ be the inverse of $U_i(t)$; it is the $n \times n$ identity matrix with the block at $\{i, i+1\} \times \{i, i+1\}$ $U_{5,3}(t) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1-t & 1 & 0 \\ 0 & 0 & t & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

$$U_{5,3}(t) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 - t & 1 & 0 \\ 0 & 0 & t & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

replaced by $\begin{pmatrix} 0 & \bar{t} \\ 1 & 1 - \bar{t} \end{pmatrix}$, where \bar{t} denotes t^{-1} .

Given a braid $b = \prod_{\alpha=1}^k \sigma_{i_\alpha}^{s_\alpha}$, where the s_α are signs and where products are taken from left to right. Let j_α be the index of the "over" strand at crossing $\#\alpha$ in b. The Gassner invariant $\Gamma(b)$ of b is given by the formula on $\Gamma(b) := \prod_{\alpha=1}^k U_{i_\alpha}^{s_\alpha}(t_{j_\alpha})$.

$$\Gamma(b) \coloneqq \prod_{\alpha=1}^k U_{i_\alpha}^{s_\alpha}(t_{j_\alpha}).$$

It is a Laurent polynomial in *n* formal variables t_1, \ldots, t_n , with coefficients in \mathbb{Z} .

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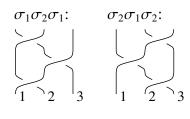
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¹Partially this is because the formulas are simplest when extended a "Gassner invariant" defined on the full braid group, but then it is not a representation and it is not unitary. Yet it has an easy "unitarity property"; see below.

For example, $\Gamma(\sigma_1\sigma_2\sigma_1) = U_1(t_1)U_2(t_1)U_1(t_2)$ while $\Gamma(\sigma_2\sigma_1\sigma_2) =$ $U_2(t_2)U_1(t_1)U_2(t_1)$. The equality of these two matrix products constitutes the bulk of the proof of the well-definedness of Γ , and the rest is even easier. The verification of this equality is a routine exercise. Impatient readers may find it in the Mathematica notebook that accompanies this note, [BN].



A second example is the braid b_0 of the first figure. Here and in [BN],

$$\Gamma(b_0) = U_1(t_1)U_3^{-1}(t_4)U_2(t_1) = \begin{pmatrix} 1 - t_1 & 1 - t_1 & 1 & 0 \\ t_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \bar{t_4} \\ 0 & t_1 & 0 & 1 - \bar{t_4} \end{pmatrix}$$

Given a permutation $\tau = [\tau 1, \dots, \tau n]$ of $1, \dots, n$, let Ω_{τ} be the triangular $n \times n$ matrix shown on the right $(\frac{1}{1-t_{\tau i}})$ on the diagonal, $\Omega_{\tau} := \begin{pmatrix} \frac{1}{1-t_{\tau 1}} & 0 & \cdots & 0 \\ 1 & \frac{1}{1-t_{\tau 2}} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \cdots & \frac{1}{1-t_{\tau 2}} \end{pmatrix}$

$$\Omega_{\tau} := \begin{pmatrix} \frac{1}{1-t_{\tau_1}} & 0 & \cdots & 0 \\ 1 & \frac{1}{1-t_{\tau_2}} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \cdots & \frac{1}{1-t_{\tau_n}} \end{pmatrix}$$

Theorem. Let b be a braid that induces a strand permutation $\tau =$ $[\tau 1, \dots, \tau n]$ (meaning, the strand indices that appear at the top of b are $\tau 1, \tau 2, \dots, \tau n$). Let $\gamma = \Gamma(b)$ be the Gassner invariant of b. Then γ satisfies the "unitarity property"

(1)
$$\Omega_{\tau} \gamma^{-1} = \bar{\gamma}^{T} \Omega_{\iota}, \quad \text{or equivalently,} \quad / \gamma^{-1} = \Omega_{\tau}^{-1} \bar{\gamma}^{T} \Omega_{\iota},$$

where $\bar{\gamma}$ is γ subject to the substitution $\forall i \, t_i \rightarrow \bar{t_i} := t_i^{-1}$, and $\bar{\gamma}^T$ is the transpose matrix of $\bar{\gamma}$. *Proof.* A direct and simple-minded computation for $b = \sigma_i$ and for $b = \sigma_i^{-1}$, namely for $\gamma = U_i(t_i)$ and for $\gamma = U_i^{-1}(t_{i+1})$ (impatient readers see [BN]), and then, clearly, using the second form of Equation (1), the statement generalizes to products with all the intermediate $\Omega_{\tau}^{-1}\Omega_{\tau}$ pairs cancelling out nicely.

If the Gassner invariant Γ is restricted to pure braids, namely to braids that induces the identity permutation, it becomes multiplicative and then it can be called "the Gassner representation" (in general Γ can be recast as a homomorphism into $M_{n \times n}(\mathbb{Z}[t_i, \bar{t}_i]) \times S_n$, where S_n acts on matrices by permuting the variables t_i appearing in their entries).

