

For reasons unknown, this notebook page got messed up. A Backup PDF is in the parent directory.

KAL-090128: Lie bialgebras, $\mathfrak{gl}(N)$, framing v-knots

January-28-09
9:53 AM

Results with Louis:

n	0	1	2	3	4
$\dim \vec{A}_n$	1	2	7	27	139
$\dim \text{im } T_{\mathfrak{gl}(N)}$	1	2	6	~ 22	less
$\dim \text{im } T_{\mathfrak{gl}(N)}^{\text{bialg}}$	1	2	7	27	≥ 118

[http://katlas.math.toronto.edu/drorbn/AcademicPensieve/Projects/Arrow_Diagrams_and_gl\(N\)/index.html](http://katlas.math.toronto.edu/drorbn/AcademicPensieve/Projects/Arrow_Diagrams_and_gl(N)/index.html)

Something must be right and something is going on. Are there really two $\mathfrak{gl}(N)$ constructions? Which of them is "right"?

[some random thoughts on the matter are below]

* Reminder: \vec{A}/\mathfrak{GT}

* Reminder: Lie bialgebras & arrow weight systems.

* Reminder: $L \oplus U = \mathfrak{gl}(N) \oplus H$
 $\{e_{ij}^t\}_{i \leq j}$ $\{e_{ij}^u\}_{i \leq j}$ $\{e_{ij}\}$ $\{h_i = \frac{1}{2}(e_{ii}^u - e_{ii}^t)\}$

* [6TFor \$\mathfrak{gl}\(N\)\$](#) with $h_{ij} = e_{ij} = \frac{1}{2}(e_{ij}^u + e_{ij}^t)$

(That is, some specific $v \in \mathfrak{gl}(N) \otimes \mathfrak{gl}(N)$ solves the IYBE $[\mathfrak{GT}]$ in $U(\mathfrak{gl}(N))^{\otimes 3}$)

$$\begin{array}{ccc}
 * & \vec{A}(\uparrow) & \xrightarrow{T_{\mathfrak{gl}(N)}} & U(\mathfrak{gl}(N)) \\
 & \downarrow d & & \updownarrow \\
 & \vec{A}(\uparrow) \uparrow^{ab} & \xrightarrow{T_{\mathfrak{gl}(N); H}} & U(\mathfrak{gl}(N) \oplus H) = U(\mathfrak{gl}(N)) \otimes S(H)
 \end{array}$$

directory.

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Something must be right and something is going on. Are there really two $gl(N)$ constructions?

Which of them is "right"?

[some random thoughts on the matter are below]

* Reminder: $\vec{A}/\sigma T$

* Reminder: Lie bialgebras & arrow weight systems.

* Reminder: $L \oplus U = gl(N) \oplus H$
 $\{e_{ij}^t\}_{i \neq j}$ $\{e_{ij}^u\}_{i \neq j}$ $\{e_{ij}\}$ $\{h_i^u = \frac{1}{2}(e_{ii}^u - e_{ii}^t)\}$
 with $h_i^t = e_{ii} = \frac{1}{2}(e_{ii}^u + e_{ii}^t)$

* [6T For \$gl\(N\)\$](#)

(That is, some specific $r \in gl(N) \otimes gl(N)$
 solves the IYBE $[\sigma T]$ in $U(gl(N))^{\otimes 3}$)

$$\begin{array}{ccc}
 * & \vec{A}(1) & \xrightarrow{T_{gl(N)}} & U(gl(N)) \\
 & \downarrow d & & \downarrow \\
 & \vec{A}(1 \uparrow^{al}) & \xrightarrow{T_{gl(N); H}} & U(gl(N) \oplus H) = U(gl(N)) \otimes S(H)
 \end{array}$$

* In Lie world, $\vec{A}(1^{al} \dots)$ represents the Cartan

* In topology, $\vec{A}(1^{al} X)$ represents a "homology class"

* In topology, $\vec{A}(\uparrow^a X)$ represents a "homology class" in the complement of X .

* Example: $\vec{A}(\uparrow^r \uparrow^{ab}) \cong \vec{A}(\uparrow)$ as vector spaces, though I'm not sure how compatible this is with $\vec{A}(\uparrow)$ on

* Remember that even on framed V -knots, \vec{A} is not the only relation.

This all suggests that it may be that the right objects to study are V -framed V -knots - these would be V -knots with a V -homology class in their complement.

[I don't expect this to be the truth, only a step in the right direction]