

why can't \mathbb{F} do something easier?

Posterior J , h condition:

$$J_u(\text{bch}(\lambda_x, \lambda_y)) = J_u(\lambda_x) // CC_u^{\lambda_y} // CC_u^{\lambda_x} + J_u(\lambda_y // CC_u^{\lambda_x})$$

Using $\lambda_x = s\lambda$, $\lambda_y = \epsilon\lambda$, infinitesimal ϵ ,
 $\lambda_s := \lambda // CC_u^{s\lambda}$, get

$$\frac{d}{ds} J(s) = J(s) // \text{der}(u \rightarrow [\lambda_s, u]) + \text{div}_u \lambda_s$$

Posterior J , t condition:

$$J_w(\lambda / u, v \rightarrow w) = [J_u(\lambda) // CC_v^{\lambda} // CC_u^{\lambda} + J_v(\lambda // CC_u^{\lambda})] // u, v \rightarrow w$$

Using $\lambda = \lambda // w \rightarrow su + \epsilon v$, infinitesimal ϵ ?

Prior J [meaning P], h condition:

$$P_u(\text{bch}(\lambda_x, \lambda_y)) // CC_u^{\lambda_x} = P_u(\lambda_x) // CC_u^{\lambda_x} + P_u(\lambda_y // CC_u^{\lambda_x})$$

Using $\lambda_x = s\lambda$, $\lambda_y = \epsilon\lambda$, infinitesimal ϵ , get

$$\left(\frac{d}{ds} P(s) \right) // CC_u^{s\lambda} = \text{div}_u (\lambda // CC_u^{s\lambda})$$

Test that!

Aside: what is $(CC_u^{\lambda})^{-1}$? Isn't it a simple-minded conjugation?

Some A-T Notions. \mathfrak{a}_n is the vector space with basis x_1, \dots, x_n , $\text{lie}_n = \text{lie}(\mathfrak{a}_n)$ is the free Lie algebra, $\text{Ass}_n = \mathcal{U}(\text{lie}_n)$ is the free associative algebra "of words", $\text{tr} : \text{Ass}_n^+ \rightarrow \text{tr}_n = \text{Ass}_n^+ / (x_{i_1} x_{i_2} \cdots x_{i_m} = x_{i_2} \cdots x_{i_m} x_{i_1})$ is the "trace" into "cyclic words", $\text{der}_n = \text{der}(\text{lie}_n)$ are all the derivations, and

Always good to compare — from

$\mathcal{U}(\mathfrak{lie}_n)$ is the free associative algebra "of words", $\text{tr} : \text{Ass}_n^+ \rightarrow \text{tr}_n = \text{Ass}_n^+ / (x_{i_1}x_{i_2}\dots x_{i_m} = x_{i_2}\dots x_{i_m}x_{i_1})$ is the "trace" into "cyclic words", $\text{der}_n = \text{der}(\mathfrak{lie}_n)$ are all the derivations, and $\mathfrak{tder}_n = \{D \in \text{der}_n : \forall i \exists a_i \text{ s.t. } D(x_i) = [x_i, a_i]\}$ are "tangential derivations", so $D \leftrightarrow (a_1, \dots, a_n)$ is a vector space isomorphism $\mathfrak{a}_n \oplus \mathfrak{tder}_n \cong \bigoplus_n \mathfrak{lie}_n$. Finally, $\text{div} : \mathfrak{tder}_n \rightarrow \text{tr}_n$ is $(a_1, \dots, a_n) \mapsto \sum_k \text{tr}(x_k(\partial_k a_k))$, where for $a \in \text{Ass}_n^+$, $\partial_k a \in \text{Ass}_n$ is determined by $a = \sum_k (\partial_k a)x_k$, and $j : \text{TAut}_n = \exp(\mathfrak{tder}_n) \rightarrow \text{tr}_n$ is $j(e^D) = \frac{e^D - 1}{D} \cdot \text{div } D$.

Theorem. Everything matches. $\langle \text{trees} \rangle$ is $\mathfrak{a}_n \oplus \mathfrak{tder}_n$ as Lie algebras, $\langle \text{wheels} \rangle$ is tr_n as $\langle \text{trees} \rangle / \mathfrak{tder}_n$ -modules, $\text{div } D = \iota^{-1}(u - l)(D)$, and $e^{uD}e^{-lD} = e^{jD}$.

Differential Operators. Interpret $\hat{U}(\mathfrak{g})$ as tangential differential operators on $\text{Fun}(\mathfrak{g})$:

- $\varphi \in \mathfrak{g}^*$ becomes a multiplication operator.
 - $x \in \mathfrak{g}$ becomes a tangential derivation, in the direction of the action of $\text{ad } x$: $(x\varphi)(y) := \varphi([x, y])$.
- Trees become vector fields and $uD \mapsto lD$ is $D \mapsto D^*$. So $\text{div } D$ is $D - D^*$ and $jD = \log(e^D(e^D)^*) = \int_0^1 dt e^{tD} \text{div } D$.

Compare — from
The Montpelier
handout.

Prior J [meaning P], t condition:

$$t m_w^{uv} // t h_a^{wx} = t h_a^{ux} // t h_a^{vx} // t m_w^{uv}$$

Given λ_x , this becomes

$$\begin{aligned} P_w(\lambda_x // u, v \rightarrow w) // RC_w^{\lambda_x} // u, v \rightarrow w &= \\ P_u(\lambda_x) // RC_u^{\lambda_x} // RC_v^{\lambda_x} // RC_u^{\lambda_x} // (u, v \rightarrow w) & \\ + P_v(\lambda_x // RC_u^{\lambda_x}) // RC_v^{\lambda_x} // RC_u^{\lambda_x} // (u, v \rightarrow w) & \end{aligned}$$

Remember,

$$\lambda // (u, v \rightarrow w) // RC_w^{\lambda_x} // (u, v \rightarrow w) = \lambda // RC_u^{\lambda_x} // RC_v^{\lambda_x} // RC_u^{\lambda_x} // (u, v \rightarrow w)$$

or

$$(u, v \rightarrow w) // C_w^{-\lambda_x} // (u, v \rightarrow w) = C_u^{-\lambda_x} // RC_v^{\lambda_x} // C_v^{-\lambda_x} // (u, v \rightarrow w)$$

I wish I really understood the rules of the game...

Aside: $(u, v \rightarrow w) // \text{div}_u = \text{div}_u // (u, v \rightarrow w)$

$$+ \operatorname{div}_V // (u, v \rightarrow w)$$