

Pensieve header: Images for <http://www.math.toronto.edu/~drorbn/Talks/Toronto-1303/>.

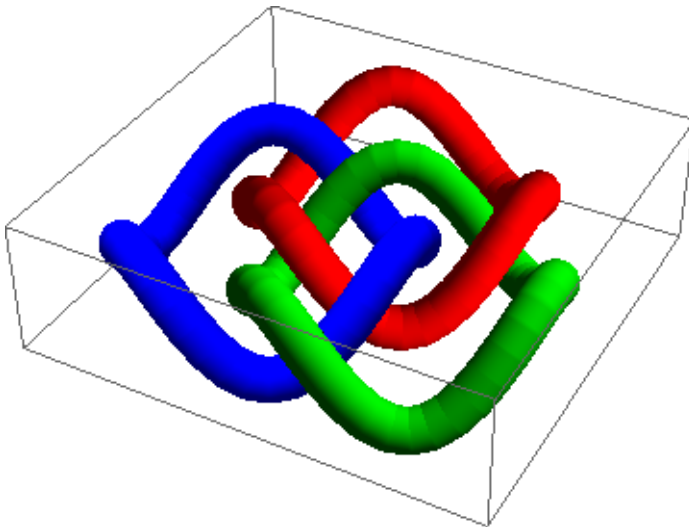
The Borromean Tangle

Formulas from <http://paulbourke.net/geometry/borromean/>

```
SetDirectory["C:\\drorbn\\AcademicPensieve\\2013-03"]
```

```
C:\\drorbn\\AcademicPensieve\\2013-03
```

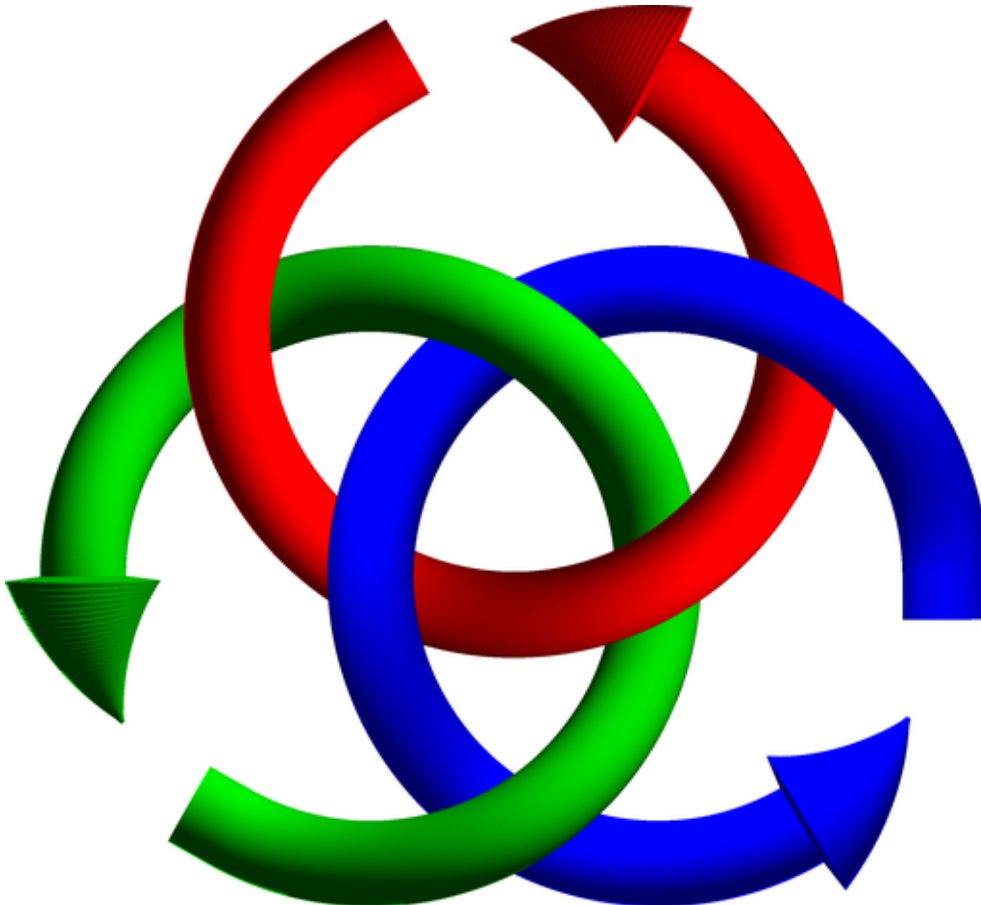
```
r = N[Sqrt[3] / 3];
{s1, s2, s3} = Table[
  {
    {Cos[u], Sin[u] + r, Cos[3 u] / 3},
    {Cos[u] + 0.5, Sin[u] - r / 2, Cos[3 u] / 3},
    {Cos[u] - 0.5, Sin[u] - r / 2, Cos[3 u] / 3}
  },
  {u, 0., 2 Pi, 2 Pi / 48}
] // Transpose;
Rasterize[Graphics3D[{
  {Red, Tube[s1, 0.15]},
  {Green, Tube[s2, 0.15]},
  {Blue, Tube[s3, 0.15]}
}]]
```



```

SetOptions[Rasterize, {RasterSize → 800, ImageSize → 800}];
rr = N[ $\sqrt{3} / 3$ ]; du =  $\pi / 192.$ ;
s1 = Table[{Cos[u], Sin[u] + rr, -Cos[3 u] / 6}, {u, 4  $\pi$  / 6, 15  $\pi$  / 6, du}];
s2 = Table[{Cos[u] + 0.5, Sin[u] - rr / 2, -Cos[3 u] / 6}, {u, 12  $\pi$  / 6, 23  $\pi$  / 6, du}];
s3 = Table[{Cos[u] - 0.5, Sin[u] - rr / 2, -Cos[3 u] / 6}, {u, 8  $\pi$  / 6, 19  $\pi$  / 6, du}];
L = Length[s1];
rs = Table[Which[
  k > L / 11, 0.15,
  k ≤ L / 11, 3 k / L
], {k, L, 1, -1}];
gg = Graphics3D[{CapForm["Square"],
  {Red, Tube[s1, rs]},
  {Blue, Tube[s2, rs]},
  {Green, Tube[s3, rs]}
},
  Boxed → False, ViewPoint → {0, 0, Infinity}];
MakeImage["BorromeanTangle", gg]

