

Degree 2 for Virtual Knots

January-13-09
1:24 PM

What are $\vec{A}(\text{anything}) / GT$?
 Does every weight system integrate?
 (for knots, for links, for long knots)
 (for braids, for tangles)
 What would x -knots be?
 Is there a local VFTI?
 Is there an extension to VKTFS?

Screen clipping taken: 14/01/2009, 9:24 AM from AcademicPensive/Projects/WKO/DegreeTwo.nb.

In[13]:= ShowMatrix[RowReduce[mat]]

Out[13]/MatrixForm=

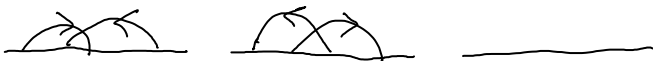
1342	2431	1324	3142	1423	1432	2341	3241	1234	1243	2134	2143
0	0	1	0	0	2	0	0	-1	0	-2	0
0	0	0	1	0	0	0	-2	0	0	0	1
0	0	0	0	1	1	0	0	-1	0	-1	0
0	0	0	0	0	0	1	1	0	0	-1	-1
0	0	0	0	0	0	0	0	0	1	-1	0
0	0	0	0	0	0	0	0	0	0	0	0

outdated

basis



Basis:



Better yet:

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In[12]:= ShowMatrix[RowReduce[mat]]

Out[12]/MatrixForm=

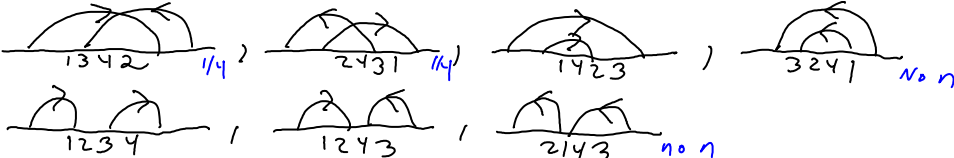
1342	2431	1324	3142	1432	1423	2341	3241	1234	2134	1243	2143
0	0	1	0	0	-2	0	0	1	0	0	0
0	0	0	1	0	0	0	-2	0	0	0	1
0	0	0	0	1	1	0	0	-1	0	-1	0
0	0	0	0	0	0	1	1	0	0	-1	-1
0	0	0	0	0	0	0	0	0	1	-1	0
0	0	0	0	0	0	0	0	0	0	0	0

basis

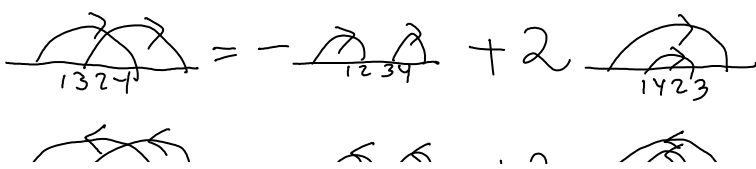
$1/4$ $1/4$ $1/4$ $1/4$ $1/n$ n $1/n$ $1/n$ $1/n$ n

$gl(N)$ (defining)

Basis:



Reductions:



$$\begin{aligned}
\frac{\text{Diagram 1}}{3142} &= - \frac{\text{Diagram 2}}{2143} + 2 \frac{\text{Diagram 3}}{3241} \\
\frac{\text{Diagram 4}}{1432} &= - \frac{\text{Diagram 5}}{1423} + \frac{\text{Diagram 6}}{1234} + \frac{\text{Diagram 7}}{1243} \\
\frac{\text{Diagram 8}}{2341} &= - \frac{\text{Diagram 9}}{3241} + \frac{\text{Diagram 10}}{1243} + \frac{\text{Diagram 11}}{2143} \\
\frac{\text{Diagram 12}}{2134} &= \frac{\text{Diagram 13}}{1243}
\end{aligned}$$

What does $gl(N)$ see? In the defining rep,

In[63]= (# → Wgl[#][n, k]) & /@ diags

Out[63]= {Diag[ar[1, 3], ar[4, 2]] → $\frac{1}{4}$, Diag[ar[2, 4], ar[3, 1]] → $\frac{1}{4}$,
 Diag[ar[1, 3], ar[2, 4]] → $\frac{1}{4}$, Diag[ar[3, 1], ar[4, 2]] → $\frac{1}{4}$,
 Diag[ar[1, 4], ar[3, 2]] → $-\frac{1}{4} + \frac{k}{2} - \frac{k^2}{2} + \frac{n^2}{2}$,
 Diag[ar[1, 4], ar[2, 3]] → $\frac{1}{4} - \frac{k}{2} + \frac{k^2}{2} + \frac{n}{2} - kn + \frac{n^2}{2}$,
 Diag[ar[2, 3], ar[4, 1]] → $-\frac{1}{4} + \frac{k}{2} - \frac{k^2}{2} - \frac{n}{2} + kn$,
 Diag[ar[3, 2], ar[4, 1]] → $\frac{1}{4} - \frac{k}{2} + \frac{k^2}{2}$,
 Diag[ar[1, 2], ar[3, 4]] → $\frac{1}{4} - k + k^2 + n - 2kn + n^2$,
 Diag[ar[2, 1], ar[3, 4]] → $-\frac{1}{4} + k - k^2 - \frac{n}{2} + kn$,
 Diag[ar[1, 2], ar[4, 3]] → $-\frac{1}{4} + k - k^2 - \frac{n}{2} + kn$,
 Diag[ar[2, 1], ar[4, 3]] → $\frac{1}{4} - k + k^2$ }

Screen clipping taken: 14/01/2009, 10:08 AM

What if I also mod out by "short arrows commute with anything" ($\frac{\text{Diagram 14}}{\circ} = \frac{\text{Diagram 15}}{\circ}$ & $\frac{\text{Diagram 16}}{\circ} = \frac{\text{Diagram 17}}{\circ}$)?

— All that's left is $\frac{\text{Diagram 18}}{\circ}$, $\frac{\text{Diagram 19}}{\circ}$, and

the three "framing numbers": $\frac{\text{Diagram 20}}{\circ}$, $\frac{\text{Diagram 21}}{\circ}$, $\frac{\text{Diagram 22}}{\circ}$

⇒ Not quite "Tails Commute", for $\frac{\text{Diagram 23}}{\circ}$ and $\frac{\text{Diagram 24}}{\circ}$ remain distinct.