

Basic idea: Motivated by
Gopakumar-Vafa & Onguri-Vafa:

(knot invariants) \Leftrightarrow GW-type invariants.

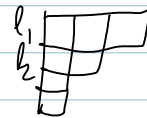
integrity props of knot invariants \Leftrightarrow integrity properties
of GW invariants
of BPS invariants

Group theoretical ingredients

R : irrep of S_l (symmetric group on l elements)

\Leftrightarrow Young diagram w/ l boxes

$\Leftrightarrow \{l_i\}_{i=1}^r(R)$



$$l(R) = \sum_{i=1}^{r(R)} l_i \quad K_R = \sum_{i=1}^{r(R)} l_i(l_i - 2i + 1)$$

Generating functions for coloured objects:

SYMMETRIC POLYNOMIALS in infinite

number of variables $\{v_i\}_{i \geq 1}$

basis: Schur Polynomials $S_R(v)$

$$V = \begin{pmatrix} v_1 & & \\ & \ddots & \\ & & v \end{pmatrix} \quad S_R(v) = \text{tr}_R V$$

Examples $S_{\square}(V) = \sum V_i$

$$S_{\square\square}(V) = \frac{1}{2}(\text{tr} V)^2 + \frac{1}{2}\text{tr} V^2 = \sum_{i \geq 1} \frac{1}{2} V_i^2 + \sum_{i < j} \frac{1}{2} V_i V_j$$

$$S_{\square\text{H}}(V) = \frac{1}{2}(\text{tr} V)^2 - \frac{1}{2}\text{tr} V^2$$

Composite representations (R_1, R_2) pairs of Young tableaux think using $V(N)$:

$$S_{R_1}(V) S_{R_2}(V) = \sum N_{R_1, R_2}^R S_R(V)$$

Littlewood-Richardson coeffs,

$$\text{also } R_1 \otimes R_2 = \sum N_{R_1, R_2}^R \cdot R$$

$$(R, S) = \sum_{UVW} (-1)^{l(u)} N_{UV}^R N_{UTW}^S V \otimes \bar{W}$$

complex conjugate

↑
Flip rows & columns

$$= R \otimes S + \text{lower (fewer boxes) corrections}$$

coloured HOMFLY Consider an oriented link L with projection D_L .

The skein of the plane is link diagrams mod skein relations: (variables t & u)



$$\begin{array}{c}
 \nearrow \nearrow - \nwarrow \nwarrow = (t - t^{-1}) \uparrow \uparrow \\
 \uparrow \rho = u \quad \uparrow \quad \uparrow \rho = u^{-1} \quad \uparrow
 \end{array}$$

under this, $D_L = \langle D_L \rangle \odot$

$$P_L(t, u) = u^{-\bar{w}(D_L)} \langle D_L \rangle$$


$\bar{w}(D_L) = \text{self-writhe} = \sum^{\text{of signs}} \text{over crossings}$
of a component w/ itself.

\Rightarrow differs from the standard def of HOMFLY by a factor $u^{2(\text{total linking number})}$

The HOMFLY invariant:

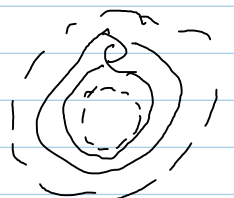
$$\mathcal{H}(L) = P_L(u, t) \mathcal{H}(O) \quad \text{with } \mathcal{H}(O) = \frac{v - v^{-1}}{t - t^{-1}}$$

Higher reps: (use satellites)

$K = \text{framed knot} = \text{a knotted annulus}$ 

$p = \text{knot drawn in the annulus}$

$K * p$: the p -satellite of K .



Skew of the annulus: there is a basis labeled by composite reps (R, S)

$$\Rightarrow P_{(R, S)}$$

can be generalized to n components

Define

$$\mathcal{H}_{(R, S)}(K) = \mathcal{H}(K * P_{(R, S)})$$

Examples

$$P_{\square} = \uparrow$$

$$P_{\square} = \frac{1}{1+t^2} \left(\uparrow \uparrow + \uparrow \downarrow \right)$$

$$P_{\square} = \frac{1}{1+t^2} \left(\uparrow \uparrow - t \uparrow \downarrow \right)$$

$$P_{(\square, \square)} = \uparrow \downarrow - 1$$

properties

1. Orientation: $P_{(R, S)} \rightarrow P_{(S, R)}$

$$\mathcal{H}_{(R, S)}(K) = \mathcal{H}_{(S, R)}(\bar{K})$$

Similarly for reversing an individual component.

2. This is the same as colored-Hopf algebras as it comes from quantum groups, under

Some change of variables:

$$t = q^{1/2} \quad u = q^{1/2}$$

$$\mathcal{H}_R(\mathbb{C}^{\curvearrowright}) = \dim_q(R)$$

Kauffman Invariant Unoriented diags in the plane, modulo

$$\begin{array}{c} \diagdown \\ \diagup \end{array} - \begin{array}{c} \diagup \\ \diagdown \end{array} = (t - t^{-1}) \left(\begin{array}{c} \diagdown \\ \diagup \end{array} \right) \left(\begin{array}{c} \diagup \\ \diagdown \end{array} \right)$$

$$\left(\begin{array}{c} | \\ \rho = v \end{array} \right) \quad \left(\begin{array}{c} \cup \\ | \\ \cup = v^{-1} \end{array} \right)$$

Let L be an unoriented link w/ plane diagram E_L , set $F_L = \langle E_L \rangle \circ$

$$F_L(t, v) = v^{-w(E_L)} \langle E_L \rangle$$

"the Kauffman poly"

$$g(L) = F_L \cdot g(\circ) = 1 + \frac{v - v^{-1}}{t - t^{-1}}$$

There is a similar procedure for the coloured Kauffman - Skein of annulus

has a basis also labeled by Young tableaux
(Beliaikova-Blanchet)

$$\mathcal{O}_R(0) = q^{\dim R} \text{ in } U_q(\mathfrak{so}(N))$$

$$t = q^{1/2} \quad v = t^{N-1}$$

Examples



$$z = t - t^{-1}$$

$$P_{3,1}(t, v) = 2v^2 - v^4 - z^2 v^2$$

$$F_{3,1}(t, v) = 2v^2 - v^4 + z(-v^3 + v^5) + z^2(v^2 - v^4)$$