```



Trees

```
SetDirectory["C:\\drorbn\\AcademicPensieve\\2013-03"];
<< FreeLie.m
```

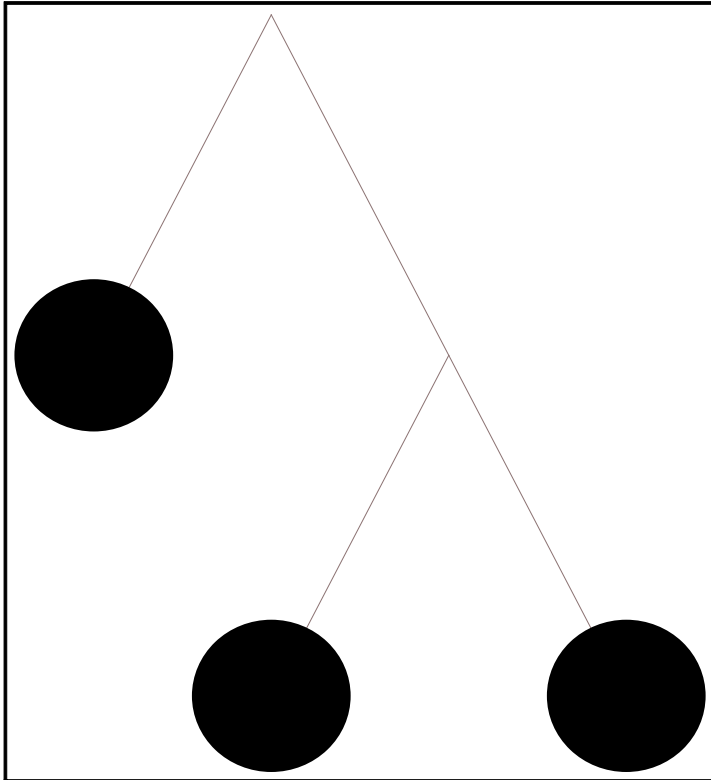
$$\begin{aligned}
 \text{trees} = \text{LS} \left[0, \langle "bg" \rangle, \frac{\langle "bbg" \rangle}{2} + \frac{\langle "bgg" \rangle}{2} + \langle "bgr" \rangle, \right. \\
 \frac{\langle "bbbg" \rangle}{6} + \frac{\langle "bbgg" \rangle}{4} + \frac{\langle "bbgr" \rangle}{2} + \frac{\langle "bggg" \rangle}{6} + \frac{\langle "bggr" \rangle}{2} + \frac{\langle "bgrr" \rangle}{2}, \\
 \frac{\langle "bbbbg" \rangle}{24} + \frac{\langle "bbbgg" \rangle}{12} + \frac{\langle "bbbgr" \rangle}{6} - \frac{\langle "bbgbg" \rangle}{12} + \frac{\langle "bbggg" \rangle}{12} + \\
 \frac{\langle "bbggr" \rangle}{4} - \langle "bbgrg" \rangle + \frac{\langle "bbgrr" \rangle}{4} - 2 \langle "bbrgg" \rangle + \frac{\langle "bgbgg" \rangle}{2} - \langle "bgbrg" \rangle + \\
 \left. \frac{\langle "bgggg" \rangle}{24} + \frac{\langle "bgggr" \rangle}{6} + \frac{\langle "bgrrr" \rangle}{4} - \frac{\langle "bgrgr" \rangle}{2} + \frac{\langle "bgrrr" \rangle}{6} \right];
 \end{aligned}$$

```
t1 = Series[
  (List@@trees /. w_LW => B@@Reverse[LyndonFactorization[w]] /. B[s_] => s /.
    t_B => Tree[t]).h^Range[Length[trees]],
  {h, 0, Length[trees]}
] /. {"r" -> r, "g" -> g, "b" -> b}
```