For pure braids $\Omega_{\tau} = \Omega_{t}$ and hence by conjugating (in the $t_{i} \rightarrow 1/t_{i}$ sense) and transposing Equation (1) and replacing γ by γ^{-1} , we find that the theorem also notes it is replaced with Ω , and hence also with $\Omega + \bar{\Omega}^T$, which is formally Hermitian. Extended the configuration of Ω with Ω is an inversion in the same as complex that the tries are specialized to complex numbers of unit norm there inversion is the same as complex that the replacement of Ω is dominated by its main diagonal than Ω .

conjugation. If also the t_i 's are sufficiently close to 1, then Ω is dominated by its main diagonal which is real and large, and hence it is positively definite and genuinely Hermitian. Thus in that case, the Gassner representation is unitary in the standard sense of the word, relative to the inner

product on Comment represents the Comment Representation of the Co

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i(iy) - i(iy) = -y - y = -2y

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[Lo] D. D. Long, *On the Linear Representation of Braid Groups*, Transactions of the American Mathematical Society **311-2** (1989) 535–560.

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Re(1-+) = Re(1-+)

= 1-605d (605a-1)2+sin2x

 $=\frac{1-652}{2-2652}=\frac{1}{2}$

A. Our closing remark is that the bassner representation easily extends to prove w-brands (e.g. [...]), by setting of Utility and whom Violty where the service of the service of the service of the service of the virturity majority of this note, and I'd he very surprised it it is unitary



Pensieve header: Mathemaica notebook accompanying "A Note on the Unitarity Property of the Gassner Invariant" by Dror Bar-Natan, http://drorbn.net/AcademicPensieve/2014-06/UnitarityOf-Gassner/...

Definitions.

$$\label{eq:Ui_[t_]} \begin{split} & \text{U}_{i_{-}}[t_{-}] := \text{ReplacePart}[\\ & \text{IdentityMatrix}[n] \,, \\ & \{\{i,\,i\} \to 1-t, \ \{i,\,i+1\} \to 1, \\ & \{i+1,\,i\} \to t, \ \{i+1,\,i+1\} \to 0\} \end{split}$$

$$Uinv_{j}[t_{-}] := Inverse[U_{i}[t]];$$
 $\Omega_{t_{-}} := Table$

Which
$$[i < j, 0, i = j, \frac{1}{1 - t_{\tau[i]}}, i > j, 1],$$

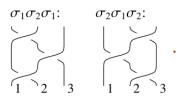
$$\{i, n\}, \{j, n\}\];$$

 $\overline{X}_{\underline{X}_{\underline{I}}} := X /. t_{i_{\underline{I}}} \Rightarrow 1 / t_{i};$

n = 3; MatrixForm /@ Simplify /@ $\{\Omega_{\{2,3,1\}}, \text{ Inverse}[\Omega_{\{2,3,1\}}]\}$

$$\left\{ \left(\begin{array}{cccc} \frac{1}{1-t_2} & 0 & 0 \\ 1 & \frac{1}{1-t_3} & 0 \\ 1 & 1 & \frac{1}{1-t_1} \end{array} \right), \left(\begin{array}{ccccc} 1-t_2 & 0 & 0 \\ -\left(-1+t_2\right)\left(-1+t_3\right) & 1-t_3 & 0 \\ -\left(-1+t_1\right)\left(-1+t_2\right) t_3 & -\left(-1+t_1\right)\left(-1+t_3\right) & 1-t_1 \end{array} \right) \right\}$$

The R3 move



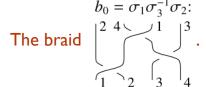
 $\label{eq:n_simplify} n = 3 \text{; } \texttt{MatrixForm /@ Simplify /@ } \{ \texttt{U}_1[\texttt{t}_1] . \texttt{U}_2[\texttt{t}_1] . \texttt{U}_1[\texttt{t}_2] \text{, } \texttt{U}_2[\texttt{t}_2] . \texttt{U}_1[\texttt{t}_1] . \texttt{U}_2[\texttt{t}_1] \}$

$$\left\{ \left(\begin{array}{cccc} 1-t_1 & 1-t_1 & 1 \\ -t_1 & (-1+t_2) & t_1 & 0 \\ t_1 & t_2 & 0 & 0 \end{array} \right), \; \left(\begin{array}{cccc} 1-t_1 & 1-t_1 & 1 \\ -t_1 & (-1+t_2) & t_1 & 0 \\ t_1 & t_2 & 0 & 0 \end{array} \right) \right\}$$

The unitarity property for the generators.

 $n = 5; \gamma = U_3[t_3];$

n = 5; $\gamma = Uinv_3[t_4]$;



n = 4; MatrixForm[$\gamma_0 = U_1[t_1].Uinv_3[t_4].U_2[t_1]$]

$$\begin{pmatrix} 1-t_1 & 1-t_1 & 1 & 0 \\ t_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{t_4} \\ 0 & t_1 & 0 & -\frac{1-t_4}{t_4} \end{pmatrix}$$

The unitarity property for b_0 .

MatrixForm /@ Simplify /@ $\{\Omega_{\{2,4,1,3\}}$.Inverse $[\gamma_0]$, Transpose $[\overline{\gamma_0}]$. $\Omega_{\{1,2,3,4\}}$