$$\begin{aligned}
 \text{Tree}[B[g, b]] h^2 + \\
 \frac{1}{2} (\text{Tree}[B[g, B[g, b]]] + 2 \text{Tree}[B[B[0.57735, g], b]] + \text{Tree}[B[B[g, b], b]]) h^3 + \\
 \frac{1}{12} (2 \text{Tree}[B[g, B[g, B[g, b]]]] + 6 \text{Tree}[B[B[0.57735, B[0.57735, g]], b]] + \\
 3 \text{Tree}[B[B[g, B[g, b]], b]] + 6 \text{Tree}[B[B[B[0.57735, g], b], b]] + \\
 6 \text{Tree}[B[B[B[0.57735, g], g], b]] + 2 \text{Tree}[B[B[B[g, b], b], b]]) h^4 + \\
 \frac{1}{24} (\text{Tree}[B[g, B[g, B[g, B[g, b]]]]] - 12 \text{Tree}[B[B[0.57735, g], B[B[0.57735, g], b]]] + \\
 4 \text{Tree}[B[B[0.57735, B[0.57735, B[0.57735, g]]], b]] - \\
 2 \text{Tree}[B[B[g, b], B[B[g, b], b]]] - 24 \text{Tree}[B[B[g, B[0.57735, b]], B[g, b]]] - \\
 48 \text{Tree}[B[B[g, B[g, B[0.57735, b]]], b]] + 2 \text{Tree}[B[B[g, B[g, B[g, b]]], b]] - 24 \\
 \text{Tree}[B[B[g, B[B[0.57735, g], b]], b]] + 12 \text{Tree}[B[B[B[0.57735, g], b], B[g, b]]] + \\
 6 \text{Tree}[B[B[B[0.57735, B[0.57735, g]], b], b]] + \\
 6 \text{Tree}[B[B[B[0.57735, B[0.57735, g]], g], b]] + 2 \text{Tree}[B[B[B[g, B[g, b]], b], b]] + \\
 4 \text{Tree}[B[B[B[B[0.57735, g], b], b], b]] + 6 \text{Tree}[B[B[B[B[0.57735, g], g], b], b]] + \\
 4 \text{Tree}[B[B[B[B[0.57735, g], g], g], b]] + \text{Tree}[B[B[B[B[g, b], b], b], b]]) h^5 + O[h]^6
 \end{aligned}$$

```
t = {x, {x, y}}
{x, {x, y}}
```

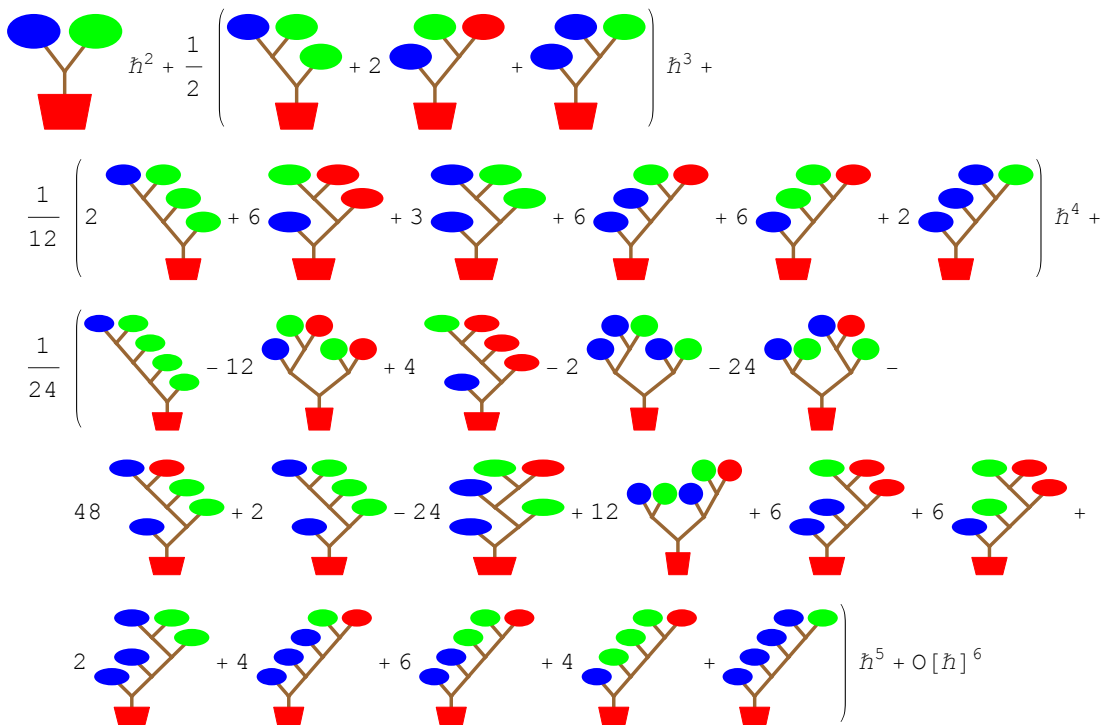
```
Framed[TreeForm[t,  
  VertexRenderingFunction -> (If[#2 === List, {},  
    {  
      Text[ToString[#2], #1],  
      Disk[#1, 0.2]  
    }  
  ] &),  
  PlotRangePadding -> 0  
]]
```



```

t1 /. t_Tree => TreeForm[t,
  VertexRenderingFunction -> (Switch[#2,
    Tree, {
      Red,
      Polygon[
        {{-0.4, 0.4} - #1, {0.4, 0.4} - #1, {0.3, -0.4} - #1, {-0.3, -0.4} - #1}
      ],
      B, {},
      _, {
        ReleaseHold[#2 /. {r -> Red, g -> Green, b -> Blue}],
        Disk[-#1, 0.4]
      }
    ] &),
  EdgeRenderingFunction -> ({
    Brown, Thickness[0.03],
    Line[-#]
  } &),
  PlotRangePadding -> 0, ImageSize -> 60, AspectRatio -> 1
]

```



Wheels

```
data = CWS[0, 0, 2 CW["bgr"],
  CW["bbgr"] - CW["bgbr"] + CW["bggr"] - CW["bgrg"] + CW["bgrr"] - CW["brgr"],
  CW["bbbgr"] - CW["bbgbr"] + CW["bbggr"] - CW["bbgrg"] + CW["bbgrr"] +
  CW["bbrbg"] - 3 CW["bbrgr"] + CW["bgbrr"] - 3 CW["bggbr"] +
  CW["bgggr"] - CW["bggrg"] + CW["bggrr"] + CW["bgrgg"] - 3 CW["bgrrg"] +
  CW["bgrrr"] + CW["brgrr"] - CW["brgrr"] + CW["brrgr"]];
```

```
SetOptions[Rasterize, {RasterSize -> 256, ImageSize -> 256}];
```

```
Collect[
  Expand[(Plus @@ data) /. CW[s_String] -> ħStringLength[s] Show[ImageCrop[PieChart3D[
    Table[1, {StringLength[s]}],
    ChartStyle -> (Characters[s] /. {"r" -> Red, "g" -> Green, "b" -> Blue}),
    SectorOrigin -> {{RandomReal[{0, 2 π}], "Counterclockwise"}, 1},
    ChartBaseStyle -> EdgeForm[{Thickness[0.03], Black}],
    ChartElementFunction -> "ProfileSector3D",
    ImagePadding -> 0, ImageMargins -> 0, PlotRangePadding -> 0
  ]], ImageSize -> 52],
  ħ, Factor] + O[ħ]6
```

$$\begin{aligned}
 & 2 \text{ (wheel)} \hbar^3 + \left(\text{ (wheel)} - \text{ (wheel)} + \text{ (wheel)} - \text{ (wheel)} + \text{ (wheel)} - \text{ (wheel)} \right) \hbar^4 + \\
 & \frac{1}{6} \left(-9 \text{ (wheel)} + 3 \text{ (wheel)} + 3 \text{ (wheel)} - 9 \text{ (wheel)} + 2 \text{ (wheel)} + 3 \text{ (wheel)} - \right. \\
 & 9 \text{ (wheel)} + 2 \text{ (wheel)} - 3 \text{ (wheel)} + 3 \text{ (wheel)} - 3 \text{ (wheel)} + 3 \text{ (wheel)} + \\
 & \left. 3 \text{ (wheel)} + 3 \text{ (wheel)} + 2 \text{ (wheel)} + 3 \text{ (wheel)} + 3 \text{ (wheel)} - 3 \text{ (wheel)} \right) \hbar^5 + O[\hbar]^6
 \end{aligned}$$